

It uses a 1200V 90A IGBT, IGBT drivers, a hardware PWM-module and a PC. It basically spins the motor at whichever frequency you set it to and it even uses the space-vector modulation scheme to achieve the highest possible amplitude. I know 90A isn't much but it's a start.



At the top you see the voltage with the little space vector "dent" and the current at the bottom.

There is one problem though: it is all open loop and it uses a PC. Also the PWM resolution is just 8 bits. My plan is to put the controller program on a little $\hat{A}\mu C$ which offers 16-bit pwms. For closing the control loop I want to start out with a speed sensor and thereby control the slip of the ACIM in some clever way that is still to be figured out. Since I have never seen any serious motor controller without current sensors and vector control I might have to implement that as well. There are closed loop sensors already on the IGBT-module but their output somehow didn't seem to linearly follow the amplitude of the current. When all is finished I want to document it like the well known Open Source Motor Controller.

So... do you think this is a promising project worth continuing? And if yes, any suggestions?

Looking forward for replies 🙂 Johannes

State of the project

As of today there are probably around 100 vehicles making use of this project. There have been forks by "Jack Bauer", arber333 and others to use the technology in OEM inverters (Tesla, Ampera, i3, Leaf, ...)

- Hardware
 - Logic (brain) board based on STM32F1
 - Simple 4A gate drivers
 - Melexis current sense boards
 - Isolated voltage sense board
- Software
 - Bootloader for firmware upgrade without programming hardware
 - Firmware with mature support for asynchronous motors and experimental support for synchronous motors
 - Web interface using ESP8266 Wifi chip supporting Parametrization, plotting and firmware upgrade

The "vanilla" kit and documentation can be found here: <u>http://johanneshuebner.com/quickcms/...er-</u>kit.10.html

Tesla Boards here: <u>http://evbmw.com/index.php/evbmw-webshop</u>, Source:<u>https://github.com/damienmaguire</u> Inverter Source code here: <u>https://github.com/tumanako</u>

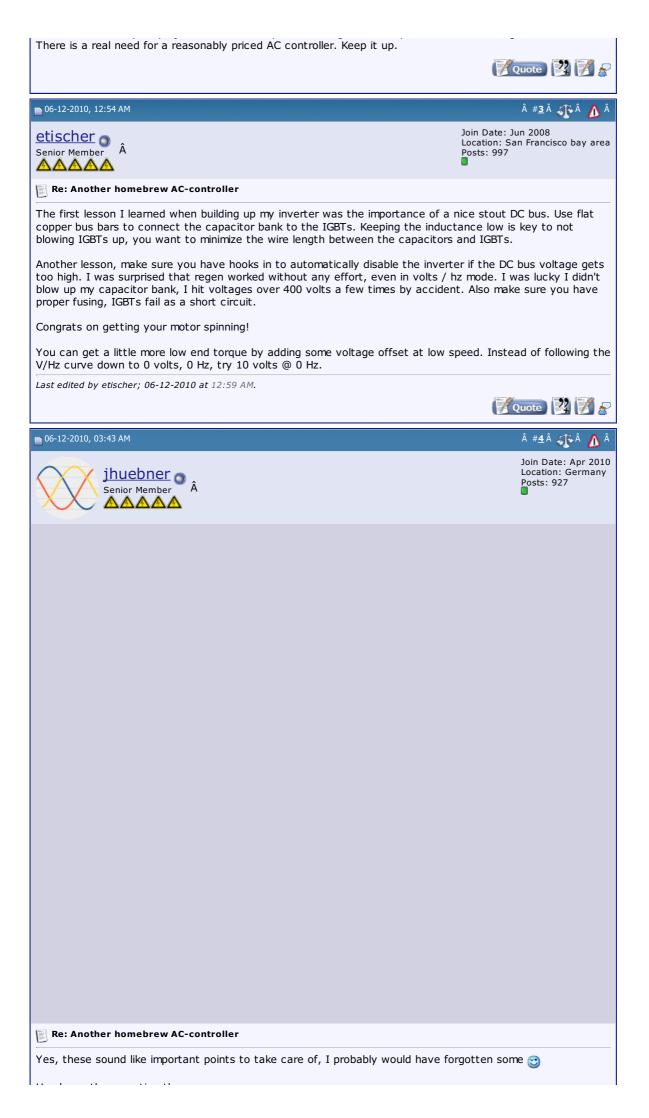
Please let me know what else should be mentioned here.

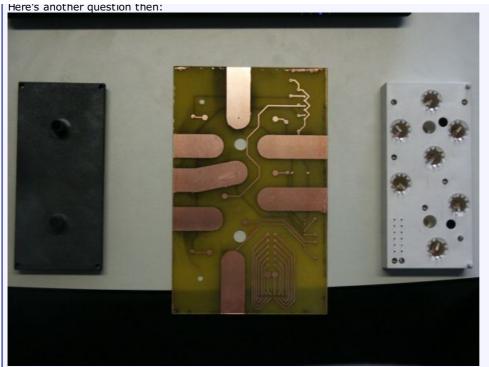
Last edited by jhuebner; 09-19-2018 at 04:33 AM.



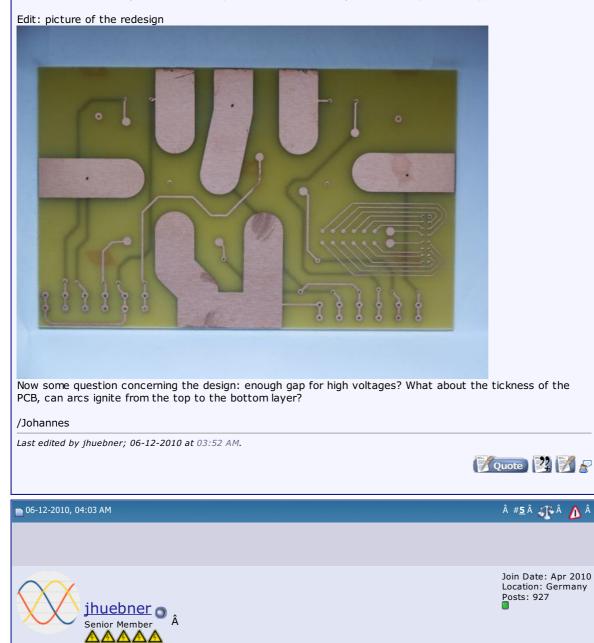


I am interested in your project but don't really know enough to be helpful. I will be following the thread.



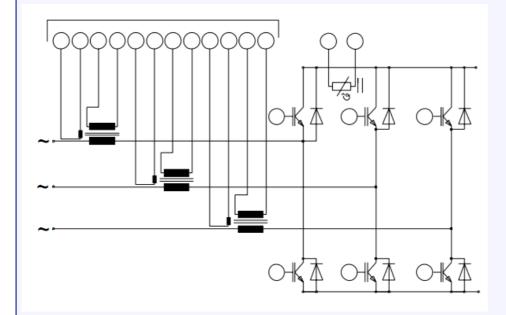


You can see here the PCB-interface to the pressure-contacts (or whatever the term is) of the IGBT interface. As you can see in the first post I simply fixed some lugs to the power contacts. Would you recommend fabricating a bus bar and try to fix it without drilling holes in the precious copper area?



Re: Another homebrew AC-controller

Yet another question:



On the left you can see the current sensors that are supposedly "closed loop". The transfer ratio is 1:2000.

Does anyone know how to make use of them? if I simply attach the scope to either the large or the small coil (or hall sensor?) I do get an output which seems to be in no way proportional to the current though. I then tried feeding the output of the small thing into an OpAmp and feed back the output of the OpAmp to the large coil. I attached the scope to the output, too. That gave me the output you see in the first post but the amplitude stayed the same no matter what the actual current was.

📝 Quote 🕺 📝 🎤

Has anyone ever build a closed-loop current sensor here? What is going wrong?

/Johannes

■ 06-12-2010, 08:34 AM	# <u>6</u> ∰ <mark>≬</mark> Â
JRoque Senior Member Â	Join Date: Mar 2010 Location: Miami, FL USA Posts: 780
🛐 Re: Another homebrew AC-controller	
Hey Johannes, welcome to the forum.	
Got a part number for the current sensors? I think you're right, that looks lik	

coil core. Current transducer these days come complete with opamp, filter, etc; you feed it a voltage and ground reference and they output half of that voltage at rest and move to either rail as current flows through.

If what you have is the discrete coil and hall, you might want to take the hall output, feed each leg to an opamp then the opamp output to one leg of the coil with the other leg being your current output. Reference the output to ground with a resistor. The opamp should output about half the rail voltage so you have both pos and neg current flow measurements. Add some ceramic caps for filtering/bypassing. Or, buy a set of Honeywell CSLA2DK current transducers that have this already done for you.
Good to see you're doing this. I'm taking the Eric T. route and using an industrial VFD brains with external IGBTs and current sensors. These VFD are cheap enough in low HP ratings but they have every possible motor control parameter already coded.
JR
 O6-12-2010, 08:55 AM A #Z Â ↓ Â ▲ Â Observation: San Francisco bay area Doin Date: Jun 2008 Location: San Francisco bay area Posts: 997
Re: Another homebrew AC-controller
Quote: Originally Posted by jhuebner You can see here the PCB-interface to the pressure-contacts (or whatever the term is) of the IGBT interface. As you can see in the first post I simply fixed some lugs to the power contacts. Would you recommend fabricating a bus bar and try to fix it without drilling holes in the precious copper
area? /Johannes
It looks like the IGBT has spade lugs? I would drill holes in the PCB and solder some spade lugs on it. Can you make a larger PCB so you can solder in some caps on the same board?
If you are planning to eventually scale up to larger IGBTs, you might consider buying those and designing your DC bus around them.
🖻 06-12-2010, 10:32 AM Â #8 Â 🐠 Â 🧄 Â
jhuebner Senior Member AAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAA
Re: Another homebrew AC-controller
Re: Another homebrew AC-controller Quote: Originally Posted by JRoque

I don't have a part number for the sensor itself, since it is integrated in the IGBT module. The latter one is called "SKiiP 82 AC 12 I" and manufactured by Semikron.

Quote:

Originally Posted by JRoque 🔊

If what you have is the discrete coil and hall, you might want to take the hall output, feed each leg to an opamp then the opamp output to one leg of the coil with the other leg being your current output. Reference the output to ground with a resistor. The opamp should output about half the rail voltage so you have both pos and neg current flow measurements. Add some ceramic caps for filtering/bypassing.

Thats basically what I did. I'll keep trying.

Quote:

Originally Posted by JRoque 🛐

Or, buy a set of Honeywell CSLA2DK current transducers that have this already done for you.

I don't really like redundancies \bigcirc These sensors are there and I want to use them. But as mentioned above, I will be starting with a V/Hz kindof control which doesn't need them. It's only later with space vector control that I do.

Quote:

Originally Posted by JRoque 🔊

Good to see you're doing this. I'm taking the Eric T. route and using an industrial VFD brains with external IGBTs and current sensors. These VFD are cheap enough in low HP ratings but they have every possible motor control parameter already coded.

Since I'm a professional software developer but a hobbyist at electrics I'd rather buy an all done hardware device and do the programming myself. Haven't found anything like it though. Can I see your progress anywhere?

Quote:

Originally Posted by etischer 🔊

It looks like the IGBT has spade lugs? I would drill holes in the PCB and solder some spade lugs on it. Can you make a larger PCB so you can solder in some caps on the same board?

If you are planning to eventually scale up to larger IGBTs, you might consider buying those and designing your DC bus around them.

Why would I need holes for soldering on spade lugs? The IGBT module itself is definitly meant to be contacted by a PCB.

A larger PCB would be a dream. I originally planned to integrate the drivers on the same PCB but failed to do so because of limited equipment for making PCBs. Maybe I should employ one of those PCB makers and reconsider that.

I also noticed that most newer Semikron modules are using screw contacts again. So once I upgrade I can just use lugs.

22 2

/Johannes

P.S. More pictures can be found here: <u>http://johanneshuebner.com/coppermin...s.php?album=60</u>

💼 06-12-2010, 04:39 РМ	â # <u>9</u> â ∢∰ â <u>∕</u> ∆ â
JRoque Senior Member Â	Join Date: Mar 2010 Location: Miami, FL USA Posts: 780
Re: Another homebrew AC-controller	
Quote:	
Can I see your progress anywhere?	
I don't have anything to show just yet. I bought a Hitachi SJ300 5HP VFD and thoug do my experiments with a known good VFD rather than having to worry about the IG other parts working, I'll do the external switches/sensors.	

I bought a smaller 5HP motor to play with and I'm now working on the accelerator/brake/regen concept. I

process - with the bra external logic to hand What language and ta with some dabbling or reference - or you ca	ake pedal. I tried to get th le it using start, stop with arget hardware do you coo	ne VFD to do this but it lo n coasting, accel/decel fur de for? I'm doing mostly ba <u>ko open source project</u> is	ll only decelerate - and regen oks like I'm going to end up w nctions. asic and assembler on Atmel o C exclusively and might be a	rith chips
JR				
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■ 06-13-2010, 03:23 AM			# <u>10</u> 4	🏹 Â <u>۸</u> Â
jhuebi Senior Me			Join Date: Location: C Posts: 927	Germany
🛐 Re: Another homeb	rew AC-controller			
	SKAI is the answer 😁 Stil nako project but they did		garanteed to work. I didn't se components.	e much
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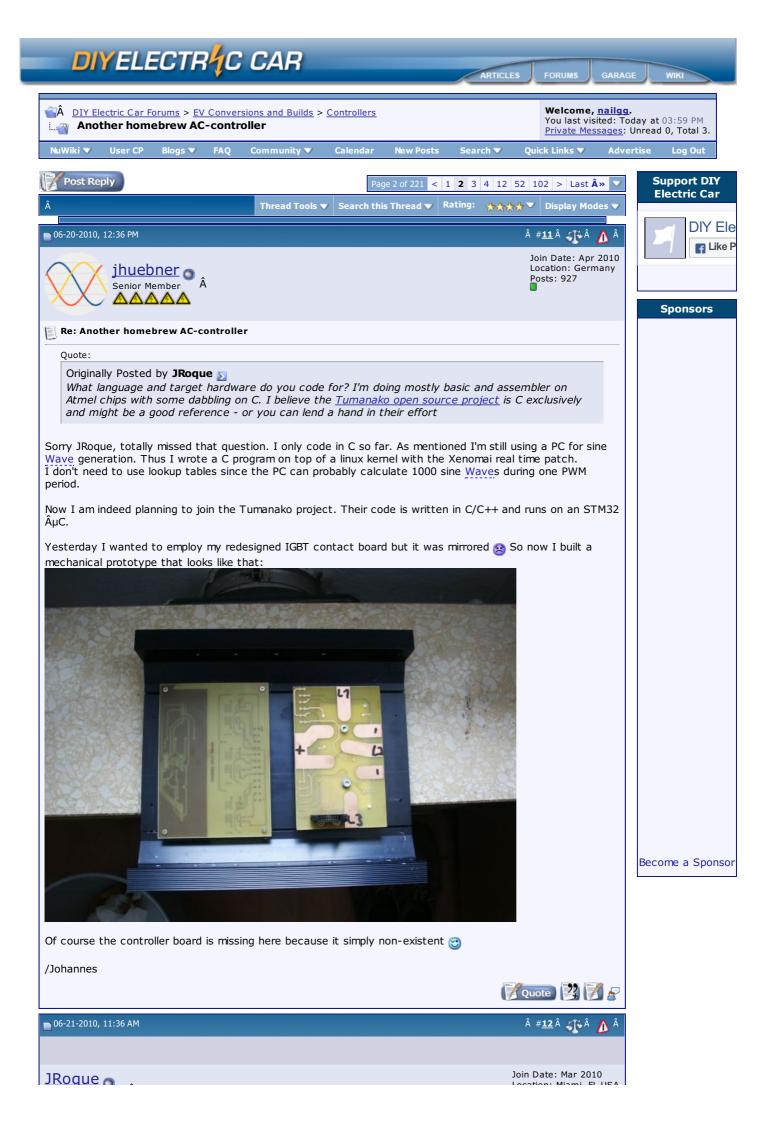
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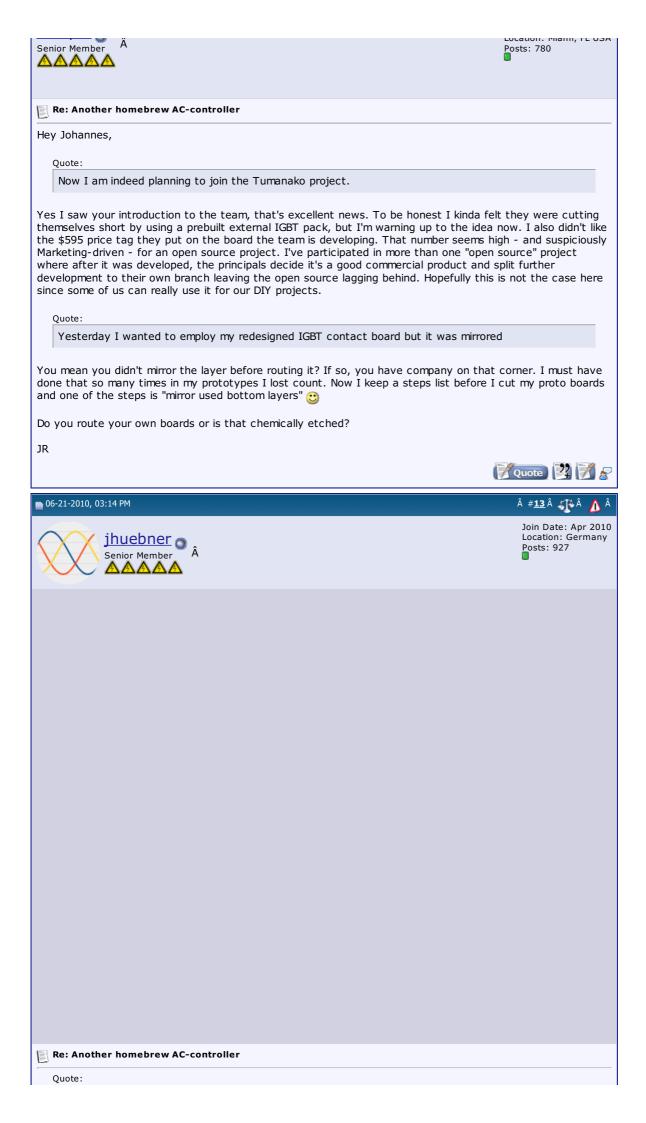
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Originally Posted by JRoque Yes I saw your introduction to the team, that's excellent news. To be honest I kinda felt they were cutting themselves short by using a prebuilt external IGBT pack, but I'm warning up to the idea now. I also didn't like the \$595 price tag they put on the board the team is developing. That number seems high - and suspiciously Marketing-driven - for an open source project. I've participated in more than one "open source" project where after it was developed, the principals decide it's a good commercial product and split further development to their own branch leaving the open source lagging behind. Hopefully this is not the case here since some of us can really use it for our DIY projects.	
I'm not planning to buy any custom-built hardware for now. I picked up some board with an STM32 from work. Concerning the power stage I'll just use what I've got so far. I designed it with a lot of help from Semikron themselves so I think the chances are good for it to actually work.	
Quote: Originally Posted by JRoque You mean you didn't mirror the layer before routing it? If so, you have company on that corner. I must have done that so many times in my prototypes I lost count. Now I keep a steps list before I cut my proto boards and one of the steps is "mirror used bottom layers" \bigcirc	
Yeah kinda like that 😋 Top and bottom line up perfectly but when putting it on top of the module it is "right side left".	t
Quote:	
Originally Posted by JRoque Do you route your own boards or is that chemically etched?	
Erm what? It's both 😋 I did the layout with a program called FreePCB, printed it on a photo-sensitive board and etched everything away that wasn't black.	
/Johannes	
	8
💼 07-28-2010, 04:07 PM Â # <u>14</u> Â 🐢 Â 🏠	÷
	A
jhuebner Senior Member Â Â	10
Join Date: Apr 20 Location: Germar Posts: 927	10
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I've mounted IGBT and drivers to a large heatsink and am now driving it with an STM32 with the help of the Tumanako project. I've implemented a very simple sine Wave generator which I submitted to Tumanako.

It also looks like I'm close to cracking the current sensor issue with the help of the DRV401 IC. Tumanako has already implemented the field oriented control methods and is waiting for a suitable driver model to run it on.

Quote 🕎 🎢 🔎

I'm pretty optimistic that we'll have a working inverter soon, though not road legal...

/Johannes





🛐 Re: Another homebr	rew AC-controller			
Thanks Paul 🙂				
intermediate circuit ca	pacity. As a result I was pikes caused by the PWM		ather thin and I lacked an shaft encoder because the C bus would reach +-100V (
around +-5V and I car a clean count.	n cleanly read the encode	er. Well, sort of. I have to	voltage spikes have droppe use the STM32s digital filte	er to get
So, next I can impleme my text book)	ent a simple slip controlle	r with the simple equation	slip ~ torque (thats what i	t says in
/Johannes				
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If you run your inverter in simple V/Hz mode (no speed feedback), do you get the stall at 40-50hz?

Could it be your DC bus voltage is sagging and you don't have enough voltage to maintain your V/Hz ratio? Could your speed PID loop just be a bit unstable?

To get the motor to come to a complete stop with simple slip control you can try implementing a DC injection brake.

Quote:

Originally Posted by **jhuebner** *Well, its about time to report some news:*

1. I implemented a simple slip control. The rotor speed is measured with a toothed wheel and the inverter tries to follow that speed. If the inverter has a higher frequency, the motor accelerates, if it runs at lower frequency the motor breaks. Works as expected, but the motor never came to a stand-still. I think there is still some EMI spikes that make it through the filter.

2. I tested the inverter with the newly arrived 18,5 kW motor. It runs smoothly, except at 40-50 Hz it jiggles about. At any higher or lower frequency it is smooth. If I accelerate too quickly, say from 30 to 70 Hz without a ramp, the bridge drivers switch off. Should be enough hardware protection for now.

3. Today I tested the inverter with a 3kW DC source and a 32 kW load resistor (3,5 Ohms). It gets fairly hot after a couple of minutes. Also one driver shut off, presumable due too over temperature. I'll add some fans to avoid hot spots.

The video should be ready soon! Johannes

Last edited by etischer; 06-03-2011 at 11:58 PM.

📄 06-07-2011, 07:30 PM



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#<u>26</u>Â **∡™** ∧ Â

Quote 🕺 🕅 🔎

Re: Another homebrew AC-controller

Quote:

Originally Posted by JRoque

Hello Johannes. Between this and your open source project work it sure sounds like you're keeping busy.

Hey so what happens if the speed sensor goes out and stops working? Would that tell the controller speed = 0 and command higher current/speed? Hopefully the controller will shutdown if there's no signal from the sensor.

Security stuff will have to wait ;-) Right now it would shut down the motor inherently, because 0 rpm is reported when the sensor connection fails.

Quote:

Originally Posted by JRoque 🔊

Is the sensor cable shielded? I wouldn't expect EMI issue at such low power (nearly stopped) and no load. Maybe your comparator is being too sensitive or needs a bit of padding. Perhaps you can filter at the switch side with a couple of caps to take up the transients.

Well, thats some hints. I have added an RC-filter right before the micro. But the cable isn't shielded.

Quote:

Originally Posted by JRoque 🔊

Could the vibration be self resonance at 50 hz? Lets hope some of the motor gurus jump in here.

A 32kW resistor! wow, never seen a monster like that. Is it a 3 phase load? Would love to see a pic of that thing or a video as you mentioned.

JR

Yep, the resistor is rather large. It has its own trolley and weighs 50kg. Its small though compared to the 1MW resistors used for some tests of the 900kW solar inverters.

Next test is scheduled for Friday next week (17th of June). I hope that I won't forget my camera this time. Maybe I can connect to the motor before that date and make a video of it spinning at 200 Hz.

Quote:

Originally Posted by etischer 🔊

If you run your inverter in simple V/Hz mode (no speed feedback), do you get the stall at 40-50hz?

Could it be your DC bus voltage is sagging and you don't have enough voltage to maintain your V/Hz ratio? Could your speed PID loop just be a bit unstable?

To get the motor to come to a complete stop with simple slip control you can try implementing a *DC* injection brake.

Yes, the stall is at 40-50 Hz. The DC-voltage is way too low for this motor anyway. Should be 500V but I only have 120V available.

Also right now there is no speed PID loop. Especially with the new motor there isn't even any slip control because the shaft encoder needs to be rebuilt. I'm simpy running at a fixed frequency with the amplitude controlled by V/Hz.

Cheers.

Johannes



#<u>27</u>Â 🕂 Â 🛕 Â

Join Date: Apr 2010 Location: Germany Posts: 927

🛐 Re: Another homebrew AC-controller

jhuebner 👩

Senior Member

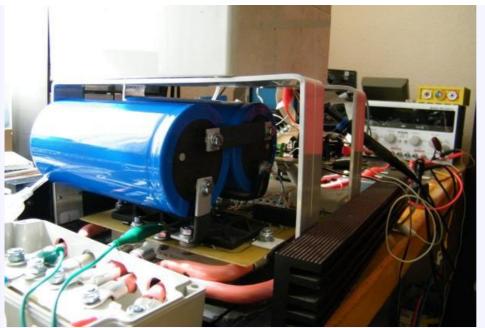
More news:

🗖 06-19-2011, 11:31 AM

Heres a video: <u>http://www.youtube.com/watch?v=PvUmBNgT1KQ</u>

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And some pics:

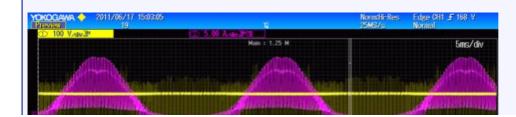


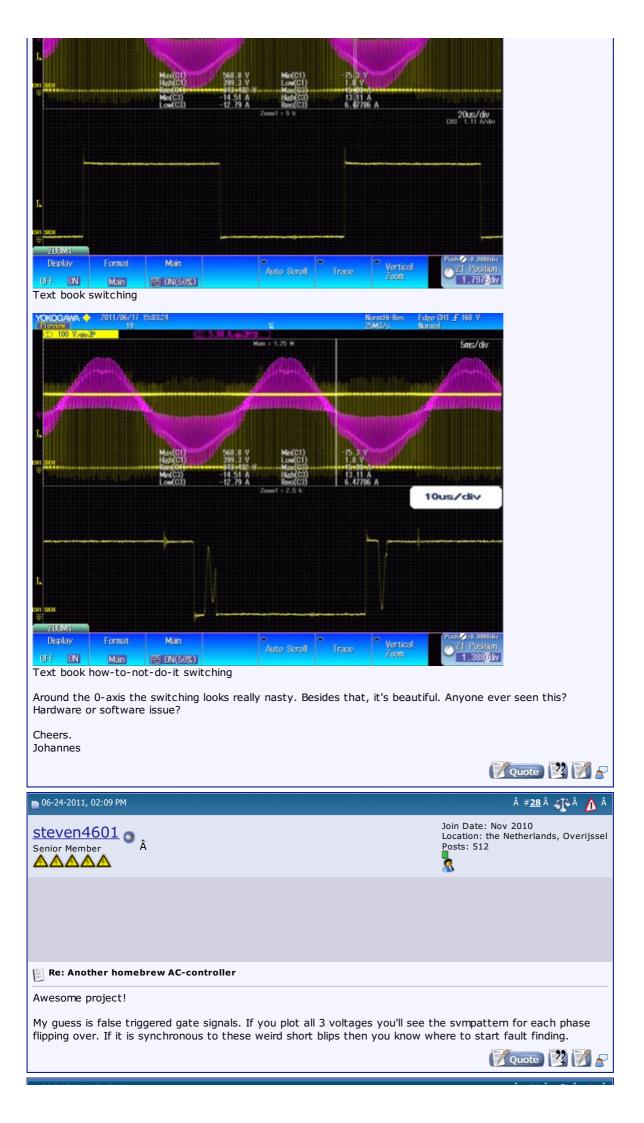
Fixed the capacitors and the adapter circuit board.



This is the 32 kW resistor. We did a 2nd test run last friday. At 480V strange noises came from the unpowered inverter. Seems like some distances need to be enlarged to hold up to the desired 600V.

We then looked at the switching patterns:







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I've spent the last couple of days rebuilding my controller. I replaced the jerky wiring with small copper bus bars, well capable of 100A. It looks much cleaner already, even though I don't like the long way from the back of the module to the front.

I also had the back of the contactor PCB and the gate driver board covered with opaque paint.

A problem I spotted though is within the red circle: The gate signal of bottom IGBT of phase 1 runs really close to phase leg 1. The gate signal is a potential of +/-15V whereas the phase leg is between 0V and Vdc, which will get as high as 600V. I guess I should cut the trace and wire it or put a big blob of paint on it. What do you guys think?

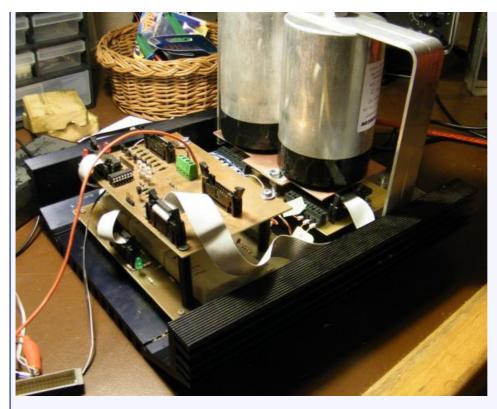


I also got some film capacitors. They read 1100V and 420ŵF. I'm planning to install 2 of those in parallel. The old electrolytic capacitors got me up to 3400ŵF and I'm just hoping that 840ŵF will be enough. A 22kW inverter that I just bought has 1100ŵF

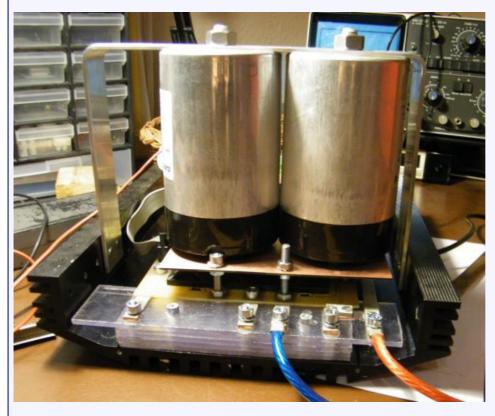
Cheers, Johannes

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Overall view of the inverter



Terminal area

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there's a base equ		e system voltage, coil indu ars to be a great deal of tri	ctance and switching freq	uency.
To be honest I didn't d Our 880kW solar invert current is 1500A. I run linearly with the currer	o any calculation but lo ers use 27 of them, so at 8 kHz and maximum it draw and decrease lir	have to buy them, just not poked at existing devices to 11340µF. They run a PWN o current will be 50A. I believ nearly with rising PWM frequ rrent as one of our solar inv	get the order of magnitud 1 frequency of 3 kHz and r ve that capacity has to ind iency. So I need 50/1500	de right. naximum crease * 3/8 *
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Post Reply		Page 4 of 221 « First <	2 3 4 5 6 14 54 104 >	Last » 🔽
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Quote:

Originally Posted by jhuebner 5

So the ADC is decoupled from the high voltage with resistors. The rather large capacitor smoothes out the voltage. It's one hell of a low-pass but the bus voltage should only change slowly. Anyone see a problem with that arrangement?

This doesn't isolate the high voltage from the controller. And you are unlikely to measure what you expect. If your controller is nominally isolated, it will tell you which side of the traction circuit has the most leakage -- probably by saturating the input range and injecting current into the pin. Or it might just pick up capacitively coupled noise.

There are reasonable ways to measure voltages using optocouplers, especially if you aren't demanding about speed or precision. But with two or more voltages you find that using a SPI A/D converter and a Si84xx or ADUM isolator is easier to build.

Quote:

Originally Posted by jhuebner 🛐

I also found out the the SKH122 drivers add $5\hat{A}\mu s$ dead time on each side of the pulse. That might explain some strange voltage jumps observed earlier.

That's a really long dead-time, suitable for old, slow IGBT modules. You might want to increase your turn-off time to compensate. The increase in thermal load might be easier than trying to modify encapsulated gate driver modules.



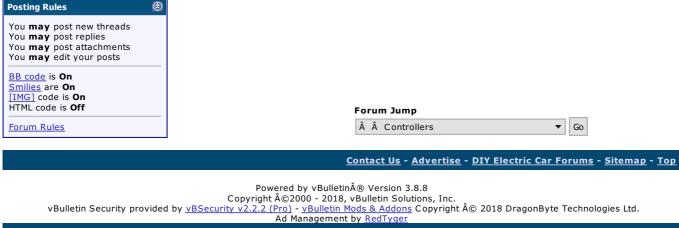




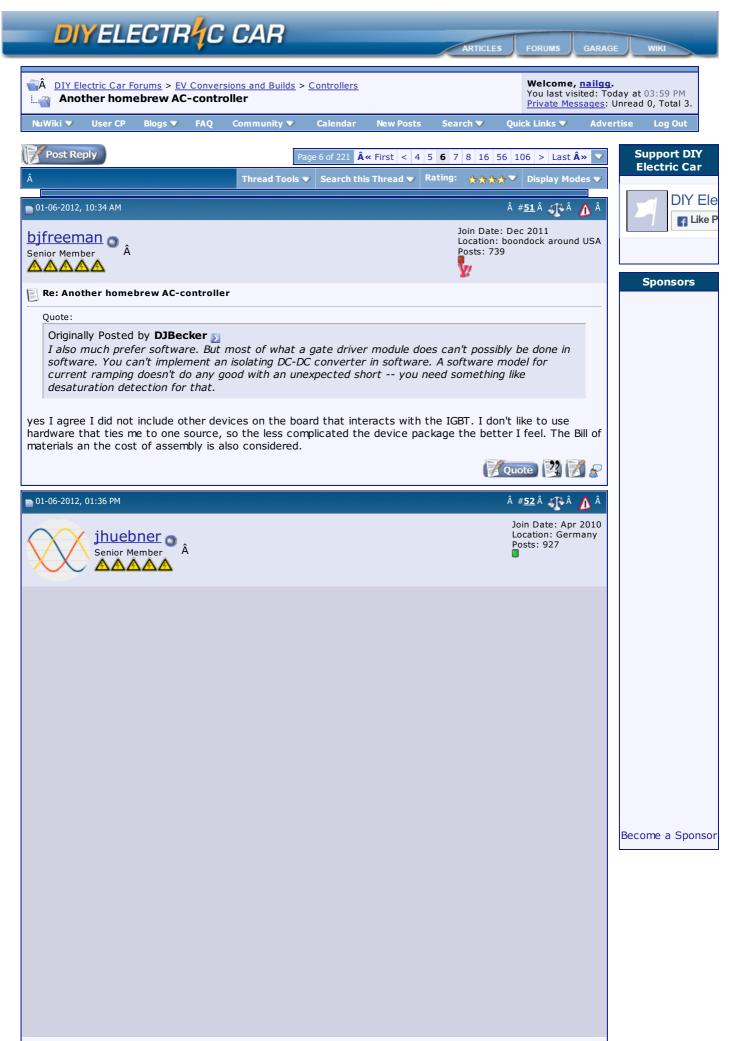


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Quote:

Originally Posted by DJBecker 53

Do you understand that you are making the traction system non-isolated? And that it's likely to return bogus values during operation because of capacitive coupling?

Yes I understand that the battery power is now connected to the logical supply voltage via a 1M or 3M resistor respectively. So the computer is no longer isolated from the power stage. What practical difference does this make? The battery pack is still isolated from the car chassis as far as I can see. I checked the circuit diagram of the solar inverter today. The main difference is an operational amplifier for higher input impedance.

By capacitive coupling you mean that a stray capacitance might develop in parallel to the resistors and thus disturb my voltage sensing?

Quote:

Originally Posted by DJBecker 5

A typical IGBT gate driver module does much more than a TC4451 gate driver chip. The module has voltage isolation, desaturation detection, fault latching, overlap/deadband enforcement, undervoltage lockout, and often an isolated gate power supply.

To get similar functionality you would need a gate driver, optoisolator, a bi-polar DC-DC converter, and some design effort. Even then you are skipping desaturation and fault protection. And the undervoltage lock-out is probably ineffective.

We use a Si8233 chip and a uni-polar DC-DC converter, and are delighted with its performance, noise rejection and isolation. But we're using MOSFETs, which are easier to turn off than IGBTs. We don't need a negative voltage on the gate or deadband timing that varies with the current.

I have to admit that desaturation detection has saved my module probably 50 times. I understand that discretely building the gate drive circuit is more than just plugging in a decoupling device. But then you're saying that you're delighted with the performance of the Si8233. I saw a diagram with a second DC-DC converter that even provides negative voltage. So if the desaturation detection is easy to replicate it should be a sane alternative. Hardware deadband generation is completely redundant with a modern $\hat{A}\mu C.$

Quote:

Originally Posted by bjfreeman 🔊

I follow similar design, I use a opto isolated gate driver with an Isolated voltage to make sure the IGBT has hard turn off and turn one. this board mount directly to the IGBT This keeps all low level circuits out of the High voltage loop.

I use IGBT with low on resistance to minimize the heat dissipation.

for Cooling I started with Cold Plates but have developed a thin Aluminum sealed case with ports for fluid flow for all IGBT, at 3gpm into a transmission cooler.

Do you have any more details an that case?

Quote:

Originally Posted by bjfreeman 🔊

yes I agree I did not include other devices on the board that interacts with the IGBT. I don't like to use hardware that ties me to one source, so the less complicated the device package the better I feel. The Bill of materials an the cost of assembly is also considered.

For the solar inverters the gate drivers are implemented using FPGA. But those are Megawatt devices that use stuff like gate current control. FPGAs are definitly fast enough for gate drive logic, not sure about DSPs

📝 Quote 😰 🏹 🎤

📄 01-06-2012, 03:37 PM

bjfreeman Senior Member Â



Join Date: Dec 2011 Location: boondock around USA Posts: 739

¥/

Re: Another homebrew AC-controller

Quote:





Hmmm I didn't quite follow the OV / phase issue you described. Do you mean the phases were fighting each

other by being energized 50% at all times? Got any scope screenshots of the latest waves? Did you get around to change the PWM frequency after all? Any plans to vary PWM base frequency with speed? Not sure that's even necessary other than to squeeze max torque and reduce switching noise. As it stands, it's a great accomplishment that it runs the truck even if it's not finished yet so congratulations on getting this far. JR Quote 🕺 🖌 🖉 📄 03-12-2012, 02:52 PM #<u>60</u>Â Join Date: Apr 2010 jhuebner O Â Location: Germany Posts: 927 Senior Member AAAAA Re: Another homebrew AC-controller Quote: Originally Posted by JRoque Hmmm I didn't quite follow the OV / phase issue you described. Do you mean the phases were fighting each other by being energized 50% at all times? Got any scope screenshots of the latest waves? No fighting ;-) Its just that the way it was the IGBTs were operated with short pulses. My old-ass drivers insert 2,5ŵs deadtime before AND after each pulse. Thus, any pulse shorter than 5ŵs will simply not do anything at all. So now, say you want 20% of your sine amplitude. You should accomplish that by varying your dutycycle from 40% to 60%. Instead I had used 0% to 20%. Ouote: Originally Posted by JRoque Did you get around to change the PWM frequency after all? Any plans to vary PWM base frequency with speed? Not sure that's even necessary other than to squeeze max torque and reduce switching noise. Yeah, changed it to 4,4 kHz. I think it is better inspite of the huge dead time. Though it is rather noisy. Whats cool though is that it sounds exactly like the tram here in Kassel 😁 The frequency is fixed, advanced stuff might follow later on. Quote: Originally Posted by JRoque 5 As it stands, it's a great accomplishment that it runs the truck even if it's not finished yet so congratulations on getting this far. Thanks 😁 Even if it sounds cocky: 4 years ago I didn't even know what "3-phase current" meant. Now I'm running a car on it. It is quite a kick. Quote 🕺 📝 ج e 6 of 221 « First < 4 5 6 7 8 16 56 106 > Last » Post Reply Share or Bookmark this del.icio.us 👷 Digg 🕳 Reddit Facebook G Google Yahoo! StumbleUpon Newsvine Edit Tags <u>Tags</u> None

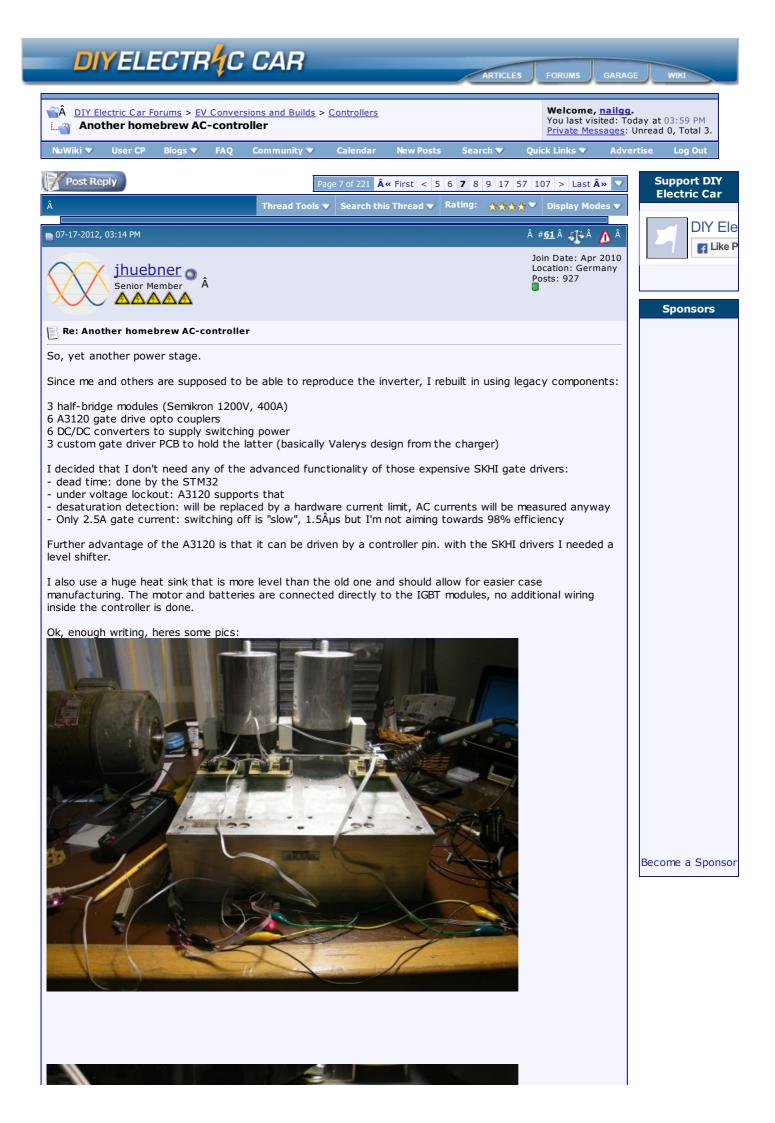


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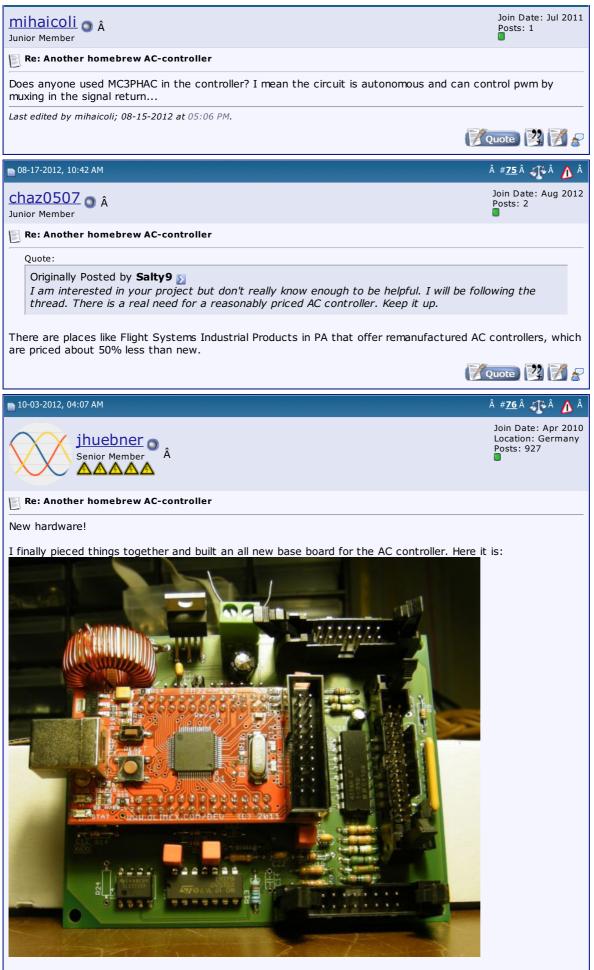
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â #<u>**74**</u> â 👫 â <u>/</u> â



Features external:

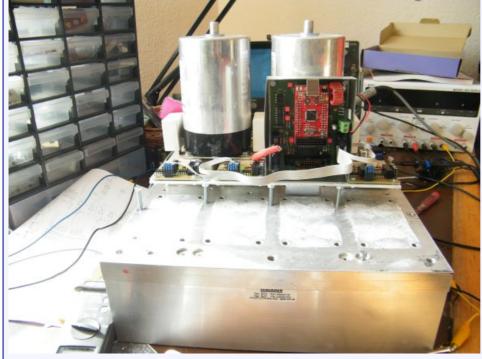
- 8 digital inputs 12V: on, start, brake, motor protection switch, forward, reverse, emergency stop, bms
- 4 digital outputs, open collector: dc switch, error, over temperature, precharge
- 1 PWM output with the highest relative temperature signal: motor or heatsink
- 3 analog inputs: throttle, throttle redundance, motor temperature

1 pulse generator input

Features internal

- 4 analog inputs: current L1, current L2, DC link voltage, heatsink temperature
- 3 complementary PWM outputs for the bridge
- Programmable hardware over current protection
- 2 UART pin headers: 1 for programming, 1 for console/communication
- USB yet unused
- Hardware PWM inhibit logic. The PWM is interrupted by: over current, motor protection signal, emergency stop signal. The latter two are failsafe: they must be high for the PWM to work

Thats pretty much it, I tried to keep it as simple as possible. Heres the baby built in:



And here are some mistakes I made/lessons I learned:

- I twisted one of the pin headers for the olimex board. Had to cut all traces and rewire 😝 I thought I'd triple-checked it because I was so afraid of it. Next time I'll quad-check
- Due to a lack of space I skipped over voltage protection diodes. When I tested the digital inputs I applied 12V to the analog throttle input. BANG, controller dead
- Also due to a lack of space I skipped OpAmps for the current measuring inputs. Now I realised that the ADC inputs have a nasty low impedance when sampling a pin. This will pose accuracy problems and it makes the over current protection a bit inaccurate, too
- Some parts are a bit close together. Didn't spend much time on determining the correct foot print for every capacitor, pin header and so on

Things that work as expected:

- PWM with AI cheapo gate drivers I'm delighted with the performance
- hardware PWM inhibit: cut any of the two digins and the motor stops immediatly.
- hardware overcurrent protection: when set low it will detect a blocked motor shaft even on my 1.5kW test motor run at 60V (instead of 380V)
- Cheap dc link voltage sensing: no galvanic isolation but high resistance (1M) to high voltage.
- Temperature measurement: lookup table in software is very accurate
- 5V Current sensors: no negative supply voltage needed

 ${\rm I}$ will conduct some more tests once the controller is in the car. But most circuits are already proven by the previous model so ${\rm I'm}$ optimistic.

As soon as I've made corrections I will post the circuit diagram. The software is still the largest question mark: as mentioned here (<u>https://www.diyelectriccar.com/forums...ics-76985.html</u>) the control algorithm is quite crude but drives a car.

Besides that it might be time to offer a kit. Anyone interested?



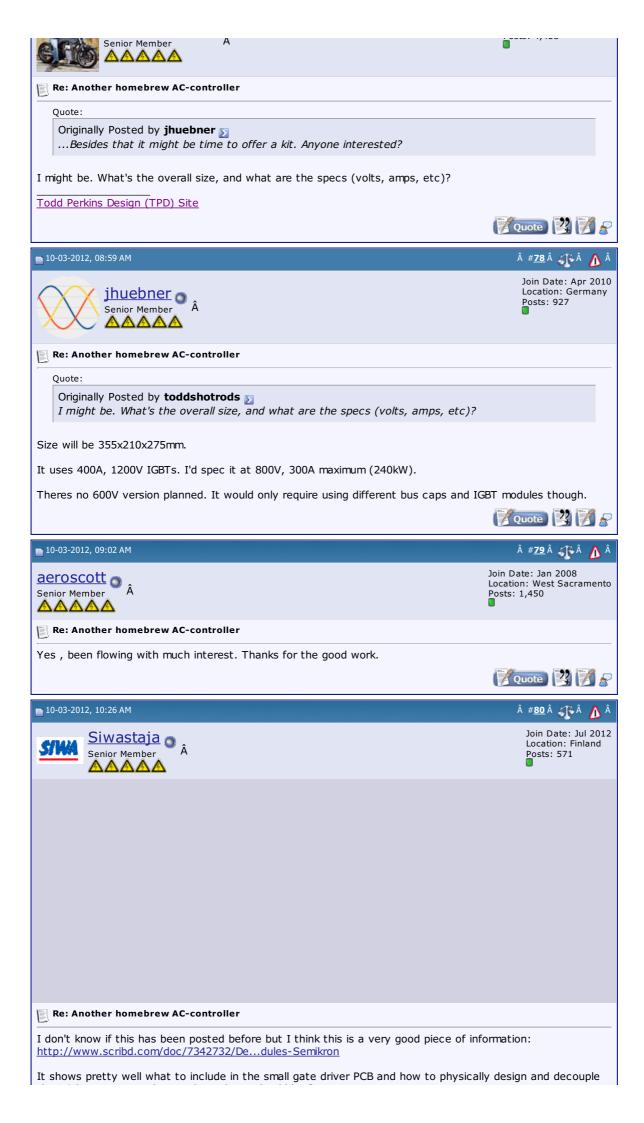
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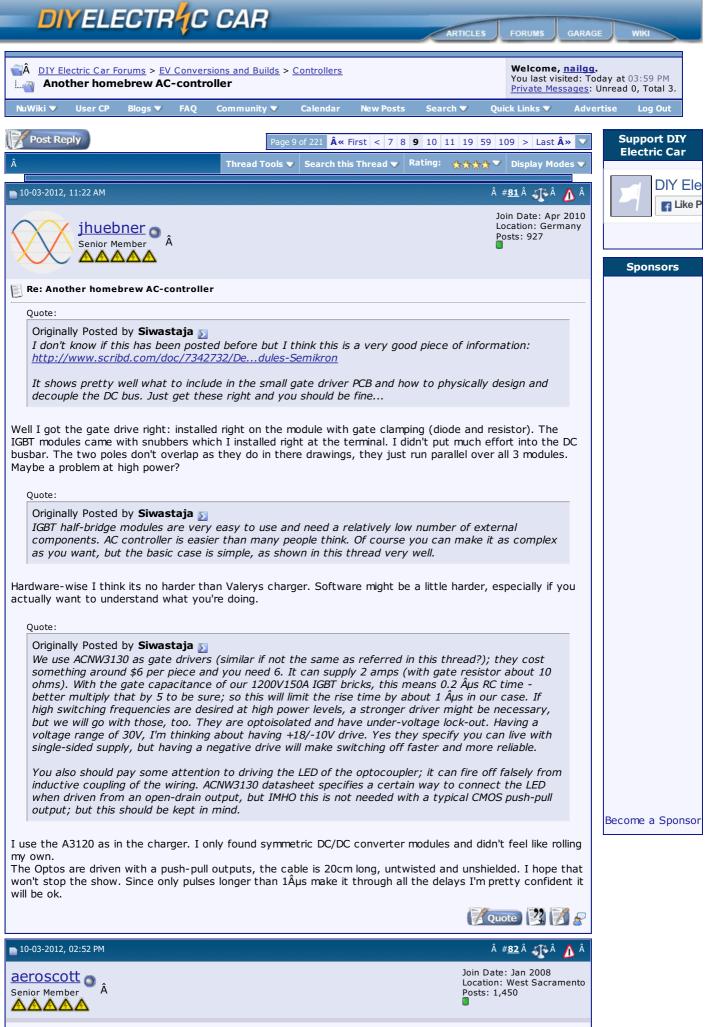
Join Date: Feb 2009 Location: Columbus, OH Posts: 4.458

#<u>77</u>Â 🕂 Â <u> </u>Â

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the DC bus. Just get these rig	ght and you should be	fine		
IGBT half-bridge modules are controller is easier than many case is simple, as shown in th	people think. Of cours			
We use ACNW3130 as gate d around \$6 per piece and you capacitance of our 1200V150 sure; so this will limit the rise high power levels, a stronger and have under-voltage lock- Yes they specify you can live faster and more reliable.	need 6. It can supply A IGBT bricks, this me time by about 1 µs i driver might be necess out. Having a voltage	2 amps (with gate res ans 0.2 µs RC time - n our case. If high sw sary, but we will go w range of 30V, I'm thir	sistor about 10 ohms). Wit better multiply that by 5 itching frequencies are de ith those, too. They are o hking about having +18/-1	h the gate to be sired at ptoisolated DV drive.
You also should pay some att coupling of the wiring. ACNW3 open-drain output, but IMHO kept in mind.	3130 datasheet specifi	es a certain way to c	onnect the LED when drive	en from an
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Re: Another homebrew AC-controller







I'm refactoring the firmware code to match the inner with the outer beauty.

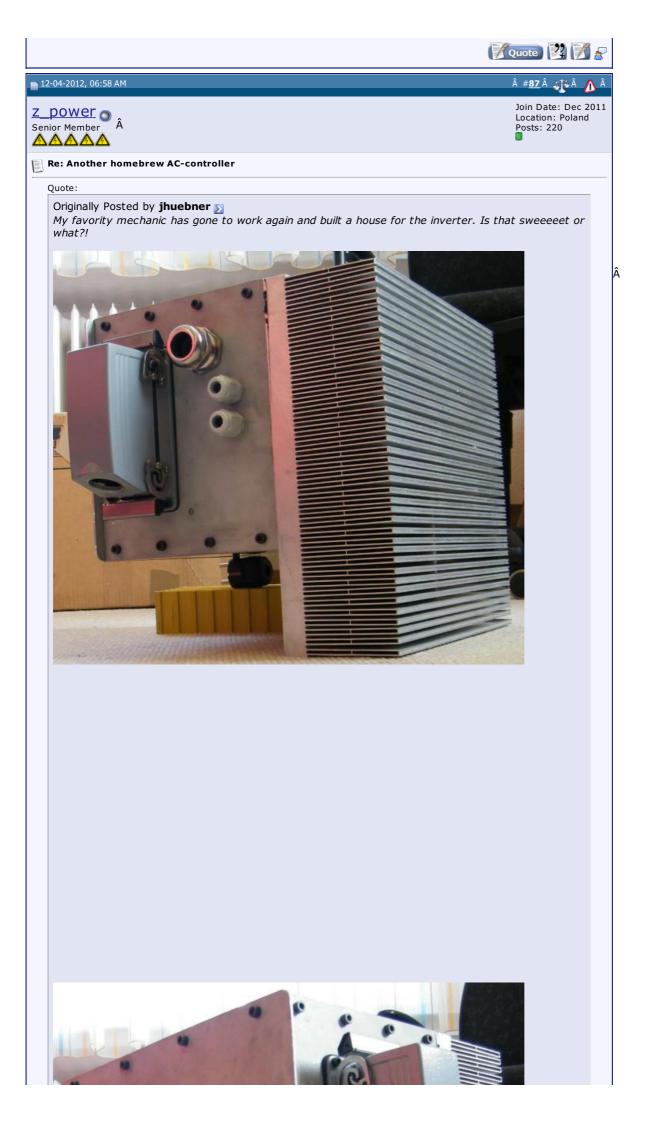
OMG so cool!!! Wow..

I want to make good controller. for remy !!

Wow!!

We are Korea's gas to EV converting company for excutive sedan only.

And Idea is welcome. 🙂





I am interested!, i like your board with olimex development board	
probably you are not interested in sell kits but i could be interested in only board	Is and list of components.
Do you run tumanako firmware with no modifications in your board? I attach some pictures i am planning to build	
jlcortex	
Attached Thumbnails	
Â	
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01-01-2013, 02:37 PM	â # <u>90</u> â 🐠 â <u> </u> â
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by jlcortex <i>Congratulations, nice controller, i am willing to see it installed and working!</i>	
Well, this it where it lives:	



Quote:

Originally Posted by **jlcortex** *I am interested!, i like your board with olimex development board probably you are not interested in sell kits but i could be interested in only boards and list of components.*

Well I guess I should just offer the PCB including components on the PCB and you have to get the heat sink and power components yourself. Complete kits might be a next step, will see.

Quote:

Originally Posted by **jlcortex** *Do you run tumanako firmware with no modifications in your board?*

I have heavily refactored the tumanako software and haven't gotten around to merging it to the svn.

 Quote:

 Originally Posted by jlcortex >

 I attach some pictures i am planning to build jlcortex

 Looks neat and very compact. Are you using concept drivers? The round things are the bus caps or just snubbers?

 Heres a preliminary circuit diagram: http://johanneshuebner.com/stuff/cb.png

 Last edited by jhuebner; 01-01-2013 at 02:50 PM.

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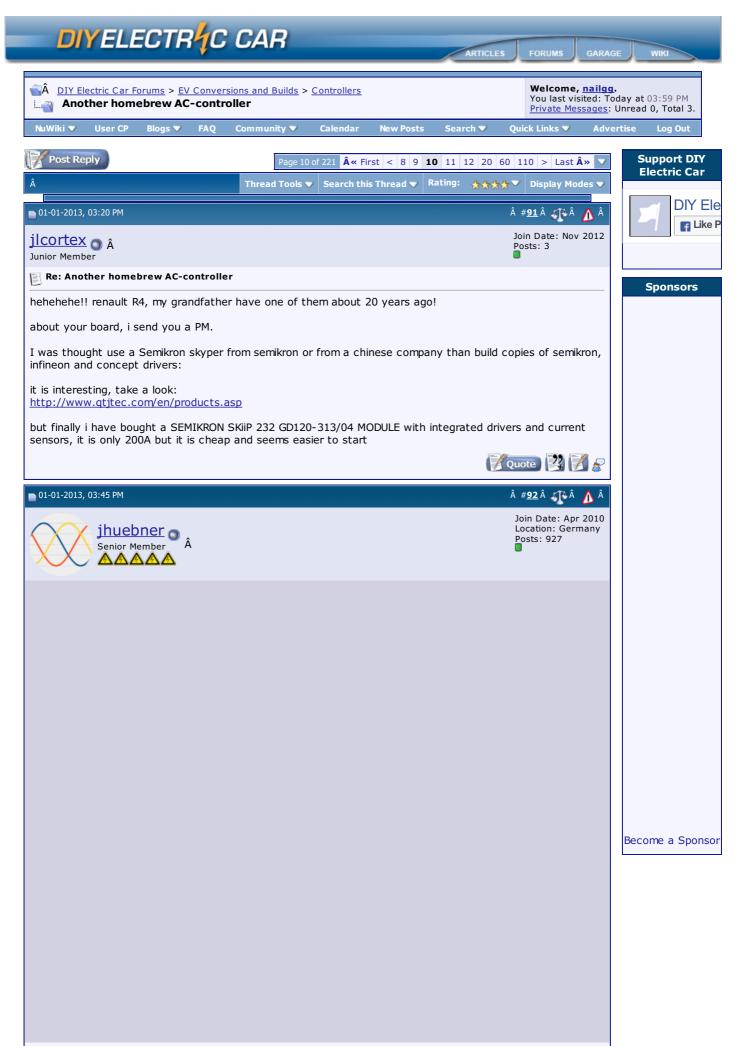
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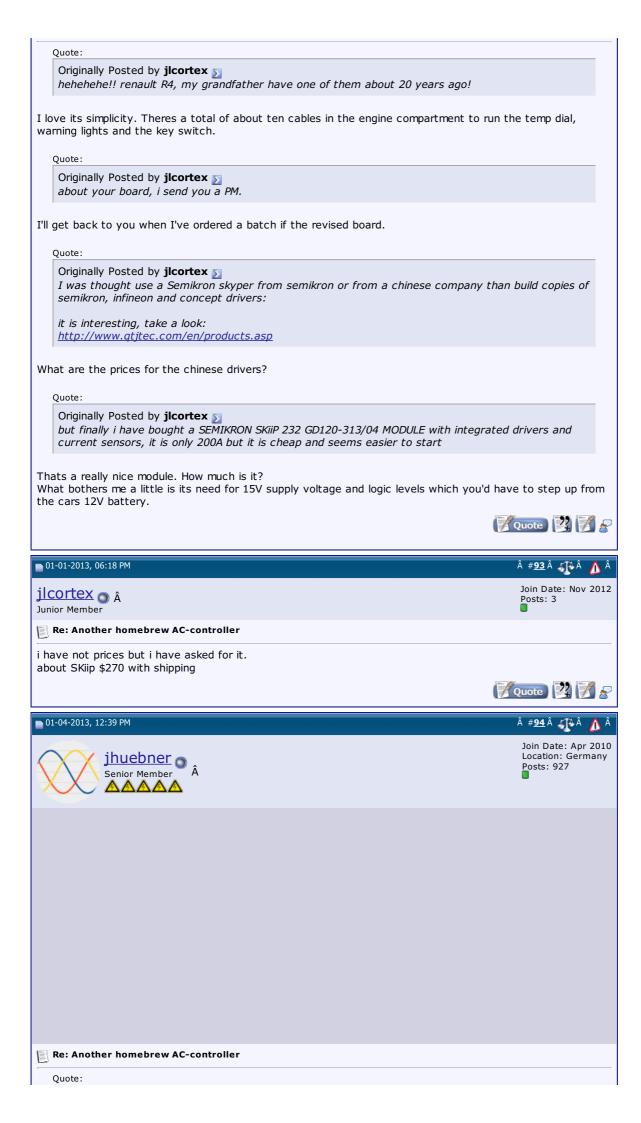


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Originally Posted by **jlcortex** *i have not prices but i have asked for it. about Skiip \$270 with shipping*

new or used part? The gate drivers of my previous inverter alone cost that much.

Did some in car testing today. First I tested my new slip control. The throttle will set the slip between 0..X%, whereas part of the throttle is for braking and gives a slip from -Y..0%. At the same time the sine amplitude is varied from Z..100%, where 100% is the respective point on the FU diagram.

The slip controller itself is a PID controller but after some simulation I removed the I and D parts as they add nothing useful to the controller response.

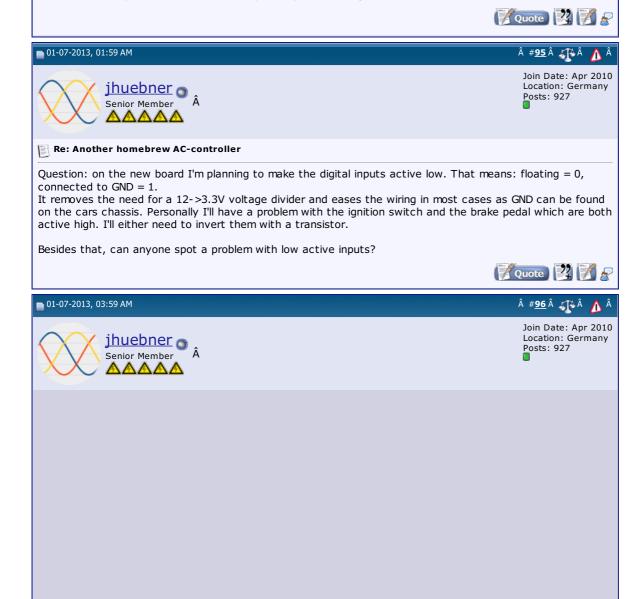
Since the controller becomes unstable at low speeds it will output a fixed frequency when below R rpm.

So first I tested this with the motor idling. It spins up nicely whereas the first 50% of the throttle don't do much. Will have to play with the parameters or maybe introduce an exponential pedal map instead of a linear one. But then I was only testing with 80V instead of 500 so maybe it will behave different when more power is at hand.

Next test was letting the car drive up a step (as in sidewalk) to see the 0rpm capabilities. It actually climbed the step nicely after playing with the parameters a bit. Doing the test I unwillingly tested the over current protection (set to 100A). Seems to work 💮

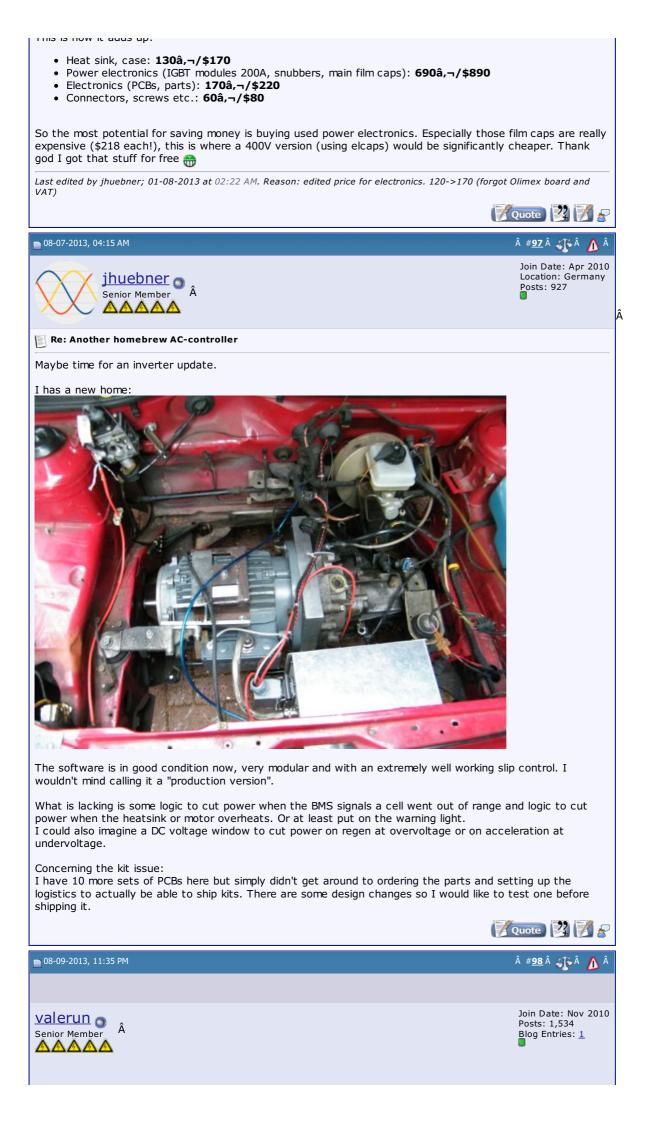
Only error I found is that the motor temperature isn't displayed. The voltage output of the sensor looked ok but apparently the ADC didn't pick it up.

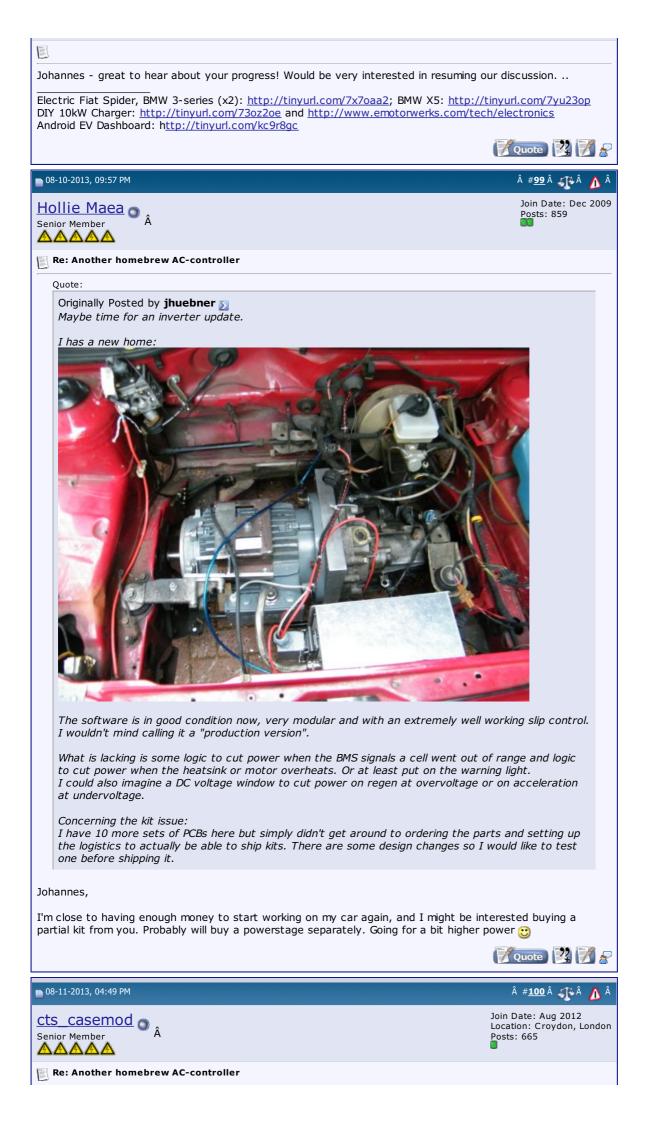
No video of today because it would have probably been boring.



Re: Another homebrew AC-controller

Just calculated parts cost when ordering for 10 inverters including German VAT (19%): 1050â,-/1360\$





Quote:

Originally Posted by **jhuebner** Maybe time for an inverter update.

I has a new home:



The software is in good condition now, very modular and with an extremely well working slip control. I wouldn't mind calling it a "production version".

What is lacking is some logic to cut power when the BMS signals a cell went out of range and logic to cut power when the heatsink or motor overheats. Or at least put on the warning light. I could also imagine a DC voltage window to cut power on regen at overvoltage or on acceleration at undervoltage.

Concerning the kit issue:

I have 10 more sets of PCBs here but simply didn't get around to ordering the parts and setting up the logistics to actually be able to ship kits. There are some design changes so I would like to test one before shipping it.

Hum.. Very familiar... Did you had to use a motor with the same color as mine too? Haha 🚗

Nice setup. I am working on something similar. Slip control. But I am having an issue with the voltage. What do you use for encoder feedback?

So far I have modified a controller to work with slip control, but it uses the same V/Hz profile. What I want to do is change this.. In fact, keeping the slip constant and increasing voltage does increase torque, but in a much more efficient way. However if the voltage is too high, like when using torque boost its quite nice for acceleration, but the motor will drain excessive power at part load with a very low poor power factor.

I am curious to know what you did to tackle this issue

The Electric Polo @ <u>https://www.diyelectriccar.com/forums...tor-78701.html</u> 300A AC POWERTRAIN + PFC CHARGER LiFePO4 440VDC 8KW AC INDUCTION

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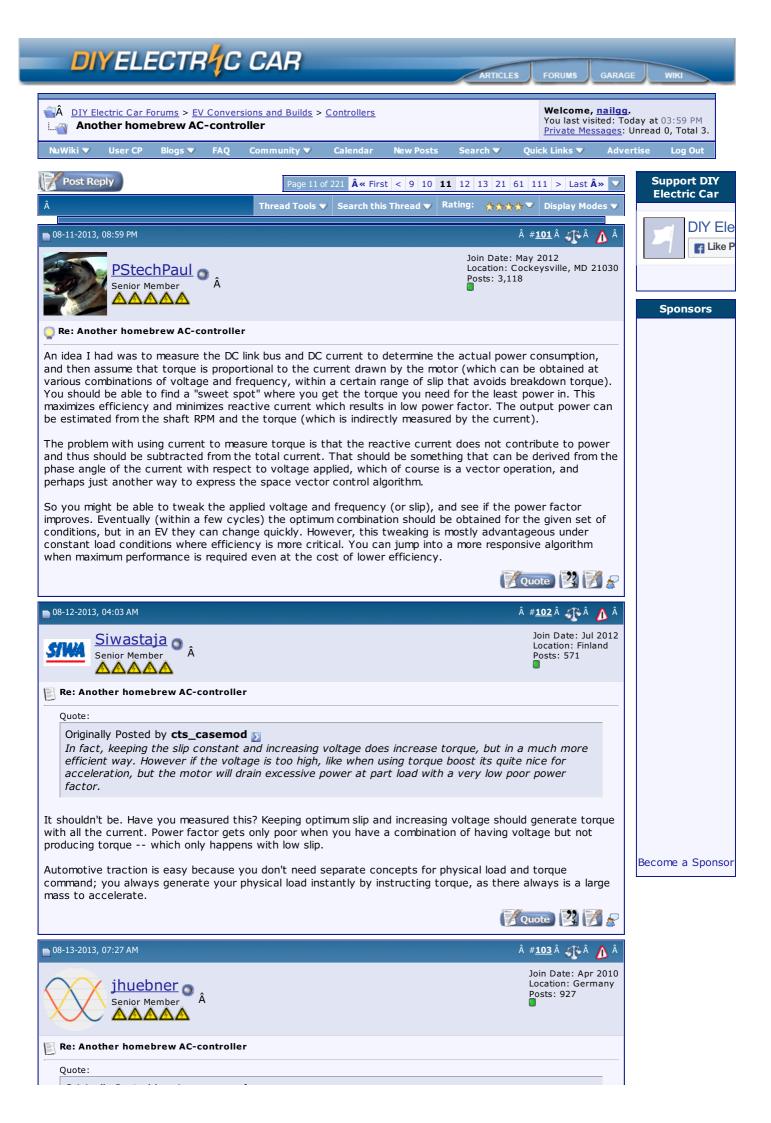
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Originally Posted by cts_casemod 🔊

Hum.. Very familiar... Did you had to use a motor with the same color as mine too? Haha 🕋

Nice setup. I am working on something similar. Slip control. But I am having an issue with the voltage. What do you use for encoder feedback?

This should give you the idea:



The shaft coupler also has the pulse encoder function.

Ouote:

Originally Posted by cts_casemod D

So far I have modified a controller to work with slip control, but it uses the same V/Hz profile. What I want to do is change this.. In fact, keeping the slip constant and increasing voltage does increase torque, but in a much more efficient way. However if the voltage is too high, like when using torque boost its quite nice for acceleration, but the motor will drain excessive power at part load with a very low poor power factor.

I am curious to know what you did to tackle this issue

I use a regular V/Hz profile scaled by the throttle input.

Quote:

Originally Posted by Siwastaja 🔊

It shouldn't be. Have you measured this? Keeping optimum slip and increasing voltage should generate torque with all the current. Power factor gets only poor when you have a combination of having voltage but not producing torque -- which only happens with low slip.

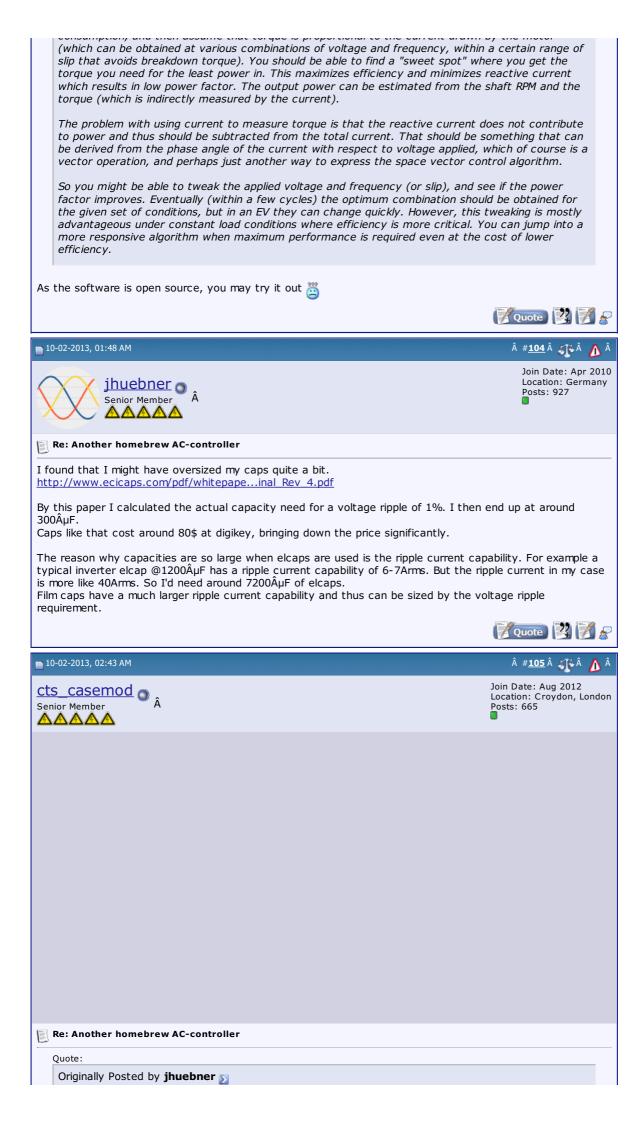
Automotive traction is easy because you don't need separate concepts for physical load and torque command; you always generate your physical load instantly by instructing torque, as there always is a large mass to accelerate.

Yeah, thats what I found. What I have repeatedly read about is saturation. So at some point your extra current won't be producing a useful magnetic field but unuseful heat. I have no idea when that happens though.

Quote:

Originally Posted by PStechPaul D

An idea I had was to measure the DC link bus and DC current to determine the actual power consumption and then assume that torque is proportional to the current drawn by the motor



I found that I might have oversized my caps quite a bit. http://www.ecicaps.com/pdf/whitepapeinal Rev 4.pdf	
By this paper I calculated the actual capacity need for a voltag	e ripple of 1%. I then end up at
around 300ĵF. Caps like that cost around 80\$ at digikey, bringing down the pri	ice significantly.
The reason why capacities are so large when elcaps are used is example a typical inverter elcap @1200µF has a ripple current current in my case is more like 40Arms. So I'd need around 720 Film caps have a much larger ripple current capability and thus requirement.	capability of 6-7Arms. But the ripple DOµF of elcaps.
I used 6x47uF 900V on my new inverter. Each is rated for a ripple c 4700uF*6 which was just a bit over the required capacity to operat	
With the increase to 440V either I would have to get some 500V on high temperatures, or I would have required about 10 of these for o 300V)	
But it is difficult to find info on this subject. Most literature refers to down to zero. Also, it is important to refer to the impedance of a lit 5mOhm + Cable losses. A good electrolytic has at least 20-30Mohm to handle the ripple current but also, because an electric current tra mpedance, which in this case would certainly be the battery and no	hium battery. On my case my pack has s, so not only paralleling them is required avels trough the path with less
The Electric Polo @ https://www.diyelectriccar.com/forumstor-78 300A AC POWERTRAIN + PFC CHARGER _iFePO4 440VDC 8KW AC INDUCTION	3701.html
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Re: Another homebrew AC-controller	
ilm caps are the way to go. That, plus a laminated copper bus. We attached). Rated Ripple current 500A continuous for a 1,000uF 600V	
Electric Fiat Spider, BMW 3-series (x2): <u>http://tinyurl.com/7x7oaa2;</u> DIY 10kW Charger: <u>http://tinyurl.com/73oz2oe</u> and <u>http://www.em</u> Android EV Dashboard: h <u>ttp://tinyurl.com/kc9r8gc</u>	
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PStechPaul Senior Member Â	Join Date: May 2012 Location: Cockeysville, MD 21030 Posts: 3,118
🖸 Re: Another homebrew AC-controller	
That's a very impressive capacitor. How much does something like t :heir website:	hat cost? I could not find any pricing on
<u>nttp://www.sbelectronics.com/</u>	

I found similar capacitors at Digikey, such as this 380 uF 400V, for \$88: http://www.digikey.com/product-detai...957-ND/2704611

Here are the specs: http://www.kemet.com/kemet/web/homep...F3303 C4DE.pdf

Rather impressive also with 100A RMS at 10kHz, 5700A peak, 810 uOhms ESR and 40 nH ESL. This compares to the Power-Ring device 1000uF 600V with 125 uOhms and 5 nH.

How do you determine the size of capacitor needed? One way might be to determine the energy storage requirement based on the switching frequency and allowed ripple. Assume 400 VDC and 100 amperes with an allowable ripple of 5% or 20 volts, and 10 kHz. The energy is 400*100*100uSec or 4 W-sec. Since E= $0.5*C*V^2$, C=50 uF. But since we need 380V minimum, the energy difference between the two voltages needs to be used. Thus, we can use dV = I * dt/C, which results in 500 uF.

It may be useful also to consider the size of an inductor that would perform similarly. $E=0.5*L*I^2$, so 4 Joules at 100A would be 800 uH, and for 5% ripple it would be 8 mH. A 100uH 10A inductor is about \$3 and to get 800 uH at 100A would take 800 pieces so the capacitor seems to be the clear winner.

There may be better ways to do this, and my calculations might not be correct, but they seem reasonable, at least for the capacitor. 🙂

I just found the reference posted previously for sizing the capacitors, and the formula is:

 $C = V / (32*L*dV*f^2)$

Using their example with L=100uH, the capacitor for 5% ripple would be $400/(32*100*20*10^2) = 62.5 \text{ uF}$. But obviously the inductance affects the result significantly, and with 10 uH the capacitor would be 625 uF. The motor would be the load inductance, and that might be estimated from the voltage, current, and PF. So a 240 VAC 10 kW motor might have a 0.8 PF which would have 41.6A resistive and 8A reactive at 60Hz so X(L) = (240*0.2)/(41.6+8) = 0.96 ohms and L = 0.96/(2*PI*60) = 2.5 mH. These are very rough calculations and I'm not sure they apply directly to a three phase induction motor inverter. The example seems to be for a DC motor.

🛛 🛛 Quote 🕺 📝 🔎

Last edited by PStechPaul; 10-02-2013 at 06:29 PM. Reason: Additional calculations based on link reference

■ 10-03-2013, 03:34 AM	# <u>108</u> ∢҈€Â <mark>∆</mark> Â
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by PStechPaul $\sum C = V / (32*L*dV*f^2)$ Using their example with L=100uH, the capacitor for 5% ripple would be 400/(32*100 62.5 uF. But obviously the inductance affects the result significantly, and with 10 uF	
would be 625 uF. The motor would be the load inductance, and that might be estimated would be 625 uF. The motor would be the load inductance, and that might be estimated would be current, and PF. So a 240 VAC 10 kW motor might have a 0.8 PF which would resistive and 8A reactive at 60Hz so $X(L) = (240*0.2)/(41.6+8) = 0.96$ ohms and $L = 2.5$ mH. These are very rough calculations and I'm not sure they apply directly to induction motor inverter. The example seems to be for a DC motor.	ated from the Id have 41.6A ± 0.96/(2*PI*60)
Yes, I calculated a similar inductance for my AC motor. I still haven't quite understood wh is independend from the actual AC load current. Any idea?	ny the ripple current
Here in Germany I'm running into troubles with the home brew inverter. It has to meet EMC regualations. Which seems ok. What isn't, is the price for getting the certificate: around 10000-20000 bucks. Clearly favors big car makers.	
	Quote 🕎 📝 🔗
■ 10-03-2013, 04:29 AM	# <u>109</u> 🐠 <u> </u> Â
valerun Senior Member Â	Join Date: Nov 2010 Posts: 1,534 Blog Entries: <u>1</u>



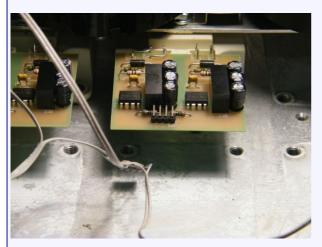
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Minor design glitch on that one: the foot prints for the current sensors are mirrored so I shifted all the parts except the opamp from top to bottom.



So to build a complete 3-phase inverter you'll need:

- IGBTs (400A, 1200V or less depending on your requirements)
 DC bus (I use simple aluminum strips from the hardware store)
 DC bus caps (like the ring cap mentioned above)
 Snubber caps (about 1ŵF film cap)
 Heat sink and case
 waterproof cable bushing for power cables
 waterproof connector for control signals
 Mounting material for fixing the PCBs to the case (screws, angles)

Some more information on pricing and build instructions can be found here: http://johanneshuebner.com/quickcms/...r-kits,10.html

I'm short on current sensors right now, all other parts are "on stock". As soon as some orders come in I will restock.

Vouote 🕺 🖌 🚽

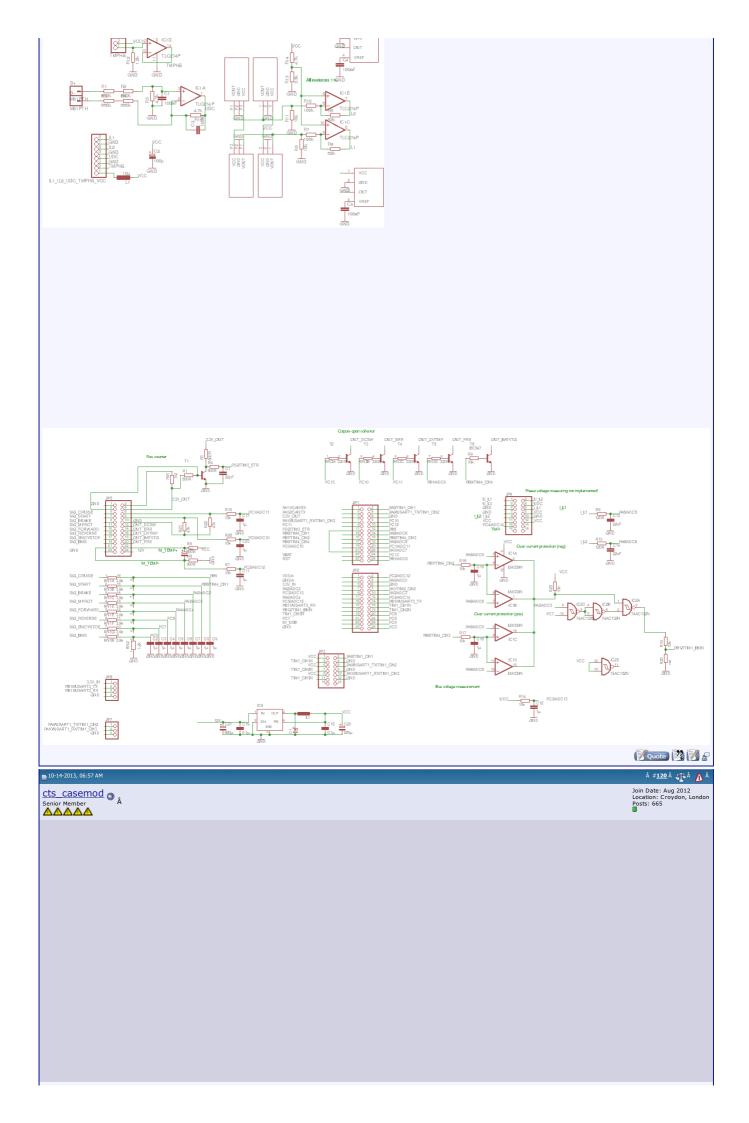
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10-13-2013, 01:14 PM	â # <u>112</u> â 🐢 â 🛕 â
cts_casemod Senior Member Â	Join Date: Aug 2012 Location: Croydon, London Posts: 665
Re: Another homebrew AC-controller	
Nice work. Without going trough the whole topic again (Ive read it a few months ago) what exactly do you claim with your inverter? Is is open loop or closed loop?	
I might be interested in those gate drivers for a bunch of 200Amp IGBTs I have for some other projects. Do they have VCE SAT protection?	
Regards	
The Electric Polo @ https://www.diyelectriccar.com/forumstor-78701.html 300A AC POWERTRAIN + PFC CHARGER LIFePO4 440VDC 8kW AC INDUCTION	
	VQuote 🕎 📝 🔗
10-13-2013, 04:34 PM	â # 113 Â 👫 Â 🧥 Â
	Join Date: Feb 2012 Location: UK Posts: 1,223
Hi Johannes What power capabilities might be achieved with your kits please? What is required to program the control boards? I'm not too experienced with electronics so need something s guidance. Thanks	simple I can handle with
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■ 10-13-2013, 05:02 PM	â # <u>114</u> â 🐠 â 🔥 â
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927





n 10-14-2013, 06:09 AM ـــــــــــــــــــــــــــــــــــ	ΔÂ
Cts_casemod Join Date: Aug 2012 Senior Member Â A A A A Posts: 665	
Re: Another homebrew AC-controller	
Quote: Originally Posted by jhuebner a) its open source, schematics and software are freely available b) its probably as simple as it gets c) It runs an ACIM in closed loop slip control I am successfully using it in my VW Polo with 1200V/400A IGBTS The drivers do not have any intelligence. The control board has fast (15µs) hardware overcurrent protection so I skipped VCE SAT. Even during hard testing while I broke a shaft coupler due to programming errors I did not break any IGBTs thanks to the overcurrent protection.	
Nice work. Not sure i fully agree with the software current limit, but assuming all connections are well done and you don't have a dead short, that should be alright. Thats actually cool. I don't plan to do a car inverter, but I was looking for some assembled hardware for some other projects of mine like the A/C or some cheap the gate drivers for the sine wave inverter so sure this can save me a lot of time.	
How much are you thinking in selling the PCB's? Also are the gate drivers parts of the main PCB or separate like on the first revs? How do you measure DC-Link Voltage? What do you use for speed input (for slip control)? Regards	
The Electric Polo @ https://www.diyelectriccar.com/forumstor-78701.html 300A AC POWERTRAIN + PFC CHARGER LIFePO4 440VDC 8KW AC INDUCTION	
	18
■ 10-14-2013, 06:34 AM Â # <u>119</u> Â √ \Â	∆ Â
Join Date: Apr 2 Location: Germa Posts: 927	
📴 Re: Another homebrew AC-controller	
Quote: Originally Posted by cts_casemod >>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>	
Thanks 😁 Who talks about software current limit? It is a hardware comparator that directly controls the gate signals. When it trips, all gate signals are shut off. The 15µs are the time constant of the low particle, so the higher the overcurrent, the faster the reaction.	ass
By the PCBs you mean PCBs only? Haven't calculated that option but I surely can if you're interested. The gate drivers are separate PCBs. The sensor board that I supply measures the DC link voltage resistively with 4 1M resistors. How dare I do that? a) The German norms dictate an isolation resistance of 500Ohm/V on each pole, so for 500V that is 250kOhms. Thus measuring with a couple of MOhms stays under that limit b) Any capacitive coupling that "shorts" those resistors only shorts the AC components being the PWM ripple. Therefore the reading is dead stable even though motor and inverter share a common ground c) The company that I used to work for (world market leader for solar inverters) does it too (recursive argument d) It costs nothing compared to an actual galvanically isolated measurement	
For measuring the speed I use an infrared light barrier that is interrupt by 60 teeth on the shaft coupler. But you can use anything that supplies an open collector pulse signal. Siwastaja seems to d fine with 8 pulses, so 60 is rather luxurios. The current software cannot handle pulse rates faster than the PWM frequency (8.8kHz) so it shouldn't be too many. One downside is the lack of a direction signal, but I think theres other ways to determine that. With the current software you shouldn't roll backwards while in forward gear.	do

1 VCC 2 ann



Re: Another homebrew AC-cor	ntroller			
Quote:				
Originally Posted by jhuebn For measuring the speed I used to be speed I used to be speed to be spee	ise an infrared light barrier that is interrupt by 60	teeth on the shaft coupler. But you can use a	anything that supplies an open collector pulse signal	. Siwastaja
Oh yes! I remember who you a	are now! All this time I though you were using the T	Fumanako "KiwiAC" controller. Guess I got con	fused 🎯	
Quote:				
		ctly controls the gate signals. When it trips, a	all gate signals are shut off. The 15µs are the time	constant of
Good choice, using a comparato	r, I thought you were using a loop to read the curr	ent sensors, which obviously takes valuable t	me.	
Quote:				
Originally Posted by jhuebn By the PCBs you mean PCBs	er 🔊 only? Haven't calculated that option but I surely c	an if you're interested. The gate drivers are	seperate PCBs.	
Likely. I will use different power	levels, so have to change a few things. Also differe	ent current sensors.		
Quote:				
Originally Posted by jhuebn The sensor board that I sup	er ply measures the DC link voltage resistively with 4	1M resistors.		
Same as i did with the MC3PHAC ground paths due to capacitive	controller board on last rev, although on last tests coupling, so I decided to fully isolate the HV GND. (s I successfully used a voltage to pulse conve Dnly £2 worth of components.	rter to read with an optocoupler. I was having a few	v issues with the
The Electric Polo @ https://www 300A AC POWERTRAIN + PFC CH LiFePO4 440VDC 8KW AC INDUCTION	v.diyelectriccar.com/forumstor-78701.html ARGER			
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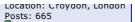
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Senior Member



Re: Another homebrew AC-controller

Â

Quote:

Originally Posted by jhuebner 🔊

By "different" you mean more or less? Because I'm afraid with an 8-DIP footprint you won't find any stronger gate drivers than the ones I use. Adding additional transistors might be the only option.

I mean less. For applications up to 10KW. The gate drivers should be the same, regardless.

Quote:

Originally Posted by jhuebner 🔊

Thats cool. Keen to share that?

I don't have a schematic since I build my prototypes on demand. By the time I need another one I usually come up with something better or with additional features.

Basically it works as every digital opto-isolated stuff .

You read the analog voltage corresponding to the input and you assign a minimum and maximum frequency. Say if your voltage is 2V your pulse rate is 1KHz and for a maximum voltage of 5V your pulse rate is 2KHz. You can use a cheap micro with an ADC or a LM2907/17. Here, on the high side, you have a real GND path so errors should be minimized when making the readings.

On the output, again, you can use an ICL2907/17 calibrated to respond to your frequency and get your analog voltage back to source to your master for reading. But since you are using a uP already it only makes sense you read this data digitally. This saves you the hassle of using the ADC.

Any decent VFD uses this method nowadays. High end cars also use this system to adjust the A/C condenser FAN speed. This gives you complete isolation and immunity to noise, since there is no analog signal anymore.

The Electric Polo @ <u>https://www.diyelectriccar.com/forums...tor-78701.html</u> 300A AC POWERTRAIN + PFC CHARGER LiFePO4 440VDC 8KW AC INDUCTION



#**127** Â 🎢 Â

n 10-15-2013, 10:19 AM



Join Date: Feb 2009 Location: Columbus, OH Posts: 4,458

ΔÂ

Re: Another homebrew AC-controller

Quote:

Originally Posted by cts_casemod D



CTS, this is actually to drive a custom motor of sorts, I have 4 Azure AC24L. 12krpm, and to reach my top speed I need to get to the full 12k to maintain I'd run less rpm in the bike, probably not much less, but the 12k is for my hy the Azure matched AT1200 single speed transaxle with 10:1 reduction. In th make huge torque but multiply by 10 and it becomes very promising. I just i power to peak rpm.	a good reduction ratio. /brid conversion using e car this motor won't
Jhuebner Would you point us to the open source software please, and maybe some ide how to build the controller and program it please? Thanks	iot's guide (for me) on
Nice, I wouldn't mind buying one of those from you 🙂	
But are you planing to drive them in constant torque up to 12KRPM!? They are wound for delta at 40V, likely 1500RPM, so you'll need 320V (assuming t these were factory used up to 170V, so as to provide constant torque up to 5.5 horsepower thereafter). But I think the original controller was rated at 650Amps. nominal voltage is low). Not that bad of a motor in fact	or 6KRPM and constant
The Electric Polo @ https://www.diyelectriccar.com/forumstor-78701.html 300A AC POWERTRAIN + PFC CHARGER LiFePO4 440VDC 8KW AC INDUCTION	
Last edited by cts_casemod; 10-16-2013 at 03:01 AM.	
	VQuote 🕎 📝 🔗
■ 10-16-2013, 01:30 AM	# <u>130</u> ∰ Â
10-16-2013, 01:30 AM ihuebner Senior Member Â	#130 Join Date: Apr 2010 Location: Germany Posts: 927
jhuebner	Join Date: Apr 2010 Location: Germany
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A A A A A A A A A A A A A A A A A A A	Join Date: Apr 2010 Location: Germany
jhuebner	Join Date: Apr 2010 Location: Germany
Re: Another homebrew AC-controller	Join Date: Apr 2010 Location: Germany Posts: 927

12 krpm is no problem. Just don't generate too many impulses (maybe 20-30) pur turn and you'll be fine. I haven't gotten around to testing a PM motor. My guess is that if I set the slip to 0 it should run fine. What I can definitly say is that regarding the hardware it is absolutely no problem to run any kind of 3-phase motor.

Different motors might require software customization. But hey, its open source.

Quote:

Originally Posted by **cts_casemod** *I mean less. For applications up to 10KW. The gate drivers should be the same, regardless.*

Absolutely. The price difference to lower current components isn't too large here. I'd just use the gate drivers as is.

Quote:

Originally Posted by cts_casemod 5

I don't have a schematic since I build my prototypes on demand. By the time I need another one I usually come up with something better or with additional features.

Basically it works as every digital opto-isolated stuff .

You read the analog voltage corresponding to the input and you assign a minimum and maximum frequency. Say if your voltage is 2V your pulse rate is 1KHz and for a maximum voltage of 5V your pulse rate is 2KHz. You can use a cheap micro with an ADC or a LM2907/17. Here, on the high side, you have a real GND path so errors should be minimized when making the readings.

On the output, again, you can use an ICL2907/17 calibrated to respond to your frequency and get your analog voltage back to source to your master for reading. But since you are using a uP already it only makes sense you read this data digitally. This saves you the hassle of using the ADC.

Ok, I understand. What do you power your HV side µC from?

Quote:

Originally Posted by **toddshotrods** *I* can buy a Rinehart, and pay to have them tune it to my motor, but really, really, wanted to go open source - and then, this!

You spotted it 🙂

The existing software is very "frameworky" so it should be easy to change control algorithms, add new parameters etc.

Quote:

Originally Posted by **tylerwatts** Would you point us to the open source software please, and maybe some idiot's guide (for me) on how to build the controller and program it please? Thanks

Use the tumanako github: https://github.com/tumanako/tumanako...aster/src/sine

I have to update it when I get home

Building it is a bit more hassle, you need a GNU ARM toolchain. Here is a linux howto:

https://wiki.ubuntu.com/Toolchain/Cr...MEABIToolchain

I will address the software topic on the project website to make it more "idiot proof" 😷

Quote 🕺 📝 🔎

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Re: Another homebrew AC-controller

Quote:

Originally Posted by cts_casemod D

Unless you are running in a sensorless kind of aproach I dont see how you can know the absolute position of the rotor to energize the correct coil on a PMDC. Does your PCB come with extra inputs that can be used for that purpose!?

Couldn't you just encode the position? Like mentioned above, leave out one tooth at the 0 position.

Quote:

Originally Posted by cts_casemod S

I usually have either a high side power supply or an isolated DC-DC, so I havent included these in cost. Same used to drive the pre-charge circuitry and low side IGBTs, which are both referenced to HVGND. Your design may differ but should not be very hard to implement.

I get it. New designs just spawned in my head 😁



■ 10-16-2013, 12:38 PM



Join Date: Aug 2012 Location: Croydon, London Posts: 665

#<u>134</u>Â 🌆 Â

ΛÂ

	Originally Posted by jhuebner Couldn't you just encode the position? Like mentioned above, leave out one tooth at the 0 position.	
car	e, but as you say it wont work out of the box, so you need to say what features the hardware has that or not be used to make it work, obviously with a change in firmware. Just being open source might not good enough if you are not a guru of programming m	
as me is a limi cre	s is not as simple as setting the slip to zero - It might run unloaded, if started from a zero frequency, bu soon as its loaded it will get out of phase and stall, so no torque is achieved (I tried it). Implementing the chod I described the controller must be able to run open loop, it will only make corrections after the moto ctually spinning, compare them to what it is trying to output and make changes as necessary. It also ts low rpm operation since the motor can count one pulse backwards and assume it as positive which will ate an error. With 3 sensors the encoder knows the actual position anytime and just uses a table, which uires less computing.	e or II
Ιc	this conversation about slip got me thinking urrently process the slip as an analog quantity, representing the motor feedback on which I add or take ore its converted back into the PWM waveform.	
res and	s add or take is done by the accelerator pedal and respective circuitry and added to the closed loop ulting in negative, nule or positive torque. I wanted to have a software to let me input the number of PPI I add or take using the accelerator pedal, so a single box that would take the throttle input (4-20mA or 1 and could read the encoder output.	
The	e parameters would be:	
Inp DC PPI Noi Pea Reg	ut from speed sensor ut from temperature sensor ·LINK Voltage R from the encoder ninal slip k slip jenerative slip (Throttle up) jenerative slip (Brake pressed)	
The if n	e idea is to regulate the charging voltage when the batteries are very cold and hence reduce regeneratio equired, as well as disable regeneration if below a certain speed, because at a certain point is starts to w power, not generate, plus the usual brake pedal controlled regeneration	'n
Bra	ke pedal slip (should be set up to 200% nominal slip and adjustable).	
The	e output would be a 4-20mA or 2-10V	
Но	v hard would it be to actually make something like this?	
300 LiF	e Electric Polo @ <u>https://www.diyelectriccar.com/forumstor-78701.html</u> A AC POWERTRAIN + PFC CHARGER ePO4 440VDC 8KW INDUCTION	
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n 10	-16-2013, 12:47 PM Â # <u>135</u> Â 🛵 Â 🏠	Â
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Ser	S_Casemod Join Date: Aug 2012 ior Member Â A Posts: 665	on
	Re: Another homebrew AC-controller	
	Quote :	
	Originally Posted by tylerwatts 🔊	





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Quote: Originally Posted by j	v AC-controller		
Originally Posted by j			
		ins economy in the first plac	е.
Why would you assume it	t would?		
The Electric Polo @ https 300A AC POWERTRAIN + LiFePO4 440VDC 8KW AC INDUCTION		ar.com/forumstor-78701.h	<u>tml</u>
AC INDUCTION			🛛 Quote 🕎 📝 🔗
■ 11-05-2013, 12:56 PM			# <u>150</u> 🐢 \Lambda Â
jhuebner Senior Membe			Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew	/ AC-controller		
Quote:			
least 50 km/h 7 km/h different) slip contro In any case a better The Polo weighs 765kg w	g. Assuming your polo kWh is very similar to l. r result than when usi yith the petrol engine.	o results we have been havi ing an average standard-inv . Assuming I haven't added a	any extra weight in the front, I
removed 50kg from the b	ack (the tank) and a	dded 150kg auf batteries. S	o now it should weigh around 860kg.
Quote:			
Originally Posted by Why would you assur			
Because I'm a doubtful p	erson 🙂 Now, I'm arr	nused by the fact that this s	imple algorithm works so well.
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Post Reply	Pag	e 15 of 221 A« First < 5 13 14	4 15 16 17 25 65 115 > Last » 🔽
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Re: Another homebrew AC-controller





I'd recommend bare half bridge modules without any integrated electronics.

a) They all have the same electrical interface, i.e. the gate can always be operated with +-15V

b) It's the setup I'm most experienced with.

IPMs on the other hand sometimes need 24V, 15V, they all vary in how they map the output current to a voltage range. Plus I find them harder to source than regular "bricks".

Quote:

Originally Posted by tylerwatts 🔊

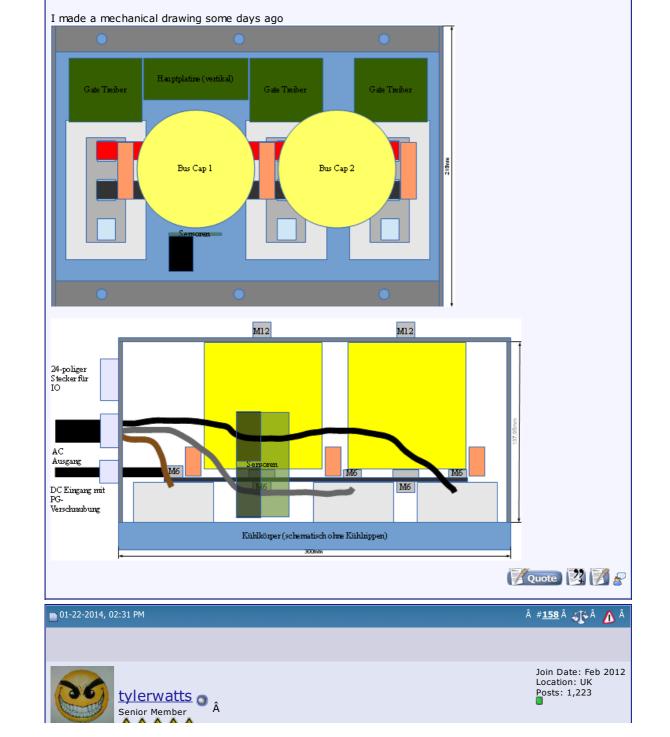
Also, where would you recommend buying IPM/IGBT modules from in eu? Is it ok to salvage from old vfd units?

Absolutely. IGBTs have a very long MTBF. For a car to reach 100000km takes 1000-2000h. Thats nothing to an IGBT with a typical MTBF of 100000h.

Same goes for film capacitors but not for elcaps. I wouldn't recommend elcaps for their poor ripple current capability.

My unit runs with parts (heatsink, caps, IGBTs) from a large solar inverter.

Â



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Thank you.	
	📝 Quote 📴 🃝 🔗
01-29-2014, 12:04 PM	# <u>159</u> ∡]€Â Â
	Join Date: Dec 2010
<u>hbthink</u> Senior Member Â	Location: Southern California Posts: 177
	•
Re: Another homebrew AC-controller	
Semikron IGBTs at auction on ebay check i	t out:
http://www.ebay.com/itm/141178683263	<u>.84.m1555.l2649</u>
OEM grade serious stuff at much less than	MSRP.
Semikron SKiM909GD066HD+P12 Semicondu	ictor Trench IGBT switch 60-1000V.
Features	
 Trench = Trenchgate technology VCE(sat) with positive temperature coeff 	
- High short circuit capability, self limiting t	0 6 x Ic
Typical Applications - Automotive Inverter	
- AC Inverter Drives	
Advanced solderless SKiM technology for e	xtended lifetime cycling.
Currently going for less than \$20 bid now!	
Last edited by hbthink; 01-31-2014 at 02:54 PM.	
	Quote 2
02-11-2014, 02:44 PM	# <u>160</u> 🕂 <u>Å</u> Â
	# <u>160</u> 🛧 \Lambda Â Join Date: Jan 2008 Location: Ireland
jackbauer Senior Member Â	Join Date: Jan 2008
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jackbauer Senior Member Â ▲ ▲ ▲ ▲ ▲ ▲ ▲ ▲ ■ Re: Another homebrew AC-controller	Join Date: Jan 2008 Location: Ireland Posts: 2,147
jackbauer Senior Member A Re: Another homebrew AC-controller Ordered my kit from Johannes and received labelled and bagged so very easy to stuff to The power stage will be built using 3 x CM6	Join Date: Jan 2008 Location: Ireland Posts: 2,147 I within 5 days. Very good service. All components individually the boards using bom and circuit diagram. 500DY12NF 600A 600V igbts on a dmoc heatsink with 6 x 450v
jackbauer Senior Member A Re: Another homebrew AC-controller Ordered my kit from Johannes and received labelled and bagged so very easy to stuff to The power stage will be built using 3 x CM6	Join Date: Jan 2008 Location: Ireland Posts: 2,147 I within 5 days. Very good service. All components individually the boards using bom and circuit diagram. 500DY12NF 600A 600V igbts on a dmoc heatsink with 6 x 450v erter. Have 1pv5135 and a 48v linde AC forklift motor for testing.
jackbauer Senior Member A Re: Another homebrew AC-controller Ordered my kit from Johannes and received labelled and bagged so very easy to stuff to The power stage will be built using 3 x CM6 1800uf el caps as used in the dmoc645 invol	Join Date: Jan 2008 Location: Ireland Posts: 2,147 Within 5 days. Very good service. All components individually the boards using bom and circuit diagram. 500DY 12NF 600A 600V igbts on a dmoc heatsink with 6 x 450v erter. Have 1pv5135 and a 48v linde AC forklift motor for testing. a few features of course
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jackbauer Â Senior Member Â Re: Another homebrew AC-controller Ordered my kit from Johannes and received labelled and bagged so very easy to stuff the The power stage will be built using 3 x CM6 1800uf el caps as used in the dmoc645 invo Should be a fun project and I plan to add at Attached Thumbnails Now, Cole, when you shift the gear and that Amps, that's bad. www.evbmw.com	Join Date: Jan 2008 Location: Ireland Posts: 2,147 I within 5 days. Very good service. All components individually the boards using bom and circuit diagram. 500DPY 12NF 600A 600V igbts on a dmoc heatsink with 6 x 450v erter. Have 1pv5135 and a 48v linde AC forklift motor for testing. a few features of course ☺ Â Â Ittle needle on the ammeter goes into the red and reads 1000 Ittle needle on the ammeter goes into the red and reads 1000

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Â Controllers

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Join Date: Apr 2010 Location: Germany Posts: 927

Senior Member Â	
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by John Metric \sum So it appears I need the capacitor amperage capability calculation not the ripple assume that is on the spec sheet? or is there a calculation for that as well?	
Is the capacitor amperage "capability" a function of heating? If my duty cycle w seconds, could I get by with much less capacitor?	vas only about 10
Yes, cooler is better. Regarding you application where neither EMI nor longevity really matters I wouldn't w capacitor topic. You only need them to keep the spikes down to prevent IGBT overvo Find out about the iductance of your motor, then size the caps for 5% ripple voltage elcaps.	oltage destruction.
	📝 Quote 😰 🏹 🎤
■ 02-17-2014, 12:18 PM	# <u>166</u> ∡҈€Â <u>∧</u> Â
Hollie Maea A	Join Date: Dec 2009
Senior Member Â	Posts: 859
Re: Another homebrew AC-controller	
Keep in mind that any inductance of the DC bus will cancel out capacitance, so design	n it to be as low as
possible.	
	📝 Quote 🕎 🏹 🎤
© 02-17-2014, 08:00 PM	
	# <u>167</u> ∢ Â
■ 02-17-2014, 08:00 PM Cts_casemod Senior Member Â Â	
Cts_casemod Â Senior Member Â	# <u>167</u> TA Â Join Date: Aug 2012 Location: Croydon, London
Re: Another homebrew AC-controller	# <u>167</u> TA Â Join Date: Aug 2012 Location: Croydon, London
Cts_casemod Â Senior Member Â	# <u>167</u> TA Â Join Date: Aug 2012 Location: Croydon, London

So it appears I need the capacitor amperage capability calculation not the ripple current capacity? I assume that is on the spec sheet? or is there a calculation for that as well?

Is the capacitor amperage "capability" a function of heating? If my duty cycle was only about 10 seconds, could I get by with much less capacitor?

Just as said above capacitor selection can be complicated and depends on a number of factors. Generally it is safe to say metal film capacitors will address most of all of the concerns.

Temperature: not just electrical, for example a car parked in the sun during the summer with the inverter/capacitors inside

Frequency: The higher the frequency the more inductive spikes hence larger ripple current capability required.

DC BUS: DC Bus construction AND material (coper, alluminium, thickness, etc) is very important when designing a capacitor Bank. The more capacitors needed (ie. Electrolitics) the bigger the DC BUS, hence the larger the inductance.

Calculate your ripple current requirements. This depends on your motor, the maximum power, etc. Once this is known select a suitable capacitor(s). Specs are listed on datasheet and vary for type. For example, my system uses 6x47uF as below for a ripple current capability of 600A in the inverter and 2x100uF for smoothing and reserve of the PFC Charger output, which has mains ripple. Both are part of the DC BUS for the integrated charger/inverter. This makes for a very compact design with a very low inductance. Check link bellow:

http://www.amazon.com/gp/aw/d/B00HKJ...dir mdp mobile

EMW also sells some power film capacitors. Check their store to have an idea of the specs.

As a summary: Electrolitics are preferred on applications without a battery since the added capacitance is often desirable, such as industrial drives and or wind turbines. We don't need that since we are operating from a battery. The capacitor only needs to handle the voltage spikes caused by switching of the IGBTs for protection of your equipment and RMI/RFI.

Be aware: The type I posted is a very low ESR, high power capacitor. There are film capacitors with larger capacitance whose primary purpose is to serve both as energy reserve and low impedance. While these can be used they will handle LESS current and will be physically larger, so choose accordingly.

As for electrolitics there is no reason to choose them other than to save money if you are uninformed. Rather spend your money in a smaller set of power film capacitors.

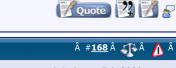
Also don't forget some decent snubbers. Good quality ones. 1uF for every 50Amps battery current is a good choice. You'll need 3, so 0.33uF per IGBT per each 50Amps.

The Electric Polo @ <u>https://www.diyelectriccar.com/forums...tor-78701.html</u> 300A AC POWERTRAIN + PFC CHARGER LIFePO4 440VDC 8KW AC INDUCTION

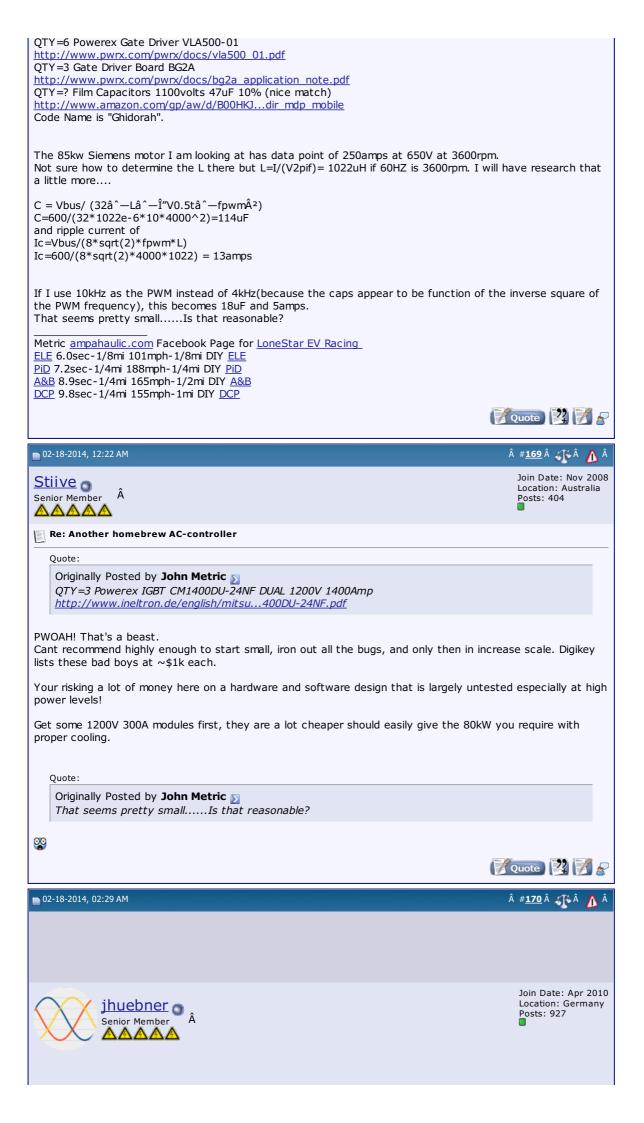
Last edited by cts_casemod; 02-17-2014 at 08:04 PM.

http://www.ineltron.de/english/mitsu...400DU-24NF.pdf

🖿 02-17-2014, 11:54 PM







I second what you wrote, but this:

Quote:

Originally Posted by cts_casemod 🔊

Frequency: The higher the frequency the more inductive spikes hence larger ripple current capability required.

You're driving an inductive load with your inverter. Higher frequency -> less current. Thats why the ripple voltage is inversely proportional to the square (!) of the PWM frequency. Check the formulars.

Quote:

Originally Posted by **John Metric** \sum The 85kw Siemens motor I am looking at has data point of 250amps at 650V at 3600rpm. Not sure how to determine the L there but L=I/(V2pif)= 1022uH if 60HZ is 3600rpm. I will have research that a little more....

 $C = Vbus/ (32\hat{a}^{-}L\hat{a}^{-}\hat{l}''V0.5t\hat{a}^{-}fpwm\hat{A}^{2})$ $C=600/(32*1022e-6*10*4000^{2})=114uF$ and ripple current of Ic = Vbus/(8*sqrt(2)*fpwm*L) Ic = 600/(8*sqrt(2)*4000*1022) = 13amps

If I use 10kHz as the PWM instead of 4kHz(because the caps appear to be function of the inverse square of the PWM frequency), this becomes 18uF and 5amps. That seems pretty small.....Is that reasonable?

Those values seem pretty small. Do some more background research about the motor inductance. I'm not sure whether "my" method is all the way correct.

Quote:

Originally Posted by **Stiive** *PWOAH!* That's a beast. *Cant recommend highly enough to start small, iron out all the bugs, and only then in increase scale. Digikey lists these bad boys at ~\$1k each.*

Your risking a lot of money here on a hardware and software design that is largely untested especially at high power levels!

Get some 1200V 300A modules first, they are a lot cheaper should easily give the 80kW you require with proper cooling.

I second that, its exactly how I developed this inverter. But thats the point, I've already made most mistakes, so the risk software-wise has become quite small. Desat and maybe overcurrent protection will catch the worst mistakes.

One thing that even destroys the strongest IGBT brick is loose gate connections. That will leave one IGBT floating somewhere in the linear region and the other will happily switch the full power.

Ok I'm starting to see your point 😳 Some testing with cheaper hardware might be appropriate.

Post Reply

Page 17 of 221 **Â**« First < 7 15 16 **17** 18 19 27 67 117 > Last **Â**»

Quote 🕎 🏹 🖉

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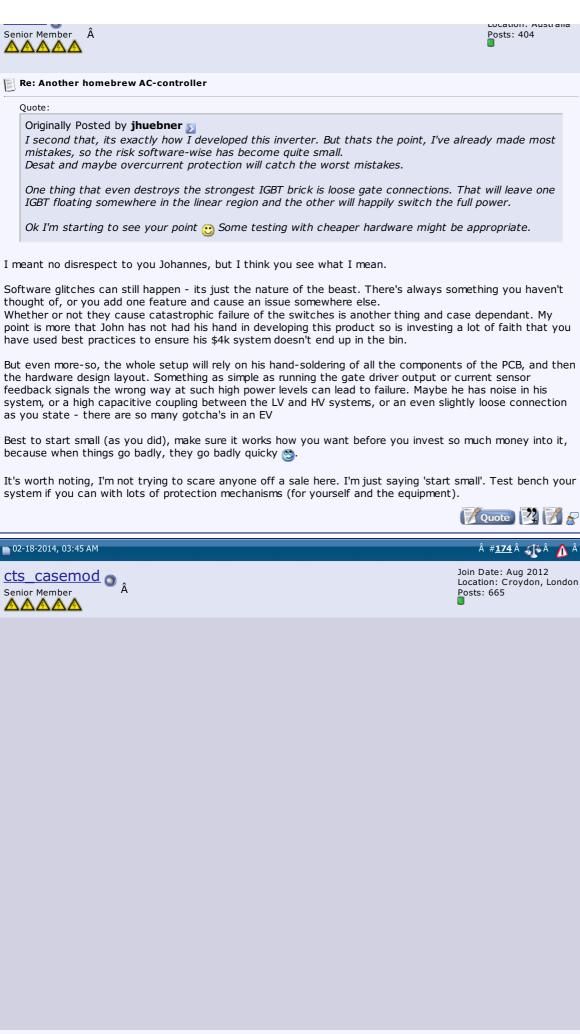
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 $C = Vbus/(32\hat{a}^2 - L\hat{a}^2 - \hat{l}''V0.5t\hat{a}^2 - fpwm\hat{A}^2)$ C=600/(32*1022e-6*10*4000^2)=114uF and ripple current of Ic=Vbus/(8*sqrt(2)*fpwm*L) Ic=600/(8*sqrt(2)*4000*1022) = 13amps

Good grief... those equations look totally made up.

Load (motor) inductance is irrelevant and, in fact, the input capacitor sees the highest ripple current when load inductance is infinite (ie - exactly opposite what eq. 1 suggests). I'll leave it as an intellectual exercise for those so inclined to reason out why this is so (hint: input current is discontinuous while output current is continuous).

The ripple current rating of the input capacitor in a 3ph. inverter does depend on the power factor, cosîl, of the load (worst case is at $\cos\hat{I}_{1}^{i} = 1$) and the modulation index, m, of the PWM waveform (worst case is at m = 0.6). The actual equation for calculating ripple current in a PWM 3ph. inverter is ridiculous, actually, so best to use the following rules of thumb: ripple current rating is 50% of RMS phase current; capacitance is 10uF per RMS amp for film types and 80uF per amp for electrolytic.

Quote:

🗖 02-18-2014, 10:38 AM

Senior Member

cts_casemod 💿 🛕

Originally Posted by John Metric 55 QTY=3 Powerex IGBT CM1400DU-24NF DUAL 1200V 1400Amp

If I use 10kHz as the PWM instead of 4kHz...

You won't be switching any 1200V IGBT at 10kHz. In fact, 4kHz is probably pushing it, as by that point switching losses will be equal to conduction losses; 1-2kHz is more realistic. And yeah, I get that you probably won't need maximum power for more than 10 seconds at a time, but thermally-induced failure of semiconductors can happen in a matter of milliseconds, so that 10 second drag race looks like an eternity to them.

Former Hardware Design Engineer for Evnetics, LLC. Please note the former part...

Writer-at-Large for ChargedEVs Magazine

Last edited by Tesseract; 02-18-2014 at 06:33 AM.

🛛 🛛 Quote 🕎 🏹 🔎

#<u>177</u>Â 🎢 Â 🧥 Â

Join Date: Aug 2012 Location: Croydon, London Posts: 665

Re: Another homebrew AC-controller

Ouote:

Originally Posted by Stiive 🔊 Of course, semiconductor fuses are essential - but are mainly to protect the source rather than the IGBTS



Quote:			
		erters we use (made by visedo) kage	are switching at 8khz hard
use 1200V IGBTs, I t	hink the latter even 1		MW models switch at 3kHz. They
			Quote 22
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I might have found the paper that states pretty much exactly what Tesseract says. <u>https://www.pes.ee.ethz.ch/uploads/t...alIEE_2006.pdf</u>

It gives an estimation formular saying ripple= $1/2^{*}$ rms current. No switching frequency or inductance seems to play a significant role. So thanks for pointing it out.

But please: keep it experimental. "You can't do this and can't do that" are not encouraging words to the amateur.

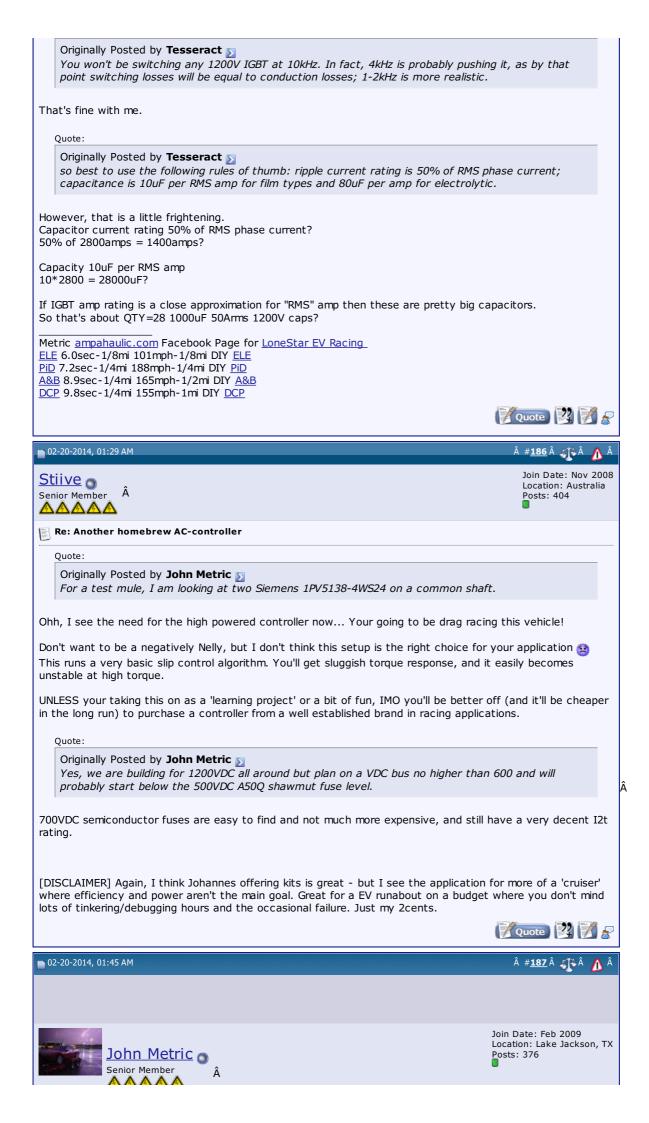
Heres a collection of things experts told me over the years while I developed the inverter:

- "The thermal paste must be spread extremely accurately or your IGBTs will overheat". Well I spread it
 with a simple scraper until my eye said "this is even" and nothing overheats
- "To control an AC motor in an EV you definitly need FOC or DTC". I use slip control which turns out to be efficient and smooth
- "You need to pay close attention to the gate resistors or you'll have rock bottom effiency". I use 100hms instead of the advised 2 Ohms. "Rock bottom" probably means 95% instead of 97% effiency.
- "Its best to galvanically isolate all inputs and outputs". The only thing I isolated are the gate driver. No
 problems anyway.

Ok, enough of that. What I'm saying: had I stuck to all that advise there would be no inverter as of now. Being an expert in software engineering I have experienced this notion to belittle the simple solutions. Its whats experts do e.g. once they accepted 95% effiency as "rock bottom" or voltage spikes of 100V as "outrageous".

John will will be sensible enough not to pump 3000A through his inverter first start. First 50A, then 100A, then 200A... And even if things go wrong - its not the end of the world.





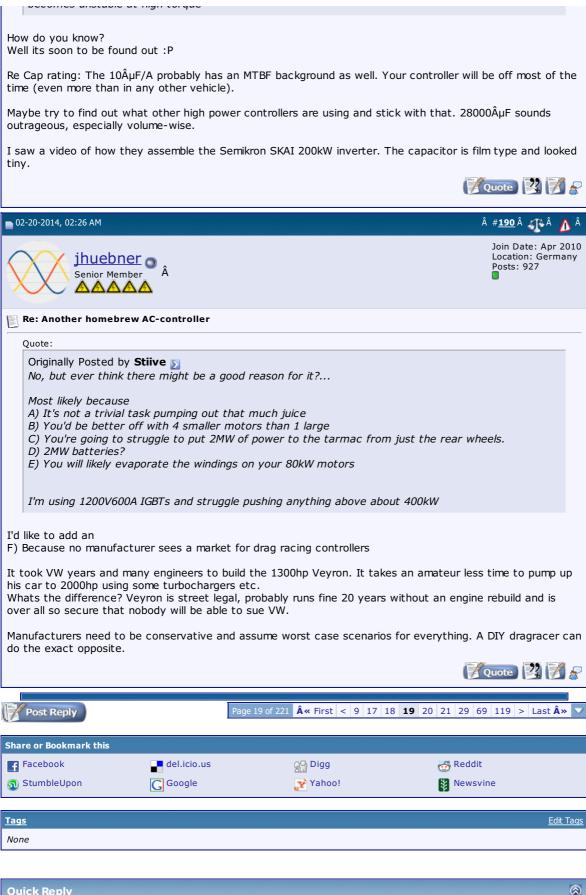
Quote:

Originally Posted by **Stiive** Ohh, I see the need for the high powered controller now... Your going to be drag racing this vehicle!

yes sir..... Ouote: Originally Posted by Stiive D This runs a very basic slip control algorithm. UNLESS your taking this on as a 'learning project' or a bit of fun, IMO you'll be better off (and it'll be cheaper in the long run) to purchase a controller from a well established brand in racing applications. Little bit of a learning project. I liked the open source idea of his kit, writing my own "slip control" algorithm, I have my own ideas on this when I only need one thing from the algorithm, acceleration at any cost. Can you point to a ~1megawatt AC racing controller I can buy? or two? Metric ampahaulic.com Facebook Page for LoneStar EV Racing ELE 6.0sec-1/8mi 101mph-1/8mi DIY ELE PiD 7.2sec-1/4mi 188mph-1/4mi DIY PiD A&B 8.9sec-1/4mi 165mph-1/2mi DIY A&B DCP 9.8sec-1/4mi 155mph-1mi DIY DCP 🛛 🛛 Quote 🕎 📝 🖉 D2-20-2014, 02:09 AM #<u>188</u>Â 🎢 Â Join Date: Nov 2008 Location: Australia Stiive 👩 Â Senior Member Posts: 404 AAAAA Re: Another homebrew AC-controller Ouote: Originally Posted by John Metric 55 Can you point to a ~1megawatt AC racing controller I can buy? or two? No, but ever think there might be a good reason for it?... Most likely because A) It's not a trivial task pumping out that much juice B) You'd be better off with 4 smaller motors than 1 large C) You're going to struggle to put 2MW of power to the tarmac from just the rear wheels. D) 2MW batteries? E) You will likely evaporate the windings on your 80kW motors I'm using 1200V600A IGBTs and struggle pushing anything above about 400kW Quote 🕺 📝 🖉 #<u>189</u>Â 📄 02-20-2014, 02:10 AM Δ Join Date: Apr 2010 jhuebner O Â Location: Germany Posts: 927 Senior Member Re: Another homebrew AC-controller Ouote:

Originally Posted by Stiive 返

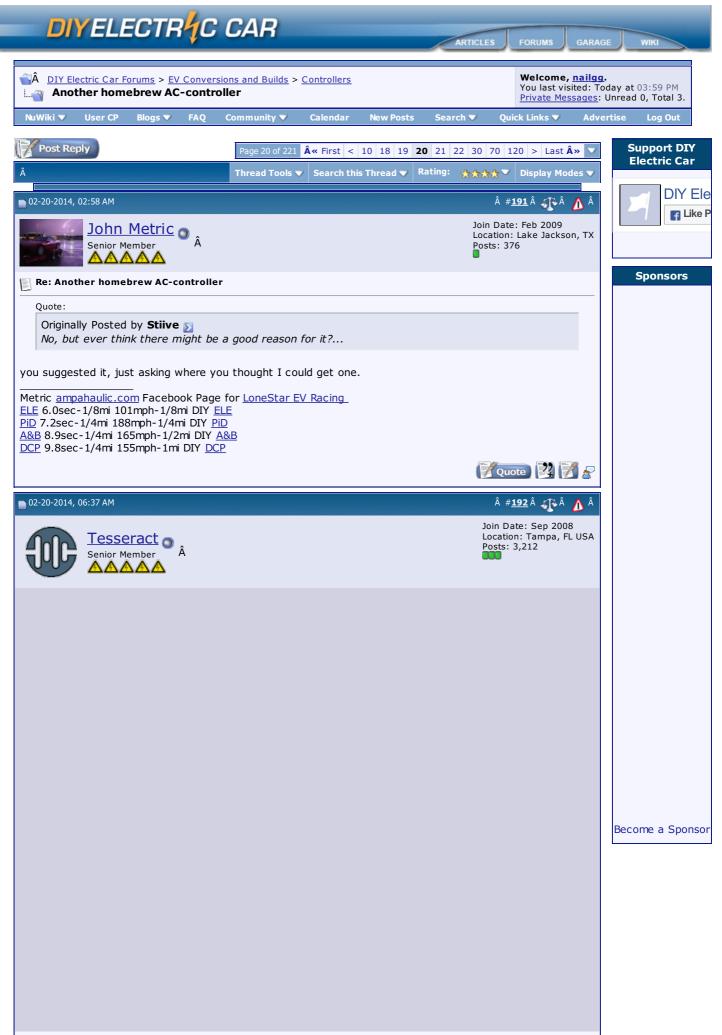
This runs a very basic slip control algorithm. You'll get sluggish torque response, and it easily becomes unstable at high torque



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Quote:

Originally Posted by jhuebner 53

I might have found the paper that states pretty much exactly what Tesseract says. <u>https://www.pes.ee.ethz.ch/uploads/t...alIEE_2006.pdf</u>

It gives an estimation formular saying ripple=1/2*rms current. No switching frequency or inductance seems to play a significant role. So thanks for pointing it out.

Good find. The similarly-titled paper I have on this is by Folker Renken of Siemens, but the one you cited is a bit easier to follow.

Quote:

Originally Posted by **jhuebner** 🔊

But please: keep it experimental. "You can't do this and can't do that" are not encouraging words to the amateur.

Fair enough, with the caveat that if someone who is demonstrably knowledgeable advises against doing something then it behooves the amateur to pay attention. And on that note...

Quote:

Originally Posted by **jhuebner D**

Heres a collection of things experts told me over the years while I developed the inverter:

- "The thermal paste must be spread extremely accurately or your IGBTs will overheat". Well I spread it with a simple scraper until my eye said "this is even" and nothing overheats
- "To control an AC motor in an EV you definitly need FOC or DTC". I use slip control which turns out to be efficient and smooth
- "You need to pay close attention to the gate resistors or you'll have rock bottom effiency". I
 use 100hms instead of the advised 2 Ohms. "Rock bottom" probably means 95% instead of 97%
 effiency.
- "Its best to galvanically isolate all inputs and outputs". The only thing I isolated are the gate driver. No problems anyway.

1. I don't think it's ever possible to spread thermal paste "extremely accurately" so that is nonsense advice, but you can definitely kill a module by spreading the paste so unevenly that there are obvious spots where there is too much paste as well as none at all. I've cut open IGBT modules where just one of the dice failed the one right above a spot on the baseplate where there was no paste. That said, many sins like this will be forgiven if you don't try to push more than half the datasheet current rating through the IGBT.

2. While your slip control approach does work, you do not know if it works as well as FOC or DTC. Granted, your point was that some "expert" (possibly even me... ref) said you needed to use FOC/DTC, and, well, you've proven that wrong, but unless you can achieve the breakdown torque rating of the motor (which ranges from 2x to 4x the full load torque) then your scheme is not the best to use for traction applications.

3. Higher gate resistance only slows down turn-on of an IGBT - it has very little effect on turn-off (until the value becomes absurdly high) - so the main effects of this are a reduction in reverse recovery current in an opposing leg's FWD and, of course, an increase in switching loss. Keep in mind that when driving a highly inductive load, switching loss is the overlap of linearly falling voltage times the full current (and not a linearly-rising current, as would be the case if driving a purely resistive load).

4. I'm with you on this one. Galvanic isolation of all I/O is the lazy designer's way of dealing with ground loops. Applying a little thought - and some judicious filtering - will let your motor controller (etc.) safely interact with the outside world.

Former Hardware Design Engineer for Evnetics, LLC. Please note the *former* part...

Writer-at-Large for <u>ChargedEVs Magazine</u>





Vouote 🕺 📝 🔎



Quote:

hetween stons

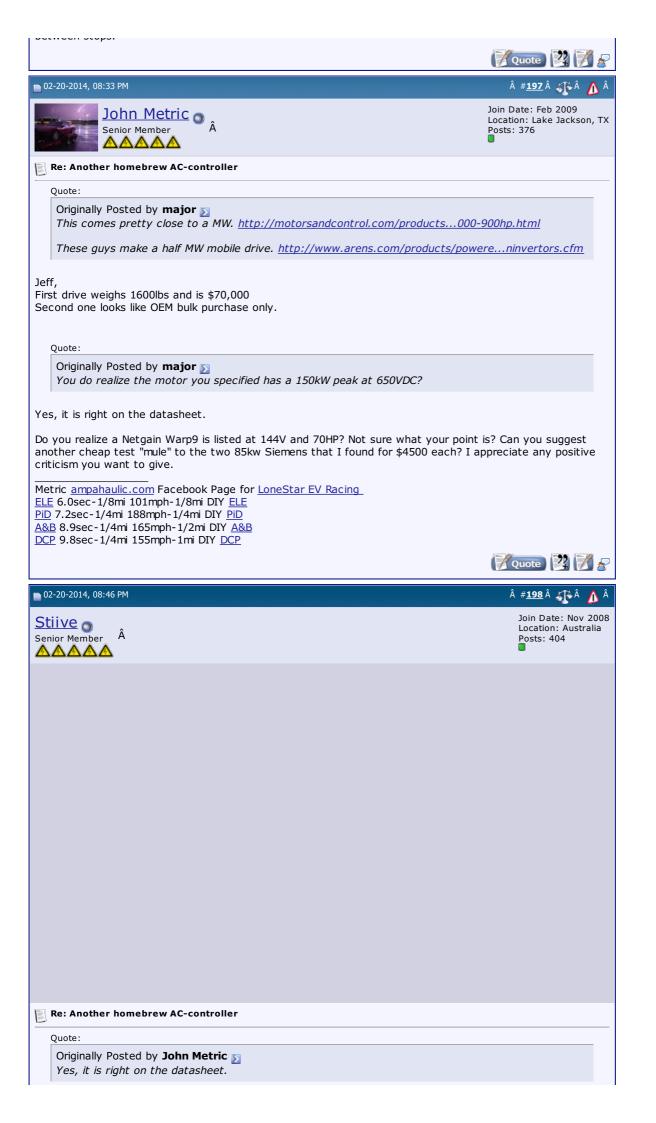
Originally Posted by **John Metric** *Can you point to a ~1megawatt AC racing controller I can buy? or two?*

This comes pretty close to a MW. http://motorsandcontrol.com/products...000-900hp.html

These guys make a half MW mobile drive. http://www.arens.com/products/powere...ninvertors.cfm

You do realize the motor you specified has a 150kW peak at 650VDC? You might be able to push that a bit, but even at 2000VDC, you'll be under half a MW.

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■ 02-20-2014, 12:32 PM	# <u>194</u> ∢∰ ⚠ Â
rochesterricer A Senior Member A	Join Date: Jan 2011 Location: Rochester, Minnesota Posts: 756
Re: Another homebrew AC-controller	
Quote: Originally Posted by John Metric <i>Can you point to a ~1megawatt AC racing controller I can buy? or a</i>	two?
You could always pester Otmar to finish development of the Tri-Zilla 💮	VQuote 🛂 🏹 😪
02-20-2014, 02:04 PM	# <u>195</u> ∰ <mark>∆</mark> Â
gunnarhs Senior Member Â	Join Date: Apr 2012 Location: Iceland Posts: 292
🛐 Re: Another homebrew AC-controller	
Quote: Originally Posted by John Metric Little bit of a learning project. I liked the open source idea of his kit algorithm, I have my own ideas on this when I only need one thing at any cost. I totally like where this thread is going starting from the homebrew cont setup only seen before in a bus configuration . But that is the beauty of the open-source that everyone can (theoretic it would be impossible to make a complete setup fulfilling all needs of the For those who are afraid of the slip-control there is also FOC-code inclu mentioned often in this thread.	from the algorithm, acceleration roller to a monster driving a motor- ally at least) make his own solution, e DIY here.
Last edited by gunnarhs; 02-20-2014 at 02:07 PM. Reason: typos	
Last earled by guinnanis, 62-20-2014 at 62.67 PM. Reason. typos	📝 Quote 🕎 🌠 🌮
■ 02-20-2014, 06:19 PM	â # <u>196</u> â 🐠 â 🦄 â
A A A A A A A A	Join Date: Feb 2012 Location: UK Posts: 1,223
E	
Would a train traction inverter not come close to MW ratings? Maybe? Clots of smaller drives on each bogie so the inverter will be smaller. Just a	



What is the motor? If its a permanent magnet one you will demagnetise the magnets. You'll need an induction if you want to abuse it.

Quote:

Originally Posted by John Metric 5

Can you suggest another cheap test "mule" to the two 85kw Siemens that I found for \$4500 each?I appreciate any positive criticism you want to give.

Try find an aluminium frame low voltage 6pole+ machine.

The higher pole count will give you lots of torque, replace the bearings and do a rotor balance and then voltage overclock to rev it up to $10 \rm k$

Best bet would be to start with buying a motor with a water cooled jacket and then get it rewound yourself. Try a \sim 30VAC 6/8-pole high current winding.

OR rewind your Siemens (if they are induction motors), but maybe best to start with a lower voltage motor so the laminations are more suitable for the winding. Not too sure how the square laminations influence the flux either - prob designed specifically for 4 pole. You would need to research.



The thing about a race vehicle is we don't need all the refinement and security that's needed for street



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Why are we comparing solar inverters to motor inverters? On the first type a higher switching frequency is better so that a simple LC filter can be used to supply a true sine wave output supply. PWM does NOT show in the output unlike a VFD where the motor is forced to act as an inductor on which the inductive peak is recycled by the snubbers and power dissipation on the later INCREASES with frequency. Of course I could also add that any capacitor ESR INCREASES with frequency effectively reducing the capacitor ability to perform the above, but let's not take this into account now.

We could start a whole debate about switching frequencies. It is known that there are specific motors VFD rated for this purpose but the same people that say higher is better fail to properly mention this. I am aware the inverter here shown is used with a VFD rated motor. My motor, for example is NOT so this should be taken into account when switching frequency is choosen for a particular setup (which can be software changed)

The only reason consumer drives typically operate at higher frequencies is in the same principle, there are several papers out there stating possible problems in failures to the insulation of the motor and bearings from the use of higher switching frequencies, core losses, increased losses on the switching transistors, etc... but then again reliability comes second in the consuner world. The point is not to say use or not use, but to make aware of possible advantages and disavantages. The only advantage I see is noise wise, at an expense of a more complex inverter design and efficiency which I personally would avoid, backed up with relevant reasons. Just because some inverters can go to 15 KHz is not a relevant reason to say higher is better, the information is here to help people make an informed decision for a particular setup.

Now it is also true that using a larger PWM the ripple seen by the power source is smaller which is interesting for an AC supply point of view. Not that I care because our supply is DC anyway, but under extreme causes it might cause the wires from the battery to act as an inductor increasing EMI and other nasty effects at very low frequencies if the capacitors are not able to cope. Perhaps this is where different opinions are based. Input ripple current decreases with frequency, BUT internal inductive losses INCREASE and the capacitors MUST be able to recycle this energy.

The Electric Polo @ <u>https://www.diyelectriccar.com/forums...tor-78701.html</u> 300A AC POWERTRAIN + PFC CHARGER LiFePO4 440VDC 8KW AC INDUCTION

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â #<u>203</u>Â 🎢 Â

02-21-2014, 01:29 AM



Join Date: Apr 2010 Location: Germany Posts: 927

Λ

Re: Another homebrew AC-controller

Wow that a lot of posts in a short time. Sorry can't reply to all personally.



Please excuse my ignorance but what is break down torque?
The T_max from this plot:
T_{em}
The second secon
n 02-21-2014, 07:58 AM Â # <u>207</u> Â 🚯 Â
major A
Re: Another homebrew AC-controller
Quote:
Originally Posted by jackbauer <i>Please excuse my ignorance but what is break down torque?</i>
You're excused First google hit: http://www.engineeringtoolbox.com/elues-d_651.html BDT is the maximum torque an induction motor can produce. As you load the motor nearing BDT, the slip starts to increase rapidly and in most cases the inverter faults out (or blows up).
Veuote 😰 🕅 🔗
n 02-21-2014, 09:53 AM Â # 208 Â 🕂 Â 🧥 Â
tomofreno Senior Member Â Â
Pe: Another homebrew AC-controller
Re: Another homebrew AC-controller
Quote: Originally Posted by John Metric <i>I did, we talked for several weeks, his price was too high, voltage too low, lead time too long, IP not</i> for sale, only the drives. I talked to a few other teams as well. I am going to do it on my own

"DIY" fashion. Plea self appointed expo Not claiming to be	se stay positive, and I erts that were bad adv	will. I have also been tok ice in the end. Too many ; just the opposite, just v	ess and the rest of you. True d several " you can't do that's" by v to count. vant to break a few paradigms.		
Seems like it might be since you could likely r	better to use multiple s maintain that torque out	maller motors that give t t to higher vehicle speed	he combined peak torque required, then without as much gear shifting a lot of thought into this is Mate	1	
			VQuote 2	§ 🔗	
02-21-2014, 11:26 AM			# <u>209</u> A A	<mark>∕</mark> ∆ Â	
Senior Mem			Join Date: Jul 2012 Location: Norco, Calif Posts: 441	ornia	
Re: Another homebr	ew AC-controller				
The GM AC drive is >1!	50kW in factory trim.				
Nobody has any idea h on the table", ie - large		tercooled drivetrain can t	olerate. GM is famous for "leaving r	neat	
Could it put out 200kW	/ per motor for 30 seco	nds? Nobody knows.			
it standalone. It is ver	You can play with the motor itself for about \$2,000. The controller? It might be easier than you think to make it standalone. It is very easy to do their gas engines. Their ECM does not need all the sensors or modules to operate. I've taken a wildly different ECM (different chipset, different code, 64-bit) and driven a totally fly by wire powertrain.				
You use foolers (device	es that mimic sensors)	to eliminate problems.			
			ectric motor controller, two motors you sell off what you're not going t		
Diesel Hotrodder					
			Quote 2] 🖉	
■ 02-21-2014, 11:33 AM			# <u>210</u> 🎻 Â	💧	
jhuebn Senior Merr	· ·		Join Date: Apr Location: Germ Posts: 927		
Re: Another homebr	ew AC-controller				
voltage=twice the torc could become an 8, 12	que? If so, the same go , 16?	es for breakdown torque	o twice the rated terminal and suddenly the magical factor of	4	
I roughly remember that could take this.	it core saturation some	how limits something. An	yway I'd like to know how far you	~	
			Quote 2	¶	
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Quote:

Originally Posted by jhuebner 🔊 So twice the rated terminal voltage=twice the torque?

I don't think this is correct. It never worked that way for me \bigcirc

	📝 Quote 🕎 🌠 🚪
■ 02-22-2014, 08:33 AM	# <u>215</u> 🔏 Â
gunnarhs Senior Member Â	Join Date: Apr 2012 Location: Iceland Posts: 292
🖹 Re: Another homebrew AC-controller	
have here pictures of the curves of Siemens 1PV5 series under different voltages (Power is increased by his motors by increasing the Voltage). One picture is showing the efficiency spectrum, the other shows th me the power/torque can be hold. hat you do by applying higher voltage is in practice that you move the base-speed to higher RPM (meaning bu can hold max torque over longer RPM-range but only for a limited time). Here the time is shown becifically for the S14-winding type at 300 V. round base speed it is more efficient to increase voltage than slip to gain constant (max) torque (meaning bu would like to hold slip constant low if possible to increase voltage for more torque). It in cases like startup condition (especially in stop/start situation) it can be better to allow more slip to wer startup current. his becomes important in vehicles with small battery-pack, used battery pack, and in cold conditions. In lat case you do not produce max-torque which inevitable draws large current but just the torque you eed" to move the vehicle.	
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Attached Images	

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D2-22-2014, 12:59 PM



Join Date: Feb 2009 Location: Lake Jackson, TX Posts: 376

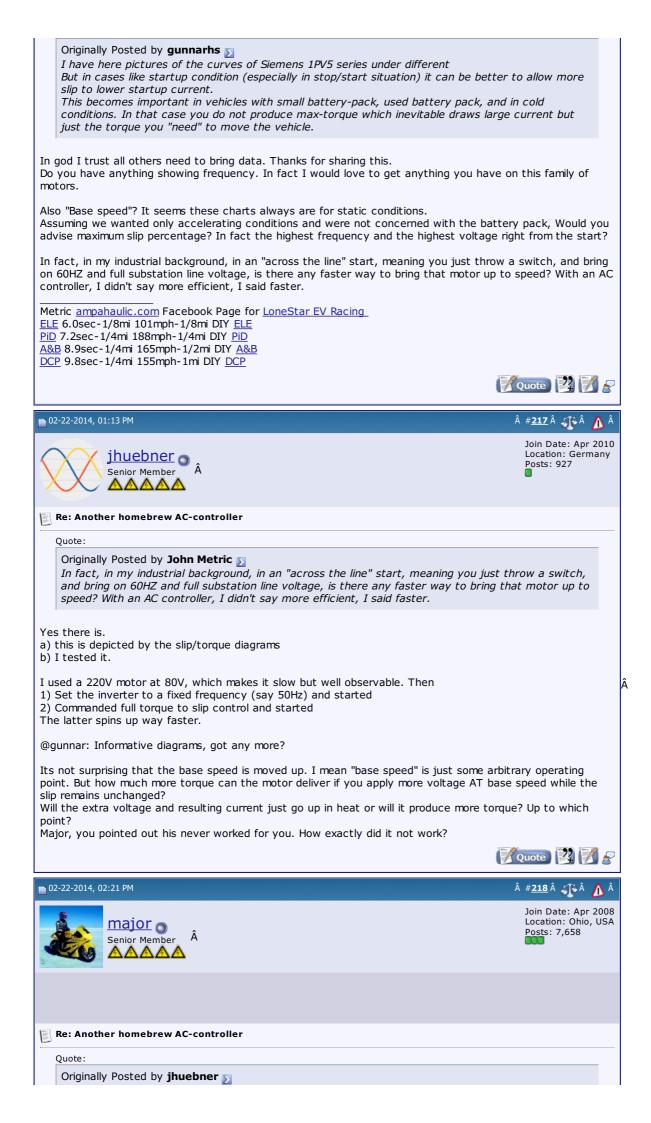
Location. Onio, USA Posts: 7,658

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â #<u>216</u> Â 🐠 Â 🥼 Â

7	Re:	Another	homebrew	AC-controller
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Quote:





I don't buy it. What magic goes on	in a DC motor that makes i	it (supposedly) lack such	an absolute maximum?
Quote: Originally Posted	by maior 🔊		
And base speed of			e winding in the motor and
Ok, V/Hz isn't arbitra reason that it is the	ry, but something like 1400 grid frequency. You might a)rpm@50Hz@230V is. For as well specify 2900rpm@	grid tie motors chosen for the simp 0100Hz@460V.
	pened to my 18.5kW Lenze ound it differently and now		rted live as a 7.5kW motor judging Hz@360V.
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	hat ratio and you lose torg higher than that ratio and		weakening (running above base get messy in a hurry, but you
ļ			
			CAN push it above the nominal V/H practical examples, not in theory (I
pun intended)?	,		
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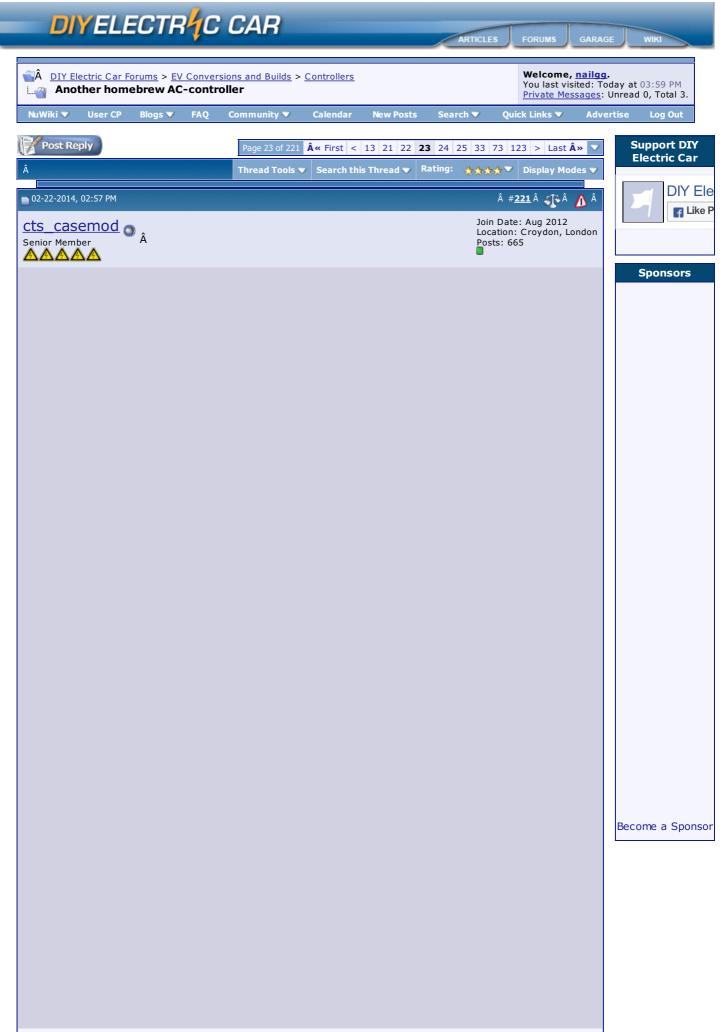
Â Controllers

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Quote:

Originally Posted by **jhuebner** 5

Its not surprising that the base speed is moved up. I mean "base speed" is just some arbitrary operating point. But how much more torque can the motor deliver if you apply more voltage AT base speed while the slip remains unchanged?

Will the extra voltage and resulting current just go up in heat or will it produce more torque? Up to which point?

Major, you pointed out his never worked for you. How exactly did it not work?

Quote:

Originally Posted by major 🔊

For a particular motor, the breakdown torque is it. The maximum. Regardless of what you connect to it whether it be the mains or a megaWatt inverter.

And base speed or base frequency isn't arbitrary. It is defined by the winding in the motor and applied voltage. This is often quantified as Volts/Hertz. Run lower than that ratio and you lose torque, as evidenced in field weakening (running above base frequency). Run higher than that ratio and you saturate and things get messy in a hurry, but you don't get more torque.

And using a flux vector drive on a motor and load can accelerate it much quicker than an across the line start because you essentially get breakdown torque from the start (zero RPM) instead of the lesser starting torque for the IM. It will also see lower phase current and source energy.

Torque on an assynchronous machine is dependednt, as major indicated, on the V/Hz Ratio, but not only that. On slip too. Because if you dont have slip there is no magnetic field on the rotor, hence the stator is a big inductor being charged on the on cycle, which returns the power on the off cicle of the inverter. This is REACTIVE POWER going from the inverter to the battery and so on, which causes nothing more than losses.

100% torque is archieved at maximun current, however most industrial motors rated for continuous duty can go up to 200% torque at the expense of a higher current and thermal load. Quite often this is the maximun you can run with linear efficiency. At 250% current you get 220% torque and so on (This can be checked on the spec sheet or a particular motor). This is the base principle of motors with a lower duty cicle, such as 15min on/30min off. They run at maximun alowable torque with no overload capacity, which makes them small for a given power output, but because of the temperature rise continuous duty cycle is not allowed, or other methods like coolant or forced air cooling must be employed.

You can have a look at this info on any manufacturer catalogue

If only the voltage is increased you have a powerfull field on the stator, but a weak field on the rotor, so current will be returned to the inverter, as exp-lained above. On the other hand, if you increase the slip too much, you have a powerfull magnetic field on the rotor and a weak magnetic field on the stator, none of which will be optimun.

So yes, you can go past the optimun V/Hz ratio if you adjust your slip boost to your V/Hz profile, (assuming the motor/windings wont overheat) within a reasonable range which is 200% nameplate current, or whatever your motor specs say). The same is valid for over nameplate speed, since you run out of voltage you need to reduce the slip and hence the torque will fall. If you dont respect this and keep increasing the slip you are no longer working on the field weakening region and a result is a waste of power (Increase in current) without a proportional increase in torque (This might answer the question on your e-mail). Always remember the working principles of a series would DC motor. What happens at zero speed? Maximun torque. Now get a Shunt motor and try to get the same torque. You cant, because the rotor torque is not proportional to the stator torque. Again, this is why a series would can reach very high speeds that a shunt wound can not (obviously assuming no electronics).

The above should give you a light is why I have been discussing, on my mails, an inverter with variable V/Hz ratio that should be ajusted to the required torque and slip mantaining optimun conditions at all times, and hence maximun torque for unit of power delivered. Most comertial inverters fail to do this, the result is something that is not 100% optimun for vehicle use. It can work, but it will not be as energy efficient as it could be, since only slip is dictating maximun current or when the V/Hz ratio is too high for low slip conditions, such as coasting (Motor powered with 0Hz slip).

The Electric Polo @ <u>https://www.diyelectriccar.com/forums...tor-78701.html</u> 300A AC POWERTRAIN + PFC CHARGER LIFePO4 440VDC 8KW AC INDUCTION

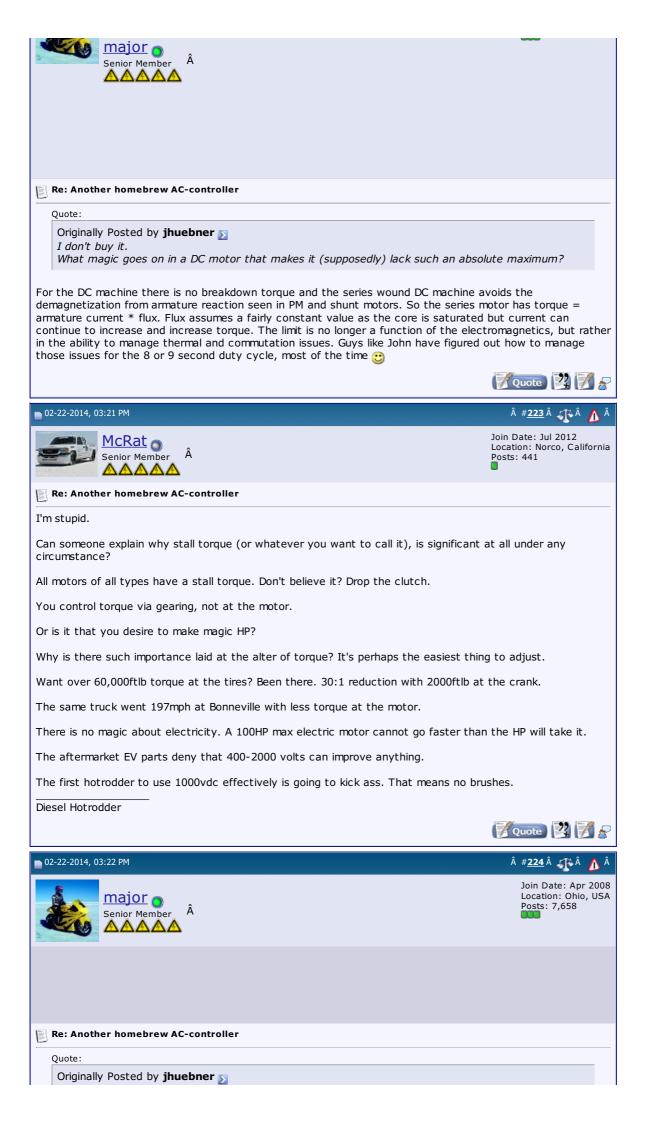
Last edited by cts_casemod; 02-22-2014 at 03:08 PM.

📝 Quote 😰 📝 🔗









	Gunnar states he ran at 1.5x nominal V/Hz. Thats exactly my point. You CAN pur nominal V/Hz. I agree its gets messy once the iron saturates. How big is the ma examples, not in theory (no pun intended)?	
	could well be that his particular motor was conservatively rated originally. 1.5x sound buy 1.2x, maybe 1.3x, but John is looking for 4 or 5x. Ain't going to happen.	unds excessive IMO. I
edi	t:	
	Quote:	
	Originally Posted by jhuebner <i>Gunnar states he ran at 1.5x nominal V/Hz.</i>	
	at's not exactly what he said. See below. He said 1.5x Voltage, not V/Hz. He does reased frequency as well.	m't say, but may have
	Quote:	
	Originally Posted by gunnarhs The maximum overvoltage I have used is 1,5 nominal voltage (for Siemens motor)	or, less for standard
	t edited by major; 02-23-2014 at 11:19 AM. Reason: reread gunnarhs' post	
LUSI	e calca by mojor, oz zo zort at ritro Am Reason reread gamarns post	Quote 🛂 📝 🖉
02	2-22-2014, 03:41 PM	# <u>225</u> ∕ î∳ <mark>∕</mark> Â
	John Metric Senior Member	Join Date: Feb 2009 Location: Lake Jackson, TX Posts: 376
	Re: Another homebrew AC-controller	
	Originally Posted by cts_casemod D	
	Torque on an assynchronous machine is dependednt, as major indicated, on the only that. On slip too. Because if you dont have slip there is no magnetic field of the stator is a big inductor being charged on the on cycle, which returns the po of the inverter. This is REACTIVE POWER going from the inverter to the battery causes nothing more than losses.	n the rotor, hence ower on the off cicle

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You can have a look at this info on any manufacturer catalogue

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This is fabulous, learning a lot here.

So if I were to pose a couple of "system requirements" to you guys, can we come up with the settings here for a drag race vehicle where pretty much only acceleration is needed.

1. Not interested in getting into the "field weakening" zone of the motor. (not interested in the motor starting to fall in horsepower above a certain rpm. I want to stay in the maximum torque from zero rpm up to "base speed". I'll handle the rest of the car design)

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5. Assume we can go much nearer the motor design insulation voltage if needed.

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What settings (V & hz) to get the motor up to base speed in the quickest time (not most efficient).

Metric <u>ampahaulic.com</u> Facebook Page for <u>LoneStar EV Racing</u> <u>ELE</u> 6.0sec-1/8mi 101mph-1/8mi DIY <u>ELE</u> <u>PiD</u> 7.2sec-1/4mi 188mph-1/4mi DIY <u>PiD</u> <u>A&B</u> 8.9sec-1/4mi 165mph-1/2mi DIY <u>A&B</u> <u>DCP</u> 9.8sec-1/4mi 155mph-1mi DIY <u>DCP</u>

VQuote 🕎 🏹 🎤

#<u>226</u>Â 🏠 Â 🧥 Â

cts_casemod Senior Member Â

🗖 02-22-2014, 03:47 PM

Join Date: Aug 2012 Location: Croydon, London Posts: 665

🛐 Re: Another homebrew AC-controller

Quote:

Originally Posted by major 5

It could well be that his particular motor was conservatively rated originally. 1.5x sounds excessive IMO. I can buy 1.2x, maybe 1.3x, but John is looking for 4 or 5x. Ain't going to happen.

Industrial motors are rated conservatively.

The have continuous duty cycle. Manufacturer specs show that overload is possible for a few seconds, limited by temperature increase, but they show overload using the same mains voltage or V/Hz profile, which results in excessive slip and hence excessive rotor temperature increase. For this reason EV type motors have copper rotors that allow less losses and higher temperatures. by increasing the voltage the losses on the rotor can be reduced and the stator can more easily be cooled as it is in contact with the outer casing.

On a vehicle torque is variable and I may well use 200% torque, and hence the equivalent flux without loss of efficiency, however at 300% current only 300% torque will result. This is no different from a series motor. There is a limit where saturation occurs and flux is no longer proportional to current. Its a trade-off. On a real road EV altough high power is needed for acceleration many times the car is coasting/stopped so the motor has time to cool down.

On a drag race the story may well be different

Oh just as a side note:

EV type motors that are rated at 150HP are actually intermitent dutty motors. they are likelly 7.5 to 11KW if rated as industrial motors. Granted they are forced cooled and have copper rotors, which might push the power above what an industrial one could go, but while I can say an industrial 7.5HP can have 100HP easily, the same is not true for a comertial EV motor, since the nameplate HP is a peak value. they know you cant put continuously 150HP to the wheels and they also rely on overvoltage, since most of these motors are rated at 90VAC but run at over 200VAC (300VDC)

🔣 ouote 🕺 📝 🔎

The Electric Polo @ <u>https://www.diyelectriccar.com/forums...tor-78701.html</u> 300A AC POWERTRAIN + PFC CHARGER LIFePO4 440VDC 8KW AC INDUCTION

Last edited by cts_casemod; 02-22-2014 at 04:10 PM.

02-22-2014, 03:52 PM	â # <u>227</u> â 🐠 â 🧥 â
A A A A A A A A A A A A A A A A A A A	Join Date: Apr 2008 Location: Ohio, USA Posts: 7,658
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by McRat <i>I'm stupid.</i>	
Can someone explain why stall torque (or whatever you want to call it), is signific any circumstance?	cant at all under

All motors of all types have a stall torque. Don't believe it? Drop the clutch.

You control torque via gearing, not at the motor.

Or is it that you desire to make magic HP?

Why is there such importance laid at the alter of torque? It's perhaps the easiest thing to adjust.

Want over 60,000ftlb torque at the tires? Been there. 30:1 reduction with 2000ftlb at the crank.

The same truck went 197mph at Bonneville with less torque at the motor.

There is no magic about electricity. A 100HP max electric motor cannot go faster than the HP will take it.

The aftermarket EV parts deny that 400-2000 volts can improve anything.

The first hotrodder to use 1000vdc effectively is going to kick ass. That means no brushes.

Power = Torque * RPM. Want power? You need both; torque and RPM, right?

You keep going on about gearing for torque. I can say the same thing about RPM, can't I? What you can't gear up is power.

John is just trying to figure out how to get the same power out of an AC drive as he has been able to push out of his DC. When his DC drive can put out 5 times the torque it is proving difficult. We can't really run the AC at 5 times the RPM.

And in your battery thread you're super safe with a 4V cell but here you advocate a couple thousand Volts on the race track. That concerns me. I'd really like to see racers kept below 400 \bigcirc Too much unexpected sh!t happens on the track.

🛛 Quote 🕎 🏹 🖉

02-22-2014, 03:55 PM	# <u>228</u> ∢ ∏ Â
cts_casemod Senior Member AAAAA	Join Date: Aug 2012 Location: Croydon, Londor Posts: 665
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by John Metric This is fabulous, learning a lot here. So if I were to pose a couple of "system requirements" to you guys, can we a settings here for a drag race vehicle where pretty much only acceleration is	
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🖹 Re: Another homebrew AC-controller

Quote:

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What settings (V & hz) to get the motor up to base speed in the quickest time (not most efficient).

Ok, I think all important bits and pieces have by now been mentioned. Let me summarize.

1) To increase horse power you have to components: speed (rpm) and torque.

2) To increase speed you need to rewind your motor to a lower voltage to avoid some kV battery pack

3) To maximize torque on an ACIM you must run it with breakdown slip and above the rated V/Hz ratio

Things to do:

1) Pick your base motor

2) Find out about its maximum speed by experimenting. The acim in my humble Ligier spun up to 12000 rpm and looked like a pretty normal industrial acim. Ok, no more speculations, test it. This indeed has a lot of potential to increase your power output.

3) Find out up to what point increasing the V/Hz ratio results in usable torque. If you don't have means to measure torque directly I can help you out with the inverter software. As mentioned this may result in a torque increase of 1.2 to 1.5 or even more.

4) Now rewind the motor so that you reach that maximum speed before you enter the (NEW) field weakening region. If its now 650V@100Hz rewind it to 300V@500Hz (totally made up values). Cramp as much copper into the slots as you possible can.

Example:

1) You start with a 70hp motor whos power is about 3-fold when running at breakdown torque. ->210hp

2) You find out that you can spin up to 16000rpm (maybe with additional balancing) instead of 3000rpm. -

>1120hp

3) You figure you can increase V/Hz by a factor of 1.3. ->1456hp

Last edited by jhuebner; 02-22-2014 at 05:45 PM. Reason: restructured



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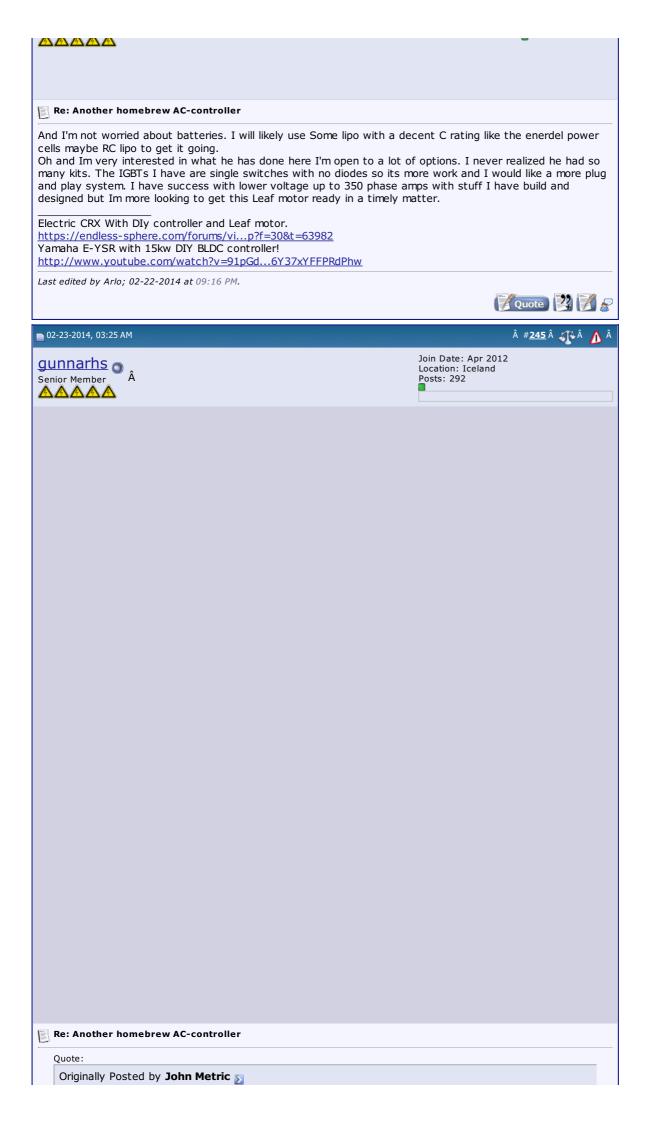
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nower cells maybe RC lino to get it going





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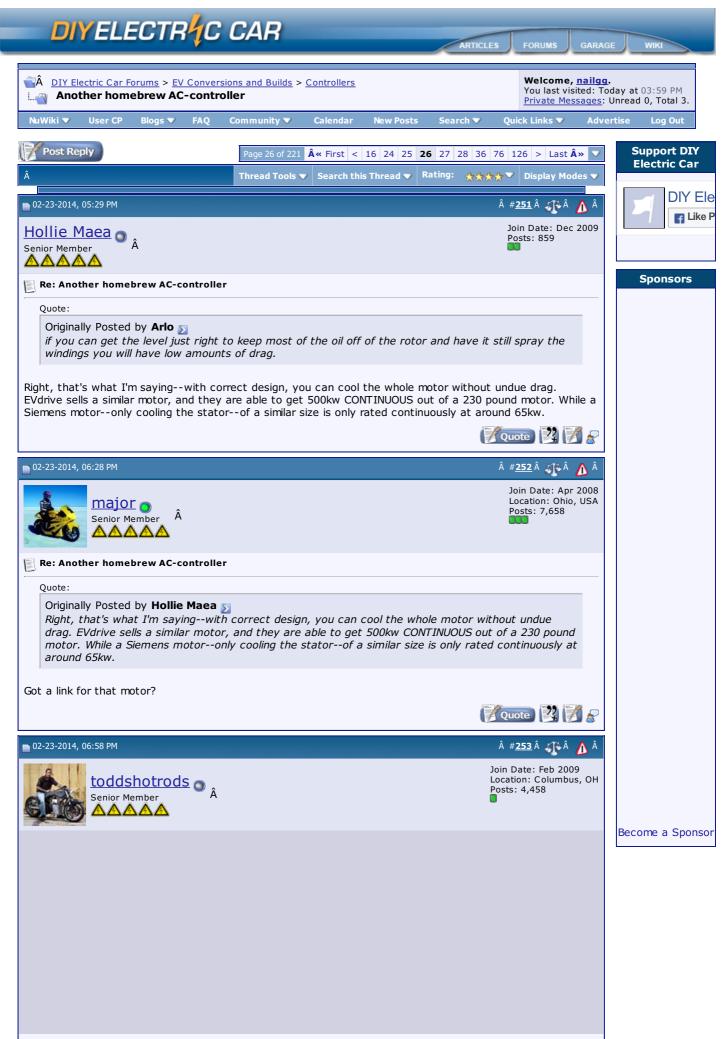
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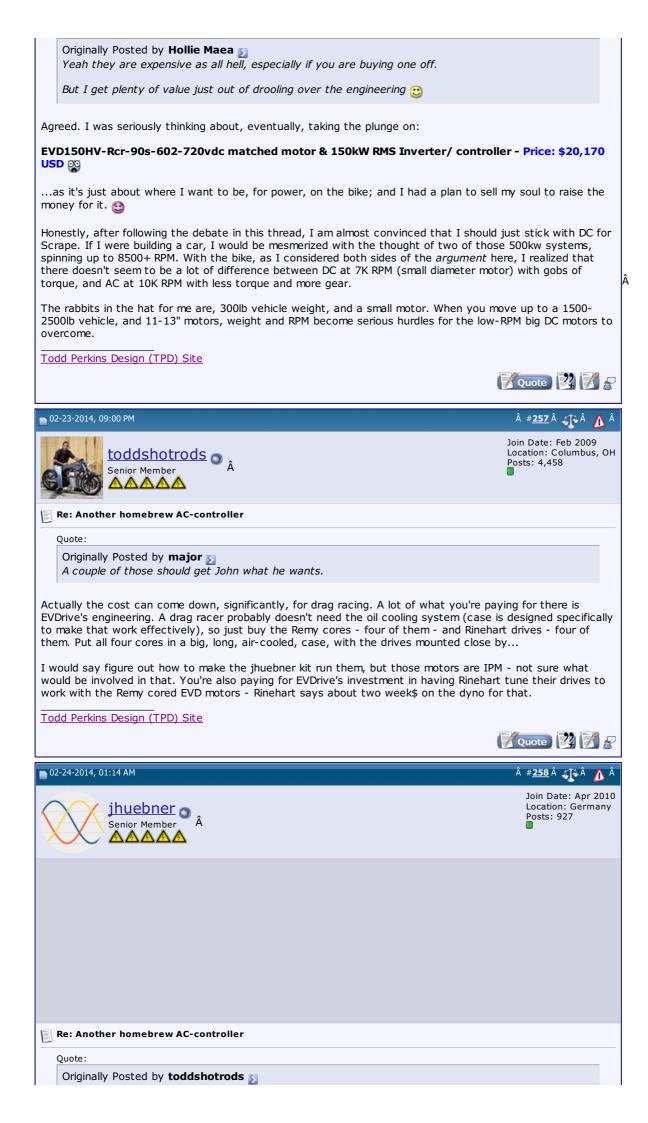
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1	Now, Cole, when you shift the gear and Amps, that's bad. www.evbmw.com	that little needle on the ammeter goes into the red and reads 1000
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L	02-24-2014, 03:28 PM	# <u>270</u> 🕂 🧘 Â
ł	jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
۱	Re: Another homebrew AC-controller	
-	Quote:	
	Originally Posted by jackbauer <i>Bit more progress. Got the gate driv</i> <i>installed.</i>	vers and main board mounted. Also contactor and hv wiring
	Nice work! And a good intermission from Did you do any test runs so far? I mean	
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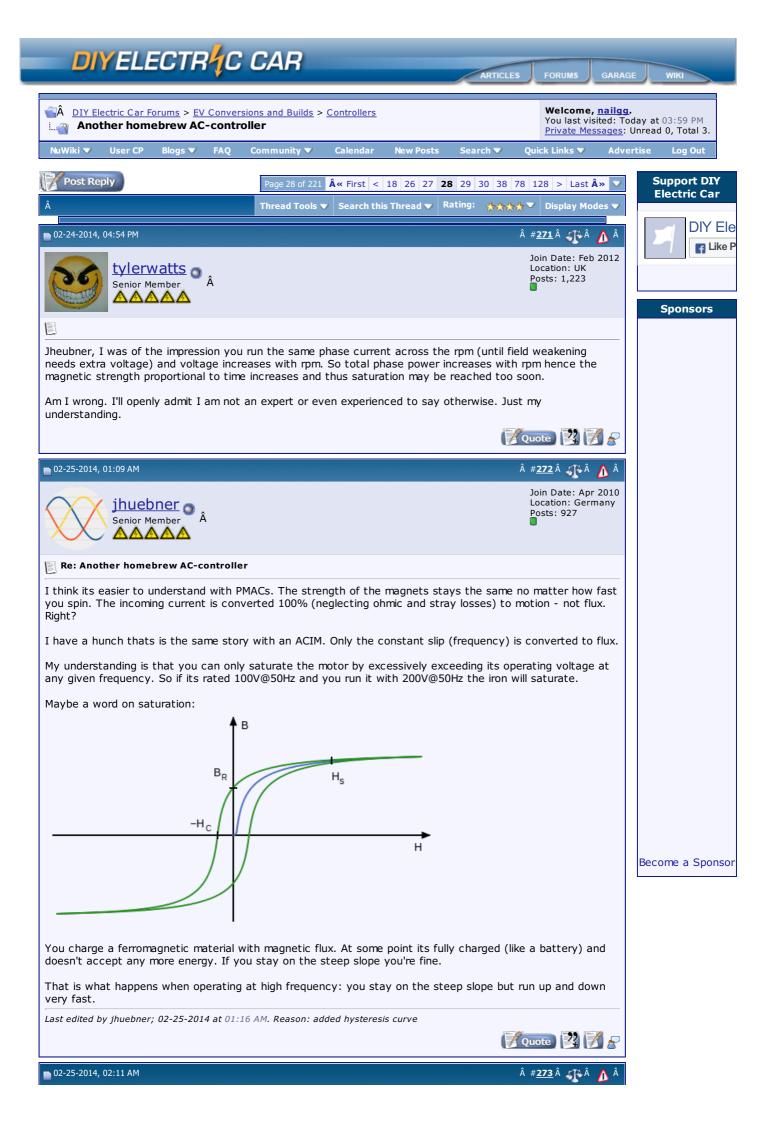
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Join Date: Feb 2009 Location: Lake Jackson, TX Posts: 376

📝 Quote 🕎 📝 ج

#<u>274</u>Â 🌆 Â

Posts: 23

Join Date: Jan 2013

Location: Bulgaria

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Re: Another homebrew AC-controller

Quote:

Originally Posted by jhuebner 55 Ok, I think all important bits and pieces have by now been mentioned. Let me summarize.

1) You start with a 70hp motor whos power is about 3-fold when running at breakdown torque. ->210hp 2) You find out that you can spin up to 16000rpm (maybe with additional balancing) instead of 3000rpm. ->1120hp

3) You figure you can increase V/Hz by a factor of 1.3. ->1456hp

That's what I am talking about.

Metric ampahaulic.com Facebook Page for LoneStar EV Racing ELE 6.0sec-1/8mi 101mph-1/8mi DIY ELE PiD 7.2sec-1/4mi 188mph-1/4mi DIY PiD A&B 8.9sec-1/4mi 165mph-1/2mi DIY A&B DCP 9.8sec-1/4mi 155mph-1mi DIY DCP

D2-25-2014, 03:31 AM

bLdC Junior Member Â AA

Re: Another homebrew AC-controller

Quote:

Originally Posted by jhuebner 5 I think its easier to understand with PMACs. The strength of the magnets stays the same no matter how fast you spin. The incoming current is converted 100% (neglecting ohmic and stray losses) to motion - not flux. Right?

And don't forget it is temperature dependent. 🤭 It will look something like this for the magnest in the furnace. For low temperatures the field strength is much better. Notice the graph for 20 C. magnet hysteresis graphs.png

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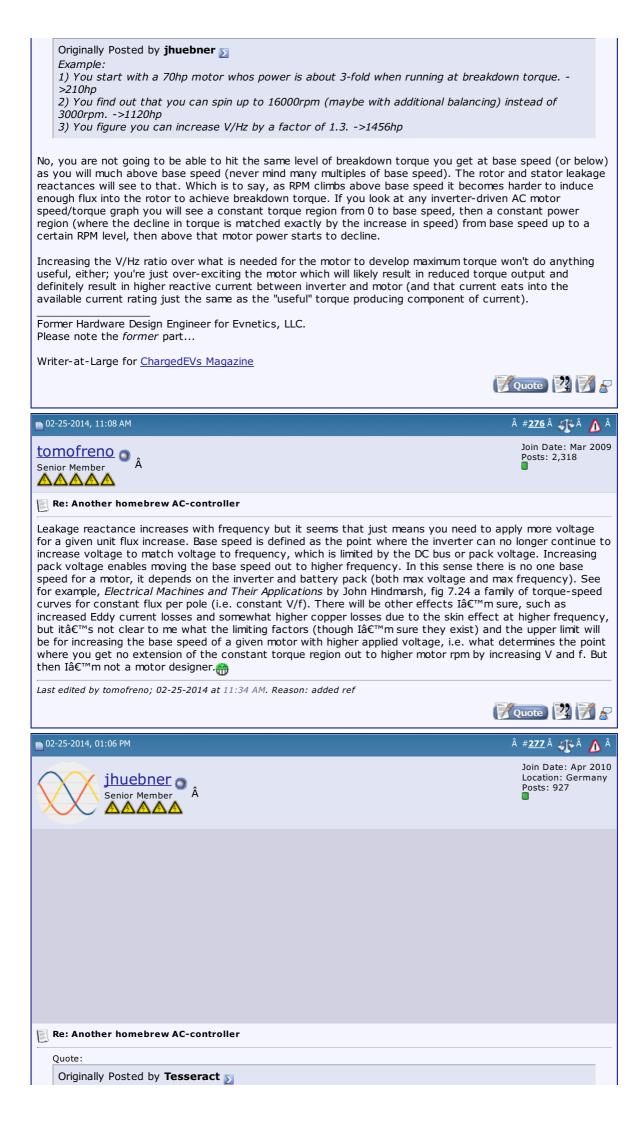
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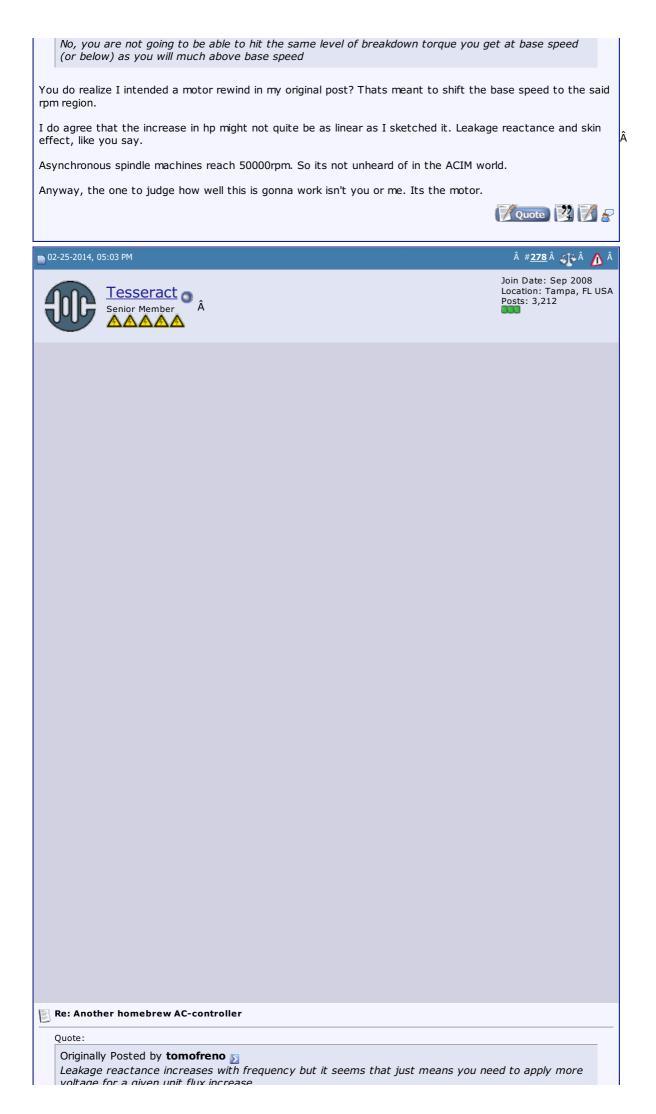
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Re: Another homebrew AC-controller

Quote:





If all you had to worry about was the stator leakage reactance, then sure, just boost the V/Hz ratio with increasing RPM, but the rotor leakage reactance is what is important here, and its impedance is proportional to slip. As the impedance of the rotor leakage reactance approaches that of the rotor bar resistance, maximum possible torque declines. This is why increasing the rotor resistance can improve torque development at high slip.

Quote:

Originally Posted by tomofreno

Base speed is defined as the point where the inverter can no longer continue to increase voltage to match voltage to frequency, which is limited by the DC bus or pack voltage. Increasing pack voltage enables moving the base speed out to higher frequency.

Yes, VFDs complicate the definition of "base speed," so I prefer to think of it as the synchronous RPM of the motor when it is driven with the designed value of voltage and frequency. In other words, base speed defines the V/Hz ratio for fully-fluxed operation.

Quote:

Originally Posted by jhuebner 🔊

You do realize I intended a motor rewind in my original post? Thats meant to shift the base speed to the said rpm region.

That is irrelevant. You can rewind the stator all you want, but the rotor parameters are the ultimate determinant of peak torque (and therefore peak power).

Quote:

Originally Posted by **jhuebner** Asynchronous spindle machines reach 50000rpm. So its not unheard of in the ACIM world.

Oh, I'm not saying you can't achieve an insane RPM with an ACIM, I'm saying you can't get the same breakdown torque at that RPM as you can at "base speed". Your conjecture that a 70hp ACIM can be overdriven to deliver 1400hp+ is, shall we say, divorced from reality. Feel free to spend as much time and resources as you like to attempt to prove me wrong.

Former Hardware Design Engineer for Evnetics, LLC. Please note the *former* part...

Writer-at-Large for ChargedEVs Magazine

💼 02-25-2014, 06:17 PM





📝 Quote 🕎 📝 💂

Join Date: Apr 2010 Location: Germany Posts: 927

Re: Another homebrew AC-controller

Quote:

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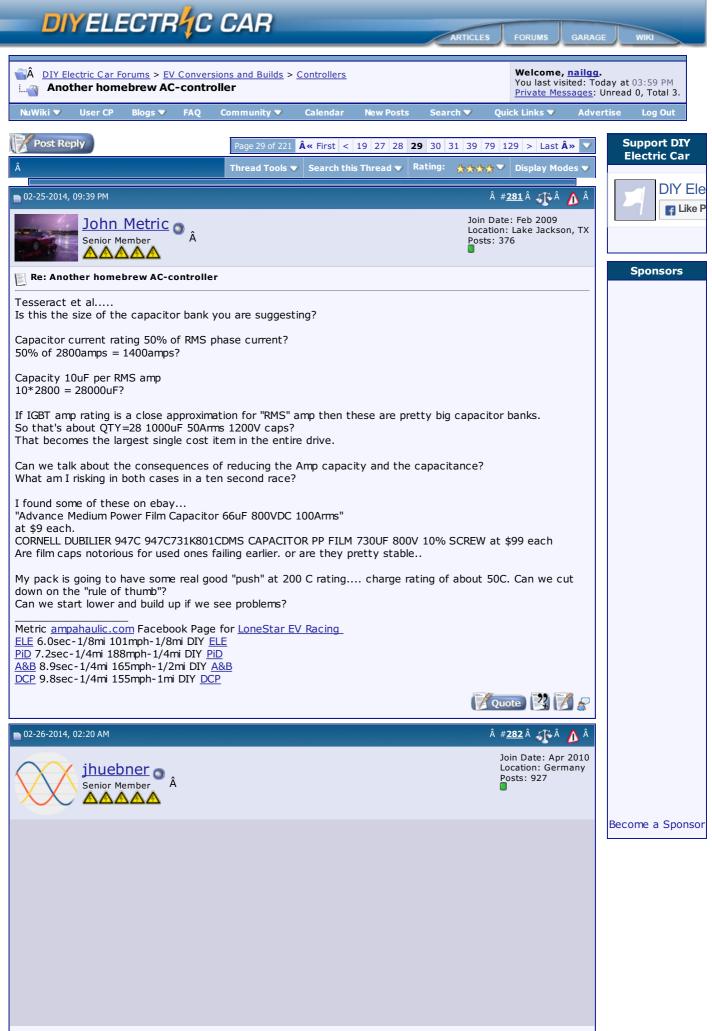
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Quote: Originally Posted by John Metric 5 I found some of these on ebay... "Advance Medium Power Film Capacitor 66uF 800VDC 100Arms" at \$9 each. CORNELL DUBILIER 947C 947C731K801CDMS CAPACITOR PP FILM 730UF 800V 10% SCREW at \$99 each So 14 of the 66µF get you the 1400arms rating. Quite amazing if true. I couldn't find a datasheet for them. The second one is rated 68Arms, so useless to you. Quote: Originally Posted by John Metric 5 Are film caps notorious for used ones failing earlier. or are they pretty stable.. They are more stable than elcaps at least. Quote: Originally Posted by John Metric 5 My pack is going to have some real good "push" at 200 C rating.... charge rating of about 50C. Can we cut down on the "rule of thumb"? Can we start lower and build up if we see problems? The rule of thumb assumes a film cap like the cornell 68A@730µF. Better cap -> lighter rule of thumb. The "advance" caps take it to $1.5A/\hat{A}\mu F$ So the rule of thumb comes down to Arms*0.75. I don't know the consequences of underrated bus caps. Film caps are considered "self-healing" as in they won't short out when they fail but they gradually loose capacity. This ring cap here: http://www1.futureelectronics.com/do...D10896-348.pdf Has a peak-rating of 10000A and an rms rating of 200A. Not sure what a peak is. Valery might know more about it. Last edited by jhuebner; 02-26-2014 at 02:30 AM. Reason: ring cap 🛛 🛛 Quote 🕺 📝 🔎 D2-26-2014, 06:36 AM #<u>283</u>Â 🎢 Â ΔÂ Join Date: Sep 2008 Tesseract Location: Tampa, FL USA Posts: 3,212 Â Senior Member Re: Another homebrew AC-controller Quote: Originally Posted by jhuebner 5 ... Of course the speed is limited by rotor imbalance and other mechanical effects. But the electrical parameters of the rotor don't limit the speed. With inverters the traditional definition of slip as a ratio between the rotor and stator frequency is completely irrelevant. That is old grid tie stuff. Firstly, I didn't say anything about the rotor electrical parameters limiting speed (though they will, actually... eventually), so that is a red herring. Secondly, "base speed" will always be relevant because it states the RPM of the AC motor at a specific frequency and voltage, and if the specified RPM is at full load, then you can also determine the slip (applies only to induction motors, obviously). Ouote: Originally Posted by John Metric 5 Capacitor current rating 50% of RMS phase current? 50% of 2800amps = 1400amps? Capacity 10uF per RMS amp $10*2800 = 28000 \mu F?$

This is a correct application of the thumb-rules I mentioned earlier, yes, but note that the second rule (e.g. - 10uF/amp for film caps) is an approximation for achieving the necessary ripple current rating; if the capacitor datasheet says it can handle more ripple current than the thumb-rule suggests then by all means go with the datasheet rating.

That said, it seems you are still operating under the incorrect assumption that you will get something useful from an ACIM by running it at over 10x its rated current... I guess you don't believe me (or major) when I (we) say breakdown torque is the best you can get from an ACIM, no matter what tricks might be up your proverbial sleeve?

Quote:

Originally Posted by John Metric 🔊

If IGBT amp rating is a close approximation for "RMS" amp then these are pretty big capacitor banks.

Sure, as long as you can keep the case temperature below whatever the datasheet says for that current (usually 80C for large modules), you can run a 1400A module at 1400A. At least for a few seconds at a time, anyway.

That said, keep in mind that the peak current in a sine wave is 41% higher than the RMS and while the RMS value can be used for sizing at higher output frequencies (*not* switching frequency), the peak value is dominant at low output frequencies (e.g. - <1/10th of base speed).

Also keep in mind that if more than one module is used to achieve the desired output current rating then derating for unequal sharing will be required. This derating is necessary even if you only want to run the inverter at max current for 10 seconds at a time.

Quote:

Originally Posted by John Metric 5 So that's about QTY=28 1000uF 50Arms 1200V caps? That becomes the largest single cost item in the entire drive.

Yep.

Quote:

Originally Posted by John Metric 5 Can we talk about the consequences of reducing the Amp capacity and the capacitance? What am I risking in both cases in a ten second race?

Increased heating in the capacitors - possibly at a rate fast enough to cause dielectric failure - and higher voltage spikes across the IGBTs during turn-off. That said, the capacitor ripple current rating is one which Otmar has successfully abused for years. That's not my design philosophy, but I certainly won't argue that it hasn't worked out well for him (especially in the Z2K). The thing is, and not to be too blunt here, but you aren't Otmar...

📝 Quote 🕎 📝 🔗

#<u>284</u>Â ⁄ 🏠

Δ Mar 2009

Former Hardware Design Engineer for Evnetics, LLC. Please note the former part...

Writer-at-Large for ChargedEVs Magazine

🗖 02-26-2014, 09:41 AM

tomo Senior AA

Re: Quo

America A A A A A A A A A A A A A A A A A A A	Join Date: M Posts: 2,318
Another homebrew AC-controller	
te:	

Originally Posted by Tesseract

If all you had to worry about was the stator leakage reactance with increasing RPM, but the rotor leakage reactance is what i proportional to slip. As the impedance of the rotor leakage rea bar resistance, maximum possible torque declines.	is important here, and its impedance is
Oh, ok, I was looking at it differently, thinking if you want more por f and maintain the same slip and torque. I didn't see people were to some V and f.	
Quote: This is why increasing the rotor resistance can improve torque	development at high slip.
Agree. Increasing rotor resistance increases starting torque, but at (decreases the slope of the torque-spd curve at low values of slip)	
Quote: Yes, VFDs complicate the definition of "base speed," so I prefe of the motor when it is driven with the designed value of volta base speed defines the V/Hz ratio for fully-fluxed operation.	r to think of it as the synchronous RPM ge and frequency. In other words,
Agree, max flux per pole, which can be obtained at various values of properly to maintain the max flux per pole.	
	📝 Quote 🕎 🌠 🌮
■ 02-26-2014, 09:47 AM	# <u>285</u> 🐠 💧
gunnarhs Senior Member Â	Join Date: Apr 2012 Location: Iceland Posts: 292
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by jhuebner <i>Example:</i>	
1) You start with a 70hp motor whos power is about 3-fold wh >210hp	nen running at breakdown torque
2) You find out that you can spin up to 16000rpm (maybe with 3000rpm>1120hp	
3) You figure you can increase V/Hz by a factor of 1.3>1450	6hp
1) When experimenting you will find out that if breakdown-torque is torque you can withhold for 30 seconds will be $2,5 \times 10^{-1}$ mm it will be $1,5 -> 2$ times)	e near base speed of motor (at very low
2) Without rewinding the motor you could spin it to 10.000 rpm (ins load and appropriate inverter. (you can see on Youtube people do motors). However when applying load you need torque to move that in 1). So practically you reach maybe	that up to 30.000 rpm with standard
6000 - 8000 rpm with nominal load (depending on induction motor t 3) By increasing V/Hz (not more than 1.3 nominal Voltage for stand above the usual base speed. You are not doing that at say 6000 rp 3000 rpm.	lard motors), you can do that just a little
So I would say you can theoretically get 4x nominal power out of a maximal for 30 seconds or less). And in that case you would probably need additional cooling.	a standard AC (70 hp nominal, 280 Hp
I have no experience with rewound motors but their main problem I in the end the rotor limits the performance	see is that the rotor is not changed, and
Last edited by gunnarhs; 02-26-2014 at 09:50 AM. Reason: typos	
	Vuote 🕎 🌠 🔗
■ 02-26-2014, 10:07 AM	
■ 02-26-2014, 10:07 AM	# <u>286</u> J Â
02-26-2014, 10:07 AM	

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Re: Another homebrew AC-controller

Quote:

Originally Posted by Tesseract D

That said, it seems you are still operating under the incorrect assumption that you will get something useful from an ACIM by running it at over 10x its rated current... I guess you don't believe me (or major) when I (we) say breakdown torque is the best you can get from an ACIM, no matter what tricks might be up your proverbial sleeve?

I do believe you that breakdown torque is the most torque you can get out of a motor of a specified design.

This is a generic drive with no motor manufacturer matched mate... so not sure how you draw your conclusion above....

I haven't picked out the final motor yet for my third race car which I haven't built yet. I am guessing I will have to build something like a twin copper rotor Tesla Motor to pull some crazy amps or four of Siemens motors or something extreme like that. But right now there is no reasonably priced megawatt AC controller out there. You hi-power DC controller guys haven't been able to make the conversion over to AC and I am tired of waiting. So, I am trying to build one.

I have picked out a test mule to test this drive. It is TWO Siemens xxxx-4WS24 on a common shaft driven by this one drive. Frankly because its in my budget and I trust the Siemens name to have more safety factor in it then your budget low V motors.

Quote 🕺 📝 🖉

What is your name? What do you do over at EVNETICS? Have we met?

Metric <u>ampahaulic.com</u> Facebook Page for <u>LoneStar EV Racing</u> <u>ELE</u> 6.0sec-1/8mi 101mph-1/8mi DIY <u>ELE</u> <u>PiD</u> 7.2sec-1/4mi 188mph-1/4mi DIY <u>PiD</u> <u>A&B</u> 8.9sec-1/4mi 165mph-1/2mi DIY <u>A&B</u> <u>DCP</u> 9.8sec-1/4mi 155mph-1mi DIY <u>DCP</u>

Last edited by John Metric; 02-26-2014 at 10:10 AM.

🗖 02-26-2014, 10:12 AM #<u>287</u>Â 🕂 Â <u> </u>Â tomofreno O Â Join Date: Mar 2009 Posts: 2,318 Senior Member Re: Another homebrew AC-controller Quote: Originally Posted by John Metric 🔊 ...You hi-power DC controller guys haven't been able to make the conversion over to AC and I am tired of waiting. So, I am trying to build one. I think it is more "unwilling" than "unable", due to lack of financial incentive - the market is very small and margins would be very slim. Now if someone were to give them a grant... 🛛 🛛 Quote 🕎 🏹 🔎 #<u>288</u>Â <u>∢</u>Â <u>∧</u>Â 02-26-2014, 01:08 PM Join Date: Sep 2008 Tesseract o A Location: Tampa, FL USA Posts: 3,212 Senior Member Re: Another homebrew AC-controller Quote: Originally Posted by John Metric 🔊 I do believe you that breakdown torque is the most torque you can get out of a motor of a specified desian.

I his is a generic drive with no motor manufacturer matched mate... so not sure how you draw your conclusion above....

Breakdown torque is fixed by design for any particular ACIM. Which is to say, torque increases with current up to a certain point - called breakdown - and then it actually declines if current continues to increase. There is no way around this fact, it is an intrinsic property of the ACIM.

The reason for this is "saturation" of the stator, which is when the maximum number of lines of magnetic force that can be carried is reached. The number of lines of magnetic force through a magnetic material depends on the number of turns of wire about it and the current through said wire. Thus, saturation can be considered a hard current limit for any magnetic material.

Now, the amount of torque a motor can produce depends on the strength of the stator magnetic force interacting with that of the rotor. In an ACIM, the stator has two duties to perform: it must creating the rotating magnetic field in space which the rotor interacts with to produce torque, and it also must induce a relatively stationary field into the rotor for said interaction to take place. If enough current is forced through the stator for it to begin saturating then there will be no increase in field strength for an incremental increase in current, and if there is no increase in field strength from the stator then there will not be an increase in field strength induced into the rotor. Ergo, no increase in torque.

Quote:

Originally Posted by John Metric 🔊

But right now there is no reasonably priced megawatt AC controller out there. You hi-power DC controller guys haven't been able to make the conversion over to AC and I am tired of waiting. So, I am trying to build one.

Right. You want a higher power AC controller and it must be affordable while I want to make at least twice as much profit on every controller just to have a sustainable business model (our gross margin on the Soliton1 is uninspiring, and on the Jr it is down right pathetic). So, we seem to be at loggerheads.

Quote:

Originally Posted by **John Metric** *What is your name? What do you do over at EVNETICS? Have we met?*

My name is Jeffrey and like it says in my sig, I'm in charge of herding the electrons 'round these parts (which is to say, I am the EE). And yes, we have met. Nice to see I am so memorable in person... 😋 🥋

Former Hardware Design Engineer for Evnetics, LLC. Please note the *former* part...

Writer-at-Large for ChargedEVs Magazine



D2-26-2014, 01:26 PM



 #289 Â A Â Â Join Date: Jul 2012 Location: Norco, California

Posts: 441

Re: Another homebrew AC-controller

Market thoughts.

An EV drive system >200hp is \$20k+.

The existing EV aftermarket folk aren't interested at hotrodding production EV's, which is the bread and butter of the ICE aftermarket powertrain companies.



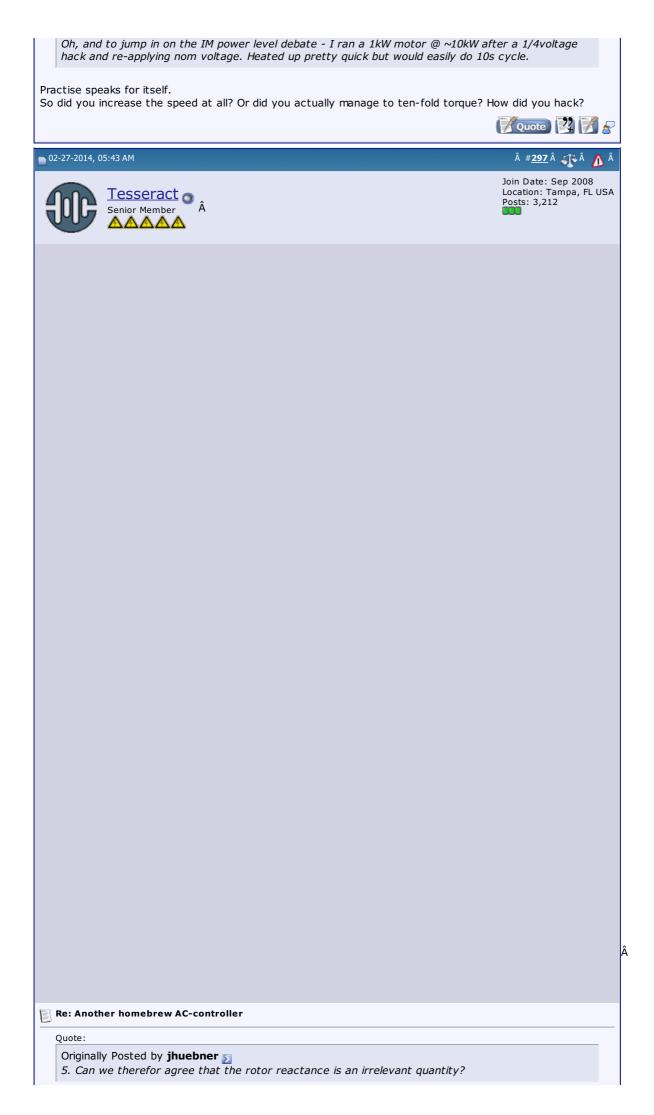
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Quote:
Originally Posted by major Thanks. RIFA PEH200VT4330MU2, 3300uF, 400VDC. Typical. Depending on the quantity there may like this one or close. Some were 2700uF, 420V and some 2200uF, 500V. I'll get a lot of all same part numbers. Yes, I know of the ballasting resistors for series connected caps. These are 5 to 10 years old. Climate controlled storage. Appear in excellent shape. Perhaps a review of the reform procedure for John's sake is in order.
Appreciated 🙂
ese are old Evox-Rifa elkos. Decent stuff, and they hold up fairly well over time. I have a bunch of PEH ries caps that are at least 20 years old but still meet their ESR and leakage specs.
e PEH line was bought by Kemet a few years ago so the <u>datasheet</u> might be "too new", but according to it ch of these caps can handle 36.3A of ripple at 10kHz/40C ambient and have an ESR of 14-26 milliohms pending on frequency and temperature. I would say that John would need 40 of these capacitors (2 in ries by 20 in parallel), as that would get him a ripple current rating of ~25% of the rated RMS phase rrent. If duty cycle is kept to 10 seconds on followed by 1-2 minutes off then that number could probably cut in half again, but that is definitely getting into subjective/seat-o-the-pants territory.
for reforming old elkos, there are several methods and which one to go with kind of depends on the uipment available. Personally, I like to simply apply a slowly increasing voltage over time, either by using a riac/isolation transformer/bridge rectifier or an adjustable, current-limited DC power supply. The most mmonly suggested procedure is to apply full rated voltage to the capacitor through a resistor which will it maximum current to around twice the rated leakage current value, and leave it there until the current ls to the rated leakage value. In this case, the leakage current is ~5.3mA, and if using a rectified 240VAC r doubled 120VAC) supply that would require a ~33k/5W resistor.
for the ballasting resistors (and yes, I know *you* know this, as well as about reforming the dielectric, c.), the typical recommendation is that the resistor needs to be able to pass the full leakage current, so two 400V caps in series, each running at, say, 350V, and with \sim 5.3mA of leakage the resistor needs to no higher than 66.5k. The closest E24 series resistor would be 62k. Oh, and rated for 5W just to be safe.
rmer Hardware Design Engineer for Evnetics, LLC. ease note the <i>former</i> part
iter-at-Large for ChargedEVs Magazine
Quote 🕎 🖉
2-27-2014, 02:37 AM Â # 294 Â 📣 Â
2-27-2014, 02:37 AM #294 I A A A Join Date: Nov 2006 Location: Australia Posts: 404
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Live Join Date: Nov 2008 Nor Member A Re: Another homebrew AC-controller Posts: 404 a reference, I use 1200V 800uF with 80A ripple capacity for 450ARMS continuous - I'm even thinking this overkill. I'm even thinking this overkill. s all about good ULESL design and very fast fault condition detection and shutdown. r your 1400A IGBTs @ 4khz you'd be looking at ~1000A derated. t sure how you got to ~30,000uF! y extra for film caps and you'll save in the long run. 28 caps is going to introduce a lot of inductance and
Live Join Date: Nov 2008 nior Member A Re: Another homebrew AC-controller Posts: 404 a reference, I use 1200V 800uF with 80A ripple capacity for 450ARMS continuous - I'm even thinking this overkill. s all about good ULESL design and very fast fault condition detection and shutdown. r your 1400A IGBTs @ 4khz you'd be looking at ~1000A derated. t sure how you got to ~30,000uF!
Live Join Date: Nov 2008 Inor Member A Re: Another homebrew AC-controller Posts: 404 a reference, I use 1200V 800uF with 80A ripple capacity for 450ARMS continuous - I'm even thinking this overkill. I'm even thinking this overkill. s all about good ULESL design and very fast fault condition detection and shutdown. r your 1400A IGBTs @ 4khz you'd be looking at ~1000A derated. t sure how you got to ~30,000uF! y extra for film caps and you'll save in the long run. 28 caps is going to introduce a lot of inductance and lds a dangerous amount of power 🐼 such high power levels, every design decision is crucial and needs to meticulously calculated - you cant
A Join Date: Nov 2006 Incation: Australia Posts: 404 Posts: 404 Posts: 404 Post: 400
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Live A A Doin Date: Nov 2006 Location: Australia Posts: 404 Posts: 404 Posts: 404 Re: Another homebrew AC-controller Image: Another homebrew AC-controller a reference, I use 1200V 800uF with 80A ripple capacity for 450ARMS continuous - I'm even thinking this overkill. s all about good ULESL design and very fast fault condition detection and shutdown. r your 1400A IGBTs @ 4khz you'd be looking at ~1000A derated. t sure how you got to ~30,000uF! y extra for film caps and you'll save in the long run. 28 caps is going to introduce a lot of inductance and lds a dangerous amount of power @ such high power levels, every design decision is crucial and needs to meticulously calculated - you cant at do whatever's easiest or cheapest - it will cost you more in the long run. a, and to jump in on the IM power level debate - I ran a 1kW motor @ ~10kW after a 1/4voltage hack and capplying nom voltage. Heated up pretty quick but would easily do 10s cycle.
A Second State State Second

1. We all agreed that breakdown torque is the maximum torque reachable 2. Can we please agree that running nominal torque at twice the base speed results in twice the POWER output? 3. Can we agree that the rotor current/flux is caused by a certain slip FREQUENCY (e.g. 5Hz) and is proportional to the stator current? 4. Can we now agree that the motor can run with the exact same slip frequency at 100rpm and at 10000rpm? 5. Can we therefor agree that the rotor reactance is an irrelevant quantity? 6. Can we agree that rewinding the stator with half as many windings will result in half the nominal voltage and twice the nominal current at nominal base speed and nominal torque? 7. Can we agree that rewinding tha stator that way does not produce any additional flux that saturates the iron? 8. Can we now agree that with the new rewound stator we can operate at twice the nominal frequency and still reach nominal torgue or breakdown torgue respectively? 9. Can we agree that breakdown torque is 2-4 times higher than nominal torque? 10. Can we now agree that we have doubled the motors power by rewinding it and that we again 2-4 folded it by running at breakdown torque? 11. Can we agree that that the motor outputs 4-8 times more power? 12. Can we sort of agree that by rewinding the stator with 10 times less windings (and therefor stronger wire) we can run at 10 times the nominal frequency and still reach nominal torque or breakdown torque respectively? 13. Can we sort of agree that this 20-40 folds the motors power? Illustration: Motor: 4 pole, 3560rpm, 50Nm (nominal) 200Nm (breakdown), 120Hz, 200V. (thats roughly what I use). Rated power is 18.5kW at rated torque and speed. Slip frequency: fslip=fnom-Nnom*p fnom=120Hz, Nnom=3560/60=59.34 1/s=59.34Hz, p=2 (2 pole pairs) fslip=120-59.34*2=1.34Hz V/hz ratio (lets call it r): r=Unom/fnom = 200V/120Hz=1.67V/HzNominal torque is now reached at different speeds by applying fslip as slip frequency and 1.67*f as terminal voltage. E.g. 1000rpm: f=2*1000/60+fslip=33.34+1.34=34.67Hz, U=1.67*34.67=58V 16000rpm: U~890V, f=534.67Hz Since 890V is a bit on the tough side we now rewind the stator with 1/3 the number of windings. This results 1/3 of the inductance and 1/3 of the reactance. Therefore we must recalculate r r=200/3/120=0.56V/Hz Now we can reach nominal torque at 534.67Hz by applying 890/3=297V. Breakdown torque is reached by letting the rpm sag as to reach breakdown slip frequency. Lets assume that is the case at 15000rpm. So now the power is P=2*Pi*15000/60*200=314kW (out of a 18.5kW motor) Of course at the same time we probably produce maybe 30% of heat which is 94kW which is a lot. For me thats the actual question, can the thermal capacity of the motor cope with that much heat for 10s? But then John has done that much overdriving with DC motors which produce the same sort of heat and they seem to hold up. Capacitors: don't get hung up with specific capacities but with the ripple current capability. Or relax, as Tesseract says and use what is used in the Zilla. Last edited by jhuebner; 02-27-2014 at 03:50 AM. Reason: corrected terminal voltage 🖌 Quote 🕺 🖌 💂 #<u>296</u>Â 🏹 Â 🖿 02-27-2014, 04:02 AM Join Date: Apr 2010 jhuebner O Â Location: Germany Posts: 927 Senior Member 📃 Re: Another homebrew AC-controller Quote: Originally Posted by Stiive 🔊



At low slip frequency (e.g. - 5Hz), sure, but keep in mind that the impedance of the rotor leakage reactance needs to only approach/exceed the resistance of the rotor shorting bars to cause a decrease in breakdown torque, and as the resistance of the rotor bars is very low, it therefore takes very little reactance (and/or a very low frequency) before its effects are felt.

Quote:

Originally Posted by jhuebner 🔊

8. Can we now agree that with the new rewound stator we can operate at twice the nominal frequency and still reach nominal torque or breakdown torque respectively?

Possibly, possibly not. You are ignoring iron losses in the stator laminations which increase at approximately the 1.6 power with frequency (e.g. - at twice the frequency losses are $2^{1.6}$ higher, which is 3x).

NB - iron losses in the typical grades of silicon steel laminations (e.g. - M19) used for stator laminations for motors originally intended for base speed at 50/60Hz will have losses at that frequency of \sim 5W/kg at full flux (\sim 1.5T). Thinner laminations and/or different types of silicon steel can have approximately half the losses, but with some reduction in maximum flux and increase in leakage reactance (due to there being a higher total amount of insulating coating present in the stator when more laminations of thinner material are used).

Quote:

Originally Posted by jhuebner 🔊

9. Can we agree that breakdown torque is 2-4 times higher than nominal torque?

I don't recall ever seeing breakdown torque exceed 3x full load torque, and it is closer to 2x in the Siemens motors that Jack Rickard is hawking these days, but, well... I'll give you this one.

Quote:

Originally Posted by **jhuebner** 10. Can we now agree that we have doubled the motors power by rewinding it and that we again 2-4 folded it by running at breakdown torque?

Sure, as long as you can agree that you have increased copper losses by 4x to 16x, and iron losses by 3x by running at twice the voltage and frequency and at 2x to 4x the current. Ergo, efficiency has taken a nosedive.

Quote:

Originally Posted by jhuebner 🔊

11. Can we agree that that the motor outputs 4-8 times more power?

Close; the inverter may be putting out 4-8x more power, but on account of the aforementioned losses, the motor will deliver some amount less than that.

Quote:

Originally Posted by **jhuebner S**

12. Can we sort of agree that by rewinding the stator with 10 times less windings (and therefor stronger wire) we can run at 10 times the nominal frequency and still reach nominal torque or breakdown torque respectively?

13. Can we sort of agree that this 20-40 folds the motors power?

Nope, this is where you depart from reality.

Former Hardware Design Engineer for Evnetics, LLC. Please note the *former* part...

Writer-at-Large for ChargedEVs Magazine

Last edited by Tesseract; 02-27-2014 at 08:05 AM. Reason: spelling

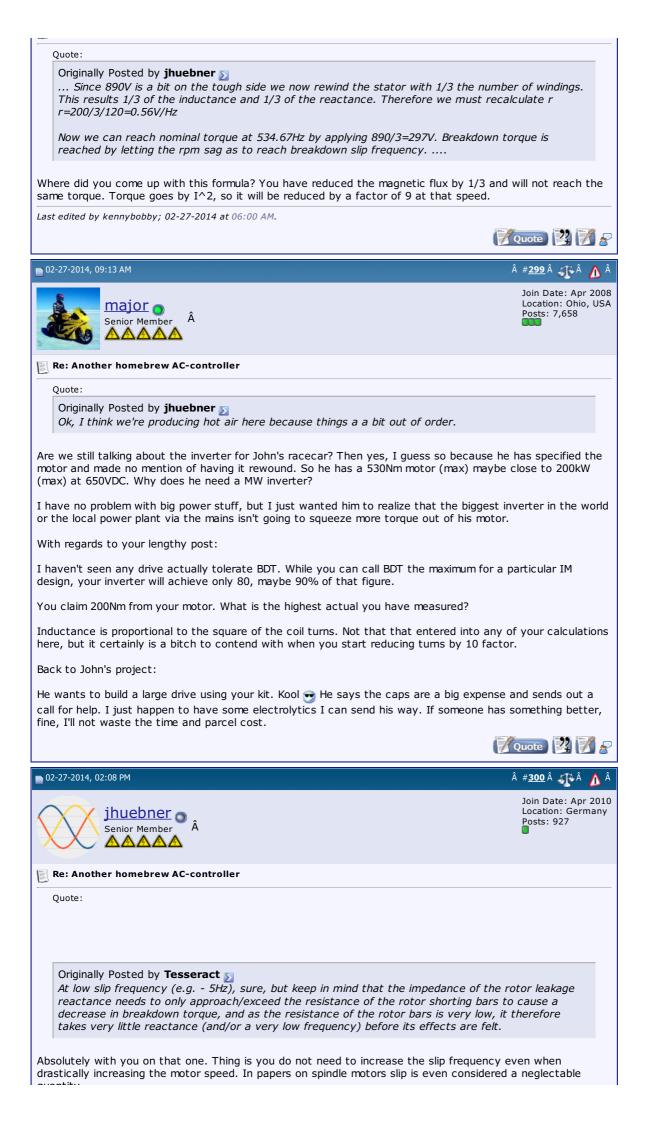
💼 02-27-2014, 05:56 AM



Join Date: Aug 2012 Location: Heart of Dixie Posts: 1,054 Blog Entries: $\underline{1}$

â #<u>298</u> â 🌆 Â 🧥 Â

Quote 🕺 📝 🔎



quantity.

Quote:

Originally Posted by Tesseract 5

Possibly, possibly not. You are ignoring iron losses in the stator laminations which increase at approximately the 1.6 power with frequency (e.g. - at twice the frequency losses are $2^{1.6}$ higher, which is 3x).

Agreed.

The iron losses are estimated at 25% of the total losses at "normal" speeds. They become prevelant at high frequency operation.

By the 25% estimation I calculated about 300W of iron losses for my motor. So at twice the frequency this becomes 1.2kW.

Quote:

Originally Posted by Tesseract 5

I don't recall ever seeing breakdown torque exceed 3x full load torque, and it is closer to 2x in the Siemens motors that Jack Rickard is hawking these days, but, well... I'll give you this one.

See below.

Quote:

Originally Posted by **Tesseract** \sum Sure, as long as you can agree that you have increased copper losses by 4x to 16x, and iron losses by 3x by running at twice the voltage and frequency and at 2x to 4x the current. Ergo, efficiency has taken a nosedive.

Absolutely. Thats why I estimated 70% effiency in my example.

Quote:

Originally Posted by **Tesseract** Nope, this is where you depart from reality.

Yes, I might be taking the concept too far. Thats for John to find out.

Quote:

Originally Posted by kennybobby 53

Where did you come up with this formula? You have reduced the magnetic flux by 1/3 and will not reach the same torque. Torque goes by 1^2 , so it will be reduced by a factor of 9 at that speed.

Actually I might have gotten confused on the exact rewinding practise. As I don't want to repeat an existing discussion I shall link here: <u>https://www.diyelectriccar.com/forums...ons-77776.html</u>

The point is: you can somehow reduce the required terminal voltage at an expense of the terminal current by rewinding the stator.

Quote:

Originally Posted by major s

I haven't seen any drive actually tolerate BDT. While you can call BDT the maximum for a particular IM design, your inverter will achieve only 80, maybe 90% of that figure.

Agreed.

Quote:

Originally Posted by **major** You claim 200Nm from your motor. What is the highest actual you have measured?

I have never measured this, its taken from the data sheet.

http://www.lenze.com/fileadmin/lenze...tors_en-GB.pdf

Page 27, motor MF----132-22.

Quote:

Originally Posted by major 🔊

Inductance is proportional to the square of the coil turns. Not that that entered into any of your calculations here, but it certainly is a bitch to contend with when you start reducing turns by 10 factor.

Ok, I will stop making any specific statements about rewinding techniques and refer to the existing thread(s)

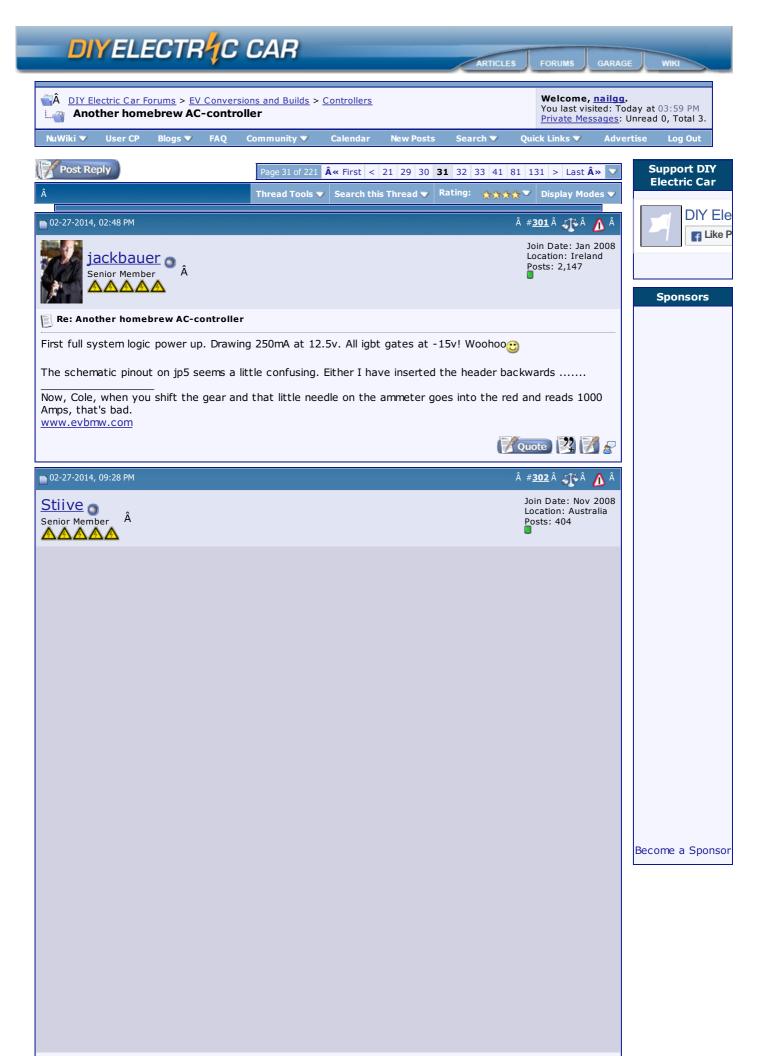
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Quote:

Originally Posted by jhuebner 5 Practise speaks for itself.

So did you increase the speed at all? Or did you actually manage to ten-fold torque? How did you hack?

Hack was by placing the four pole coils in parallel in each phase. Motor then can be run at 4x speed with same input voltage.(1400*4=5600RPM for a 4pole in Aus).

No idea what the torque/RPM was at max power, but was reading electrical output power from a generator which was reading about ~ 10.5 kW. Assuming with efficiency loss somewhere just under 10kW mech.

BUT before John thinks he can do the same with his Siemens - he cant. You can only get big gains out of industrial motors because they are so conservatively rated to allow for 24hr operation in 50degC mine sites in the desert for 20+ years. That's a long duty cycle in harsh conditions. That Siemens EV motor has already taken shorter duty cycles into acocunt on its nameplate, and they're max torque rating is already breakdown torque, whereas torque on an industrial motor is listed as nominal.

I agree with Major, you're not going to get much/any more than the 200kW rated max. Maybe 250kW if your controller and motor parameter model is faultless - which it wont be. Things heat up so quickly at breakdown torque its hard to keep track of the changing parameters.

Considering that frame is similar to a ~12.5kW industrial motor - thats already a 16x overloock for the same amount of iron (diameter and length)! The only addition is the water cooling which would allow it to be run at higher power for longer, and it knows itll be powered by a vector VSD and not off the line. It most likely also has higher grade laminations and possibly a copper rotor (but I don't think the latter).

Now buy a 100kW continuous IM like we have in the bus, and run that at 1MW... only problem is its 400kg+. High powered motor also have much lower inductance (this has <10uH), making it hard to control.

Best power to weight option would be getting a good PM motor and staying within its limits.

OR get some cheap aluminium frame industrial motors, rewind for lower voltage and abuse the %#* outta them. I'd assume roughly a 10x overclock max for 10s. But your not going to get good power or near breakdown torque reliably with slip control.

OR run your Siemens @ 250kW each. They are already overclocked for you, are well built, and well balanced. They spin hard, so you can have a mean reduction on them geared for your projected top speed. Then just concentrate on Weight Reduction while still maintaining power to the ground. Power isn't everything. Or if you absolutely need more, put two smaller high power PMs with different gear ratio on the front axle as well and just use the IM overload to get you off the line and when they hit field weakening, the PMSM are starting their CPSR.



Posts: 927

02-28-2014, 01:<u>29</u> AM #<u>303</u>Â 🎢 Â ΛÂ <u>John Metric</u> 🗿 _Â Join Date: Feb 2009 Location: Lake Jackson, TX Posts: 376 Senior Member AAA Re: Another homebrew AC-controller Quote: Originally Posted by Tesseract 5 My name is Jeffrey and like it says in my sig, I'm in charge of herding the electrons 'round these parts (which is to say, I am the EE). And yes, we have met. Nice to see I am so memorable in person... 🤭 💮 Jeffery Jenkins, yes I remember you. What the heck is "TESSERACT"? Metric ampahaulic.com Facebook Page for LoneStar EV Racing ELE 6.0sec-1/8mi 101mph-1/8mi DIY ELE PiD 7.2sec-1/4mi 188mph-1/4mi DIY PiD A&B 8.9sec-1/4mi 165mph-1/2mi DIY A&B DCP 9.8sec-1/4mi 155mph-1mi DIY DCP Last edited by John Metric; 03-01-2014 at 02:26 PM. 📝 Quote 🕎 📝 🔗 #<u>304</u>Â <u>∢</u>Â <u>∧</u>Â 🖿 02-28-2014, 02:56 AM Join Date: Apr 2010 ihuebner o Location: Germany

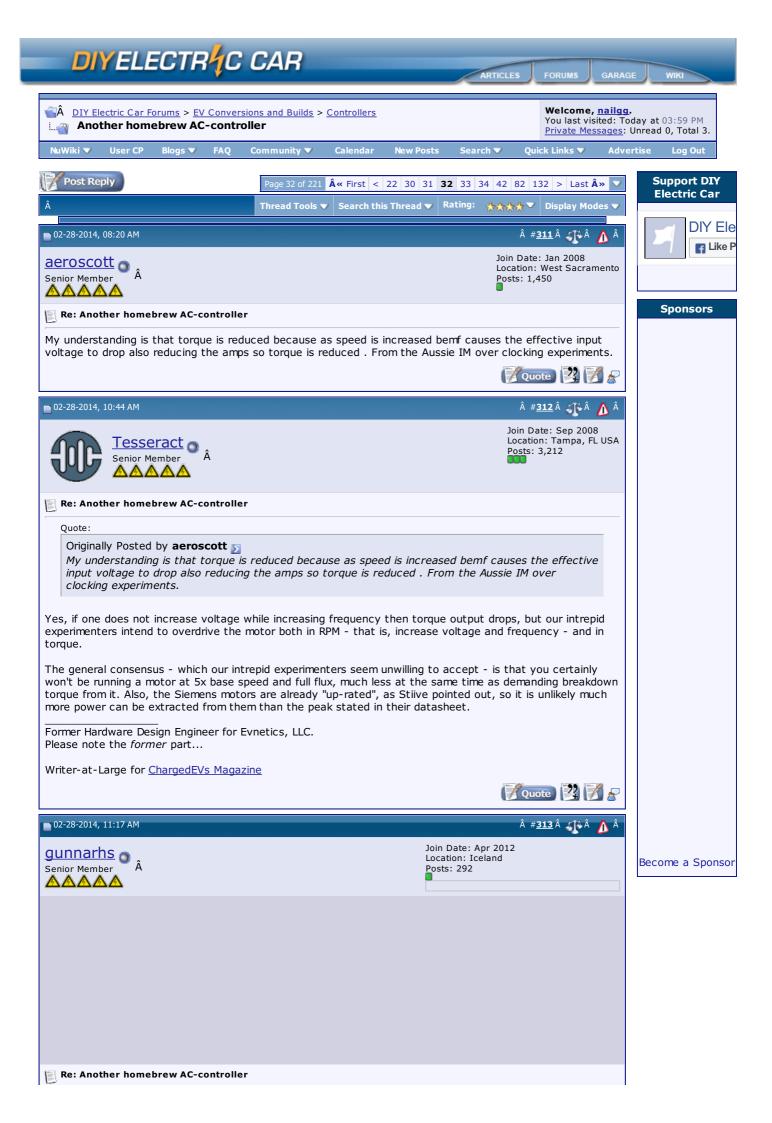




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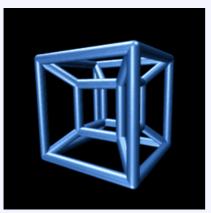




Re: Another homebrew AC-controller

Quote:

Originally Posted by **John Metric** Jeffery Jenkins, yes I remember you. I don't visit this blog very often, what the heck is "TESSERACT"?



That is a tesseract. From Wikipedia, btw. Also, my name is spelled Jeffrey, not Jeffery.

Quote:

Originally Posted by **John Metric** I promise not to break any of the laws of physics.

Yet that is what you are expecting to do if you think that cramming more current through an AC motor beyond what it takes to achieve breakdown torque will get you even more torque.

Quote:

Originally Posted by **John Metric** *I haven't said anything about 5X base speed.... yet....*

And given that you would need over 3kV to push the Siemens motor to 5x base speed, I rather think you won't be saying much about it in the future, either.

Quote:

Originally Posted by John Metric 🔊

BTW, What did you use for a test mule for the Shiva? Have you actually pushed the claimed 1.2MW into a motor off of batteries yet? I will bet so far no Shiva EV customer has actually been able to make rated power from batteries.

Acknowledging that this is wildly off-topic, of course no Shiva customer has even come close to reaching the 1.2MW power rating, but at least one customer (who goes by DIYguy here) routinely hits 3000A with his. I did test the prototype at 450V and at 3500A on our dyno, just not both at the same time.

Quote:

Originally Posted by John Metric 🔊

How about three Siemes 85kW or four, once I have the controller I can just parallel more identical motors, I think.?

Nope, you can't parallel AC motors. Well, maybe if you run them in open-loop V/Hz (aka "scalar") mode you can, but not with any form of closed-loop control (e.g. - slip, field-oriented current vector, etc.).

Now, you might be able to drive two PMAC motors from one inverter if their shafts are locked together and their rotors are at the exact same position relative to their phase windings - and their phase windings are electrically very similar - but this is pure conjecture on my part. Crusty ol' major can speak with more authority on that than me.

Quote:

Originally Posted by **John Metric** *In business development , you can be pessimistic and kill the project yourself or you can be optimistic and learn something when the assumption fails...*

I'm not being pessimistic and actually. I am a big fan of insane levels of nower - I designed the Shiva after

all, as well as a quadruple do with an ACIM is simply Former Hardware Design E Please note the <i>former</i> p	650V/1600A d not possible. I Engineer for Evr	rive system f nduction mot	or locomotiv	es - it's	just tl	hat w	hat yo	u are	prop	oosing	
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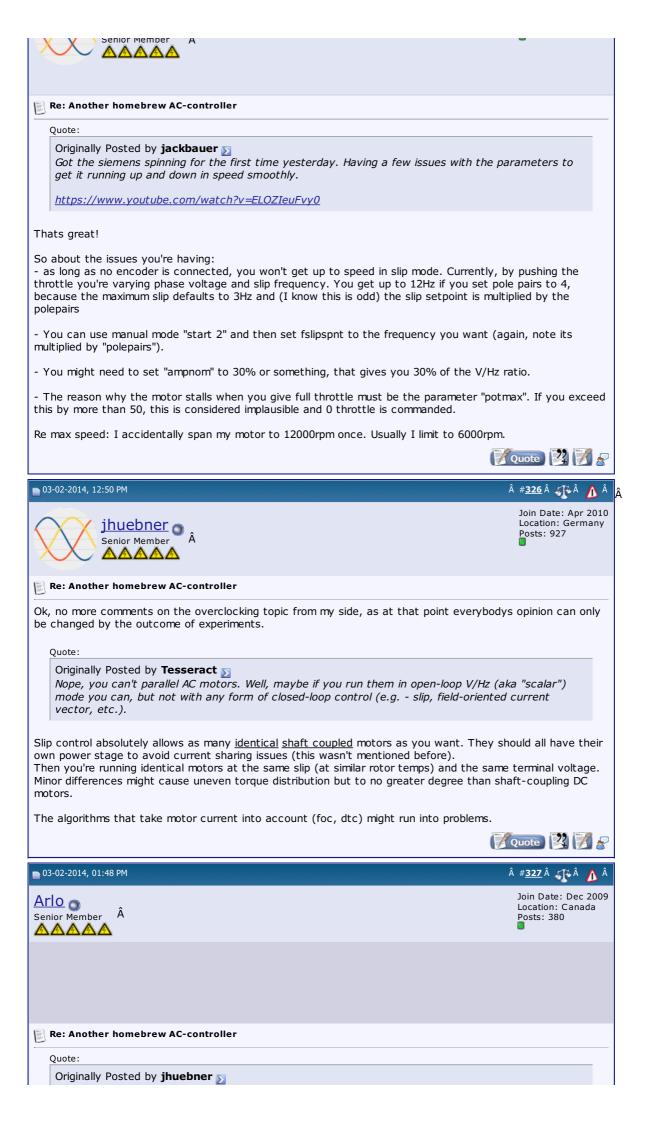


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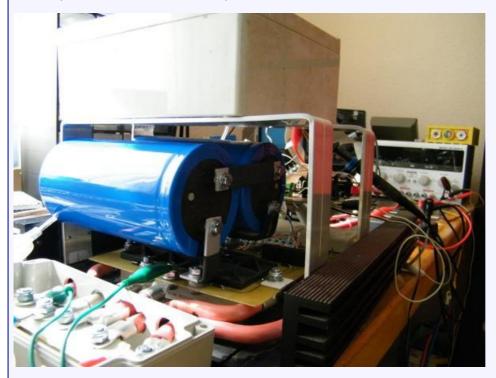
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Reminder, the old version looked like this, with the control board in the white box:



I added support for the KTY84 temp sensor which is used in the Siemens 1PV motors.

I'm planning to make a little web interface to make things easier to handle than with the text terminal.

 $I^{\prime}m$ also planning to use the park/clark transformation of FOC to be able to display reactive and real power and the power factor.

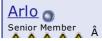
I'm still hesitant of actually using FOC for motor control as I think its results may be less predictable. The factors of a PI regulator are just way more abstract to me than slip and voltage. Also since the sensorless approach doesn't seem to work for traction applications it looses its largest actual advantage. Transient response is not really a requirement in traction unless you expect your cruise control to be rock steady in hilly terrain.

Heres a funny article (which reveals that slip control wasn't invented on this forum - unfortunately) http://industrial.embedded-computing...ented-control/



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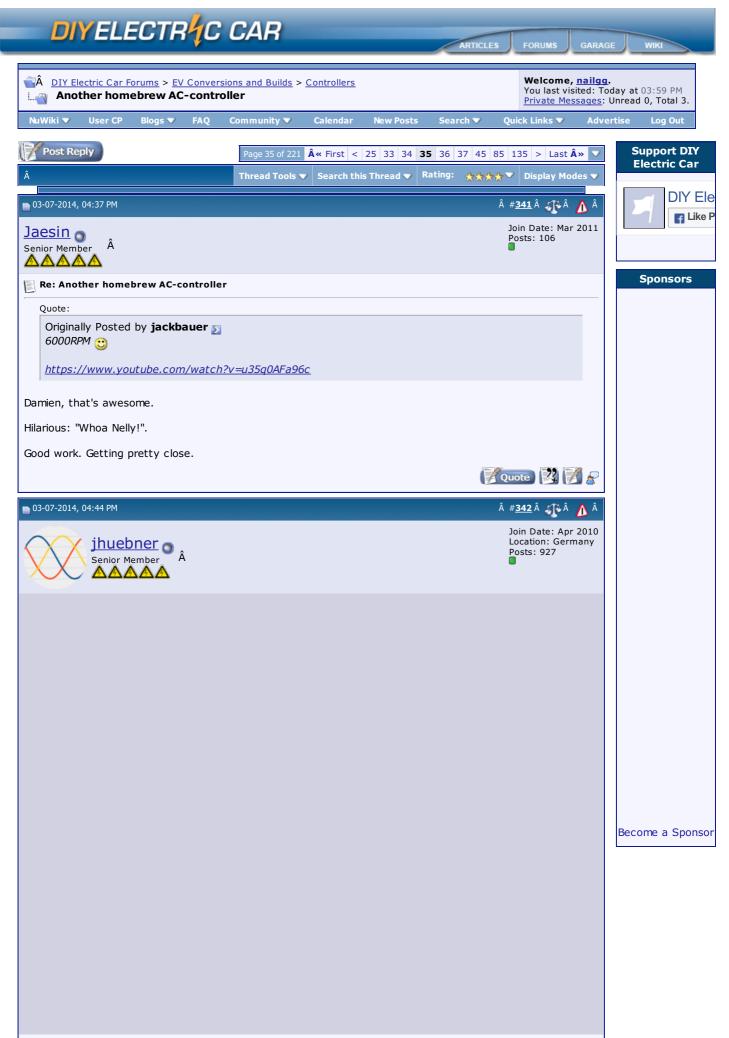




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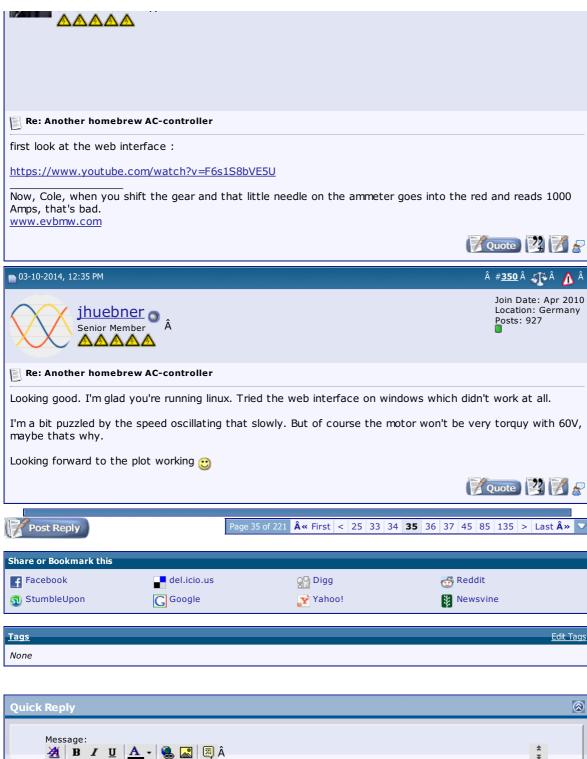
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Join Date: Feb 2009 Location: Lake Jackson, TX Posts: 376

Re: Another homebrew AC-controller

Quote:

Originally Posted by toddshotrods

Actually the cost can come down, significantly, for drag racing. A lot of what you're paying for there is EVDrive's engineering. A drag racer probably doesn't need the oil cooling system (case is designed specifically to make that work effectively), so just buy the Remy cores - four of them - and Rinehart drives - four of them. Put all four cores in a big, long, air-cooled, case, with the drives mounted close by...

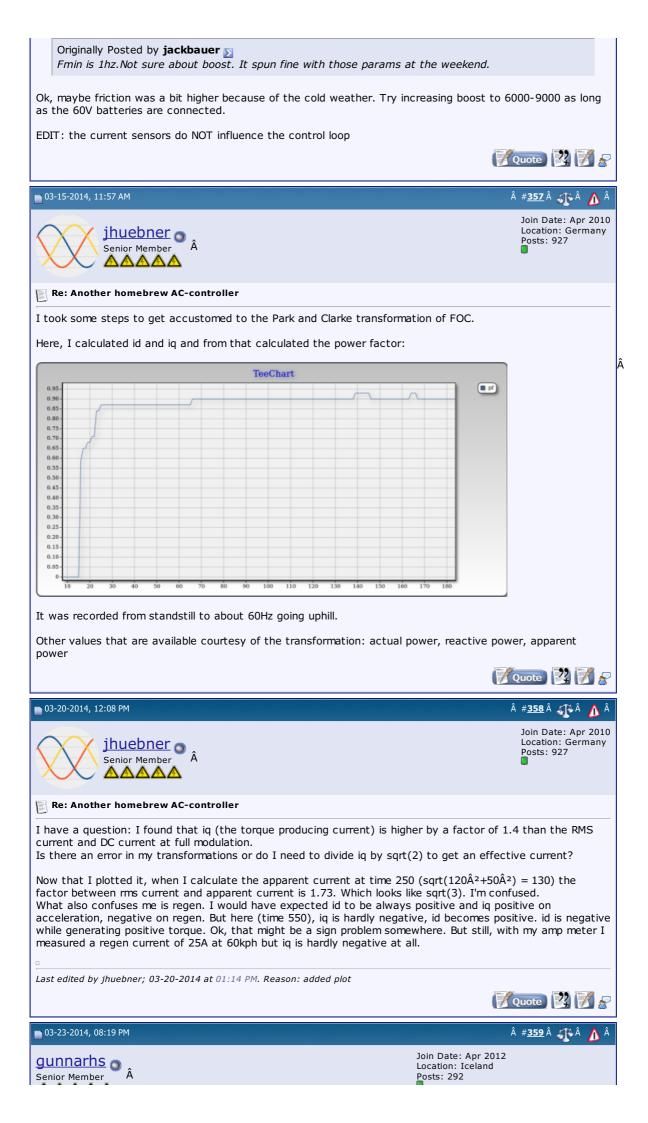
I would say figure out how to make the jhuebner kit run them, but those motors are IPM - not sure what would be involved in that. You're also paying for EVDrive's investment in having Rinehart tune their drives to work with the Remy cored EVD motors - Rinehart says about two week\$ on the dyno for that.

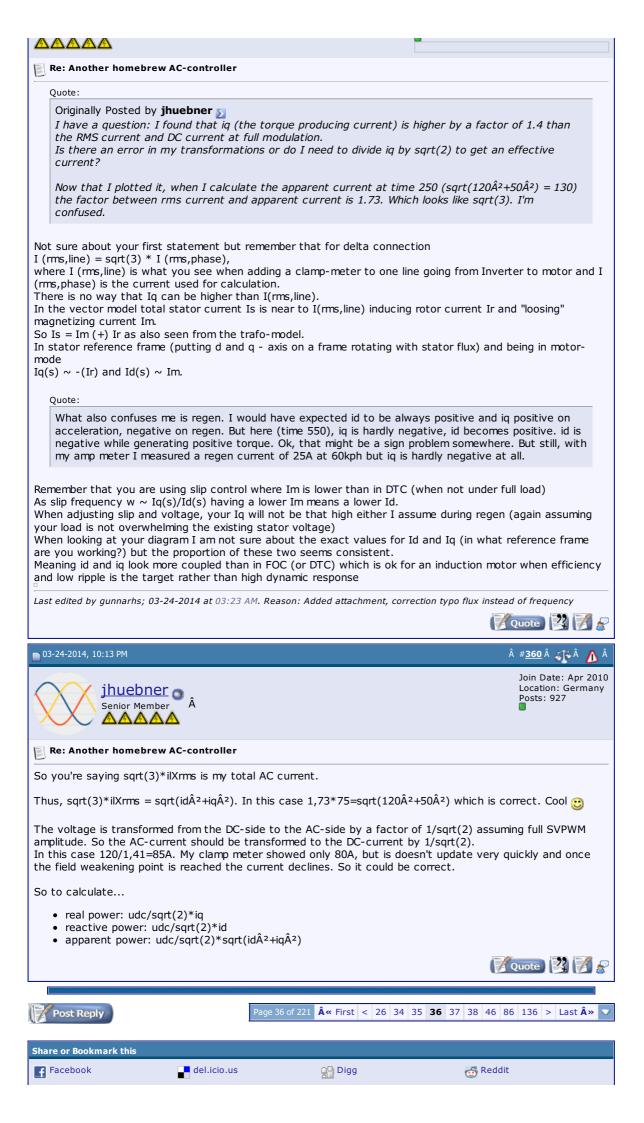
Can an industrial permanent magent motor be hooked up "across the line", meaning, turn on the 60HZ and 3 phase 480V and bring it up to speed. Or do all PM motors require a drive?

Can you guys speculate on what it would take to build the simplest permanent magnet motor controller that wouldn't over drain the battery pack?

Metric <u>ampahaulic.com</u> Facebook Page for <u>LoneStar EV Racing</u> <u>ELE</u> 6.0sec-1/8mi 101mph-1/8mi DIY <u>ELE</u> <u>PiD</u> 7.2sec-1/4mi 188mph-1/4mi DIY <u>PiD</u> <u>A&B</u> 8.9sec-1/4mi 165mph-1/2mi DIY <u>A&B</u> <u>DCP</u> 9.8sec-1/4mi 155mph-1mi DIY <u>DCP</u>







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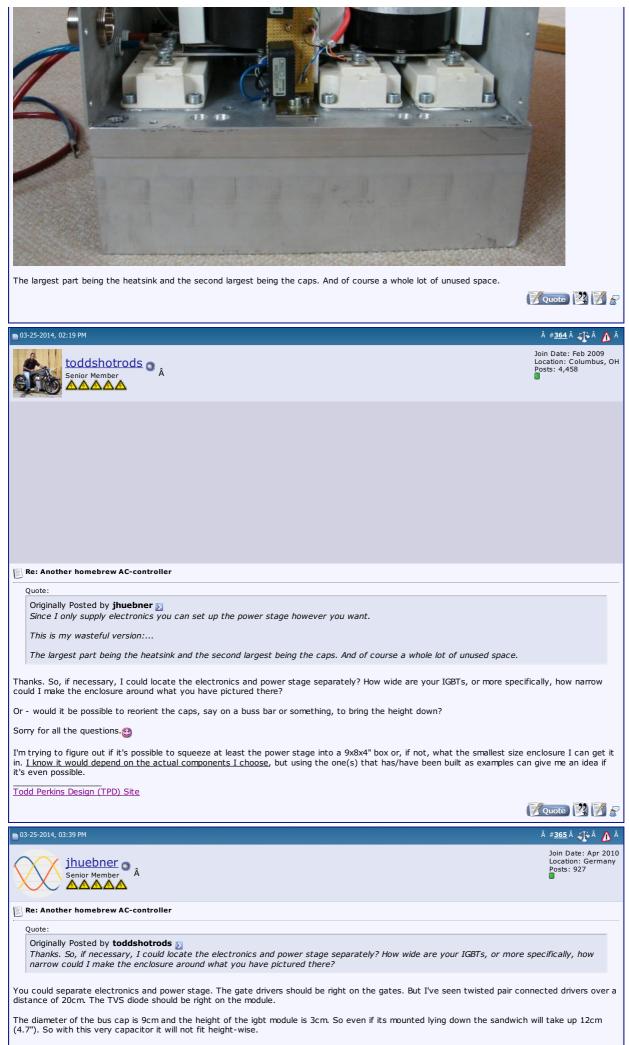
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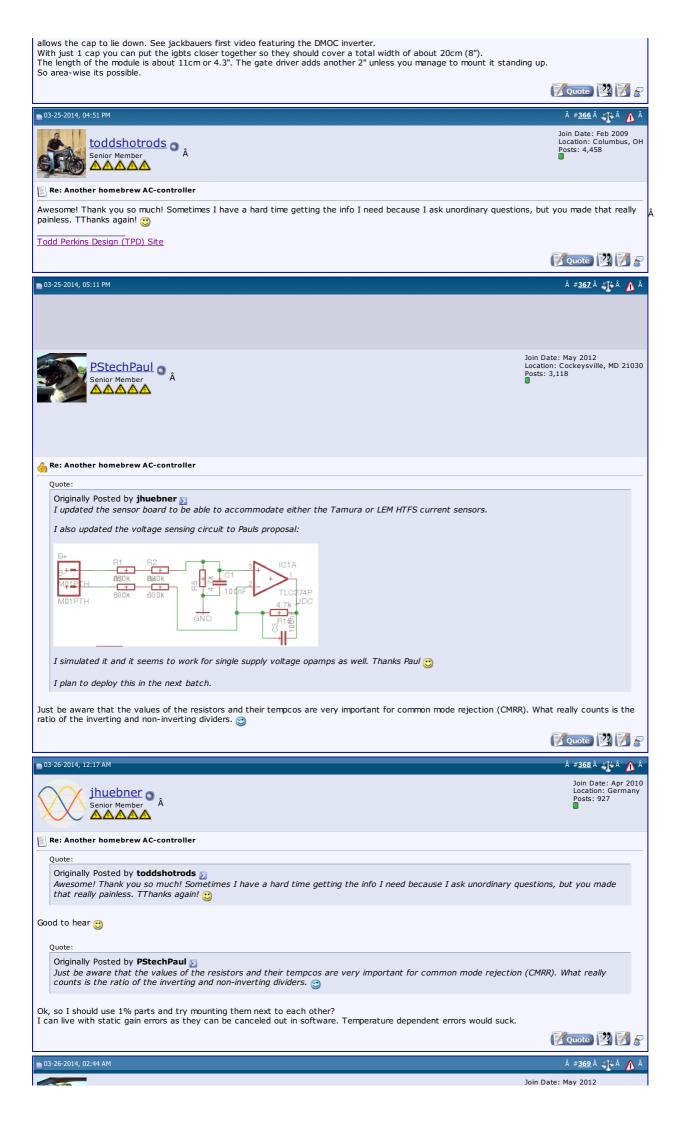
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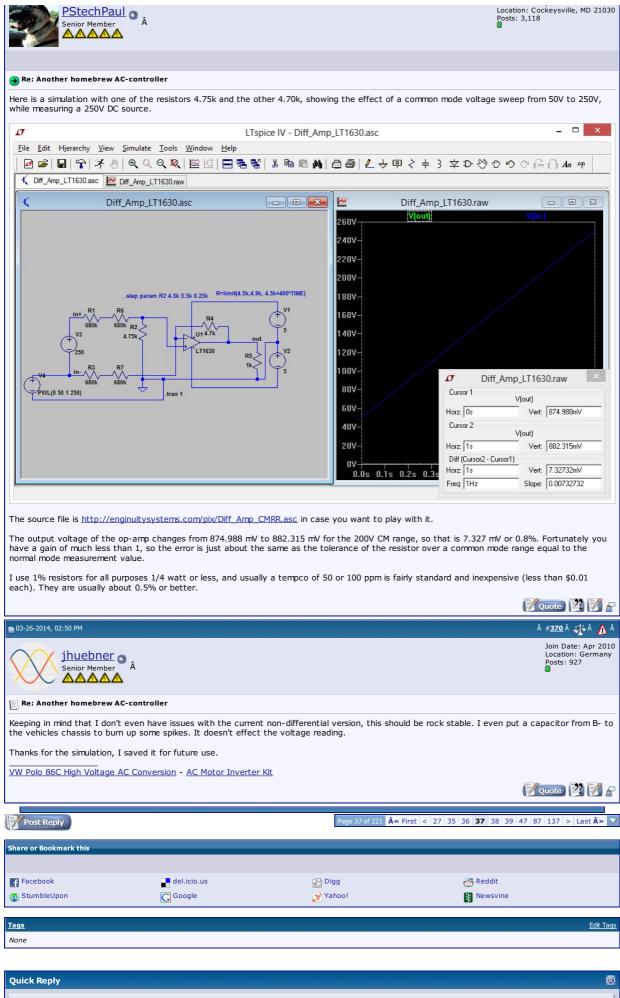
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Each module is about 6cm wide. I suspect the inverter will run fine with just one cap. With a bit of machining effort you can make a busbar that





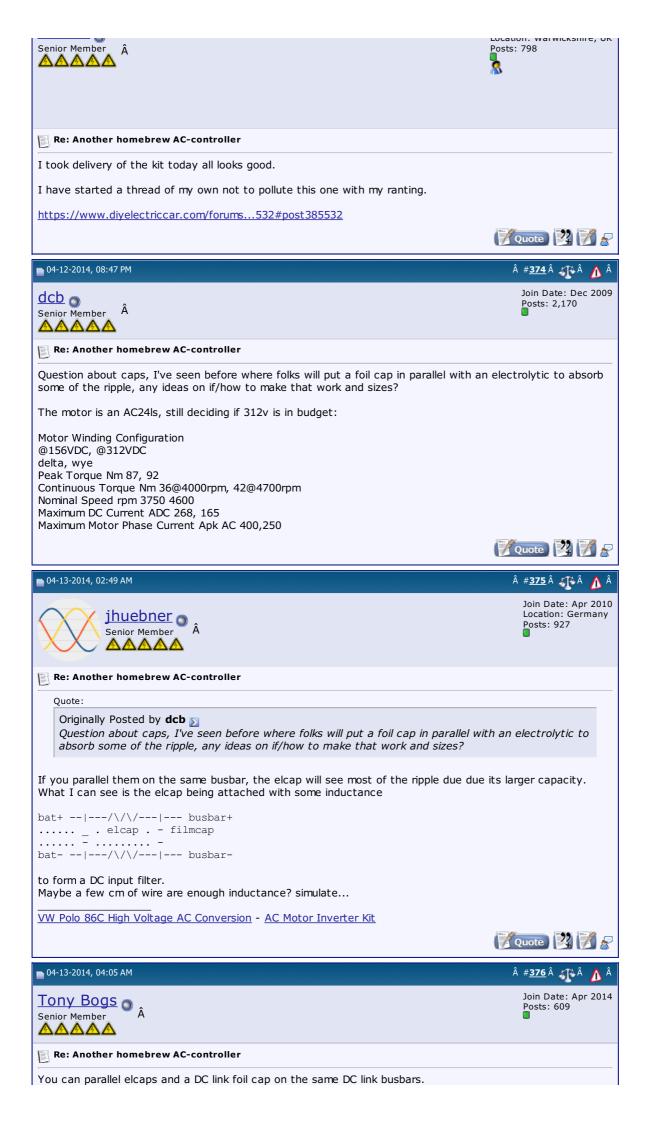
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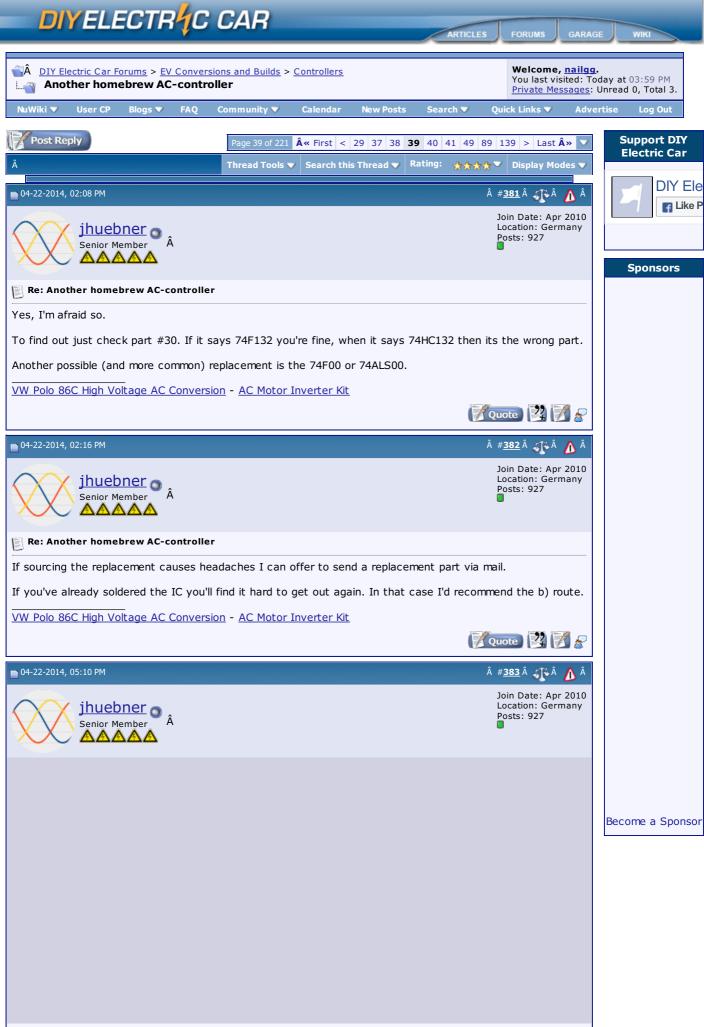




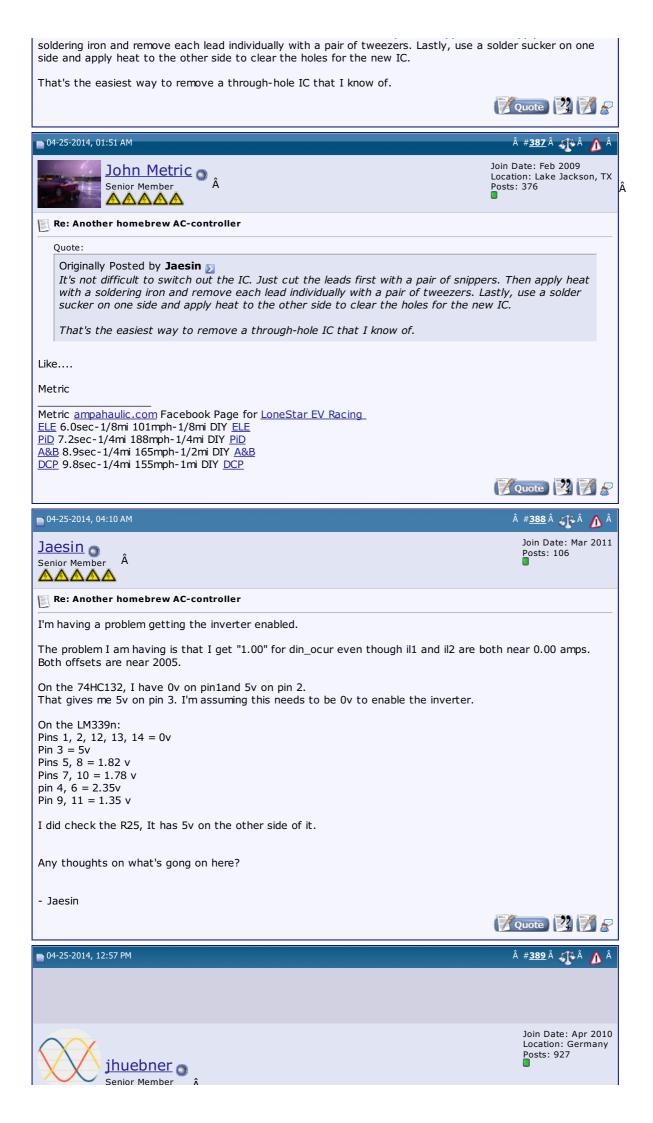
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realized, that the high This causes the PWM below 13.5V. There ar a) Replace the 74HC12 c) Keep the voltage of b) Change the input vo The latter is done by s looks like a 16DIP IC). The STM32 input pins	level threshold is 3.15V to be constantly inhibite e three solutions: 32 with a 74F132N or a n said pins above 13.5V bltage divider. soldering a 12k-15k resis are 5V tolerant so they	for the HC device. ed when the two signals DI SN74AHCT132N if you easily can		are
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Tomdb Senior Member Â			Join Date: Jan 2013 Location: Warwickshire Posts: 798	, UK
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You actually run a 4 to 1 ratio of V,	/f on the same motor?
ended up setting this to 10% because of So at small throttle values the V/f ratio motors nameplate V/f ratio.	Il percentage for the V/f at 0% throttle (well a bit above 0 throttle). I otherwise its hard to do parallel parking or any precise maneuvers. is 10x less than at full throttle in this example. 100% is about the lue (or whatever you program) and linearly increases with the throttle is set this from 1Hz to 3Hz.
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throttle). I ended up setting this to precise maneuvers. So at small throttle values the V/f i about the motors nameplate V/f ra The slip starts out at the nameplat the throttle to some maximum valu I've been reading this topic with some in I noticed you have a few libraries on th Also regarding V/Hz any reason you are SMT32F103, which I believe it is similar http://d1.ourdev.cn/bbs_upload782111 Other than this I would like to know hov PS: I know how to load the files, simply Kind Regards The Electric Polo @ https://www.diyele 300A AC POWERTRAIN + PFC CHARGER LiFePO4 440VDC 8KW AC INDUCTION	e value (or whatever you program) and linearly increases with ue. For my motor I set this from 1Hz to 3Hz. Interest. Very informative. Thanks for sharing. e tumanako repository. Are you a developer for them by any chance? not using FOC? ST have an aplication note on this for the to the one you are currently using and can be found here dev 459355.PDF v to load this files into the SMT, do you have any toturial? there is more than one binary. ctriccar.com/forumstor-78701.html
Last edited by cts_casemod; 05-04-2014 at 06	5:07 PM.
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Originally Posted by **jhuebner** *Onto another topic*.

Last week I tested the inverter on a testbench with a synchronous motor.

First test was running it open loop. This works fine at first, but even a 2Hz jump in frequency gets you out of sync and the motor stalls.

Next we tried closed loop operation with an incremental sensor. I started with 1Hz until I picked up 1Hz from the incremental encoder. Then I switch over to synchronous mode. The problem was that not much torque was produced because the angle between stator and rotor field was close to $0\hat{A}^\circ$.

I tried normal slip control with 0.2Hz. This leads to a "torque ripple" with 0.2Hz. I.e. the motor speeds up then looses speed, then speeds up again. When I set the slip to 0Hz during the acceleration phase the motor ran fine in synchronous mode. It produced the nameplate torque.

So the only issue with synchronous motors and an incremental encoder is finding the right angle when starting up.

I can picture an encoder with an additional 0-signal that fires once per turn.

(because I can't interface resolvers with the current hardware)

I am using a version of FOC and my own resolver decoder to control my synchronous motors out of a Toyota Prius.

I did however push a car around the block not using FOC with this motor. In this mode I was just applying a voltage synchronous to rotor angle. This would be like using your 0Hz slip I assume. I didn't have any phase current feedback to do FOC at the time.

The reason I think FOC is beneficial for me is that I want to maintain a very specific Id to Iq relationship in order to get maximum torque per amp. This motor prefers to have a negative Id unlike normal BLDC motors that I have used in the past.

In my application the rotor flux angle is based on the resolver angle so I don't have to try and approximate it using a bunch of motor parameters as with ACIM. So in my case FOC is very straight forward.

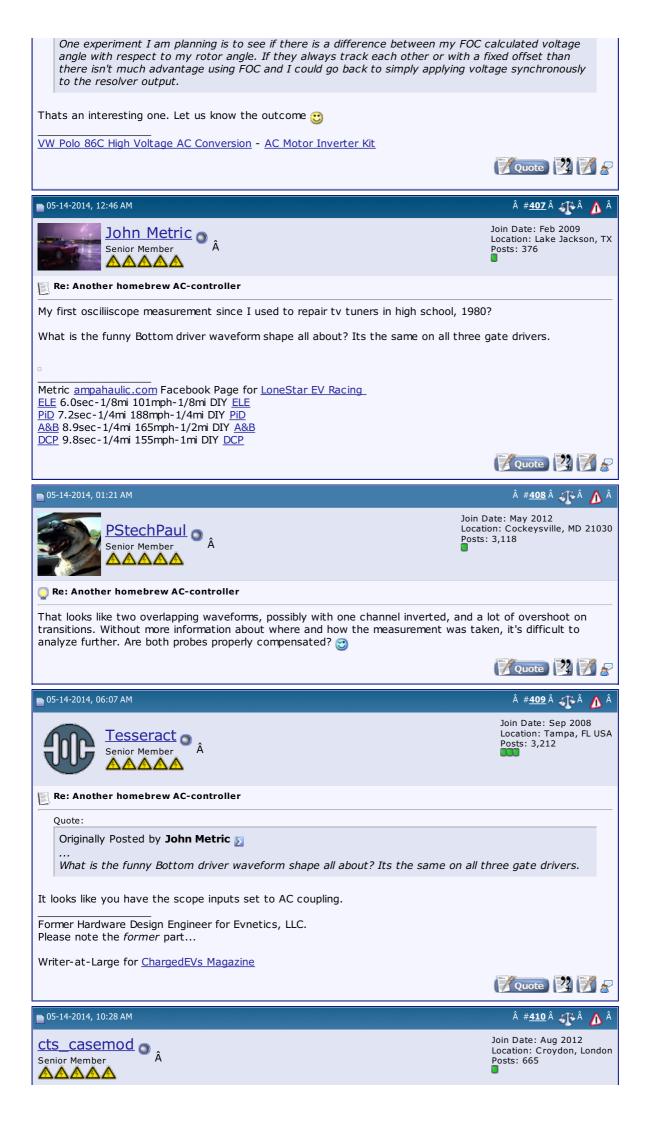
One experiment I am planning is to see if there is a difference between my FOC calculated voltage angle with respect to my rotor angle. If they always track each other or with a fixed offset than there isn't much advantage using FOC and I could go back to simply applying voltage synchronously to the resolver output.

Regards Jeff

JDDCircuit: Work in progress requiring a custom ECU for the Prius Inverter and Electric Transaxle.my MR2 conversion



■ 05-08-2014, 10:24 AM	â # <u>406</u> â 🐠 â 🛕 â
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by jddcircuit 🔊	



		w AC-controller			
	Quote:				
	Originally Posted by Yes, I developed the	jhuebner e so called "sine" proje	ect.		
			vell I couldn't be bothered. Formations already working.	I will experiment with closed	
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	Sorry for not follow	ing up on your last ma	il btw got shifted out of	my mind.	
Hi,					
The		want to look into FOC got the time to invest		am looking at the ST libraries	for the
for hov	example. is this used wever I want to cruiz	l also while driving? An	example: Supose I have the time of the transmission of the termination of termin	ile with the accelerator for pa ne motor at synchronous spee eed it with only 1/4 of the V/H	ed,
I h If i	got this right, the "s	i use to load the softw	actual code and the "stm32	_loader" is some sort of linux	binary
	gards	5 . ,			
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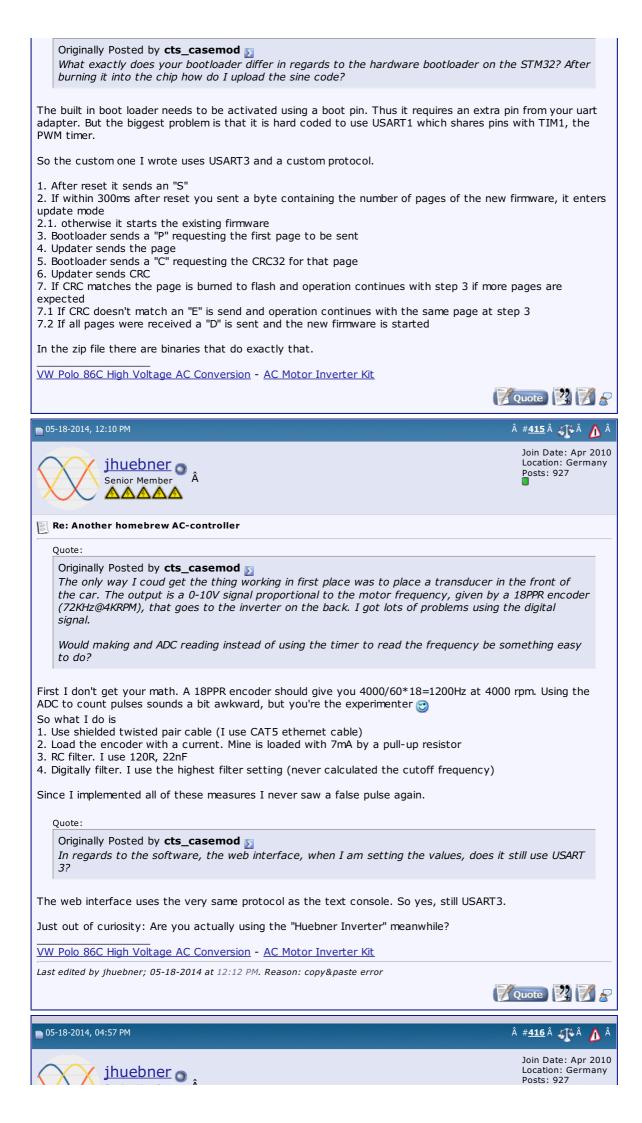
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ł,	Re: Another	homebrew	AC-controller
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Quote:

Originally Posted by cts_casemod S

If you can clarify exactly what the off topic is I can create a suitable topic,

Its just that this thread isn't a general home built VFD thread but its specifically on the inverter I designed. Now stuff is getting mixed up if you start asking questions about an inverter you built with an entirely different approach.

Why don't you create a topic on your device where you specify what you've done, how you did it and the problems you are currently having.

Quote:

Originally Posted by cts_casemod 5

the only that comes to mind is asking if the encoder input can be selected as an an analog reference signal, which would actually be a feature implementation as most industrial equip. works with a 4-20mA signal, converted to 2-10V to allow detection of a failed wiring (and low impedance). All others as technical stuff about the inverter

Like said, this is a question specific to your implementation, as I've already decided on pulse counting. Anyway, the analog solution <u>might</u> suffer the same problems as the digital one if not sufficiently filtered and shielded.

Broken wire and low impedance is no security threat when pulse counting. You simply won't see anymore pulses and the motor won't move. So thats not really an argument for the analog version. But who am I to judge; just try it.

Quote:

Originally Posted by cts_casemod 🔊

Now looking at your graphics above, have you tried to reduce the field voltage (V/Hz ratio) while regenerating? This should have a positive inpact on the PF.

Yes, if I change the according parameter or press the throttle a little bit exactly that is done to reduce braking torque. Like said, the slip is fixed so the field voltage is the only quantity left to control. I have never looked at the PF with reduced braking torque though. Maybe the slip is even too low?

Quote:

05 24 2014 04.07 44

Originally Posted by **cts_casemod** Where's your Part Load / Cruize on the graph?

You can see some part load on the beginning of the p/q/s graph. I could make a part load id/iq plot as well, but it won't really be surprising: the currents will be smaller, both magnetizing and torque producing current.

VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit

Last edited by jhuebner; 05-24-2014 at 01:40 AM.

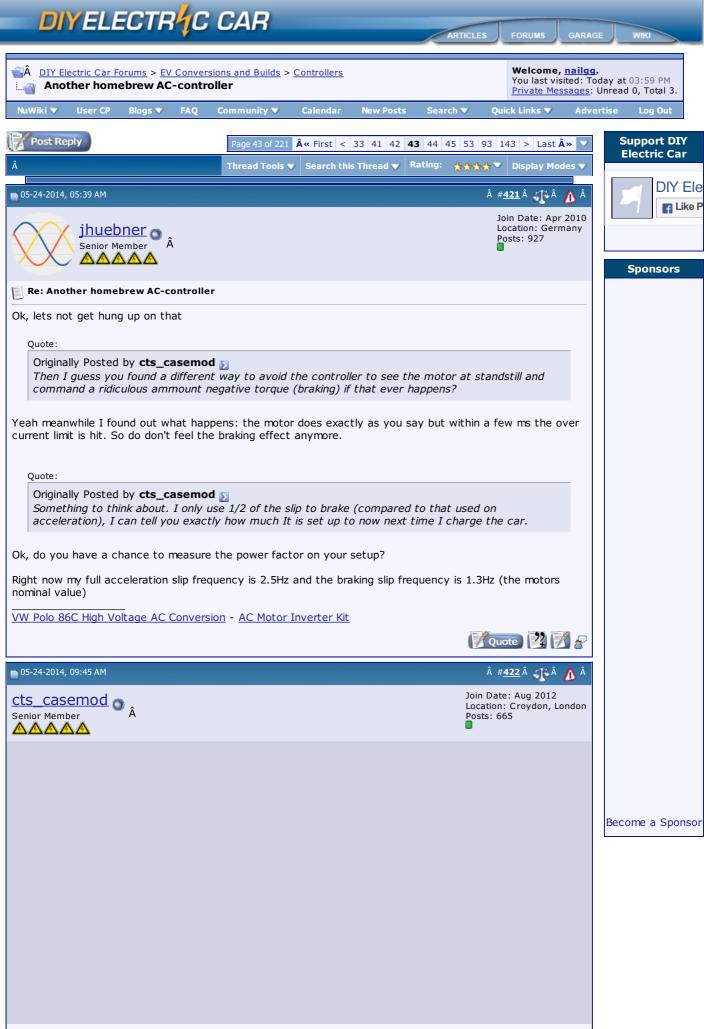
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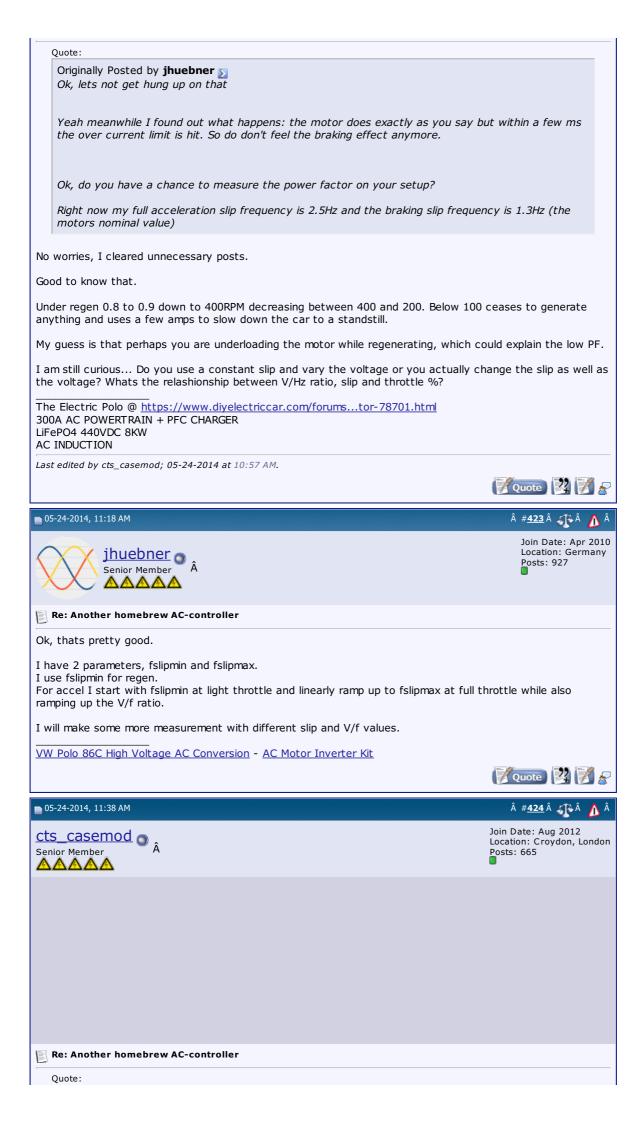
Join Date: Aug 2012 Location: Croydon, London Posts: 665
on the inverter I erter you built with

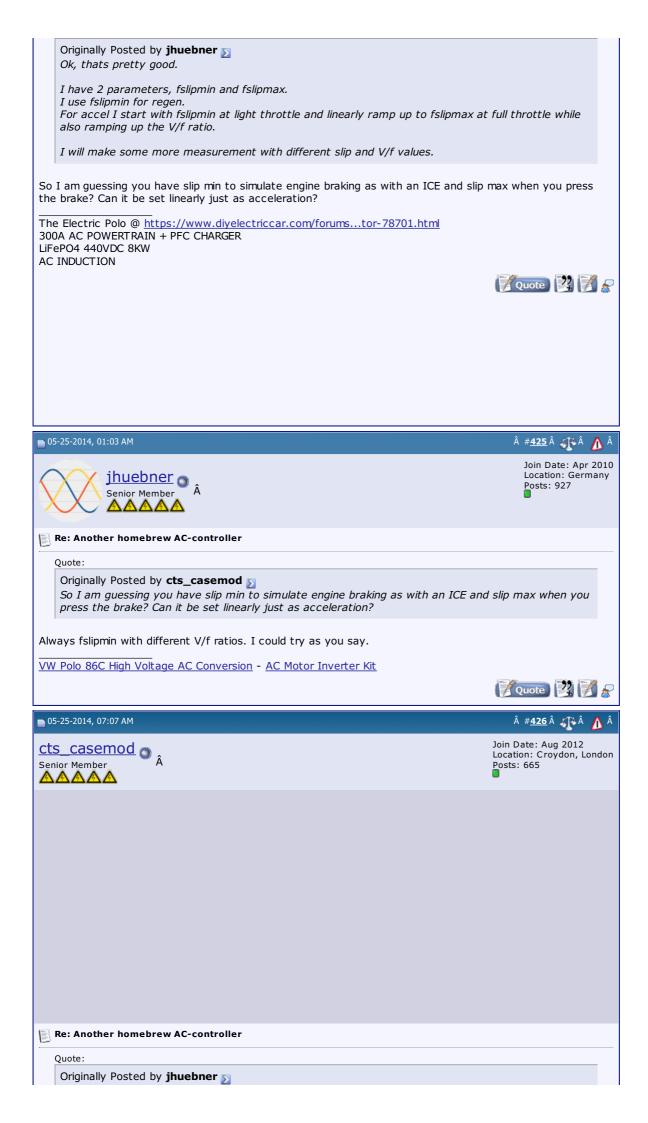
and the problems you are currently having.	It
I see your point. I am not questioning any of my problems, I am questioning how your inverter works it matches exactly what I am looking or what issues I will face while upgrading. I only posted the det since you asked me what setup I was using.	
Quote:	
Originally Posted by jhuebner as I've already decided on pulse counting.	
Surelly I can see that. My original question was if it was hard or possibke to make the implementation just because I asked to as I said I am looking at doing things a certain way with what I already have in the car. Surelly I cou for your time to do so if it is not a ridiculous ammount.	
Quote:	
Originally Posted by jhuebner Broken wire and low impedance is no security threat when pulse counting. You simply won't see anymore pulses and the motor won't move.	
Then I guess you found a different way to avoid the controller to see the motor at standstill and con ridiculous ammount negative torque (braking) if that ever happens?	nmand a
Quote:	
Originally Posted by jhuebner Yes, if I change the according parameter or press the throttle a little bit exactly that is done to reduce braking torque. Like said, the slip is fixed so the field voltage is the only quantity left to control. I have never looked at the PF with reduced braking torque though. Maybe the slip is even too low?	
Something to think about. I only use 1/2 of the slip to brake (compared to that used on acceleration tell you exactly how much It is set up to now next time I charge the car.), I can
The Electric Polo @ https://www.diyelectriccar.com/forumstor-78701.html	
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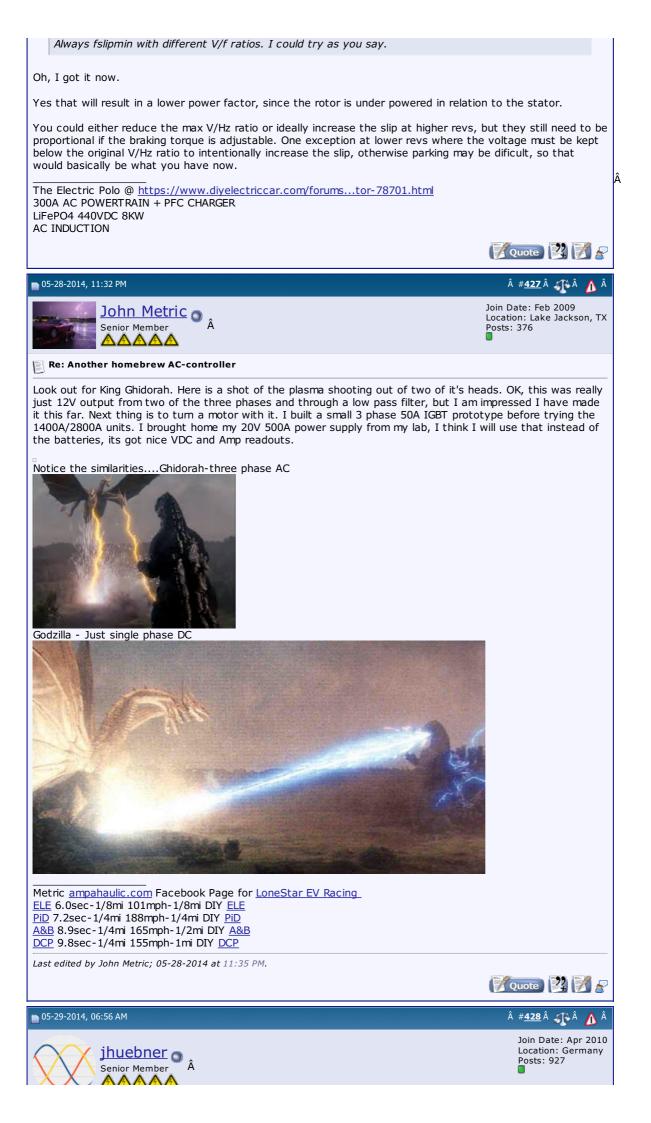
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 Interpolation takes was the best compro- long (10µs) Updated the slip an multiplied with the po Changed the regen 	and the extra values are 4 median values out of 3 s mise between spike suppre gle calculation so now fslip le pairs. ramp to go all the way do	samples and then takes the ession and and cpu time. A pmax and fslipmin represer wn to 0 instead of ampmin	ne average of those 4 media A true 12 sample median tak Int the true slip frequency, n n er over speed. Of course th	kes too no longer
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Apart from that I'll be each other out.	off the internet the next	3 weeks. So I hope peopl	e who are currently building	can help
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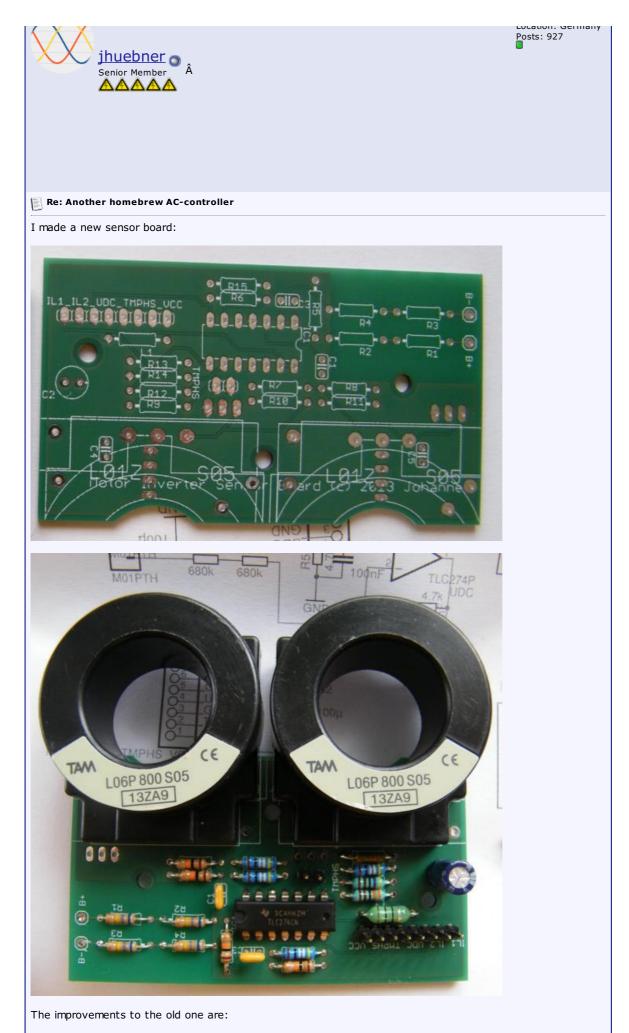




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More accurate footprints for the current sensors
 3 Types of current sensors supported: <u>Tamura L01Z</u> (up to 600A, the one I used up to now), <u>Tamura L06P</u> (up to 800A), <u>LEM HTFS</u> (up to 1200A)



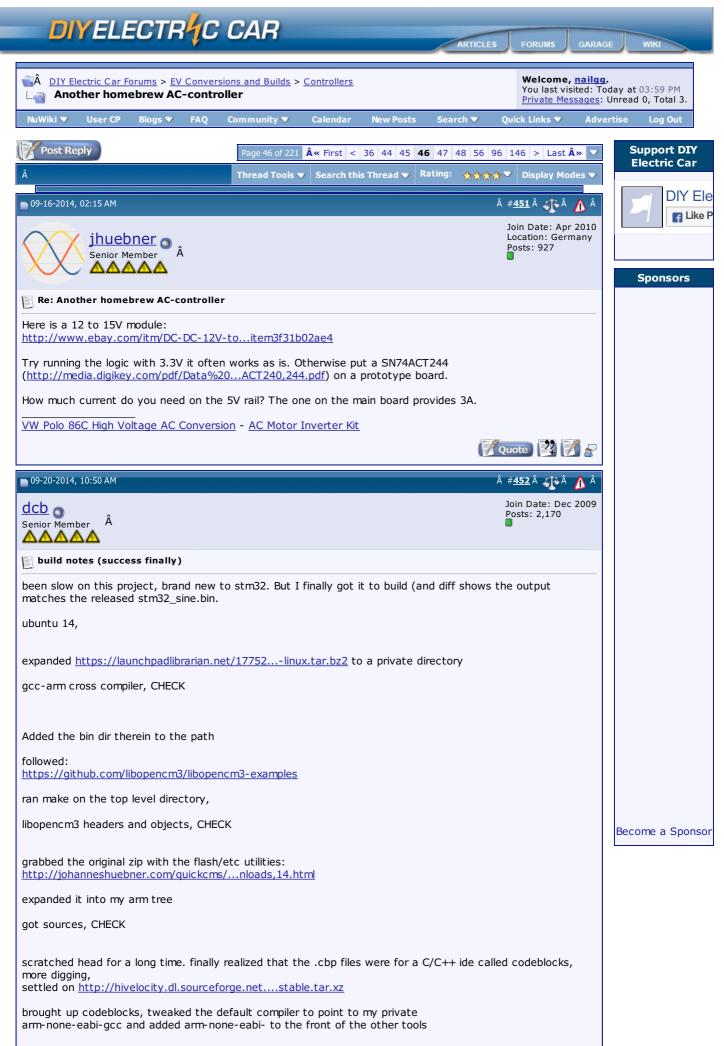


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more common)	/ (FOUND THE 5V to	15V converter, now just r	need the 3.3V to 5V which should	
speed opto coupler inside t	he VLA500 series dr	iver. A CMOS buffer that a	ng 15mA in order to turn on the hi ctively pulls its output high is ff state. Open collector type drive	
Need a 12V to 5V and 15V	6amp power supply	also.		
Is there a quick level shifte	er board available for	r just such an application.		
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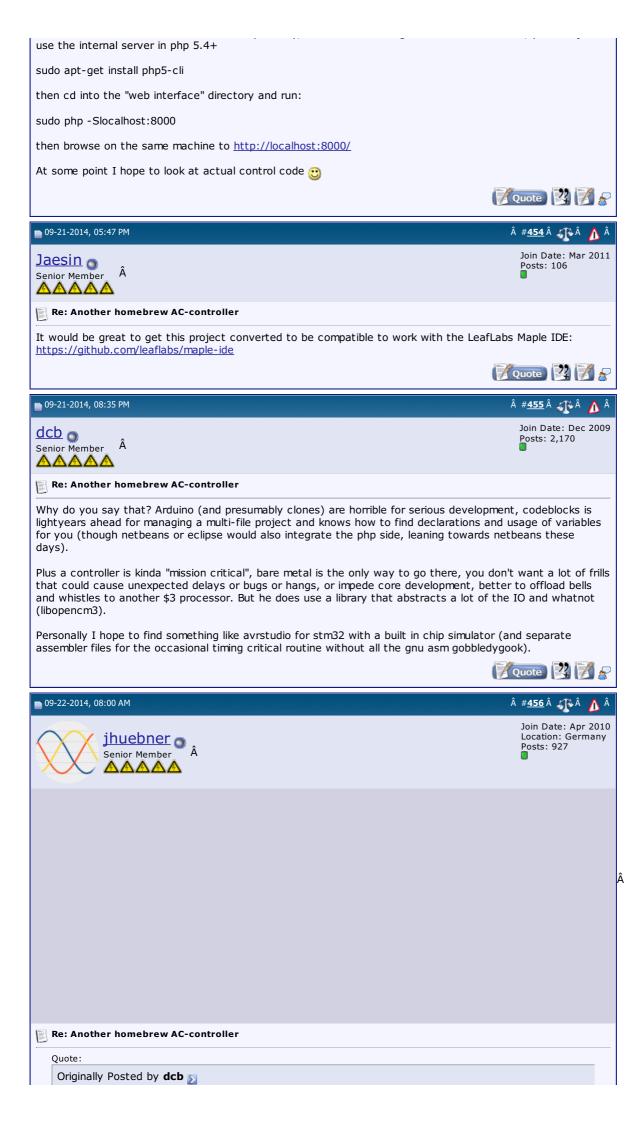
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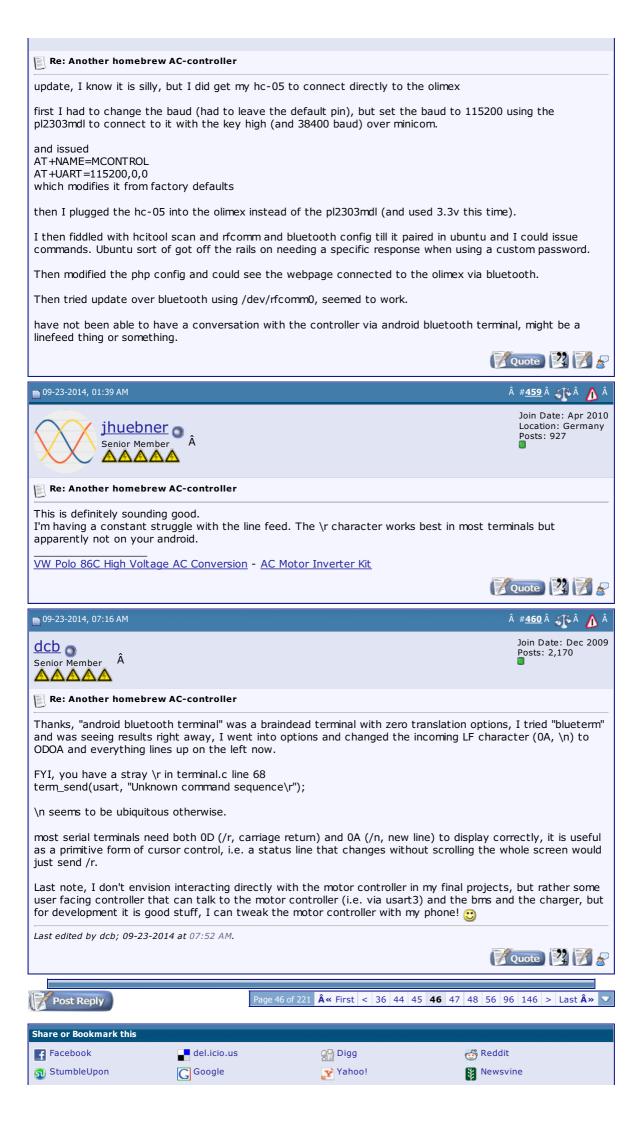


viewing source in IDE, CHECK
hit build, saw include errors
Modded the CFLAGS and CPPFLAGS lines in Makefile (added -I for libopencm3)
$\label{eq:cflags} CFLAGS = -Os - Wall - Wextra - Iinclude - I/var/arm-eabi/proj/libopencm3-examples/libopencm3/include/ -fno-common - fno-builtin \ \$
<pre>-mcpu=cortex-m3 -mthumb -std=gnu99 -ffunction-sections -fdata-sections CPPFLAGS = -Os -Wall -Wextra -Iinclude -II/var/arm-eabi/proj/libopencm3-examples/libopencm3/include/ fno-common \</pre>
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hit buid, saw linker problems, added -L flag to a libopen ld file directory: LDFLAGS = -L\$(TOOLCHAIN_DIR)/lib -L/var/arm-eabi/proj/libopencm3-examples/libopencm3/lib/ - T\$(LDSCRIPT) -nostartfiles -WI,gc-sections,-Map,linker.map
Hit Build, SUCCESS!
ran diff, no differences between original bin and newly compiled bin, CHECK
TODO: flash
scratched head some more, wondering how programmer connects. opened the bootloader project in codeblocks firmware_loader.cbp
Saw UART3 referenced.
reviewed: <u>https://www.olimex.com/Products/ARM/STM32-H103.pdf</u> page 10.
hooked up the pl2303mdl to the EXT2 port on the olimex (useful for upgrades even if you don't build)
gussing this should work: pl2303mdl pin, STM32-H103 EXT2 pin GND, 6 GND RX, 14 PB10/UART3.TX TX, 15 P11/UART3.RX
VCC, 23 +5V USB
Maybe not the ideal setup, but if it works. I plug in the pl2303mdl and the olimex starts blinking anyway w try actual flashing later.
Edit, wound up using sudo to flash for now. some various flashes, and the green light is back to steady fast flash, so apparent success 😶
sudo ./updater /var/arm-eabi/proj/tumanako-inverter-fw-motorControl/src/sine/stm32_sine.bin /dev/ttyUSB
Attached Files
Last edited by dcb; 11-20-2014 at 09:14 PM.
Quote 2
📄 09-20-2014, 01:21 PM Â # 453 Â 💦 Â 🧥
dcb Join Date: Dec 20 Senior Member Â
🖹 Re: Another homebrew AC-controller

oh a little shortcut for the web interface (ubuntu), instead of installing the whole LAMP stack, you can just



Why do you say that? Arduino (and presumably clones) are horrible for serious development, codeblocks is lightyears ahead for managing a multi-file project and knows how to find declarations and usage of variables for you (though netbeans or eclipse would also integrate the php side, leaning towards netbeans these days). Plus a controller is kinda "mission critical", bare metal is the only way to go there, you don't want a lot of frills that could cause unexpected delays or bugs or hangs, or impede core development, better to offload bells and whistles to another \$3 processor. But he does use a library that abstracts a lot of the IO and whatnot (libopencm3). Personally I hope to find something like avrstudio for stm32 with a built in chip simulator (and separate assembler files for the occasional timing critical routine without all the gnu asm gobbledygook). I agree here. Personally I never do on-chip debugging because its pointless within the real time routines. I develop the more complex routines on my PC and run them using stubs. You'll also notice that many routines don't access the hardware directly but return some values that are then passed on to the hardware. E.g. I can call the sine function and print its results to a file to verify that its doing the right thing. Ouote: Originally Posted by dcb 🔊 oh a little shortcut for the web interface (ubuntu), instead of installing the whole LAMP stack, you can just use the internal server in php 5.4+ sudo apt-get install php5-cli then cd into the "web interface" directory and run: sudo php -Slocalhost:8000 then browse on the same machine to http://localhost:8000/ At some point I hope to look at actual control code 😁 Thats great! It'd be good to come up with some bootable disk image that does exactly that. Just kernel+libs+php. Should be reasonable small. VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit / Quote 📄 09-22-2014, 08:47 AM #**457** Â Δ Join Date: Dec 2009 dcb 👩 Posts: 2,170 Â Senior Member Re: Another homebrew AC-controller Ouote: Originally Posted by jhuebner 🔊 Thats great! It'd be good to come up with some bootable disk image that does exactly that. Just kernel+libs+php. Should be reasonable small. Just thinking out loud on this fyi, At some point I was thinking of experimenting with connecting my \$5bluetooth adapter to the controller. It *might* work with php for sl4a, but almost certainly I can get to the command interface with an android phone terminal that way (and have lots of gui options). As a developer a laptop is nice, but as a user not so much (and even as a developer having a wireless connection is nice). But make sure you change the pin at least (and the baud). Though a boot disk could be a useful option too for many. Though it is working just fine for now 😁 Edit, maybe this for android: <u>https://play.google.com/store/apps/d...rver.php&hl=en</u> Last edited by dcb; 09-22-2014 at 09:15 AM. Quote 🕎 🏹 🔗 🗖 09-22-2014, 12:35 PM #<u>458</u>Â 🎢 Â Join Date: Dec 2009 dcb 🕥 Posts: 2,170 Senior Member Â



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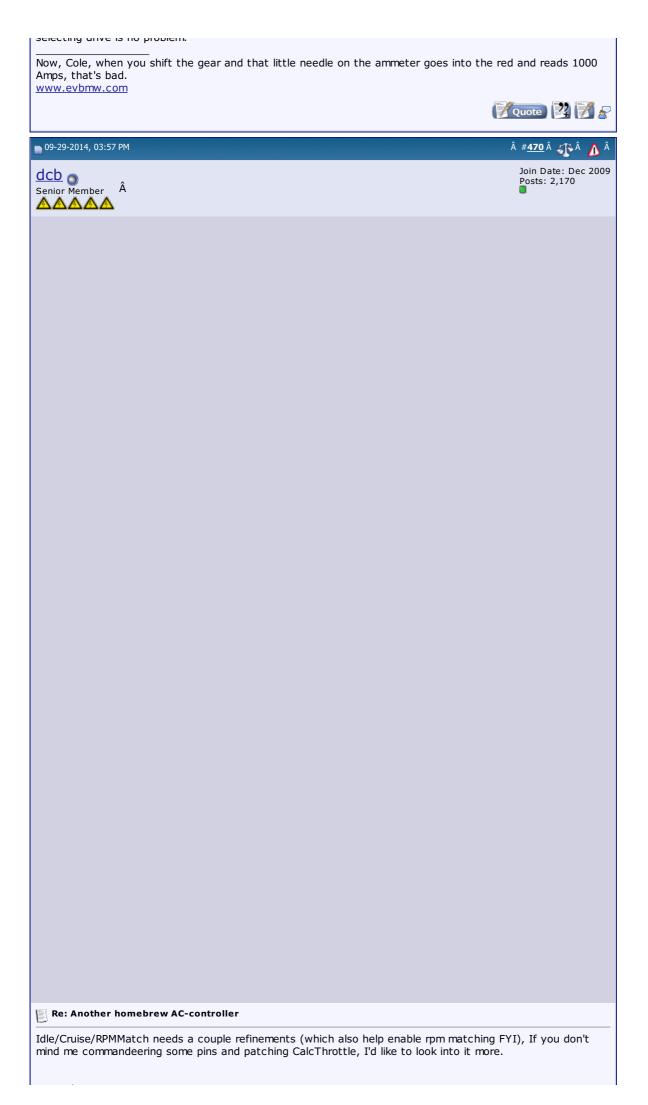
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general: need speed control algorithm. Idle specific: override min throttle and ignore brake under certain rpm (parameter), do not engage till start signal received, disable with ignition off. Cruise specific: It needs to disable if the brake is tapped. (easy one) It needs to disable if the clutch is engaged or transmission put in neutral (add parameters for overall gear ratios, vehicle speed sensor input, at least one set button). If the motor rpm to vehicle speed doesn't match a known gear ratio then we are in neutral, clutch out. (or possibly out of lockup, will have to think about that more, looking at load might help). Needs to allow the user to command more speed with the throttle temporarily. It needs to be tied to vehicle speed in the case of torque converters as well as detecting driveline disengagement. OEM cruise buttons are all over the map. I think if users could use at least one button from the stalk to set the cruise at the current speed, then tap the brake to cancel it they would be happy. RPM match: need an adc for gear selection. vehicle speed/known ratios (from cruise control). continually adjust rotor speed based on changing vehicle speed to be suitable for engagement into the gear selected (which can also change). I'm really in this for the rpm match personally. If I can remove a 30 lb lump of rotating mass and have good driveability, I'd be happy. Cruise would be nice too. I could really use 2 adc, or one adc (for rpm match gear selection) and 1 encoder channel (for vehicle speed, like 5000 pulses/mile). Tracking vehicle speed/distance also enables KW/mile reporting (except for a fixie). I don't know if multiple gears are going to go away, even tesla saw some benefit on paper in trying to make it happen (but failed in execution and favored time to market). As usual, I'm probably over-thinking it. But if anything is on an adc/encoder pin that doesn't need to be, I would like to look at moving it. Or go with the \$10 arduino intermediate, which is a bit more universal, can be put in front of a lot of different controllers to provide these functions. @Jack, what is your comfort level? you building from source? or ok with flashing a patched binary on to the olimex? Or are you more comfortable with an intermediate controller (i.e. arduino)? It looks like just getting idle is reasonably simple patch in any event. Basically add a parameter to the list (idle_speed, 0=disabled) and modify CalcThrottle to enable a minimum rpm once we are in (VALUE_opmode, MOD_RUN) mode by tweaking the throttle reading up or down. Quote 🛂 💋 🛜 « First < 37 45 46 47 48 49 57 97 147 > Last » Post Reply Share or Bookmark this del.icio.us 😭 Digg 🥳 Reddit Facebook StumbleUpon G Google 📝 Yahoo! Newsvine Tags Edit Tags None



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09-29-2014, 04:01 PM	Â	# <u>471</u> Â 🏠 Â 🧥 Â	DIY Ele
dcb Senior Member Â		Join Date: Dec 2009 Posts: 2,170	Like F
			Sponsors
Re: Another homebrew AC-cont			Sponsors
Ok, just saw your post, really all y pretty trivial, add parameter idle_	you need is a minimum throttle setting once you are in run min_throttle (0=disabled).	mode, that is	
		Quote 🕺 🃝 🔗	
09-29-2014, 04:45 PM	Â	# <u>472</u> Â 🏠Â 🍐 Â	
A Senior Member Â		Join Date: Dec 2009 Posts: 2,170	
Re: Another homebrew AC-cont	roller		
here's my stab at idle if you are ir			
Code:			
inserted into line 69 (pa PARAM_ENTRY(idlepotmi	aram_prj.h) in, "dig", 0,4095,0, 50)\		
	GetInt(PARAM_idlepotmin); opmode)==MOD_RUN && idlepotmin != 0 &&idlepotmin :	>potnom)	
<		>	
	into reverse 🙂 Please start low with the setting (idlepotmi table idle speed, you probably don't need much to keep th		
Last edited by dcb; 09-29-2014 at 11:0	7 PM.		
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09-29-2014, 05:40 PM	Â	# <u>473</u> Â 🔊 Â 🧥 Â	
dcb Senior Member Â		Join Date: Dec 2009 Posts: 2,170	
Re: Another homebrew AC-cont	roller		Become a Sponsor
	o interface with the new binary. It hosed the sine app (see	med fine from the	
	use the web interface with the new idle parameter build if		
Edit, web interface seems ok now with the port, but it seems ok now	, not sure if something was cached, or maybe another prov w.	gram was messing	
Last edited by dcb; 09-29-2014 at 06:5		Quote 🕎 🎢 🔗	
09-29-2014, 07:14 PM	Â	# <u>474</u> Â ∢ î≱Â ∧ Â	
dcb 👩		Join Date: Dec 2009	





He has a zip file with a custom uploader (for ubuntu, hope that works for ya). http://johanneshuebner.com/quickcms/files/inverter.zip expand that zip file somewhere, that gets you some binaries for reflashing

put the stmt32-sine.bin file in the zip file I created in the tools directory you created from johannes zip.

go to a terminal screen and cd into the tools directory (under where you expanded the zip from johannes and which is also the directory where you put the stm32_sine.bin from the zip in post 475)

if you run "Is -latr" it should look like this:



```
dave@dave-Inspiron-N5010:/var/arm-eabi/proj/tumanako-inverter-fw-motorControl/toc
total 124
-rwxr-xr-x 1 dave dave 62143 Jan 24 2013 stm32flash
-rwxr-xr-x 1 dave dave 10496 Mar 5 2014 updater
drwxr-xr-x 4 dave dave 4096 Mar 5 2014 src
-rwxr-xr-x 1 dave dave 9732 Mar 6 2014 updater32
drwxrwxr-x 9 dave dave 4096 Sep 20 20:40 ..
-rwxrwxr-x 1 dave dave 18732 Sep 29 19:34 stm32 sine.bin
drwxr-xr-x 7 dave dave 4096 Sep 30 08:51 web interface drwxrwxr-x 4 dave dave 4096 Sep 30 15:41 .
```

>

🛛 🖉 Quote

run:

<

sudo ./updater stm32_sine.bin /dev/ttyUSB0

(or updater32 if you are not 64 bit).

and hopefully see something like this:

Code:

dave@dave-Inspiron-N5010:/var/arm-eabi/proj/tumanako-inverter-fw-motorContr	col/toc
[sudo] password for dave:	
File length is 18732 bytes/19 pages	
Resetting device	
Sending number of pages	
Sending page 0 Sending CRC CRC correct!	
Sending page 1 Sending CRC CRC correct!	
Sending page 2 Sending CRC CRC correct!	
Sending page 3 Sending CRC CRC correct!	
Sending page 4 Sending CRC CRC correct!	
Sending page 5 Sending CRC CRC correct!	
Sending page 6 Sending CRC CRC correct!	
Sending page 7 Sending CRC CRC correct!	
Sending page 8 Sending CRC CRC correct!	
Sending page 9 Sending CRC CRC correct!	
Sending page 10 Sending CRC CRC correct!	
Sending page 11 Sending CRC CRC correct!	
Sending page 12 Sending CRC CRC correct!	
Sending page 13 Sending CRC CRC correct!	
Sending page 14 Sending CRC CRC correct!	
Sending page 15 Sending CRC CRC correct!	
Sending page 16 Sending CRC CRC correct!	
Sending page 17 Sending CRC CRC correct!	
Sending page 18 Sending CRC CRC correct!	
Update done!	
<	>
looks good, you might as well go into it and set some parameters. So then run:	
lo minicom -b 115200 -D /dev/ttyUSB0	
d do get/set/save/list/all etc. You should be able to see idlepotmin if you do an "all" now (a	nd let me k
he carriage returns look right for you.	nu iet nie k
te canage recards look fight for you.	
exit minicom, hit ctrl +a, then x	

Last edited by dcb; 09-30-2014 at 04:56 PM.

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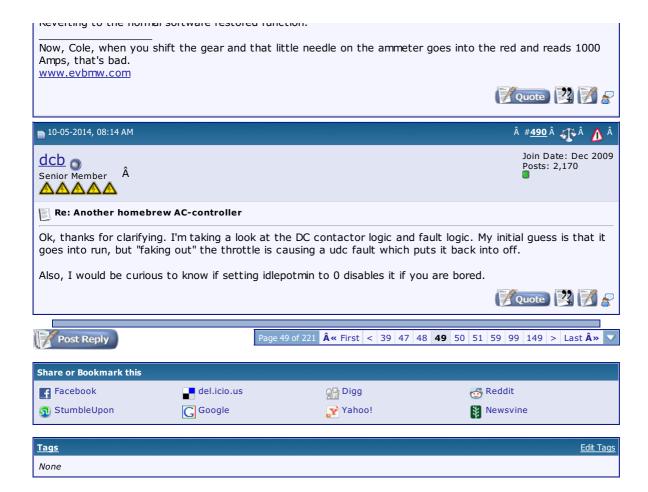
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Re: Another homebrew AC-controller

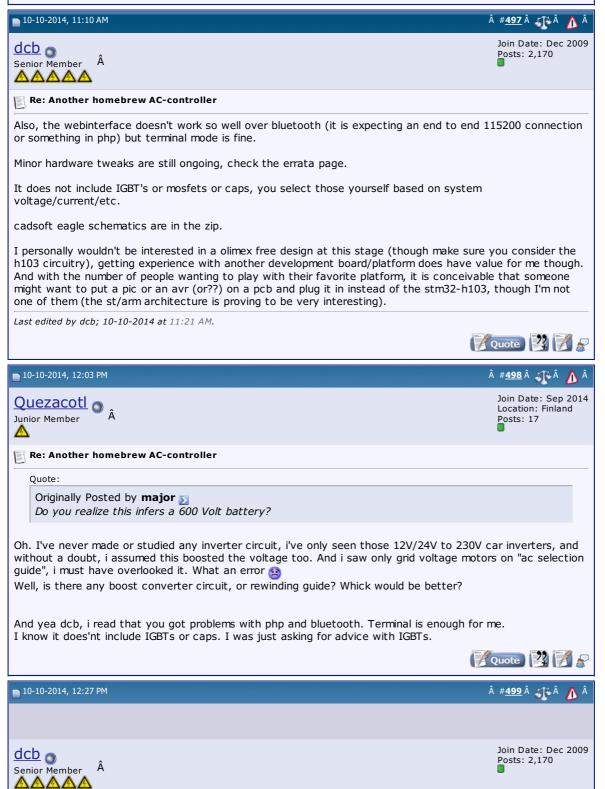
Quote:

Originally Posted by Quezacotl 🔊

And i got an advice that i should ask in this thread that is my motor compatible with this controller? ABB Motors M2AA 132 M (3G AA 132 002-ADA) -AC three phase -380-420V/15,3A, 50Hz, 1450rpm, 7,5kW (delta)

Do you realize this infers a 600 Volt battery?





Re: Another homet	prew AC-controller		
Quote:			
Originally Posted	by Quezacotl ∑		
Well, is there any	v boost converter circuit,	, or rewinding guide? Whic	k would be better?
			it, how much performance (range and ve to spend, and how much you can
leaf batteries, and so performance, and on	ome older \$20 igbts, so I'ı	m gonna be on the low end com charger/bms/controlled	, an old chain drive bike, and 11 used d of cost, in the middle on r/instrumentation/reconfiguring leaf
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■ 10-10-2014, 02:52 PM			â # <u>500</u> â 🐠 â 🔥
jhueb Senior Me			Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another home	orew AC-controller		
Hi Q,			
	e and runs induction mot requirements spawned, th	•	ed. Like the idle speed feature.
They usually have a connected in series. working voltage (and nominal voltage will d same current as before	couple of independent co If you open it up and cor current!). With said exa	nnect them in a parallel/se mple (8 coils per phase) if ninal current will double. Ea er removed.	n. in 400V motors they are all ries fashion you can change the you connect the coils 4s2p the ach individual coil will see exactly the
If you attempt to go motor.	this hardcore diy route,	you need to know what yo	ou're doing to end up with a working
The STM32 is pretty how to it.	"advanced". That means	you can offload many thir	ngs to dedicated hardware if you know
Atmels AVR are a lot etc.	easier to get started wit	h but lack features like D№	1A, fully automatic ADC sequencing
Since I managed to h	arness the STM there is	no motivation for me to m	ove to a different controller.
VW Polo 86C High Vo	_ Itage AC Conversion - AC	<u>C Motor Inverter Kit</u>	
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📃 Re: Another homebrew AC-controller					
O, and by the way, I'm an	engineering ty	/pe.			
				Quote 🕎 🌠 🖉	
■ 10-12-2014, 11:16 AM				â # <u>510</u> â 🐠â <u>۸</u> â	
dcb Senior Member Â▲▲▲▲				Join Date: Dec 2009 Posts: 2,170	
📃 Re: Another homebrew	AC-controller				
if you have the budget for brand spanking new cas300m12b2s then go for it. You probably don't need a div controller in that case. Not sure what you have against stm except unfamiliarity or some other agenda though, the speculative returns (kumbaya?) on the effort on porting it are hardly convincing though, and it isn't clear who does the porting and who gets the "benefits", or that all the cons of porting are even remotely being considered.					
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jhuebner Senior Member Â	Posts: 927
Re: Another homebrew AC-controller	
Ok, just saw another parameter also has id 52. Will fix it tomorrow.	
VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
	Quote 🕎 📝 🎤
■ 10-13-2014, 07:06 РМ	â # <u>515</u> â 🐠 â <u>۸</u> â
dcb Senior Member Â	Join Date: Dec 2009 Posts: 2,170
Re: Another homebrew AC-controller	
For the bluetooth averse, testing android -> otg usb cable -> ftdi232rl -> olimex via ftdi u program, success. (sorry, the pl2303 folks didn't provide pl2303hx android support).	art terminal
El-cheapo 7" mid tablet running 4.0.4.	
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Last edited by dcb; 10-13-2014 at 08:53 PM.	Quote 📴 🌠 🔗
■ 10-15-2014, 05:29 AM	# <u>516</u> ₄♪ ⚠Â
Tony Bogs Senior Member Â	Join Date: Apr 2014 Posts: 609
Re: Another homebrew AC-controller	
Quote:	
Originally posted by if you have the budget for brand spanking new cas300m12b2s then go for it. You proba diy controller in that case.	oably don't need
Not sure what you have against stm except unfamiliarity or some other agenda though speculative returns (kumbaya?) on the effort on porting it are hardly convincing thoug clear who does the porting and who gets the "benefits", or that all the cons of porting remotely being considered.	h, and it isn't
The big \$\$\$ is in the battery. It will take a few years before the \$/kWh has dropped subst \$200/kWh. The SiC price will probably have gone down also by that time.	antailly, say below
I've read somewhere that Johannes thought that the software could use a a review/clean whatever you want to call it. Why not also port it to a platform that is more appealing to Besides, the software still uses copyrighted/non open source libraries or am I mistaken? Ar source.	non-techies.
Last edited by Tony Bogs; 10-15-2014 at 05:30 AM. Reason: typo	
	Quote 🕎 📝 🎤
■ 10-15-2014, 06:03 AM	â # <u>517</u> â 🐠 â 🧥 â
dcb A Senior Member Â	Join Date: Dec 2009 Posts: 2,170
Re: Another homebrew AC-controller	

Because it does things like grab timers and other resources, and it is in a constant state of flux, and is a

PITA for serious development. Have you ever tried to do a complicated timing critical assembler function in arduino?!? And non-techies aren't going to contribute much to the core anyway except distractions. I consider myself very techie and already I destroyed one of Damiens components. You would have to be completely insane to open up a vehicle motor controller project to the art club. Besides olimex and gcc are both completely open source as well, (though I'm not married to the olimex). You really should force yourself to do something besides arduino so you have personal experience to draw from. I still borrow from arduino examples a lot, but use a wide variety of atmel chips (not all arduino friendly) and am glad to be getting some stm exposure, this was a good opportunity for me. If you want to contribute then $|^A$ bring it. Last edited by dcb; 10-15-2014 at 06:21 AM. Quote 🕺 🕅 두 n 10-15-2014, 07:09 AM #<u>518</u>Â 🌆 Â Δ <u>Tony Bogs</u> O _Â Join Date: Apr 2014 Posts: 609 Senior Member AAAAARe: Another homebrew AC-controller I've done quite a bit a timing critical assembler programming on a range of early controllers. In the early years programming microcontrollers was considered to be a bit of an art. On the Arduino Due timing critical functions are off-loadable to hardware. The Arduino Due M3 Cortex is very easy to program in C/C++. And don't get confused about the "educational" software top layer of the Arduino family. It's easy to bypass to get at the underlaying C/C++ software framework. I'd be very supprised if art people are interested in EV controllers. How about those closed source STM32 libraries? Quote 2 7 #<u>519</u>Â 🎊 Â <u> </u>Â n 10-15-2014, 07:33 AM Join Date: Dec 2009 dcb 👩 Posts: 2,170 Â Senior Member Re: Another homebrew AC-controller You don't know what you are talking about here, have a nice day. Edit, sorry if that sounds harsh. I have had lots of bad experiences with arduino everytime I try to push a chip to its limits, for all the reasons noted and then some. It always finds a way to consume my time, even now. (and I don't know what closed source library you are referring to that would have used in the toolchain here) Last edited by dcb; 10-15-2014 at 07:59 AM. 🛛 🛛 Quote 🕺 📝 🖉 🖿 10-15-2014, 08:06 AM #**520** Â 🎢 Â ΛÂ Join Date: Dec 2009 CKidder Location: Grand Rapids, MI Â Senior Member Posts: 275 AAA 📃 Re: Another homebrew AC-controller Quote: Originally Posted by Tony Bogs

I disagree on Arduino. The Arduino Due has an Atmel ARM chip on board with all the major hardware goodies needed for an EV controller: sophisticated DMA, multi phase PWM with H/W protection, timers, it's all there.			
The top Arduino software layer, that most engineers despise, is really very thin. Below it is a complete open source C/C++ ARM software framework.			
I see you've taken a lot of crap from certain people over this viewpoint. The thing is, when people think of Arduino they think of the old ATMega based boards that were junk. At that point the Arduino library did take over all sorts of resources and was kind of a pain to work with. I don't think that many people realize that what you said is true: On the Arduino Due the Arduino library is just a thin shim over the core ARM libraries. Much of the dumb stuff that happened on the ATMega chips isn't relevant any longer. There are still a couple of issues:			
 The Arduino library code disables the watchdog and you cannot re-enable it. It does automatically set up a bunch of stuff still. You get something like 4 serial ports automatically configured. You can use the ARM library functions to disable this stuff again but it's a little bit of a pain The Arduino IDE still sucks. Use something else. Visual Micro for Visual Studio is a reasonable choice. 			
I actually have used the Arduino library with the Due for a big project (GEVCU). We did step around the Arduino core for some things. All in all I've never really seen the Arduino library slow anyone down on the Due. If it gets in the way we just don't use it or reconfigure behind its back.			
So, is the Due viable for a wide range of projects? Sure. Even large, complicated projects can be done. But, you'll end up writing a lot of code directly against the ARM libraries and pushing the Arduino stuff out of the way. So, one might argue that it'd be better to just use the ARM libraries directly. Perhaps. However, the Arduino core stuff still does a good job of setting up the hardware for you for the most part. There's a lot of code in there that you'd either end up stealing or having to rewrite. I suppose my point is that it makes a reasonably decent springboard for development. Once you outgrow a section of it you just quit using that section and do it yourself.			
And, I'm not just saying all of this because I'm dead set on ARM development. I've done projects on PIC, ATMega, ARM, and STM32. They all have their uses. I don't think that it is helpful to have pissing matches about processors. Each one has a use.			
But, I'm not advocating for anything here. Use STM32, use a CortexM3 / Due, doesn't matter to me. I'm just explaining why the Arduino Due is potentially a better choice than people sometimes think.			
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Page 52 of 221 Â « First < 2 42 50 51 52 53 54 62 102 152 > Last »			
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jhuebner Senior Member Â		Lo	oin Date: Ap ocation: Ger osts: 927		
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Quote:

Originally Posted by Tony Bogs 🔊

I've read somewhere that Johannes thought that the software could use a a review/cleanup/reorganization or whatever you want to call it.

I might have said so on the tumanako list a few years back. But meanwhile the code is like 95% clean. Just look at it.

Quote:

Originally Posted by **Tony Bogs** *How about those closed source STM32 libraries?*

Nope, the libopencm3 is used. It really is a true open source project.

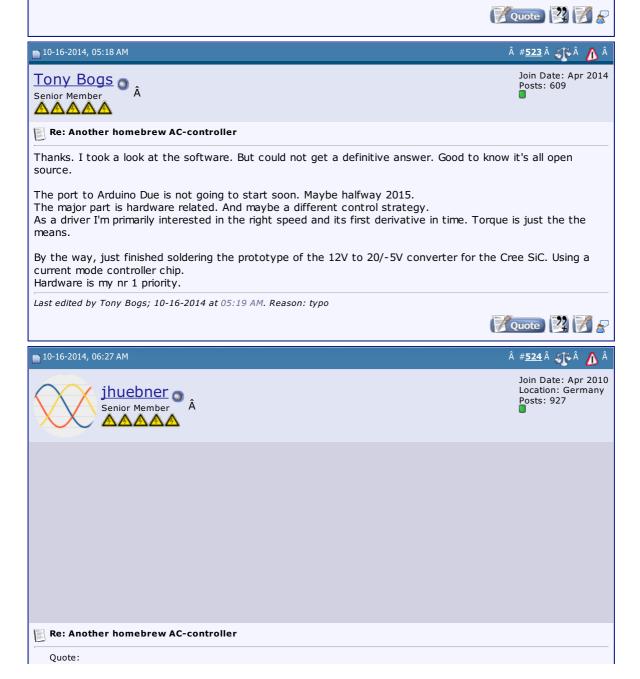
But I don't want to pour oil in the ongoing platform discussion. I chose the STM32 because the tumanako crew had decided on it. As far as I know they decided on it because:

- the hardware suits the needs
- It was the only platform supported by an open source HAL lib (libopencm3) back then
- It is supported by the open source arm gcc

Maybe today they'd decide to go with Arduino. I don't know enough about Arduino to decide whether is suitable or not.

A lot of code is platform independent and could be used on any MCU. If any one feels like porting it to Arduino - go ahead.

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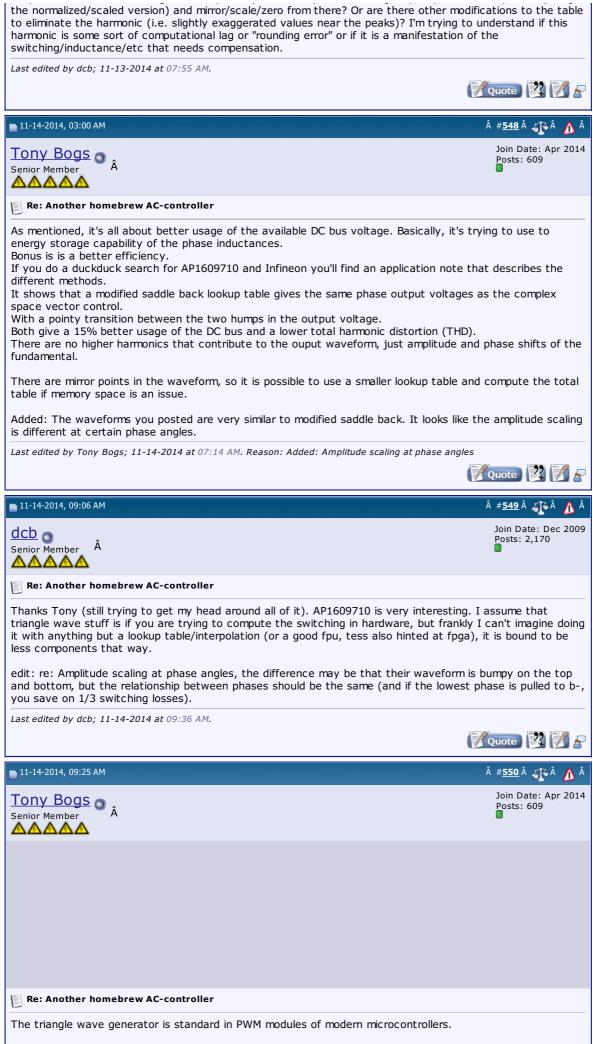


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The basis for the DW/M is almost always comparison with a scaled lookun table. Johannes uses a standard

sinus table and cpu tin PWM registers need up the software.	ne to calculate the neces dating. I remember some start with a modified tab	sary modifications of the thing about shifting the r	output waveform every time the neutral point from the comments in e desired output voltage. Very	
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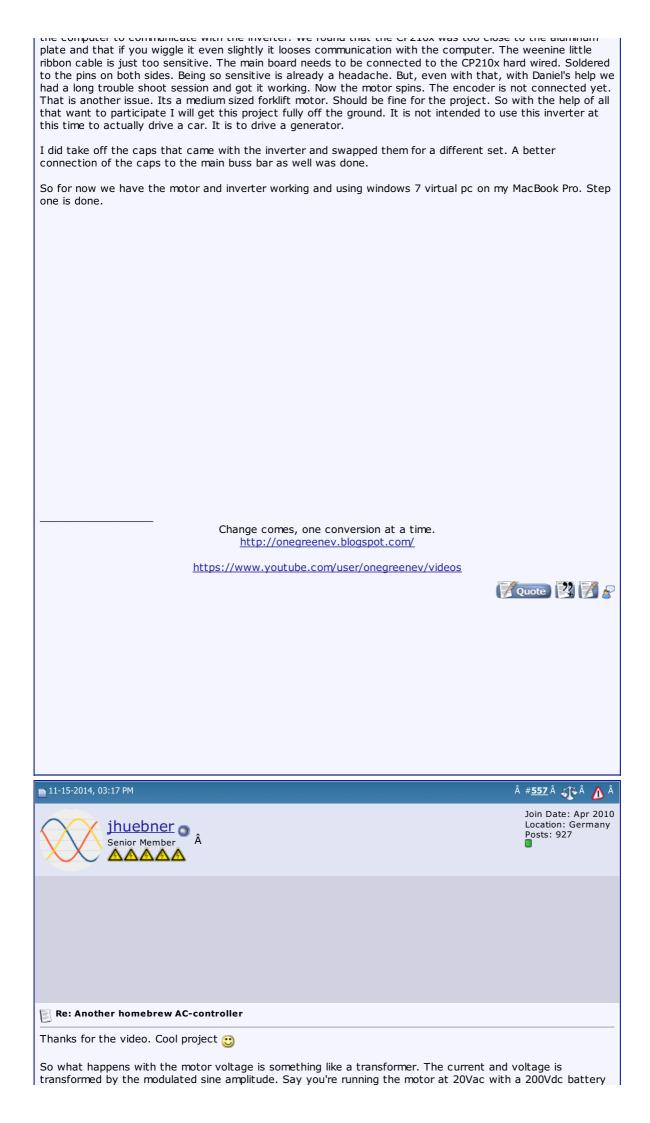
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I am using a 2.5amp output driver part sort of like that one, but is a 16 pin version (FOD8316)



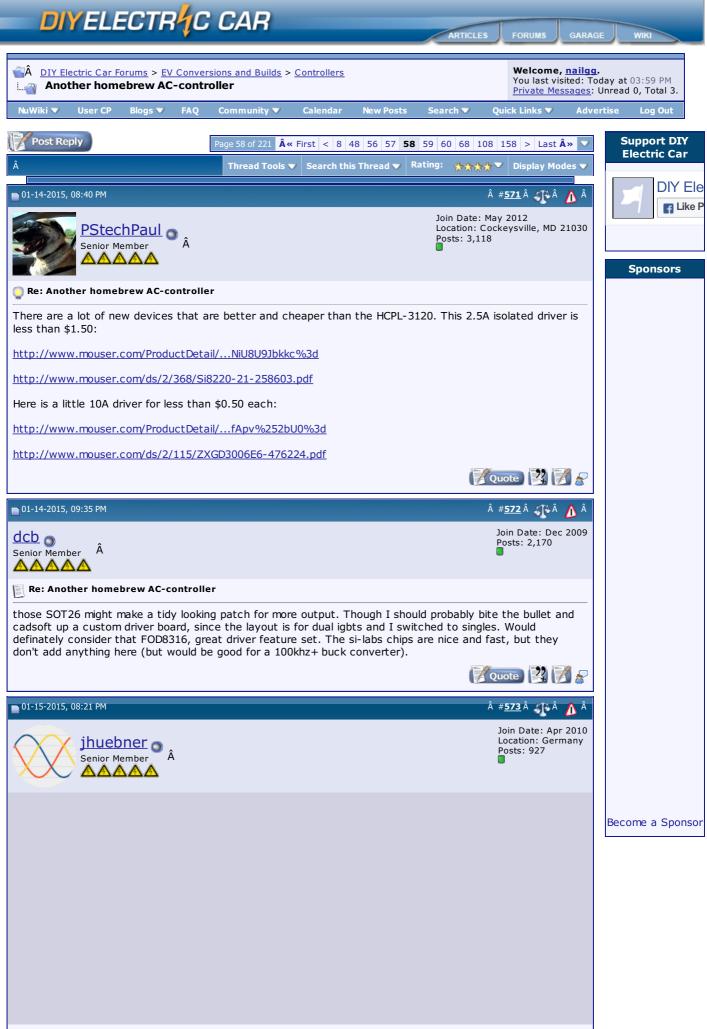
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Re: Another homebrew AC-controller Finally got this sucker to move again. Some long hours of trouble shooting. Lots of help from Johannes Huber. Change comes, one conversion at a time. http://onegreenev.blogspot.com/ https://www.youtube.com/user/onegreenev/videos
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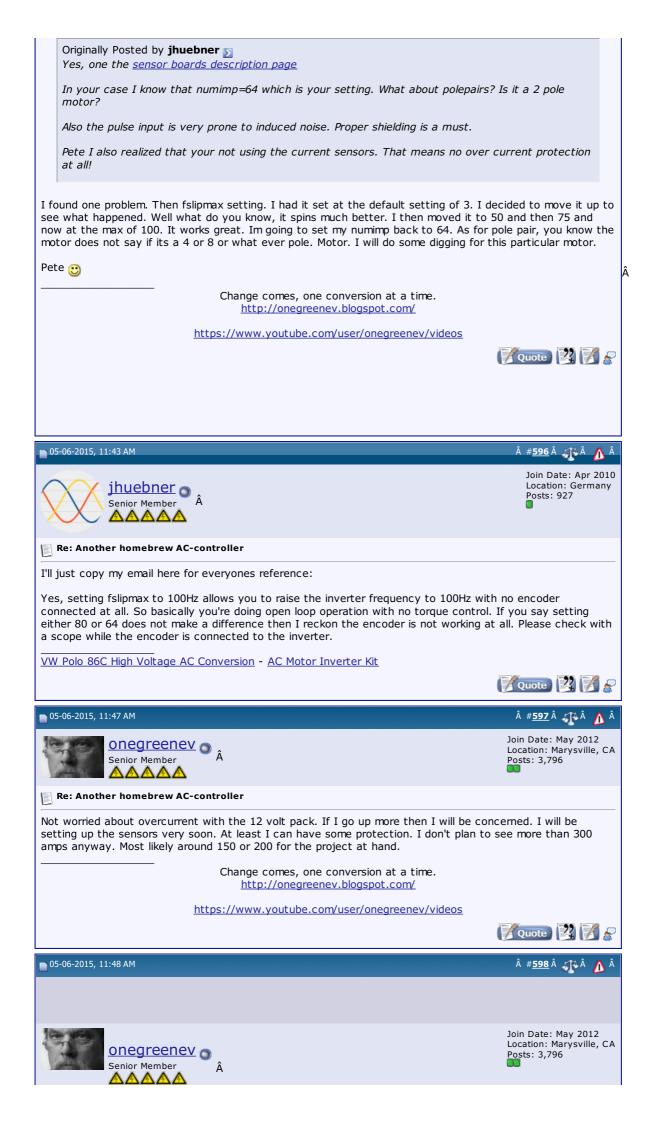




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Re	e: Another	homebrew	AC-controller
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Quote:

Originally Posted by **jhuebner** *I'll just copy my email here for everyones reference:*

Yes, setting fslipmax to 100Hz allows you to raise the inverter frequency to 100Hz with no encoder connected at all. So basically you're doing open loop operation with no torque control. If you say setting either 80 or 64 does not make a difference then I reckon the encoder is not working at all. Please check with a scope while the encoder is connected to the inverter.

I'll do that.

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Onegreene Senior Member	⊻ o _Â		Join Date: May 2012 Location: Marysville, CA Posts: 3,796
Re: Another homebrew A	2-controller		
What would a trace look like Scopes are new to me.	on the scope w	hen checking the encoder?	
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Tomdb Â Senior Member Â			Join Date: Jan 2013 Location: Warwickshire, UK Posts: 798
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a nice square wave, 0-3.3V			
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So thats what you want.																		
Always 500 rpm is indeed very suspicious.																		
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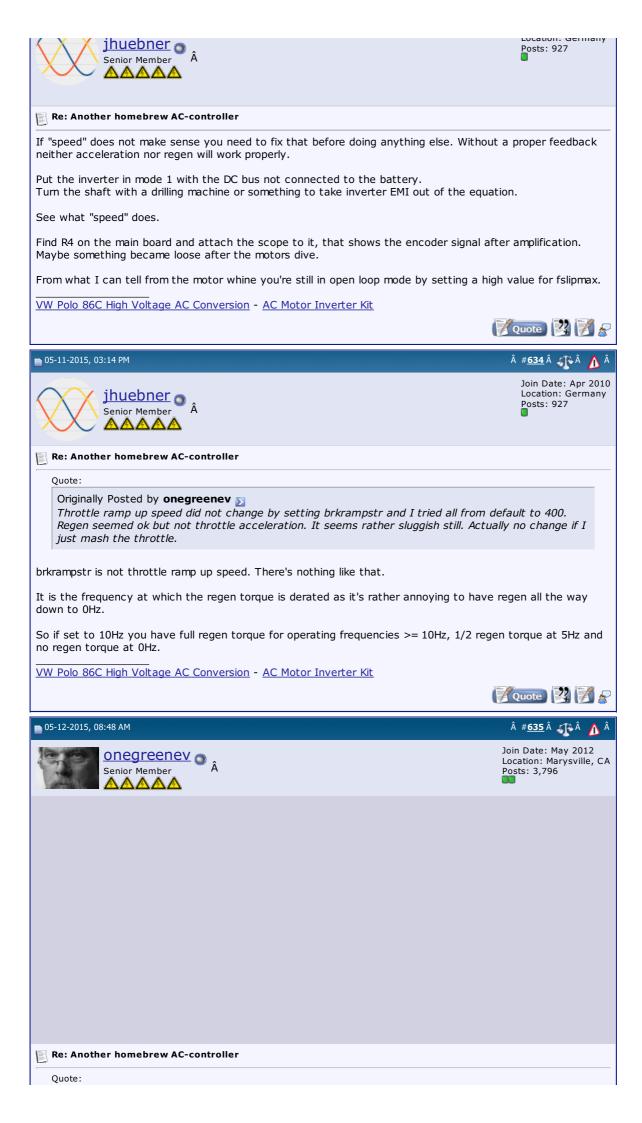


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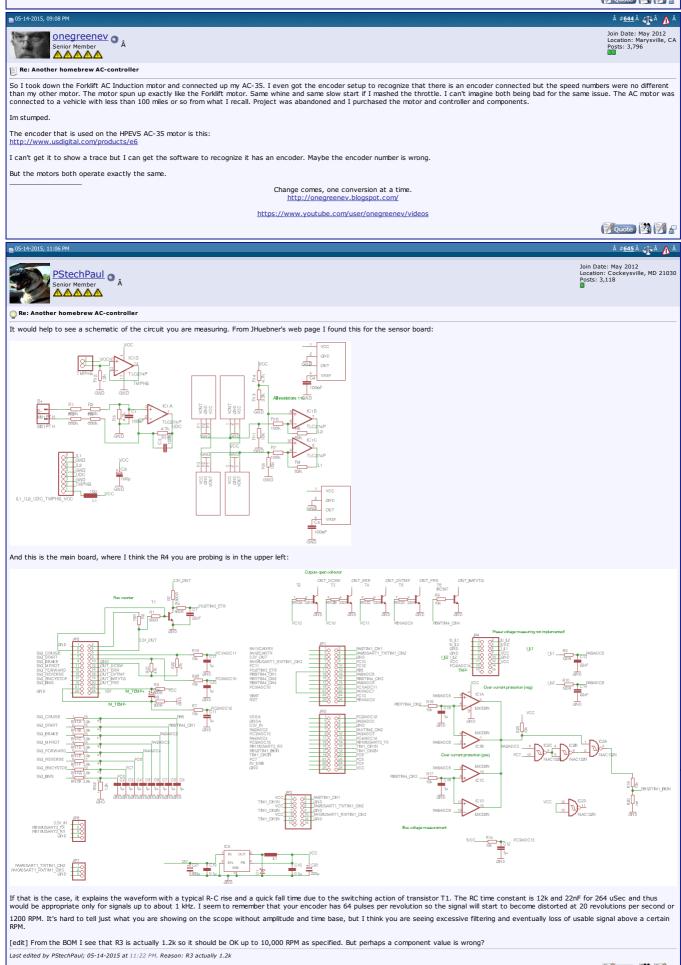
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Join Date: Apr 2010 Location: Germany Posts: 927

■ 05-16-2015, <u>01:15 AM</u>



Re: Another homebrew AC-controller	
I just realize my RC filter design is not as intended, of course the major R-contributes arme. Can we get a close-up image of C1?	or is R3, not R4. Anyway the slope is a bit shallow, could it be that C1 is 1µ instead of 22n? They almost look the
Since your signal looks clean you can try to remove C1 alltogether and test without	it.
EDIT: the resistor R3 and R4 look correct.	
EDIT2: The time base of his scope is 2ms/div. Thus the filter time constant is about	2/5 div=800µs, i.e. cutoff frequency is 1250Hz.
As he spins up the amplitude becomes so low that the MCU only just sees it.	
I'll scope my own encoder tomorrow.	
VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
Last edited by jhuebner; 05-16-2015 at 02:11 AM.	(Mouote) 122 1 8
■ 05-16-2015, 08:15 AM	# <u>647</u> √ ∀ ∧ Â
	Join Date: May 2012
Senior Member Â	Location: Marysville, CA Posts: 3,796
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Quote:	
	ributor is R3, not R4. Anyway the slope is a bit shallow, could it be that C1 is 1µ instead of 22n? They almost
look the same. Can we get a close-up image of C1? Since your signal looks clean you can try to remove C1 alltogether and test wi	thout it
EDIT: the resistor R3 and R4 look correct.	
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As he spins up the amplitude becomes so low that the MCU only just sees it.	
I'll scope my own encoder tomorrow.	
	o boards. The one I did and the one Daniel did. It looks like maybe I did get that one wrong as I found a package in
	e the ones on the board. I may have also gotten another one wrong as well but I will double check that later.
I can take that off the board and try without it. Ill have more time this evening to r Thanks	iess with it dii.
Pete 🙂	
	nge comes, one conversion at a time. http://onegreenev.blogspot.com/
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iackbauer	Join Date: Jan 2008 Location: Ireland Posts: 2,147
Senior Member Â	033.2,147
E Re: Another homebrew AC-controller	
Fired up the Siemens in Der Panzer today for the first time with new sensor board.	Smooth as silk :
<u>https://youtu.be/nQSYnykJFOo</u> Working on a new Designspark layout for the control board complete with an Ampse	al 23 connector
Attached Thumbnails	
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Now, Cole, when you shift the gear and that little needle on the ammeter goes into	the red and reads 1000 Amps, that's bad.
www.evbmw.com	(Vouote) 124 17 2
■ 05-16-2015, 12:03 PM	
	# <u>649</u> ∰ Â Join Date: Jan 2013
Senior Member Â	Location: Warwickshire, UK Posts: 798
Re: Another homebrew AC-controller	8
	so the flat cable for the main connection is quite a headache when searching for the pins and getting good
connections.	
■ 05-16-2015, 02:11 PM	#650 ∰A A Â Join Date: May 2012
Onegreenev Senior Member	Join Date: May 2012 Location: Marysville, CA Posts: 3,796
Re: Another homebrew AC-controller	
E Another nomebrew AC-controller	
Nice work. Glad to see you have movement. I look forward to a new design.	
Pete 🙄	
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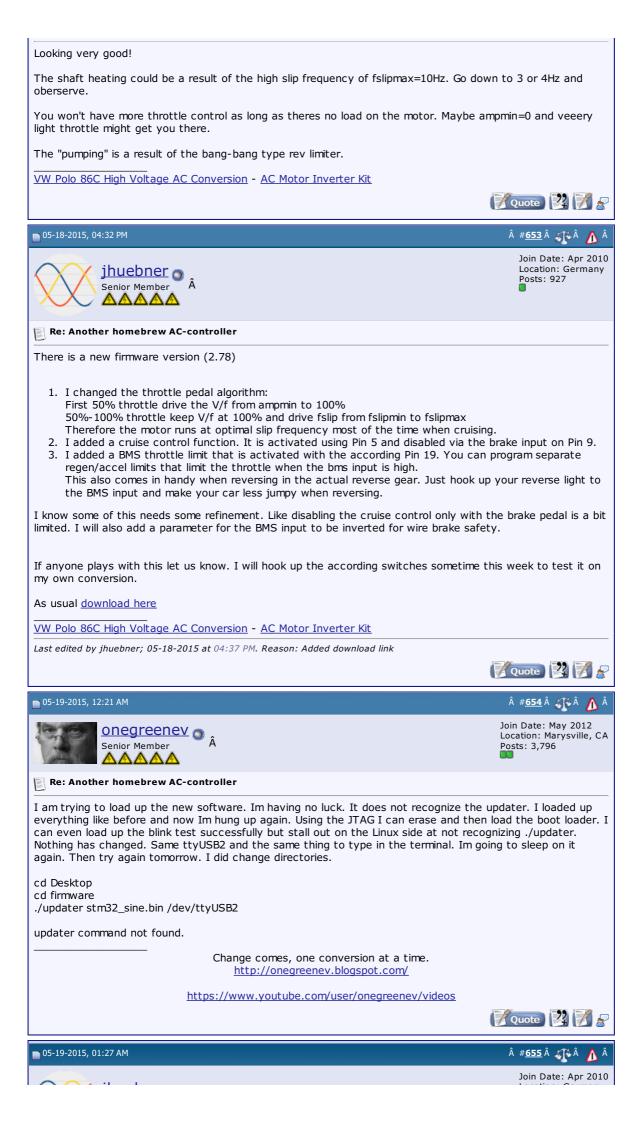
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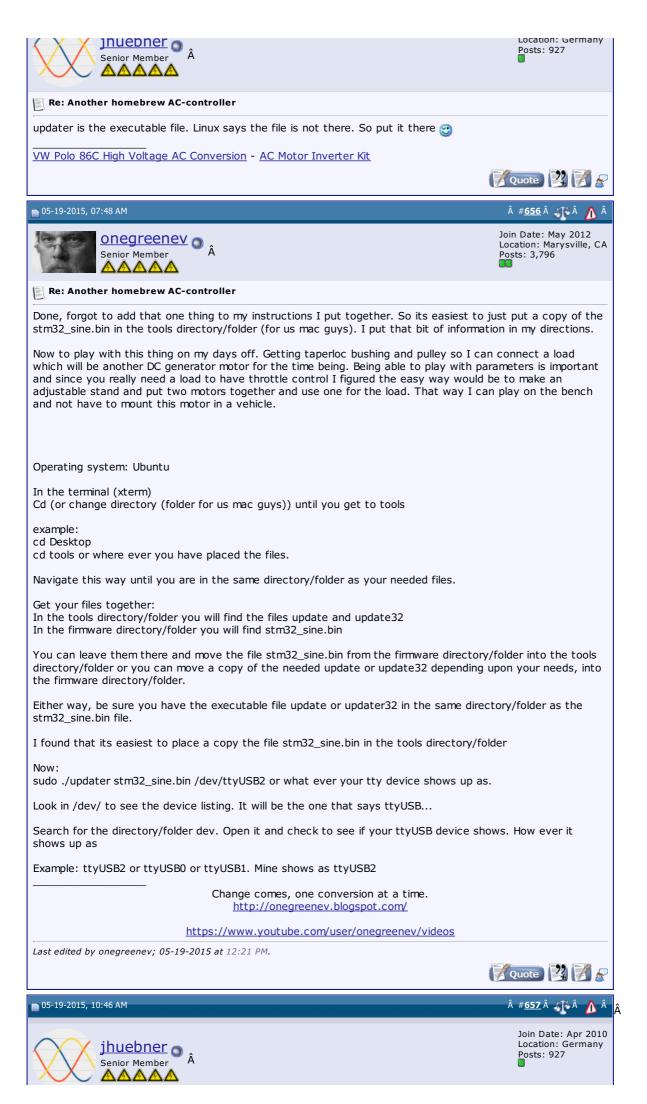
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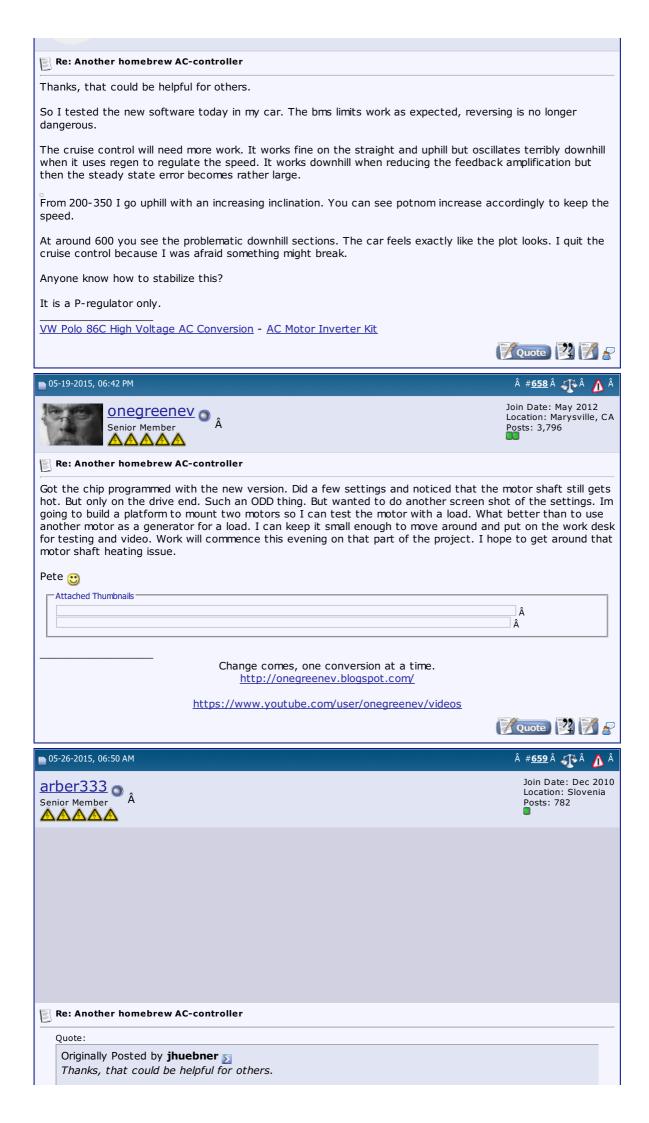
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So I tested the new software today in my car. The bms limits work as expected, reversing is no longer dangerous.

The cruise control will need more work. It works fine on the straight and uphill but oscillates terribly downhill when it uses regen to regulate the speed. It works downhill when reducing the feedback amplification but then the steady state error becomes rather large.

From 200-350 I go uphill with an increasing inclination. You can see potnom increase accordingly to keep the speed.

At around 600 you see the problematic downhill sections. The car feels exactly like the plot looks. I quit the cruise control because I was afraid something might break.

Anyone know how to stabilize this?

It is a P-regulator only.

Hi J

Have you considered programming lower possible slip for regen in case cruise control is active. Like with reduction when reversing.

I guess i still dont know what you use for slowing the motor down, negative slip or regen region slip or both?

With my wifes petrol car (it has cruise control) i noticed that in case of heavy downhill car actually goes a bit out of speed range but slowly returns in the region of preset speed. It works so slowly that i dont even notice i went 10km/h out of range, because in cca 5s i am back inside preset speed range.

I guess you dont need very fast speed corrections when cruising. Can you dampen the slip response loop? You could maybe only allow up to nominal slip when in cruise mode. If incline requires more slip than nominal, inverter should drop out of cruise anyway, because of energy consumption and motor overheating.

When i suggested cruise control with your inverter i did it with my highway driving in mind. I really drive long distance every day. Usually EVs drive more locally or at various speeds. So driver performs the function of cruise control, as it should be \bigcirc .

А

Last edited by arber333; 05-26-2015 at 06:58 AM.



n 05-26-2015, 07:13 AM



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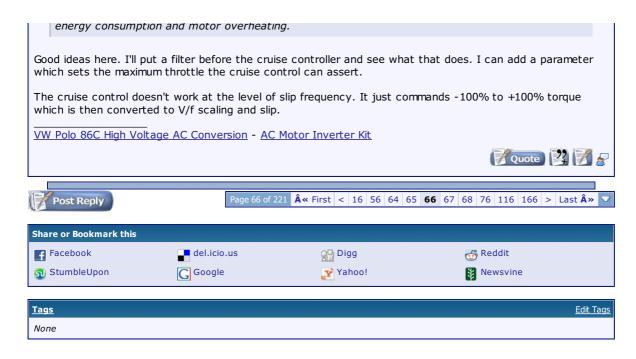
Join Date: Apr 2010 Location: Germany Posts: 927

Re: Another homebrew AC-controller

Quote:

Originally Posted by **arber333** I guess you dont need very fast speed corrections when cruising. Can you dampen the slip response loop? You could maybe only allow up to nominal slip when in cruise mode.

If incline requires more slip than nominal, inverter should drop out of cruise anyway, because of



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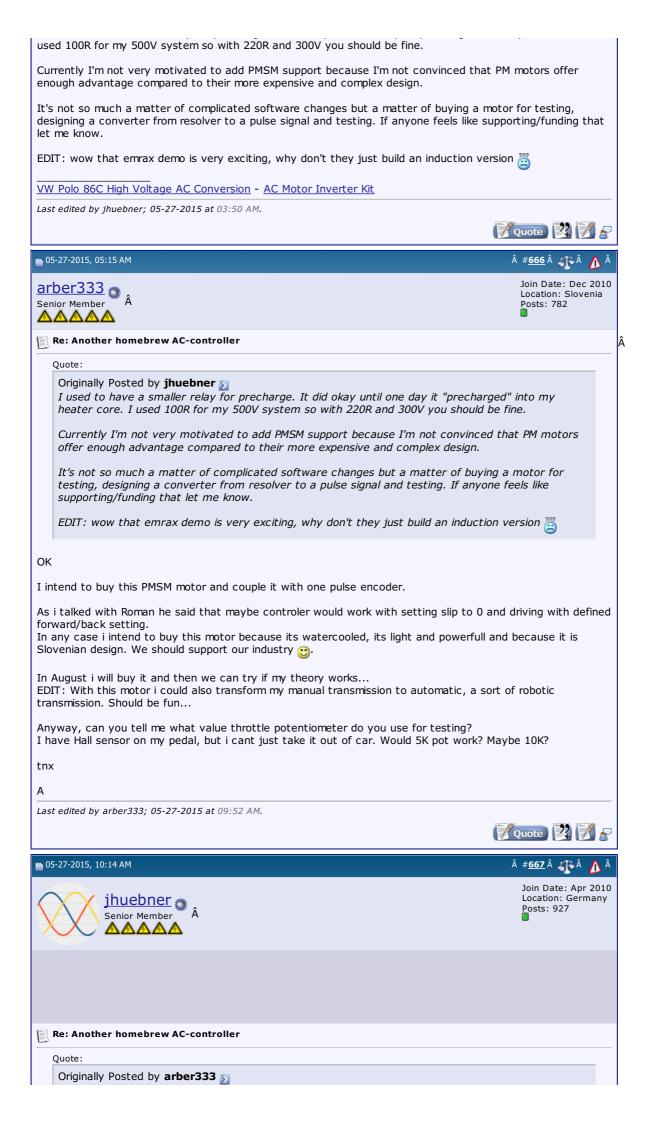
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■ 05-26-2015, 07:46 AM		# <u>661</u> ⁄ 🧥 Â	
arber333 Senior Member Â		Join Date: Dec 2010 Location: Slovenia Posts: 782	
Re: Another homebrew AC-co	ntroller		Sponsors
parameter which sets the m The cruise control doesn't w torque which is then conver Hah! Then you absolutely have to reduce oscillation. Maybe it would be good to have proportionally extend time this m outside disturbance.	lter before the cruise controller and see naximum throttle the cruise control can vork at the level of slip frequency. It just	assert. commands -100% to +100% have to implement full PID control esponse to outside pulse and	
		Quote 🕎 👔	2
■ 05-26-2015, 05:06 PM arber333 Senior Member Â ▲ ▲ ▲ ▲		# <u>662</u> TA Â Join Date: Dec 2011 Location: Slovenia Posts: 782	0
Re: Another homebrew AC-co	ntroller		
Since i bought kit from Johannes I made most of the hardware an motor. I decided to test one sm flywheel and gearbox.	a 140VDC LiFe cells on 28kW german ACIN is in february 2015 i am trying to convert d connections. Now i have to connect 12 all 3phase motor, since my EV motor is fix d i am thinking of changing the motor jac oler being built:	my car to 300VDC 300A. 2V and test it before i test spin xed and it needs 2kW to spin up the	Become a Sponso
Arber			
Last edited by arber333; 05-27-2015	at 02:35 AM.	VQuote 🕎 📝	2
■ 05-27-2015, 12:55 AM		Â# <u>663</u> Â 🏹 Â 🧥	Â



I used to have a smaller relay for precharge. It did okay until one day it "precharged" into my heater core. I





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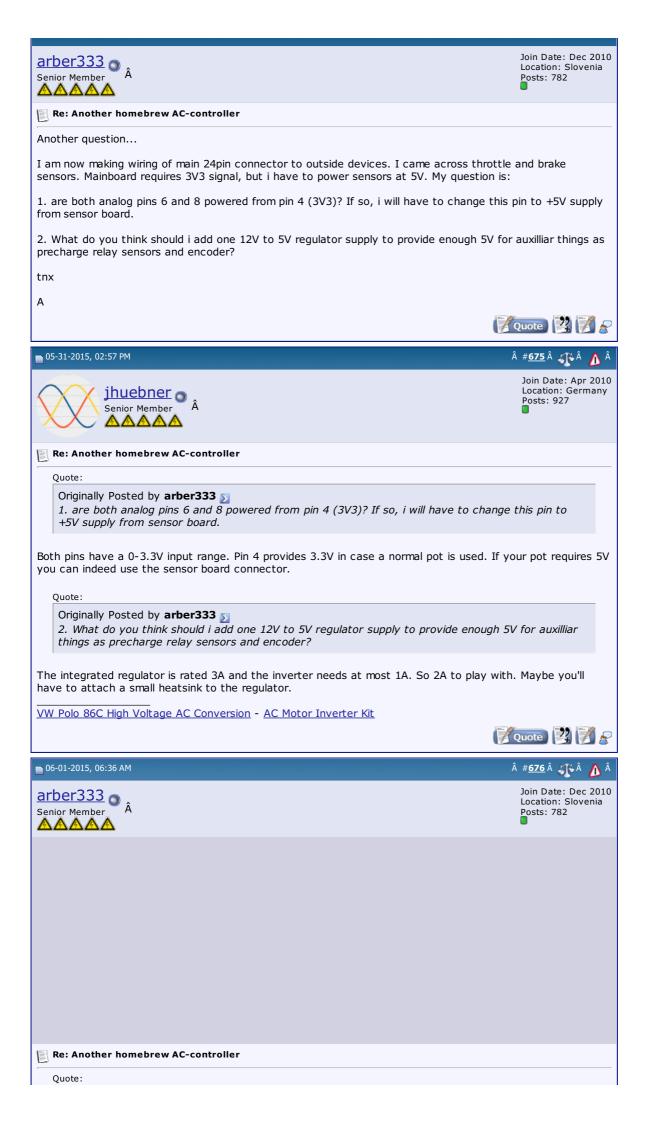
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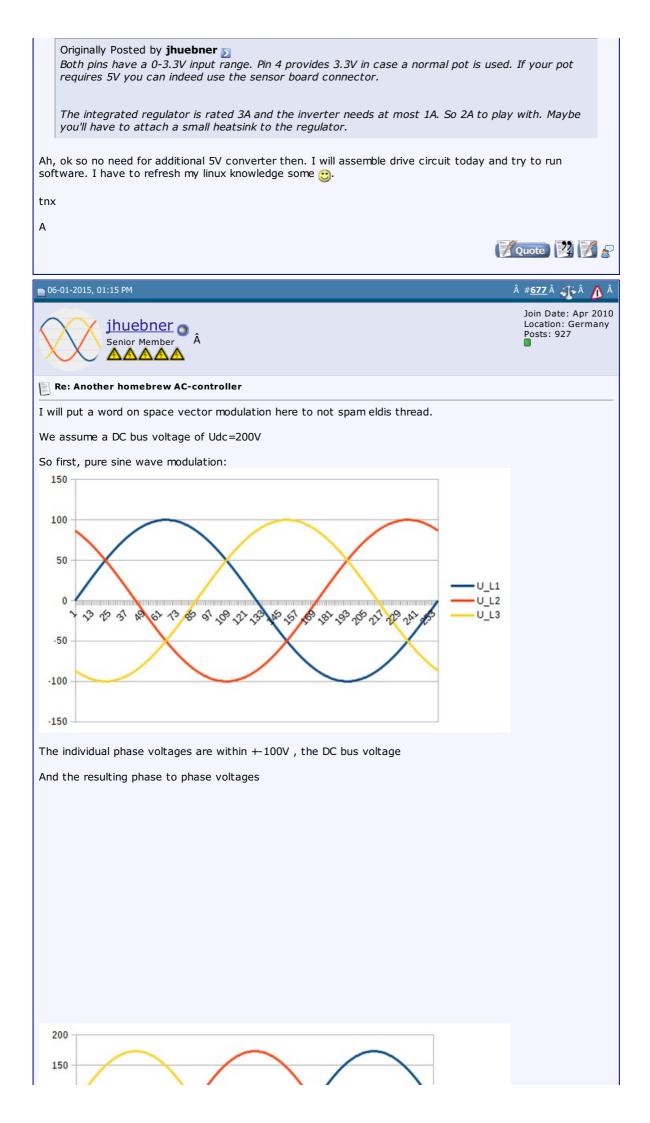
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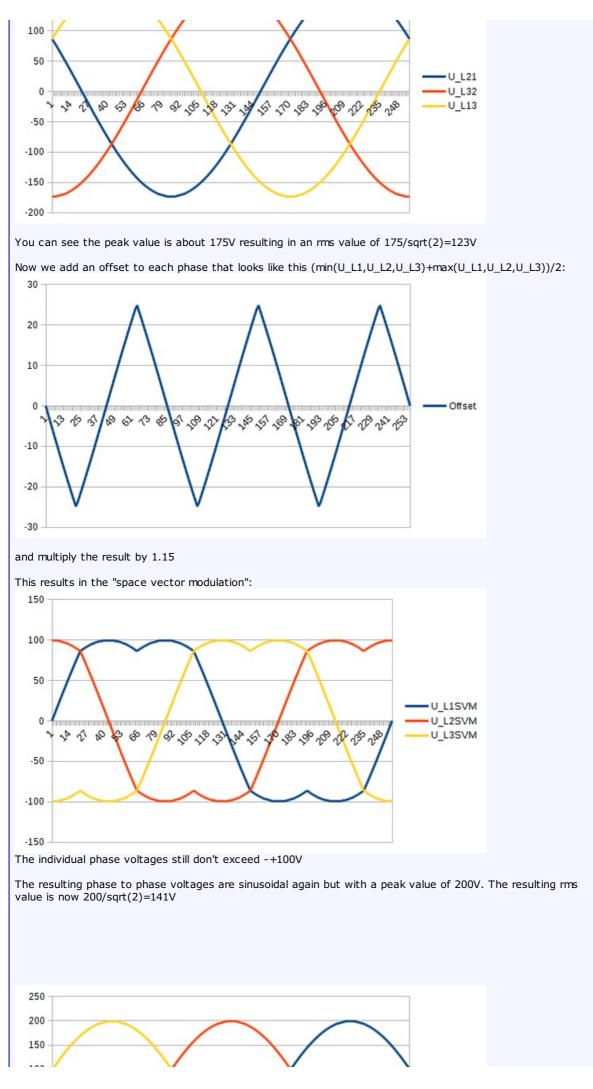
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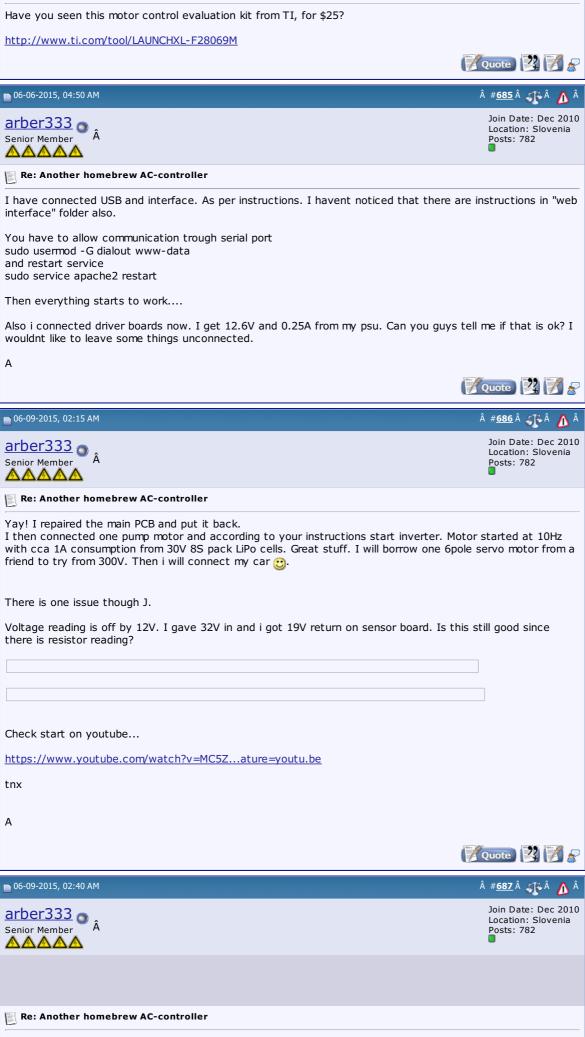
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■ 06-01-2015, 10:04 PM	#678 xT\ 🔥 Â
PStechPaul Senior Member Â	# <u>678</u> TA Â Join Date: May 2012 Location: Cockeysville, MD 21030 Posts: 3,118
Re: Another homebrew AC-controller	
I have seen something like that before, way back in 2004 or so when I atte conference and a session on ACIM control.	nded the Microchip MASTERS
It may not directly apply here, but I found this paper about pure sine wave http://www.wpi.edu/Pubs/E-project/Avques_final.pdf	inverters quite interesting:
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D0-U2-2015, U2:55 AM	#679 🖍 TA 🔥 Â
■ 06-02-2015, 02:55 AM arber333 Senior Member Â ▲ ▲ ▲ ▲ ▲	# <u>679</u> TA Â Join Date: Dec 2010 Location: Slovenia Posts: 782
arber333 Å	Join Date: Dec 2010 Location: Slovenia
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A A A A A A A A A A A A A A A A A A A	Join Date: Dec 2010 Location: Slovenia

to get logarithmic effect. Btw we figured logarithm	ic pot is the best for lines in code that de	EV, since start is very quic scribe the curve, zero poin	i would have to setup kinemat k, later power is added more s it from cca 5% pot movement	slowly.
ie.: throttle value starts	at X=10%, Y=0% and	1 at X=30% has Y=40% eff	ect and at X=60%, Y=80%	
A bit slower logarithmic c	urve. Picture attache	ed.		
tnx				
А				
Last edited by arber333; 06-0	02-2015 at 03:17 AM.			
			Quote 2	1
■ 06-03-2015, 01:35 AM			# <u>680</u> Â	<u> </u> Â
arber333			Join Date: [Location: Sl	
Senior Member Â			Posts: 782	oveniu
Re: Another homebrew	/ AC-controller			
I connected +12 wrong!!	!			
It seems that when i pre	pared cables i switche ent to 3V and current	ed colour of two wires, DOI t jumped to 2A as PSU was me.	H! s limited. Do you think main PC	В
I will try again later toda	y if you think it is goo	od?		
tnx				
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Post Reply	Page 68 of 2	221 A « First < 18 58 66 67	7 68 69 70 78 118 168 > La	st » 🔽
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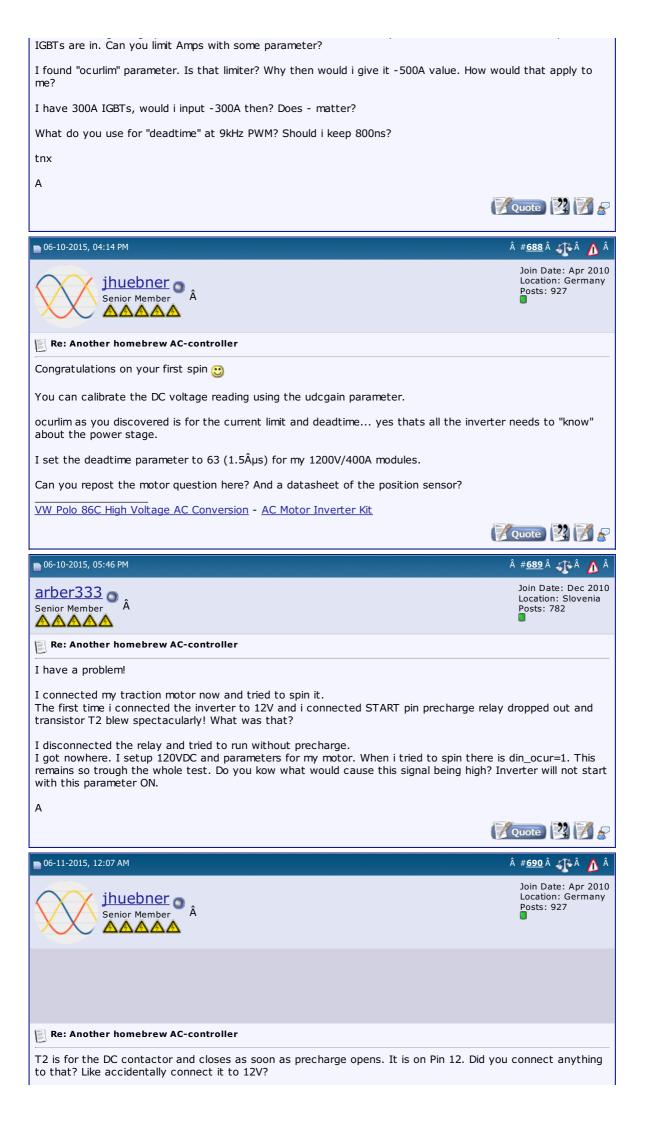
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I was skimming trough parameters and i noticed that there is no way for the inverter to know what power





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Quote:	
Originally Posted by jhuebner The 12V trace is quite far away from the digital outputs so I don't t PCB.	hink it's a short circuit on the
Can you unplug JP5 and check if Pin 12 is short circuit to Pin 11 or 1	3?
If Pin 3 is at around 0.7V then the transistor is still ok.	
Is V/Hz mode working again or still din_ocur=1?	
You are correct. I got some time today and i measured like you said. Pins 11 and 12 were not short rather it was the wire in main connecto directly towards transistor that pulled it to GND. With PSU that was no p connected to 12V battery poor ZTX was toast	
Encoder pin 3 though i got a signal on it, 2,9V towards GND. Is that be to lower voltage on signal pin from 5V to 3.2V. But i checked and my encisional from 11V to some 3V pulse. Do you think i should order another Oli	coder needs 12V! So i have to lower
Do you think i could use optocoupler? From one side i would power led from would transmit 3V towards pin 3 You think it would work? Like this: http://www.ebay.co.uk/itm/37129648	2 · · ·
tnx	<u></u>
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■ 06-13-2015, 06:38 PM	# <u>694</u> 🐠 🏠
jhuebner Senior Member Â	Join Date: Apr 201 Location: Germany Posts: 927
Re: Another homebrew AC-controller	
It sounds like you damaged T1 but the Olimex should still be ok. Yes, the You can just connect the receiving side to GND (Emitter) and Pin 3 beca	• •
<u>VW Polo 86C High Voltage AC Conversion</u> - <u>AC Motor Inverter Kit</u>	Quote 22
D6-14-2015, 08:34 AM	# <u>695</u> ∢∰ <mark>∆</mark>
jackbauer Senior Member Â	Join Date: Jan 200 Location: Ireland Posts: 2,147
Re: Another homebrew AC-controller	
Johannes , your inverter works 🙂	
https://youtu.be/aWPgEf6abUo	
Now, Cole, when you shift the gear and that little needle on the ammete Amps, that's bad. www.evbmw.com	er goes into the red and reads 1000
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р 06-14-2015, 11:28 АМ	# <u>696</u> 🕂 🔊
ihuebner	Join Date: Apr 20 Location: German
\hat{A}	Posts: 927





As i said it is a success! Motor was spinning in car, in neutral of course, because i havent bui
encoder 5V - 3V level interface yet.

Congratulations 🙂

Quote:

Originally Posted by arber333 5

I noticed that overcurrent protection is very effective. Very good. Can you explain why the parameter has to be -200 for the inverter to operate? I tried to set to 200 and it just kept switching off.

Yes, on the very first hardware version the sensor polarity was not inverted, now it is because of the inverting opamp. So I had that old hardware buried in my car and new hardware on my desk (and "out in the field").

To be able to use the same software on both, I made the parameter bipolar. Negative value for the new boards, positive value for the old one. Seeing it now that was a silly decision.

If I change it now, then everybody who does a software update will have to correct the parameter.

Quote:
Originally Posted by arber333

I set fweak at 150Hz, Fslipmin is 3 and i found out Fslipmax at 6 causes motor to rotate very slowly and draw lots of amps. Then i changed it to 50Hz! Motor went spinning instantly. Why? I taught this parameter shouoldnt be higher than 2xFslipmin.

tnx

Α

Also i saw that changing boost value can increase engine speed, but can throw overcurrent protection. I have it set to 2400.

Fslipmin and max only have their actual meaning once an encoder is connected.

Right now, without encoder, you can vary the output frequency between 3 and 6 Hz. Once the encoder is connected the shaft speed will be added on top of that and the motor will spin up quite rapidly.

In idle you will have the feeling that you can't control the motor, it only starts to make sense when you put a load on it.

VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit



None

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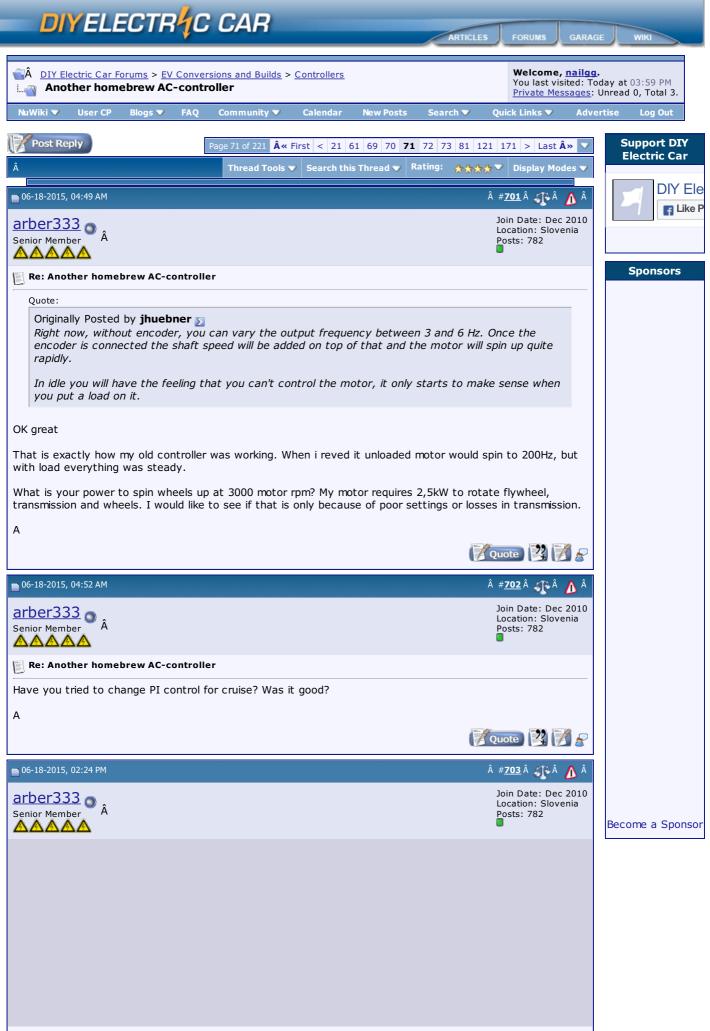
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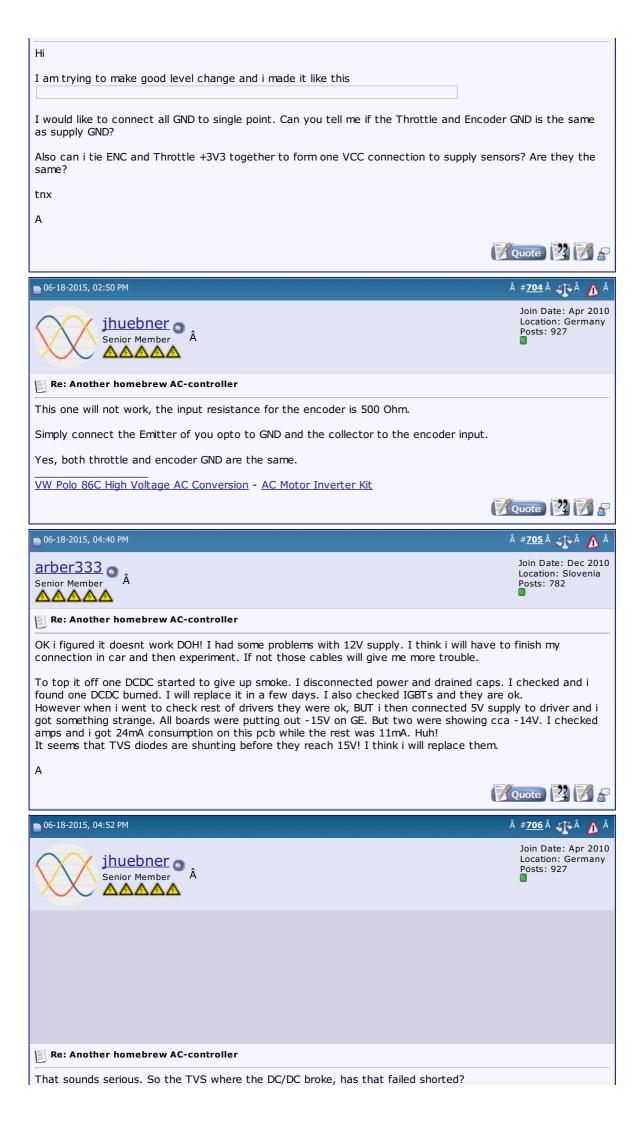
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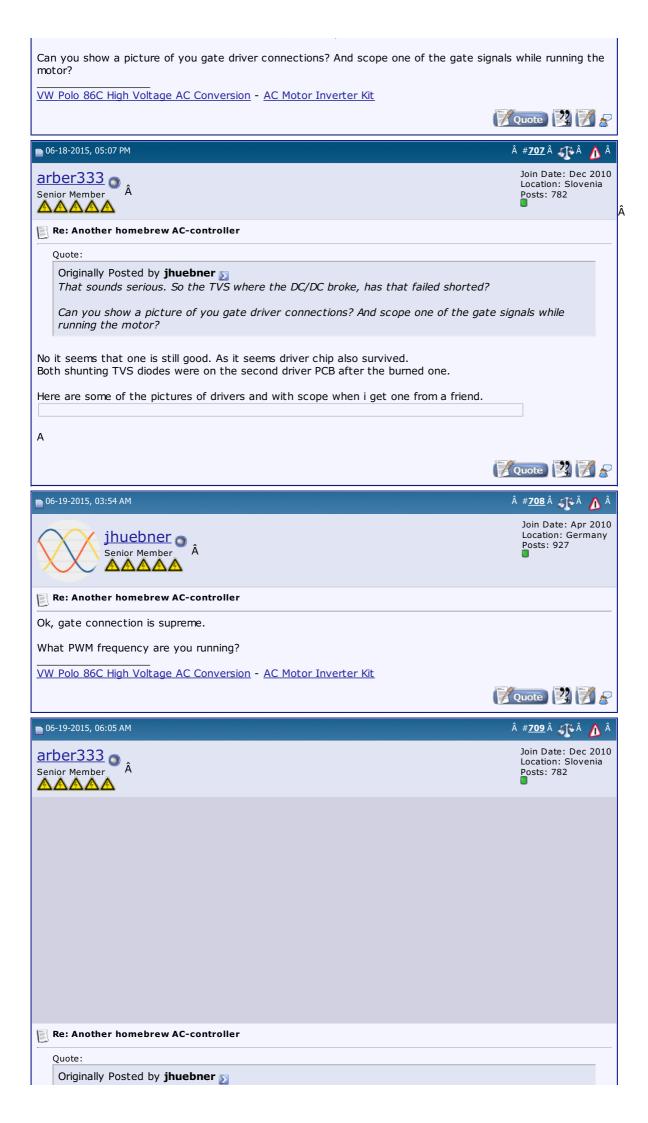
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Ok, gate connection is suprem	ie.	
What PWM frequency are you	running?	
energy for turning the IGBT on is s	till lower that DCDC supplies. BC-C-IP. It is one tough moth	resistors. This shouldnt be a problem since I suspect that driver IC takes more than its her since it survived two IGBTs dying in my poor thing that released smoke.
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■ 06-19-2015, 06:08 AM		# <u>710</u> √ <mark>∕</mark> Â
jhuebner Senior Member Â		Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew AC-contr	oller	
Yes 8.8kHz is fine. I thought it mig	ht be 17.6kHz which could ex	plain an overload.
VW Polo 86C High Voltage AC Conv	version - <u>AC Motor Inverter Ki</u> t	<u>t</u>
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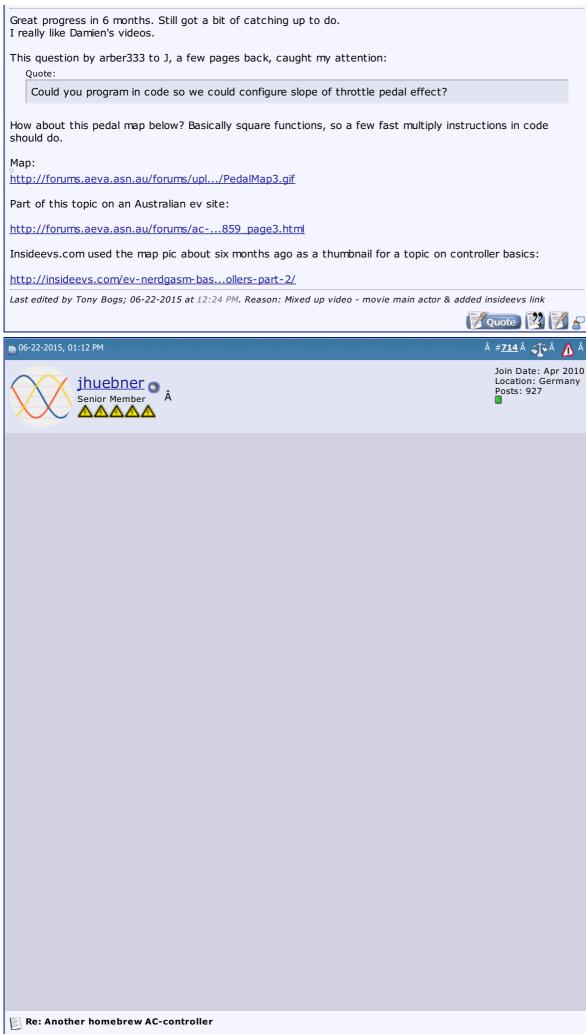
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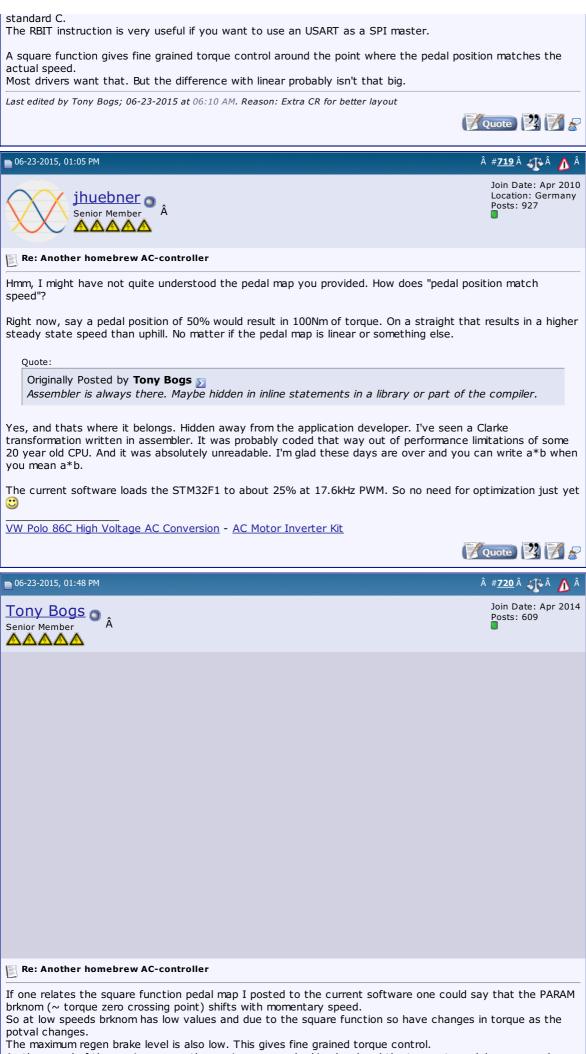
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	Originally Posted by PStechPaul For TVS diodes you need to look at the rated voltage Vbr) as well as the standoff voltage and maximum clamping voltage at rated peak current. A 1.5W 15V bidirectional TVS has a Vbr of 14.3 to 15.7V (for the tighter "A" version), and a reverse standoff voltage Vwm of 12.8V at 5uA leakage. Its maximum clamping voltage is 21.2V at 78A. According to the rating curves, the incremental clamping voltage will add about 0.3V to the usual 10A or less IGBT drive current.	
	The unregulated 15V DC-DC converters generally are OK with a common 15V zener diode to limit its output to 15V or below, and the IGBT driver will usually drop the voltage by another volts, so the TVS should not draw very much current when the drive is ON. The breakdown voltages are specified at 1 mA. The drivers are rated into a heavy capacitive load and should be current limited, and the DC-DC converters should have fairly large (20-50 uF) low impedance capacitors on the output and across the driver supply, so they will supply the surge current and not the DC-DC. So the cause of the failure may be something else.	
	[edit] BTW, TVS diodes do not "open normally". They only open when subject to excessive power and overheating, and do not exhibit the aging/use effect of MOVs, which gradually reduce their breakdown voltage until they start drawing excess current at rated voltage and then trip a protective device or blow open spectacularly.	
Bre	, good to check. So I'm using <u>18V bidirectional TVS</u> eakdown @17.1, Reverse Standoff 15V <u>pacitors</u> are 100ÂμF, 200mA RMS ripple current. Not explicitly Low-ESR types.	
	Quote:	_
	Originally Posted by Tony Bogs Great progress in 6 months. Still got a bit of catching up to do. I really like Damien's videos.	
	This question by arber333 to J, a few pages back, caught my attention: How about this pedal map below? Basically square functions, so a few fast multiply instructions in code should do.	
Abs	solutely, if you guys fancy that it is an easy feature to add.	
Che	eck attachment	
Γ	Attached Thumbnails	
	/ Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
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	Quote 2	∫ <i>⊱</i> ∧ Â
06	6-22-2015, 04:09 PM Â # <u>715</u> Â 🐢 Â	
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■ ⁰⁰ Tc Ser	6-22-2015, 04:09 PM #715 A Â DNY BOGS hior Member Â	
■ ⁰⁰ Tc Ser ▲	6-22-2015, 04:09 PM #715 A A DNY BOGS hior Member Â Â Â	2014
■ ⁰⁰ Ser ▲ ICE in f But Car pro	6-22-2015, 04:09 PM Â #715 Â JA A 6-22-2015, 04:09 PM Â #715 Â JA A Ony Bogs Â Dior Member Â A Posts: 609 Re: Another homebrew AC-controller E tuners surely will think it's easy. ICE controllers are stuffed with all kinds of 3D maps. Basically a 2D and the state of the sta	2014 ray
■ ⁰⁰ Serr ▲ ICE in f But Car pro Fol The A s	6-22-2015, 04:09 PM Â #715 Â JA Â 6-22-2015, 04:09 PM Â #715 Â JA Â Ony Bogs A Join Date: Apr 2 Posts: 609 Posts: 609 Re: Another homebrew AC-controller Posts: 609 E tuners surely will think it's easy. ICE controllers are stuffed with all kinds of 3D maps. Basically a 2D an flash. t the Australian pedal map has simple square functions. n be implemented with the simple equation b = a * a or MUL R1,R0,R0 I guess (have to check the stm32 ogramming manual for the exact assembler syntax)	2014 ray 2F1
ICE in f But Car pro Fol The A s tha Btv	6-22-2015, 04:09 PM A #715 Â QAA Doin Date: Apr 2 Posts: 609 Re: Another homebrew AC-controller E tuners surely will think it's easy. ICE controllers are stuffed with all kinds of 3D maps. Basically a 2D ar flash. t the Australian pedal map has simple square functions. n be implemented with the simple equation b = a * a or MUL R1,R0,R0 I guess (have to check the stm32 oparaming manual for the exact assembler syntax) lowed by a few other simple artmetic functions for the speed dependency. e map I posted is an ICE like map. set of functions that closely match the solutions to the differential equation	2014 ray 2F1
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December 2010 Service 2010 S	6:22-2015, 04:09 PM A #215 Å () Å 6:22-2015, 04:09 PM A #215 Å () Å 0 ny Bogs A nov Member A A Participation B Euners surely will think it's easy. ICE controllers are stuffed with all kinds of 3D maps. Basically a 2D and flash. t the Australian pedal map has simple square functions. no be implemented with the simple equation b = a * a or MUL R1, R0, R0 I guess (have to check the stm32 bigramming manual for the exact assembler syntax) Blowed by a few other simple artmetic functions for the speed dependency. e map I posted is an ICE like map. set of functions that closely match the solutions to the differential equation at governs the combustion in an ICE in relation to the throttle position (valve opening) and engine speed w, the nonlinear function in throttle.png looks like it is also a close match to two square functions, participative. t edited by Tony Bogs; 06-22-2015 at 04:20 PM. Reason: Added sentence about throttle.png	2014 ray 2F1
December 2010 Service 2010 S	6-22-2015, 04:09 PM Â #715 Â ÇLÂ Conversion Â Only Bogs Â State A Better homebrew AC-controller Better homebrew AC-controller E tuners surely will think it's easy. ICE controllers are stuffed with all kinds of 3D maps. Basically a 2D and flash. t the Australian pedal map has simple square functions. n be implemented with the simple equation b = a * a or MUL R1,R0,R0 I guess (have to check the stm32 bogramming manual for the exact assembler syntax) llowed by a few other simple artmetic functions for the speed dependency. ee map I posted is an ICE like map. set of functions that closely match the solutions to the differential equation at governs the combustion in an ICE in relation to the throttle position (valve opening) and engine speed w, the nonlinear function in throttle.png looks like it is also a close match to two square functions, partingative. t deited by Tony Bogs; 06-22-2015 at 04:20 PM. Reason: Added sentence about throttle.png	2014 ray 2F1
December 2010 Service 2010 S	6:22-2015, 04:09 PM A #215 Å () Å 6:22-2015, 04:09 PM A #215 Å () Å 0 nov Bogs A nov Member A A Posts: 609 Posts: 609 Posts: 609 Re: Another homebrew AC-controller Posts: 609 E tuners surely will think it's easy. ICE controllers are stuffed with all kinds of 3D maps. Basically a 2D an flash. t the Australian pedal map has simple square functions. n be implemented with the simple equation b = a * a or MUL R1,R0,R0 I guess (have to check the stm32 bigramming manual for the exact assembler syntax) llowed by a few other simple artmetic functions for the speed dependency. e map I posted is an ICE like map. set of functions that closely match the solutions to the differential equation at governs the combustion in an ICE in relation to the throttle position (valve opening) and engine speed w, the nonlinear function in throttle.png looks like it is also a close match to two square functions, parthgative. t edited by Tony Bogs; 06-22-2015 at 04:20 PM. Reason: Added sentence about throttle.png	2F1





As the speed of the car increases, the maximum reaen brakina level and the toraue to pedal response also

increase proportionally to the And that's just right. A driver			f the car.	
In some cases the only way to get efficient and/or fast (enough) code is to use assembler. That's just how it is.				
Of course, one prefers higher level languages for readabilityINLINE and comments do help.				
The readability of RBIT in C is questionable.				
I really like the idle speed control. No external pump for the auto tranny.				
ADDED for clarity. Pedal to speed match: pedal is somewhere close to the point where the torque and speed are in balance for maintaining a certain speed. The map in the insideevs.com link is the right map. With negative torque values in the regen area. The direct link to the Australian pic has positive regen torque values, which might be confusing. Of course, the PARAM (brkmax?) for max <u>Regenerative Braking</u> also shifts with speed. Low values at low speed and matching low pedal value.				
Last edited by Tony Bogs; 06-23-2	015 at 02:55 PM. Re	ason: Added readability of RBI	T in C,INLINE takes two statem	nents.
			Quote	1
Post Reply	Page 72 of 22	21 Â « First < 22 62 70 71	72 73 74 82 122 172 > Las	st » 🔽
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Â Controllers



Exactly. This is what CalcThrottle looks like when I add the shifting of brknom and brkmax v	
Makes the PARAM brknompedal and probably brkrampstr obsolete. The map stays linear. Some prefer it that way. But with dynamic (speed shifted) zo Quote:	
int Throttle::CalcThrottle(int potval, bool brkpedal, int speed)	
<pre>{ int potnom = 0; // Added 2 lines of code; shift brknom and brkmax speed (frequency) with spee // Without shaft speed sensor frequency shifting always works: // call with frequency converted to speed value</pre>	ed.
<pre>int brknomspeed = (speed * brknom) / speedmaxvalue; int brkmaxspeed = (speed * brkmax) / speedmaxvalue; // MUST DO: add declaration for speedmaxvalue = value of VAR speed @ fweat // Or choose another frequency/speedpoint</pre>	k (PARAM)
if (brknomspeed > brknom) brknomspeed = brknom; if (brkmaxspeed > brkmax) brkmaxspeed = brkmax;	
<pre>// brkpedal means no foot on throttle > potnom stays 0 if (!brkpedal) potnom = potval - potmin;</pre>	
// replaced brknom with brknomspeed and bkrmax with brkmaxspeed below	
<pre>potnom = ((100 + brknomspeed) * potnom) / (potmax-potmin); potnom -= brknomspeed; if (potnom < 0) potnom = (potnom * brkmaxspeed) / brknomspeed;</pre>	
return potnom;	
	📝 Quote 😰 🏹 🔗
06-24-2015, 01:01 PM	â # <u>725</u> â 🐢 â <u>۸</u> â
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew AC-controller	
Re: Another homebrew AC-controller Great! I'll test it onboard as soon as I can.	
D	
Great! I'll test it onboard as soon as I can.	(VQuote) 🔀 📝 🔗
Great! I'll test it onboard as soon as I can.	# <u>726</u> 🛺 Â
Great! I'll test it onboard as soon as I can. <u>VW Polo 86C High Voltage AC Conversion</u> - <u>AC Motor Inverter Kit</u> 06-25-2015, 04:24 PM	# 726 ॖ ि Â Join Date: Dec 2009
Great! I'll test it onboard as soon as I can. <u>VW Polo 86C High Voltage AC Conversion</u> - <u>AC Motor Inverter Kit</u>	# <u>726</u> 🏠 🧥 Â
Great! I'll test it onboard as soon as I can. <u>VW Polo 86C High Voltage AC Conversion</u> - <u>AC Motor Inverter Kit</u> 06-25-2015, 04:24 PM <u>dcb</u> Senior Member Â	# 726 ॖ ि Â Join Date: Dec 2009
Great! I'll test it onboard as soon as I can. <u>VW Polo 86C High Voltage AC Conversion</u> - <u>AC Motor Inverter Kit</u> 06-25-2015, 04:24 PM <u>dcb</u> Senior Member Â	# 726 ॖ ि Â Join Date: Dec 2009
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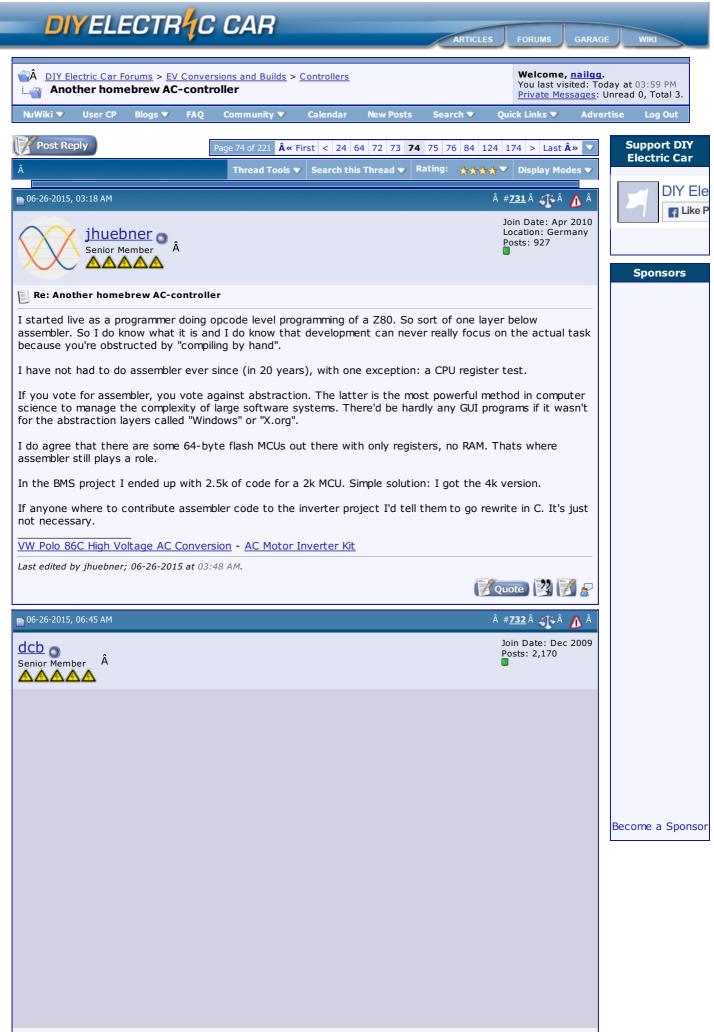




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Quote:

Originally Posted by jhuebner 5

If you vote for assembler, you vote against abstraction.

It isn't all or nothing. Sometimes it does make sense, in large volumes or when there is no sane way to do something otherwise (i.e. with cycle level precision). And nobody these days is saying ditch C completely for assembler, yet plenty of folks are too willing to ditch assembler even when it does make sense to use it.

Quote:

Originally Posted by **jhuebner** The latter is the most powerful method in computer science to manage the complexity of large software systems.

An inverter or a charger isn't a large software project.

Quote:

Originally Posted by **jhuebner D**

If anyone where to contribute assembler code to the inverter project I'd tell them to go rewrite in C. It's just not necessary.

I cannot think of an absolutely necessary reason for assembler on your particular inverter project.

But you and I had the benefit of learning assembly at some point, and as a result we know how CPU's "think". Younger programmers are often not able to bridge the gap between the abstraction and reality if we constantly deter them, for no good reason, except abstraction, which is occasionally divorced from reality.

Besides, a bigger faster CPU generally consumes more power, throw more hardware at it is rarely the right answer if a software solution exists. I see little problem in adding ram, but there is no good universal fix for timing slop except to narrow it down to actual CPU cycles.

Besides, C is really good at mixing the two.

an impressive demonstration of what can be done with an atmega88 and assembly (it is admittedly madness, but demonstrates lots of precise timing solutions and space utilization): https://www.youtube.com/watch?v=sNCqryINY-0

Voting for complete prohibition of assembler is voting for ignorance.

 $I \mbox{'ve}$ actually seen something of a resurgence of assembler in microcontrollers recently, and given the totalitarian attitudes of the last decade, that is a good thing.

Last edited by dcb; 06-26-2015 at 07:29 AM.





That demo apparently did the sound processing during the horizontal blanking periods, and other processing

during vertical blanking. That is reminiscent of the old Clive Sinclair's ZX80/81, which did that in "slow" mode on a 3.25 MHz CPU with only 1k RAM and 4k EPROM. It used some of the extended 8 bit ASCII characters as tokens for assembler commands.

https://en.wikipedia.org/wiki/ZX80

I think all programmers should learn the basics of logic (NAND, NOR, NOT) and basic hardware functions (flipflops, adders, shift registers), and the basic assembler code for simple programming. Just as it is important for most people to learn basic number theory, manual addition, subtraction, multiplication, and division, and also learn how to use a slide rule (and why it works). There is a recent movement (<u>reform math</u>) that assumes everyone has access to a calculator and no need for manual processes, but I think it's important to know the basics.

It is already evident that the proliferation of cell phones has largely compromised peoples' ability to think for themselves and converse face-to-face, and the "drive by wire" and collision avoidance measures may eventually eliminate the ability to drive safely and perform maneuvers like parallel parking. I think it is similar in the case of programming.

Of course, writing a Windows GUI program requires a high level language with a great deal of abstraction from bit-banging code, but for microcontrollers I contend that you should refer to a copy of the chip's data sheet for details on registers and architecture, unless you are doing hobby-level work on a BASIC Stamp or Arduino. I do most of my PIC programming using C, especially since I have a good optimizing compiler, but occasionally I need to fine tune timing of ISRs or reduce latency and overhead, or make sure certain code is located in a particular place in flash memory, and that generally requires some assembler and a deeper level of knowledge.



#<u>735</u>Â 🌆 Â

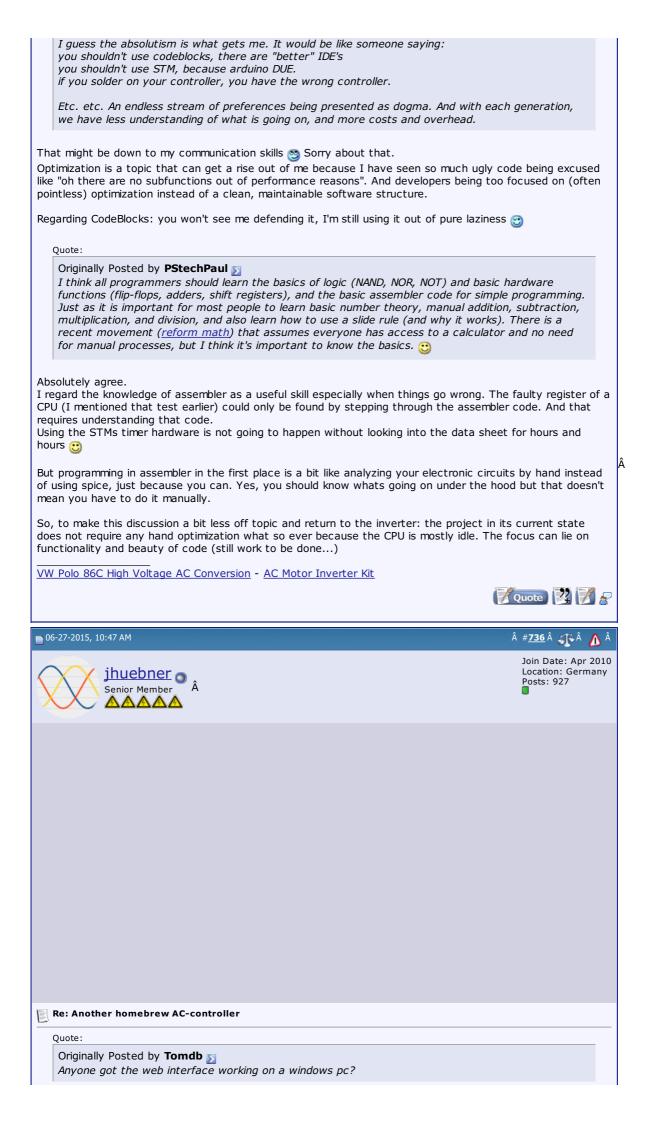
🗖 06-27-2015, 06:04 AM



Join Date: Apr 2010 Location: Germany Posts: 927

Δ

Re: Another homebrew AC-controller





precharge. Yes I should have checked before attempting a reconnect. So : One channel had its transorb , ACNW3190 driver and DC DC converter blown. Replaced these and ran some tests with a lightbulb in series to

prevent any more fireworks. No motor action and the inverter whine sounded "wrong". Got out the scope. All 6 transistors were driving fine on the gates but what's thisthe channel thad had blown was ringing slightly on the gate where the other 5 were solid square waves. Broke out the HV differential probe and looked at the C-E on all 6 IGBTS when running at Fslip 10 ampnom 10 in manual mode with light bulb current limiter on the HV. The bad one was displaying a funny sort of "double dip" on it's C-E. Replaced the module and rewired everything and we are back in business. Has anyone ever experienced and IGBT to half fail? I can test this on the bench with a 12v lamp and it switches it on and off no problem. More critically , what the heck caused those Panasonic contactors to weld. Cause or effect? One thing I don't like is the idle ramp up is super fast. With the torque converter and flexplate on the shaft it takes an almighty surge when starting up. 220A at 275v on my Fluke! IS there any way to slow the ramp up when starting up on idle? Also the throttle is very coarse. Perhaps my settings? I disabled idle selected R to reverse out of the shed and gave it a little gas. The motor wound up and I headbutted the steering wheel Thoughts? P.S. anyone have any CM600DY 12NF IGBTs spare? Now, Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. www.evbmw.com Quote 🕺 🕅 두 **06-29-2015, 01:51 PM** #<u>739</u>Â 🎢 Â Join Date: Apr 2010 jhuebner O Â Location: Germany Posts: 927 Senior Member Re: Another homebrew AC-controller I only have a crude theory about the IGBT failure. I think something caused the DC/DC to fail which leaves only the voltage in the 100Å μ caps to supply the driver. As that only starts to lock out at 11V Vcc-Vee you are operating the IGBT with only 5.5V for at least one cycle which is dangerously close to its threshold voltage. Linear region - bang. The root cause for the DC/DC failure is till to be determined. Over temperature? Current surges? (Unlikey with the 100µ caps) Quote: Originally Posted by jackbauer 🔊 One thing I don't like is the idle ramp up is super fast. With the torgue converter and flexplate on the shaft it takes an almighty surge when starting up. 220A at 275v on my Fluke! IS there any way to slow the ramp up when starting up on idle? Also the throttle is very coarse. Perhaps my settings? I disabled idle selected R to reverse out of the shed and gave it a little gas. The motor wound up and I headbutted the steering wheel Concerning the idle ramp you can lower idlekp. There is no ramp, just a simple P-controller. If that doesn't help I'll have to think of something else. Concerning throttle I can't tell how much of it is caused by the motor and how much by the transmission. Is just as bad with the idle loop enabled? How about the forward gears? You can use the BMS input to limit throttle. I have connected the BMS input to the reverse gear contact and am limiting throttle to 30%. That function requires an update to the recent software. VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit Last edited by jhuebner; 06-29-2015 at 02:35 PM. Reason: Added theory 📝 Quote 🕎 🏹 🔎 #<u>740</u>Â 🌾Â <u> </u>Â 🗖 06-30-2015, 06:39 AM Join Date: May 2009 Weisheimer Location: Columbus, Ohio Senior Member Posts: 151 Â A A ARe: Another homebrew AC-controller

Damien,				
Your failures were most likely started by a failed DC/DC and then cascaded from there.				
As regards the throttle way?	As regards the throttle sensitivity and ramp up rate, did it change after the failure, or was it always that way?			
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Post Reply	Page 74 of 2	21 Â « First < 24 64 72 73	74 75 76 84 124 174 > Last Â≫ ▼	
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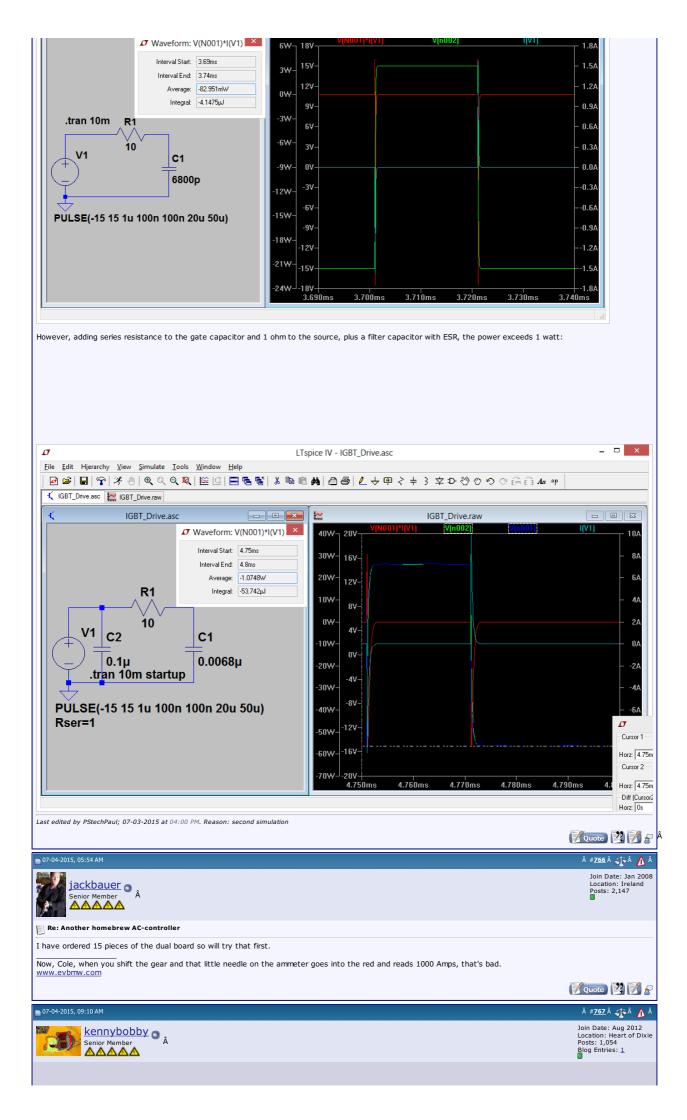


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	Join Date: Jan 2008	f Like P
jackbauer senior Member Â	Location: Ireland Posts: 2,147	
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Re: Another homebrew AC-controller Thinking about the driver schematic , is it fair to use the top side kelvin emitter as the bottom side collector connection for the bottom	am cida dasat?	-
Now, Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad.		
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jackbauer Â	Location: Ireland Posts: 2,147	
Re: Another homebrew AC-controller		-
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07-03-2015, 03:01 PM	# <u>763</u> 🐠 🥻 Join Date: Jan 2008	
jackbauer Â	Location: Ireland Posts: 2,147	
Re: Another homebrew AC-controller		-
Boards ordered from Seeedstudio. Should be here in about 10 days. Next move is to make a 6 way board. IE a full three phase driver Now, Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad.	caro.	Become a Sponsor
www.evbmw.com		
07-03-2015, 03:05 PM	# <u>764</u> 🐴 🥻 Â	4
Tomdb Senior Member Å	Location: Warwickshire, UK Posts: 798	
	8	
Re: Another homebrew AC-controller		
Are you going for direct mounting to the igbt's?		-
Why bunch all the boards togethor? I believe you want a short a path as possible from the gate driver to the IGBT and when making a family of the second sec	a single board this make you less	
flexible. But what I am really interested in is the total parts cost, with or without pcb.		
	📝 Quote 😰 📝 🖉	>
07-03-2015, 03:47 PM	# <u>765</u> 🎝 🧥	
	Join Date: May 2012	
PStechPaul Senior Member Â	Location: Cockeysville, MD 21030 Posts: 3,118	
Re: Another homebrew AC-controller Turnuld at least law out the board so that the drivers could be cut and senarated and then connected with ribbon cable or similar may	ans. That would provide more	-
I would at least lay out the board so that the drivers could be cut and separated and then connected with ribbon cable or similar mea flexibility.	ans. That would provide more	
Here is a simulation of an IGBT gate drive using 10 ohms and 6800 pF at 20 kHz and +/-15V. Power seems to be well under 100 mW:		
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K IGBT_Drive.asc K IGBT_Drive.raw		
K IGBT_Drive.asc □ □ 🖾 IGBT_Drive.raw		



Re: Another homebrew AC-controller

Quote:

Originally Posted by **jackbauer** *Take two*

Is this intended to mount to the CM600DY-12NF igbt? If this is to scale, then the spacing for the terminals doesn't look right.

These igbt are duals and have both a top and bottom transistor--are you just using half of each device for some reason?

📝 Quote) 🕎 📝 🔗

07-05-2015, 04:39 AM	# <u>768</u> 🎝 Â
jackbauer Senior Member Â	Join Date: Jan 2008 Location: Ireland Posts: 2,147
Re: Another homebrew AC-controller	
It's a dual driver. High and low side.	
Now, Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads www.evbmw.com	1000 Amps, that's bad.
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■ 07-05-2015, 05:03 AM	# <u>769</u> "T ê 🔥 Â
EVElvis	Join Date: Jun 2009 Location: Sussex UK
Member A	Posts: 99
Re: Another homebrew AC-controller	
Hì	
Sorry to change the subject a bit. Im not as far advanced with my kit. Greatly appreciate the help pro	vided on this thread.
Please can anyone suggest why I cannot install the firmware? Tried Lubuntu and my raspberry Pi. Both Any suggestions greatly appreciated.	give me the error shown in the attached picture.
Cheers Tim	
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07-05-2015, 12:12 PM	# <u>770</u> 🎝 🧥 Â
	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew AC-controller	
Quote: Originally Posted by EVElvis <i>Hi</i>	
Sorry to change the subject a bit. Im not as far advanced with my kit. Greatly appreciate the hel	
Please can anyone suggest why I cannot install the firmware? Tried Lubuntu and my raspberry Pi. Any suggestions greatly appreciated.	. Both give me the error shown in the attached picture.
Cheers Tim	
You are using a binary compiled for i386 cpus on an ARM CPU. Thats causing the error.	
You can use the python version of the updater: Code:	
python updater.py -f stm32_sine.bin -d /dev/ttyUSB0	
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<u>DIY Electric Car Forums</u> > <u>EV Co</u> Another homebrew AC-cc	nversions and Builds > <u>Controllers</u> ontroller		Welcome, nailgg. You last visited: To Private Messages:	day at 03:59 PM
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ÊVEIvis Member Â		Loc	n Date: Jun 2009 ation: Sussex UK its: 99	Like P
Re: Another homebrew AC-cont	roller			Sponsors
Thanks Johannes Never have worked that out myse Not quite there yet and get anoth Ill try again after dinner. cheers Tim		Â		
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arber333 Senior Member Â		Loc	n Date: Dec 2010 ation: Slovenia sts: 782	
Re: Another homebrew AC-cont	roller			
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Re: Another homebrew AC-cont	roller			
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From the picture it looks like there maybe a magnetic pickup device v	e is already some sort of encoder/speed with a toothed wheel?			
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Now, Cole, when you Amps, that's bad. www.evbmw.com	shift the gear and that lit	tle needle on the ammete	r goes into the red and reads 1000
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■ 07-07-2015, 02:50 PM			â # <u>780</u> â 🐠 â 🦄 â
jackbaue Senior Membe			Join Date: Jan 2008 Location: Ireland Posts: 2,147
📃 Re: Another homet	orew AC-controller		
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	ls from the IGBT driver bo es brought out to the Amp		inhibit system. Throttle has scaling on planes.
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Now, Cole, when you Amps, that's bad. www.evbmw.com	shift the gear and that lit	tle needle on the ammete	er goes into the red and reads 1000
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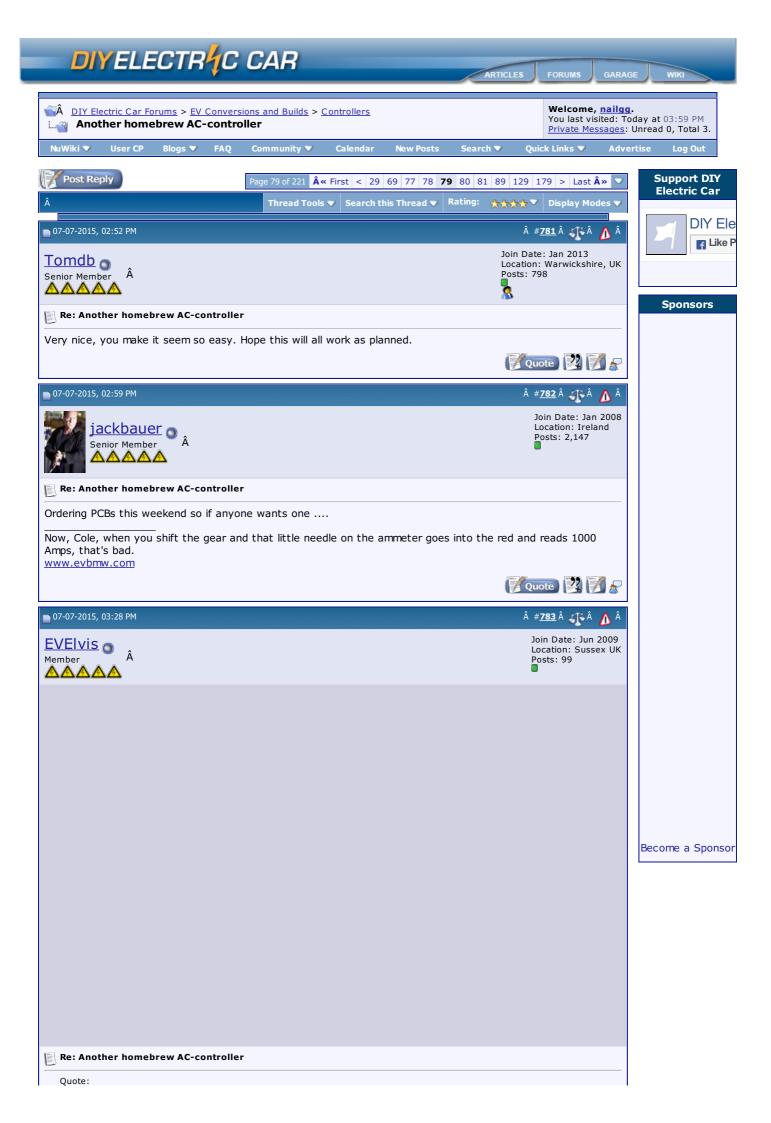


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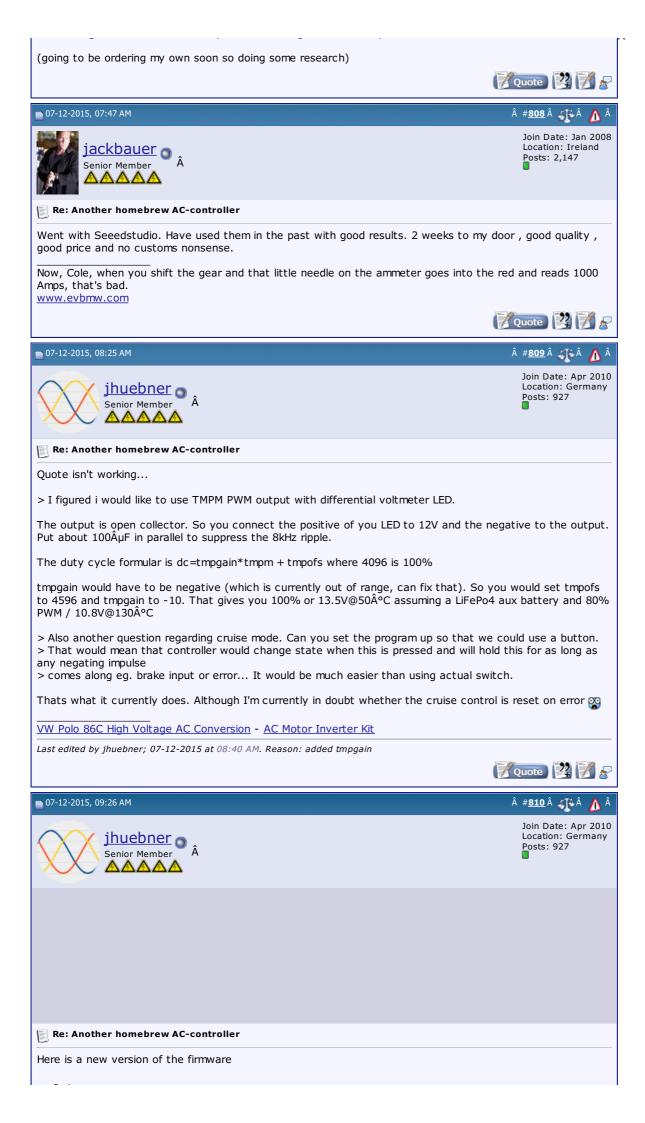
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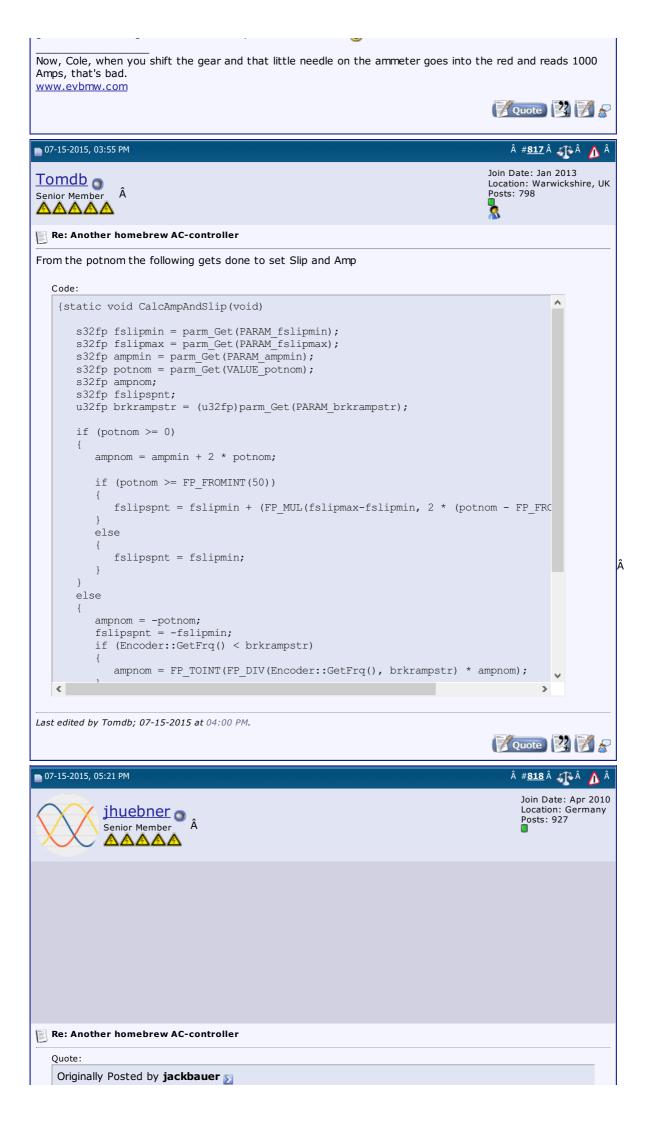
So I think I might be able to explain the welded contactors. Was running some pre charge tests this evening using a filament lamp. Pack voltage 280v , reading 282v in the inverter. UDCSW set at 250v. Placed a 100w 240v filament lamp in place of the pack fuse. At key on the negative contactor and precharge relay close (pre charge resistor is 10R 100w) and the lamp illuminates and begins to dim as the caps charge. Less than a second later the main contactor closes with lots of brightness left on the lamp so that over a period of cycles would have hurt the contactors. So i played with the parameters for UDCGAIN and UDCSW a bit where I could get the inverter to read 275v and set udcsw at 240v. Again with the lamp in place it starts off bright and ran to fully extinguished but the main contactor never closed and inverter state equalled OFF. So I quickly recycled the key , not giving the bus caps time to discharge and all contactors close and inverter is in RUN mode. Is there a precharge time out somewhere in the code?

Once I got that sorted I started playing with the idle speed and idle kp. Had idlekp set at 1. Any larger number causes the motor to hunt between rpm. The startup at key on and 500rpm idle is very abrupt and my fluke clamp meter caught a 150A surge. Is there any way to have an idle soft start?

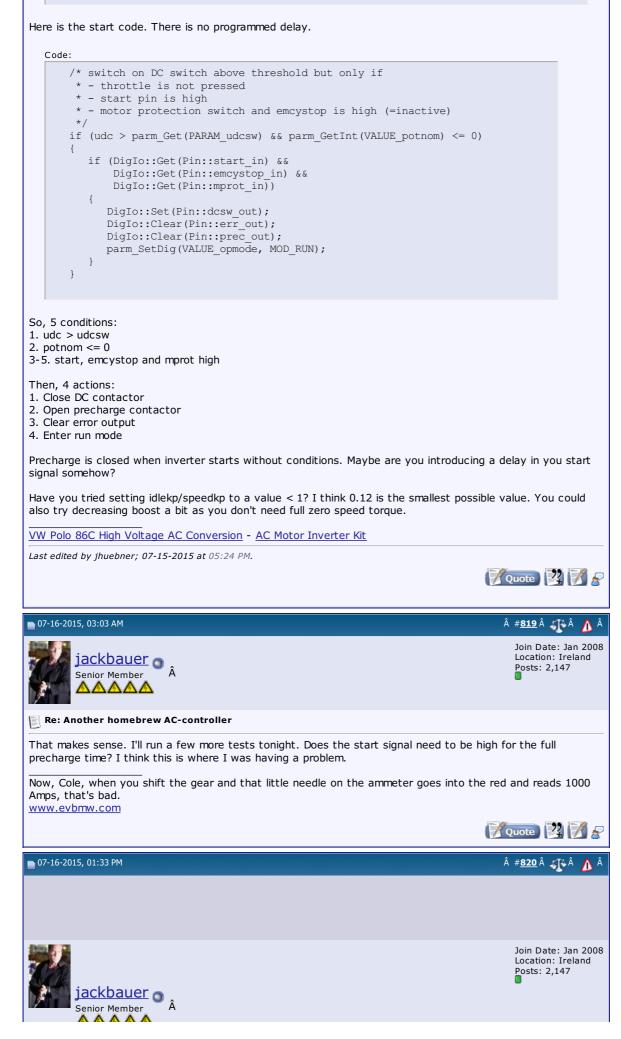
In other news , the new PCBs are processing hapilly \bigcirc I should have them in about 10 days. BOMs underway also.

Now, Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad.





I can confirm that the precharge will not engage the main contactor if the precharge time is more than a few seconds



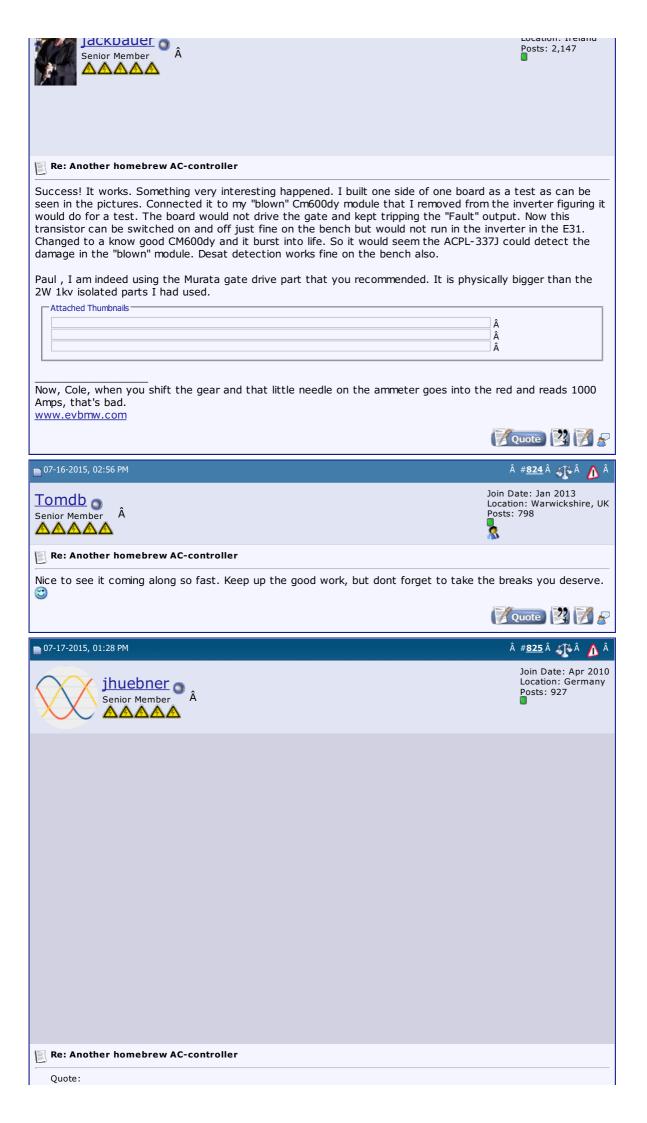
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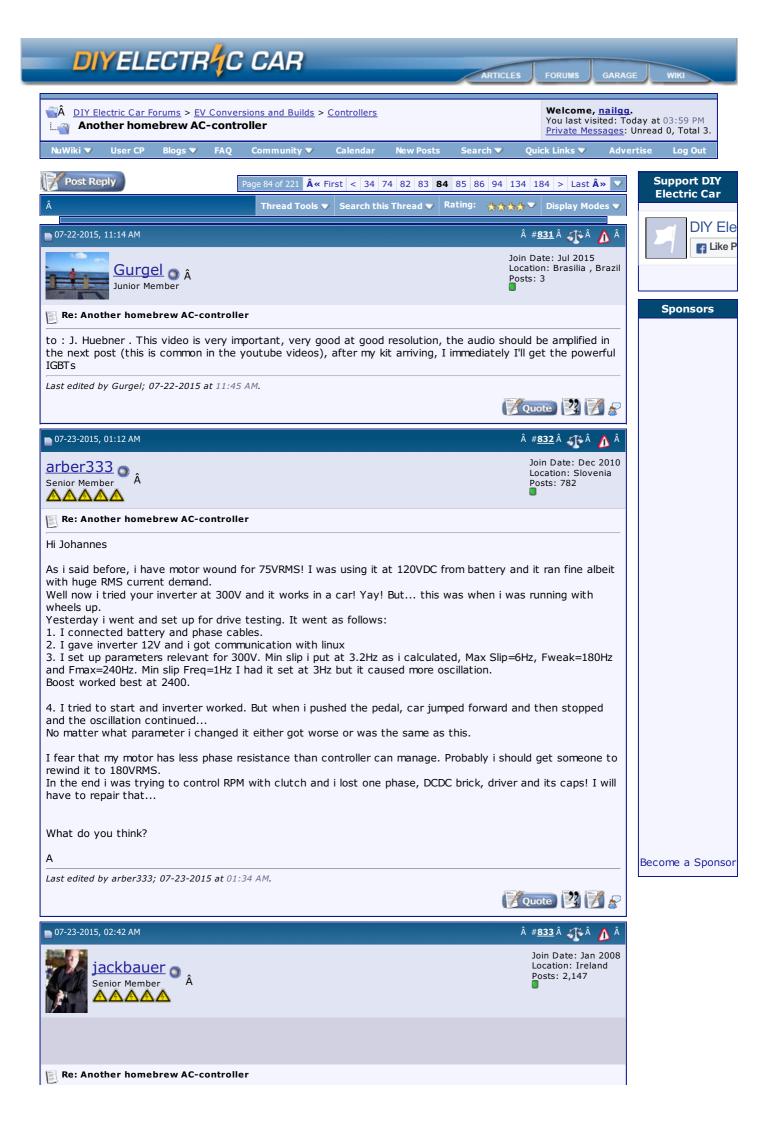




Now, Cole, when you sh Amps, that's bad. www.evbmw.com	ift the gear and that littl	e needle on the ammet	er goes into the red and reads 1000
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understand why they cannot be dealt with. The peak current of each PWM pulse before saturation depends on the winding inductance, applied voltage, and time, so I can see where a low voltage motor driven from a high voltage source could quickly see current rise to the point of saturation, at which point only winding resistance (and the rest of the circuit) limits the current.

The construction and operating conditions of the motor may have some effect on the inductance. If the gap between the rotor and the stator is wide, the inductance will be lower, so for a rewound motor it may be important to choose one that has a tight fit. I would think such close spacing would also provide higher torque, but it may also contribute to friction at higher speeds due to the "windage" or resistance of air. Then again, it may act as an "air bearing".

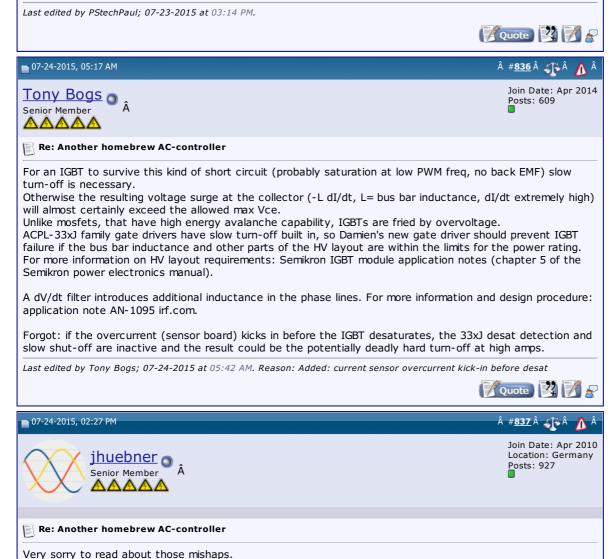
The effective inductance is also influenced by the coupling of the stator to the rotor, and the inductance and resistance of the rotor squirrel cage will be reflected as a complex impedance at the motor's windings.

In any case, however, there should be a practical lower limit to the possible inductance and resistance that can be presented to the controller by a motor and its connections, and the controller also should be able to withstand a short circuit. For that to be possible, there may need to be internal resistance and inductance that limit the di/dt of the current as well as its maximum value so that internal sensors have time to shut down the system before damage is done.

Adding inductance to the motor lead connections, along with some capacitance, may be able to filter out the PWM carrier frequency to some extent and improve efficiency as well as reduce radiated noise and losses in the cables, motor windings, and bearings. I don't think such inductors would need to be very large or costly. Probably some ferrite, powdered iron, or even tape steel toroids, with a few turns of wire, would be sufficient.

Another idea I had was to make an adjustable voltage bus so that, at low speeds, a higher PWM value could be used, and a much lower dV/dt would be imposed on the motor windings. This could be accomplished with a simple buck converter front end that could reduce the bus voltage from, say, 350 VDC, to 180 VDC or even 90 VDC. The converter need not handle the maximum power requirement, as that could be accomplished by bypassing it entirely with a power relay. Another alternative would be a relay matrix that could connect two or four battery packs in combinations of series and parallel depending on need. Transition may be difficult, but there may be ways to smooth out the doubling or halving of the bus voltage.

This might be a topic for a separate discussion, if anyone thinks it may have merit. I think I have seen articles on something similar, and I may have even proposed it elsewhere some time ago. It may or may not be practical or even feasible, but it may be interesting to talk about.



I can't see any nonliam with the narameters excent northans houst 2100 (-1011) seems a hit much for a 7511



Fig 5.2.14 in chapter 5 (In (low phase frequency).	GBT module application	on) shows the peaks in the	junction temperature a	at startup
Fig 5.2.13 shows the hug 5 Hz and 50 Hz. Simulatio		ences in junction temperat	ure at very low freq (cl	ose to 0 Hz),
So it's better to think twice before running a setup at low phase freqs without checking the cooling.				
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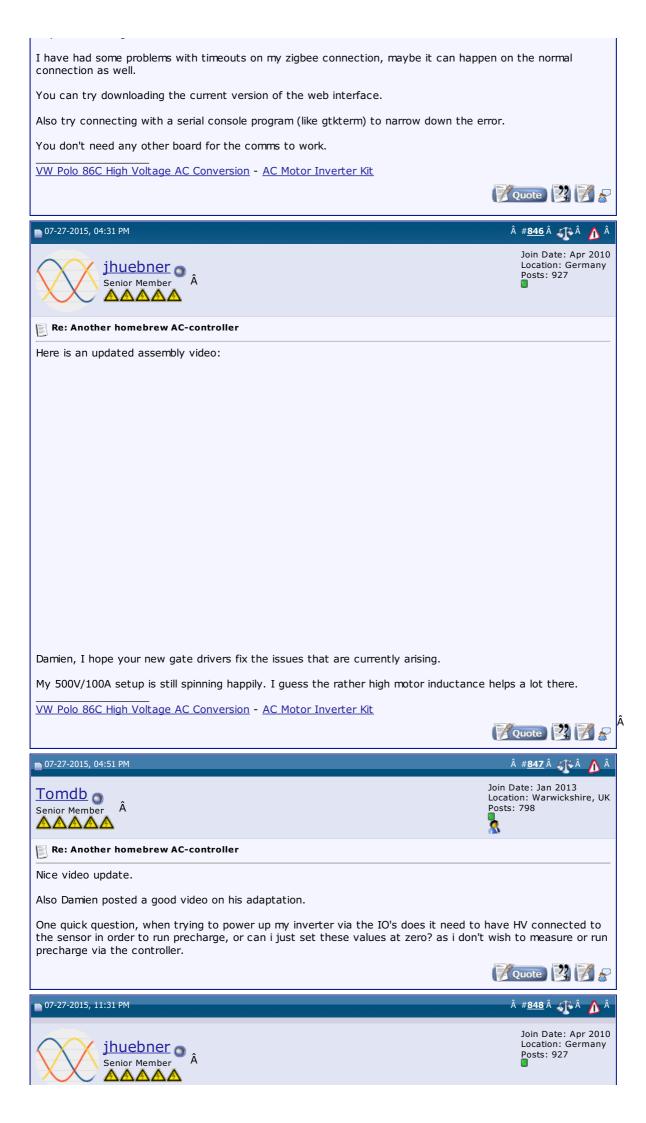
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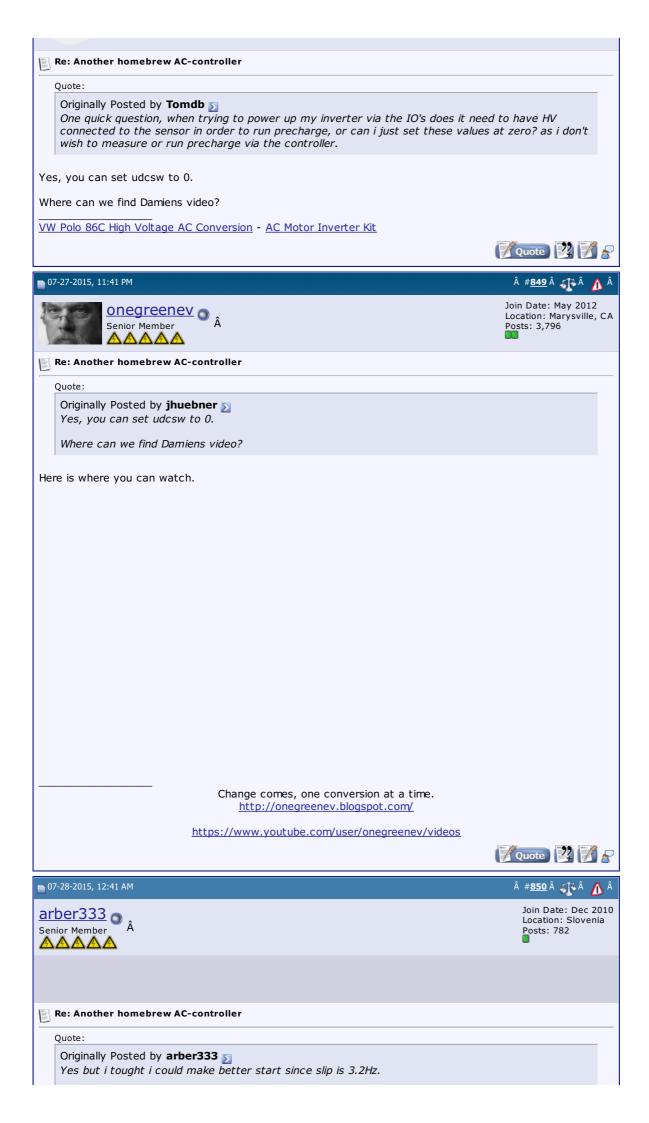
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Now, Cole, when you shift the gear Amps, that's bad. www.evbmw.com	r and that little needle on the ammeter go	es into the red an	d reads 100	0	
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EVElvis Member Â		Loc	n Date: Jun 2 cation: Susses sts: 99		
Re: Another homebrew AC-contro	oller				
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arber333 Senior Member Â		Lo	n Date: Dec 2 cation: Slover sts: 782	nia	ecome a Sponsor

Quote:	
Originally Posted by EVElvis D	
Hi All Just powered up the board and tested all ok as described in Johannes video. Just power with olimex board connected up to main board. Web interface opens up of Please can anyone tell me why my web interface does not show the parameter to connected up to board with olimex on? Software went on ok and green LED flash Sure its something simple, but I am very green when it comes to this. Any pointers appreciated. cheers Tim	k - localhost:8000. tables when
Hi	
In folder Web Interface inside software you have one readme file that has instruction: (apache) server. When you do this then you should be able to start your interface.	s how to install PHPS
You should start PHP server from console in web interface folder sudo php -Slocalhost:8000	
Keep the console open	
then you can start your browser and type localhost:8000	
Warning! I found out that in Lubuntu firefox browser remembers your input and sugge you just hit enter then web interface will not work completely. You should truly write then hit enter!	
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07-27-2015, 07:22 AM	â # <u>844</u> â 🐠 â <u> â</u> â
EVElvis Member Â A	Join Date: Jun 2009 Location: Sussex UK Posts: 99
🛐 Re: Another homebrew AC-controller	
Thanks	
Ill try later tonight, hopefully.	
I run Lubuntu, after trying Ubuntu (Too much for my old laptop)	
I did wonder whether I should have had the sensor board connected?	
Now I have asked it should work :-)	
Cheers	
Tim	
Last edited by EVElvis; 07-27-2015 at 07:26 AM.	
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07-27-2015, 12:24 PM	# <u>845</u> ∡∏ ∿ ∧ Â
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew AC-controller	
Any error message?	





	<i>I also tried boost with 700, 1400, 2400, 3000, 4000!</i> At 700 motor just threw OClimit, when pedal reached 30%, it didnt even turn. At 1400 it was turning but with too much force. With larger boost things just went worse <i>I also varied with slip, max slip from 4Hz to 6Hz and i tried even low slip from 1.5Hz to 4Hz.</i>							
			voltage with acceleration led motor jumps dangero	that requires lots of amps. I usly.				
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We	Well i made post mortem							
			of of middle IGBT was dea ! I guess i know now wha	d, nothing specialbut, when that bang was.	i			
on Iow Hul	some Fuji 2MBI450U4E- resistance gates? Tha	-120 igbts but they ha its almost nothing! Rg with Murata +15/-8	ve Rg 0,68R!!! Does anyo	ed to be replaced. I got a good ne have any experience with su en i can use my drivers to 4A f	uch			
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Originally Posted by PStechPaul Looks like 6R8 would increase the switching times from about 400 nSec to 8 lot more switching energy for turn-on using the higher resistance, so mayb across the resistor to get a fast turn-on and slower turn-off.	300. One graph shows a e you can use a diode	
<u>http://www.ixys.com/Documents/AppNotes/IXAN0010.pdf</u> (shows diode for off)	slow turn-on, fast turn-	
Hm, i think i can go up to Rg 4R7 max because of $+15V/-8V$ DCDC regulators and that gate gets little more than 3A for on pulse and 2A for shutoff. Can you tell v curve?		
I could put one Rg 4R7 and one parallel another 4R7 with one superfast diode in would be sharper. Which one would be better?	series reversed so one slope	:
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■ 07-29-2015, 03:02 PM	# <u>857</u> ∡∰ ∧♪	Â
jackbauer Senior Member Â	Join Date: Jan 200 Location: Ireland Posts: 2,147	08 Â
E Re: Another homebrew AC-controller		
First power up test of the new main board complete. communicated with the PC change the pin header on the board to be compatible with standard FTDI cables messing about. Got started on building the sensor board. No problems so far. Wi prototype ready to test at the weekend.	. Will eliminate a lot of	
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Now, Cole, when you shift the gear and that little needle on the ammeter goes i Amps, that's bad. www.evbmw.com	nto the red and reads 1000	
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n 07-29-2015, 05:53 PM	# <u>858</u> ∢∰ 🔥	Â
Tony Bogs Senior Member Â	Join Date: Apr 20: Posts: 609	14
Re: Another homebrew AC-controller		
The gate resistor determines the switching speed of the IGBT or MOSFET as Pst	echPaul mentioned.	—
The IGBT turn-on switching time affects the losses in IGBT and in the diode in the		



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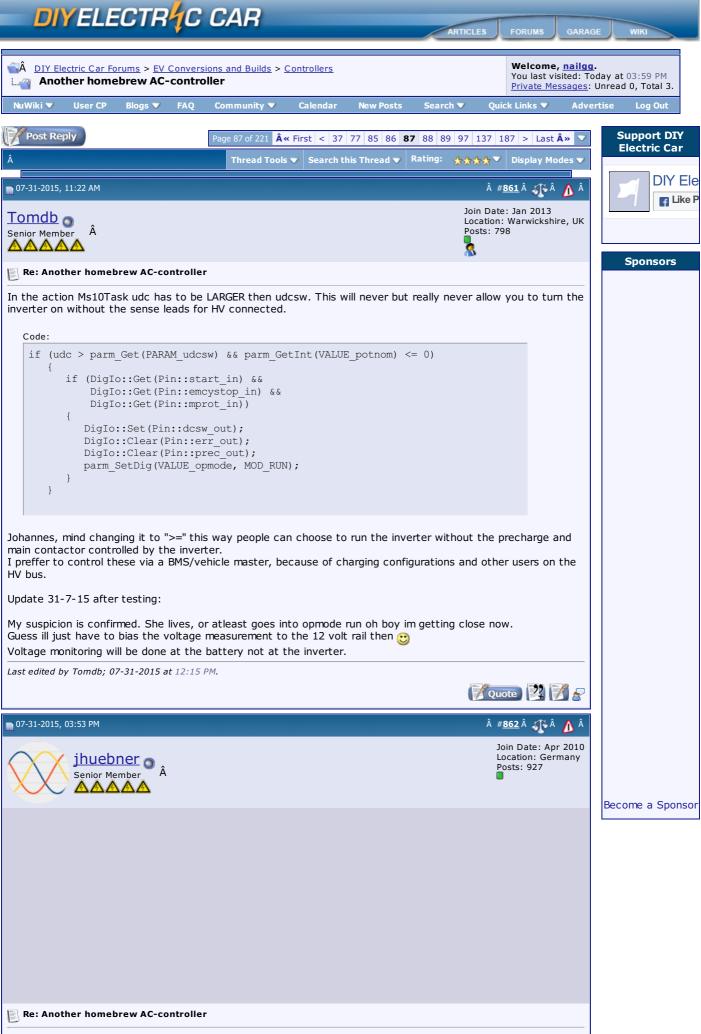
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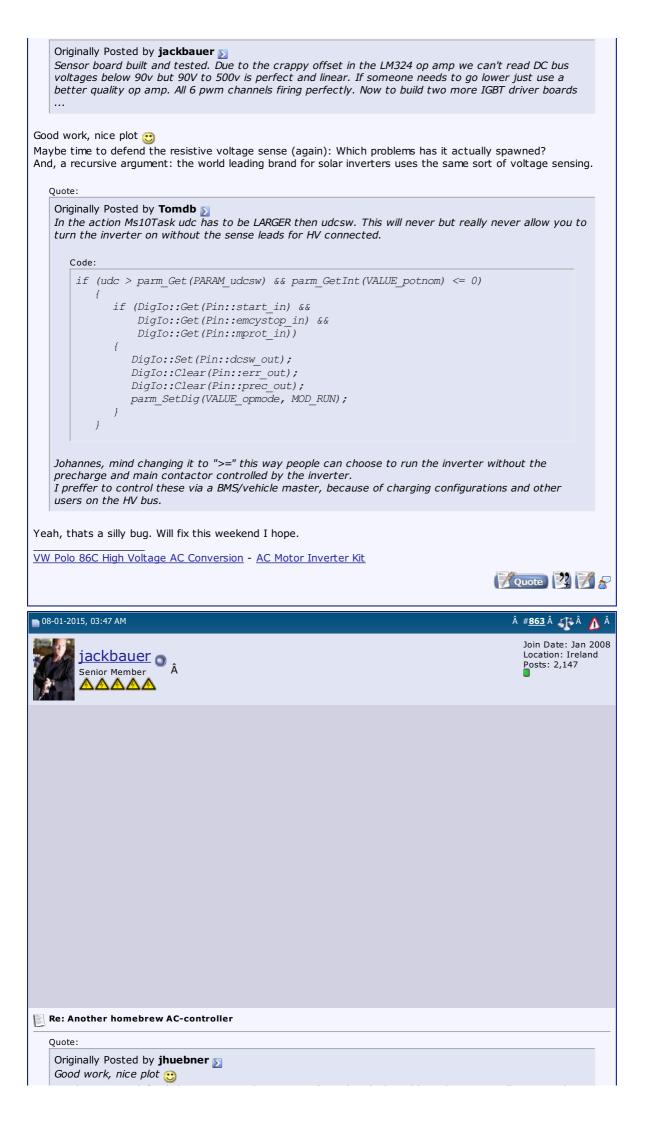
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And, a re sensing.	ime to defend the resistive voltage sense (again): Which problems has it a ecursive argument: the world leading brand for solar inverters uses the sa ats a silly bug. Will fix this weekend I hope.	
galvanic isola SMD solderin	e simplicity of the resistor divider option however in an automotive environm ation. The ACPL C870 system introduces no problems as far as I can tell ot g. I will track the pcb for both options so the builder can choose the one b	her than a bit of simple best suited.
	one driver board attached this morning. Interface between UVLO and FAUL and the hardware PWM interlock working perfectly.	T outputs from the
	פווסדוע	Â
Now, Cole, w Amps, that's <u>www.evbmw</u>		
		Quote 🕎 🖌 🔗
08-01-2015, 02	2:29 PM	# <u>864</u> ∢ ∏ À Å ∧A Â
	ckbauer or Member Â Â Â	Join Date: Jan 2008 Location: Ireland Posts: 2,147
<u> </u>	er homebrew AC-controller	
AC output. If	ve my new inverter built and the hardware seems fine , igbts driving perfec t seems the drive signals are not giving any overlap so no current flows to o shorts on the pcb etc and all channels seem to be on the correct pins.	
	Â Â Â	
Now, Cole, w Amps, that's www.evbmw		red and reads 1000
		🛛 🖓 Quote
08-02-2015, 03	3:01 AM	â # <u>865</u> â 🕂 â 🔥 â
\bigotimes	jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Anothe	er homebrew AC-controller	
Will reply her I think no dir	e again: ection is selected, i.e. neither FWD nor REV high.	
All three sigr	hals look exactly the same on your scope, so no voltage difference between	n them.
Yes, "neutral	" mode is a bit silly right now, I should shut down the PWM all together.	
VW Polo 86C	High Voltage AC Conversion - AC Motor Inverter Kit	
		Vuote 🔀 💋 🔗
08-02-2015, 03	3:22 AM	# <u>866</u> ∕∏ À ⚠Â
	ckbauer Â or Member Â	Join Date: Jan 2008 Location: Ireland Posts: 2,147
💽 Re: Anoth	er homebrew AC-controller	





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Re: Another homebrew AC-controller

Quote:

Originally Posted by jhuebner 🔊

Wow, nice work 😳

Output is fixed duty cycle (50/50) variable frequency up to 500Hz.

Untested yet, thats your job here 😁

Maybe we should spawn the PMSM discussion here, as it is currently going on via various emails.

So my take was to not support PMSM motors at all because I think they're stupid mm (no, not to be taken serious). Now I must admit that there's a lot of synchronous motors around and it could be a real gain for the project to support them.

Of course the plan is to control them in a similar fashion as the async motors, i.e. without FOC and the need for good current sensing.

The differences to async motors in a nutshell:

- No slip needed/wanted
- Absolute rotor angle is of importance
- current lagging voltage must be accounted for
- Accelerating torque generated by setting the electrical angle to the rotor angle + 90Ű
- Decelerating/regen torque generated by setting the electrical angle to rotor angle 90°
- Torque amount controlled by only stator V/Hz

So the idea is to leave out one tooth on the encoder disk to detect the 0° position. Or, more straight forward, to add an additional signal that fires once per turn. Whenever the signal fires, we set the angle to a fixed (configurable) offset that account for the current lag.

Whether this is all going to work must be seen in practice.

OK J you forced my hand 😁

While i wait on rewiring of my ACIM motor I got one PMSM on loan and have made test setup to see if i can drive this beauty with our DIY controller.

This is 40kW nominal PMSM sine comutated axial flux motor. It has 10 pole pairs! and is currently wired to 500VDC at 6000RPM. Oh its weight is cca 13kg....beat that!

Basicaly my intention is next:

- 1. Run the motor with variable speed control
- 2. Run the motor, put some load on it and see it software can hold RPM with load
- 3. Put the thing in a car and drive if feasible.

Load will consist from two wood poles hooked under the motor with ends overlaping motor axis. When i squeeze this setup should load motor at least with 10kW.

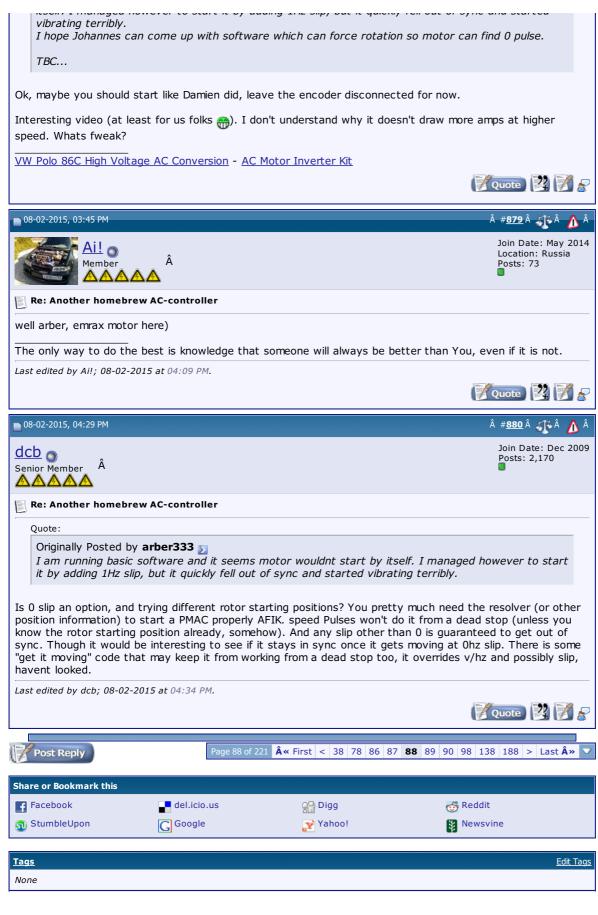
@jackbauer

If you can manage resolver to pulse conversion that would be great!

Up till now i havent succeeded. I am running basic software and it seems motor wouldnt start by itself. I managed however to start it by adding 1Hz slip, but it quickly fell out of sync and started vibrating terribly. I hope Johannes can come up with software which can force rotation so motor can find 0 pulse.

твс...

Attached Thumbnails	Â
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■ 08-02-2015, 11:42 AM	# 878 <i>3</i>] ∳ <mark>∧</mark> Â
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by arber333 Up till now i havent succeeded. I am running basic soft itself. I managed however to start it by adding 1Hz slir	



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Damian's VDC iso amplifier circuit draw my attention back to accuracy

Janiens VDC 150 ampliner circuit arew my attention back to accuracy. The ACPL-C87x seems to have it all: high iso voltage, SMT, high accuracy that matches the other FOC sensor (LEM). I'll modify my main board layout to free up an ADC input (PC5, ADC15). The FOC control system in SW is based on an observer. Accurate measurement of the phase currents and the bus voltage is critical. Measurements are done with the STM32-H103 on chip ADC. It uses a LM1117 adjustable voltage regulator as supply and as a voltage reference. The accuracy is no way near the 1% accuracy of the sensors. The LM1117 has 2% base accuracy over temperature (-40 to 85 degrees C) and the resistors in the divider to set the output voltage are 1% with unknown temperature drift. The STM on chip voltage reference (ADC17 input) is even worse: 5% base. And there's no option to connect an external reference to replace the LM1117. But there is a way to fix the accuracy. It does require HW and SW mods: connect a precision voltage reference to an ADC input for calibration in SW. I've already modified my main board layout: ADC input PC2 (ADC12) is connected to a LT1461AIS reference (0.04% base accuracy). SPEED SENSOR How about a common magnetic pickup. That's the one I'll try first. Often used on AT in- and output shafts and the ICE crankshaft. The output is a sine wave. Nothing simpler than that. The LM1815 is the workhorse for zero crossing conversion to digital in noisy environments. It has been used in huge numbers in cars and it's simple, straight forward and readily available 👩 An AT with a suitable disc and sensor on the input shaft shouldn't be too hard to find on the scrapyard. Usually 60 pulses/360 degrees (frequency matches shaft RPM) MISHAPS Since there have been mishaps, I'll try a low power setup first with cheap but fast PT IGBTs (high PWM freq) and a low cost, low power (few kW) standard motor. 🛛 🖓 Quote 🗖 08-03-2015, 10:44 AM #<u>890</u>Â 🎢 Â Â Join Date: Jan 2008 jackbauer 👩 Location: Ireland Posts: 2,147 Senior Member AΑ Re: Another homebrew AC-controller I would like the PM stuff to remain on thread but that is up to Johannes. Yes , the Siemens motor has an encoder that works fine. I am trying to adapt a common industrial ACIM with an encoder for some tests. I don't want to invest a lot of time in this so an off the shelf solution is preferable but thanks for the suggestions. Now, Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. www.evbmw.com Quote 🕺 📝 🔗 « First < 39 79 87 88 89 90 91 99 139 189 > Last » Post Reply Share or Bookmark this del.icio.us Facebook 😭 Digg 🕳 Reddit

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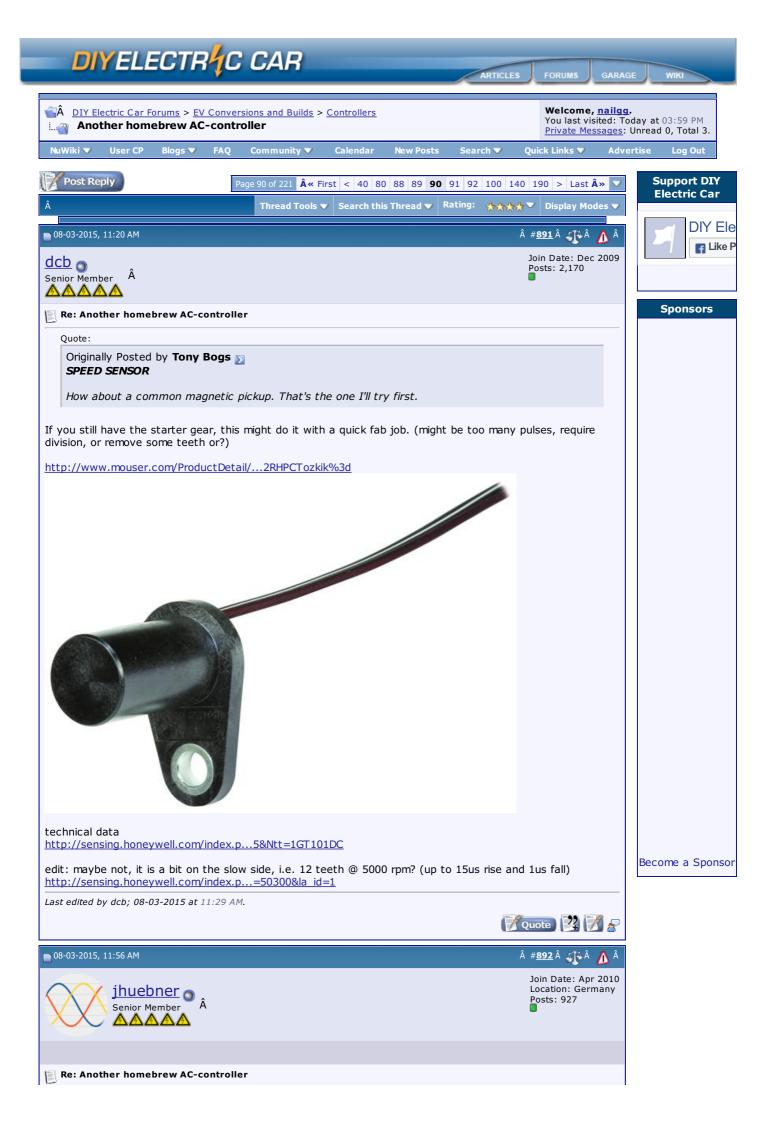
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PM stuff can stay here as it's still got to do with the inverter.

Yes, you can run a PM motor with an incremental encoder if you find out the 0-position once.

The startup code needs no great engineering either, simply dump 1Hz (at an amplitude set by the throttle) at the motor until you pick up the 0-pulse. If in a vehicle the motor will start moving sooner or later even without a clutch.

That eval board is larger than the main board a Anyway, good enough for experiments. We'd still need to find a suitable input for the 0/north signal. Maybe one of the digital inputs with the low pass filter cap changed.

The 1024 ppr resolution is a bit much, 100kHz@6000rpm. But of course the low pass filter for the pulse signal can be omitted or changed if the converter board is close enough to the main board. The smallest time frame the current code can measure is $1\hat{A}\mu$ s, so that shouldn't be an issue.

The digital filter introduces a delay of $3.5 \hat{A} \mu s$ because I programmed it to it's highest setting. But thats not god-given either, just all optimized towards noise immunity.

I don't have a whole lot of time to spare as I'm working on two customer projects. But I can see this being done with only a few 10 lines of code.

I would like to start with a separate north signal instead of detecting a missing hole on the disk. We can still do that later.

📝 Ouote 😰 📝 🔎

So first question: which digital input could be sacrificed for PM operation:

- 1. cruise control
- 2. FWD
- 3. REV
- 4. BMS
- ?

VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit

■ 08-03-2015, 12:23 PM	â # <u>893</u> â 🐢 â 🍌 â
Tomdb Senior Member Â	Join Date: Jan 2013 Location: Warwickshire, UK Posts: 798
Re: Another homebrew AC-controller	
I vote for BMS. Or the cruise control.	
However, you could decide to kick the motorprot input, and later on implement a ten via the motor temp sensor.	nperature throttle back
	VQuote 🕎 🌠 🔗
■ 08-03-2015, 12:54 PM	â # <u>894</u> â 🐠 â \Lambda
dcb Senior Member Â	Join Date: Dec 2009 Posts: 2,170
🛐 Re: Another homebrew AC-controller	

ok, now I get the clutch comment...



Location: Ireland Posts: 2,147

jackbauer 💿 🔒





a few pins unuse	d analog and digital		
	analog and digital.		
I'd agree to that	. So are you thinking of p	utting it on board or as an	extra card?
Well , I can safely sa I give it throttle. And some success with th we need and get tha populate these parts input. I can just sold	y the ACIM side works gro that's only on 280v and he Eval board I will design t working. Then my prefer if using an IPM. they will er a wire to the back of t	eat with the Siemens in the an unlocked torque conver a separate board for tests rence would be to design it be SMD though. No option he PCB.	e E31. It will punch me in the back if ter with a 3k rpm stall. If we have s with just the minimum components onto the main board as an option to I'm afraid. For tests we can use any r goes into the red and reads 1000
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Software is almost done. I don't have any means to test it as I'm not home right now.





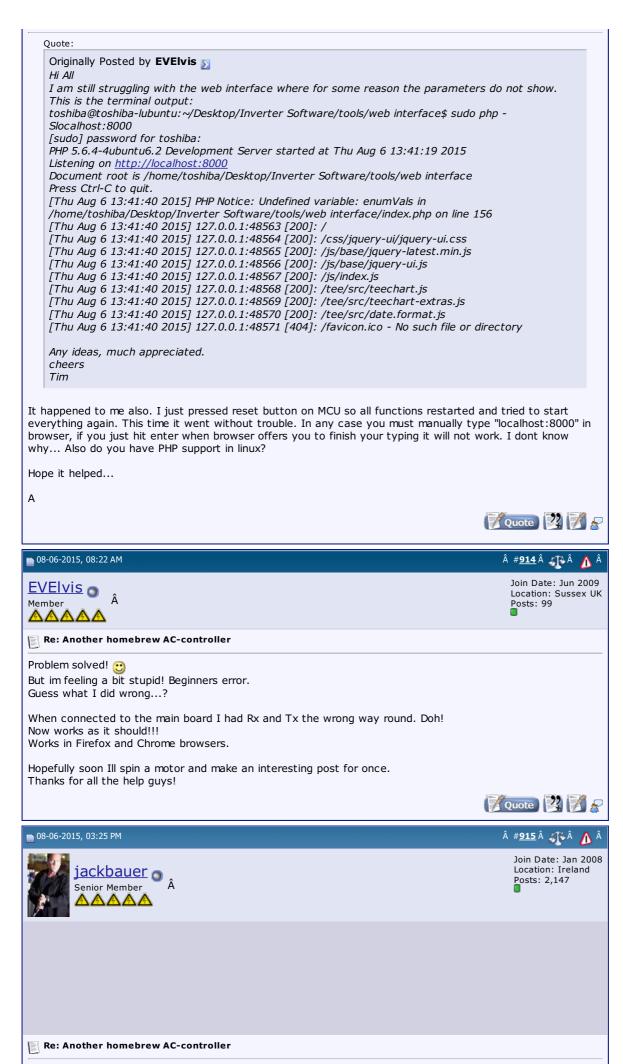
	Then i packed it up an good, lots of precision Although in 3rd it ofter	there, also drawing o d rewired phases to . I then tried to drive n throws OCLIMIT an	e and it worked. I drove	12A from battery wheeling. The feeling was very up to 70km/h in 2nd and 3rd. ve is very pleasant. I still have to	
I think something is different from the first few versions. Is it the throttle pedal?					
	tnx johannes i hope to	be driving soon norr	maly		
Yes	ll thats great news! 5, the throttle logic is cl led.	hanged. Up to 50% t	hrottle only the v/f ratio	is scaled, beyond 50% the slip is	
	Quote:				_
		fweak parameter is i	ridiculously large @316Hz happen to Fslipmin then?	?? I will never reach that point.	
	Now i had it set at fsli	omin 1.5Hz and fslipr	max 4,7Hz. Boost 1400 a	nd ampmin 10%. Oclimit at 450A.	
			ottle it is easy to reach nit max slip and increase	5000rpm. But if i suddenly add e ampmin and boost?	
	Inverter gets hot quic. A	kly because i dont ha	ave any fan on radiator a	and speed is low 🙂.	
	omax of 4.7Hz is quite a		gh voltage battery. So fu ne current limit being hit.	weak must be high. Limit to 2Hz and increase slowly fi	rom
	Quote:				_
		e will need to have a Can we not just set	FMAX anyway? We can	and just limit the stator determine the relationship	
if (1	ax is only a parameter, t frq > fmax) o = 0;	hat does nothing by:	itself. This code does th	ne trick:	
			n't work smoothly. So wit ation can be ramped dow	th the sync motor fslip is always 0 /n.	. So
	Polo 86C High Voltage				
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I've done that myself so many times. The next rev PCB will have a standard FTDI header to remove this



Sine_core.

Code:

```
stm32_sine
static void CalcNextAngle()
{
  static uint16 t slipAngle = 0;
   uint16 t polePairs = parm GetInt(PARAM polepairs);
  uint32 t ampnom = parm GetInt(PARAM ampnom);
  s32fp fslip = parm_Get(PARAM_fslipspnt);
s32fp fmax = parm_Get(PARAM_fmax);
  Encoder::Update();
   uint16 t motorAngle = Encoder::GetAngle();
  s32fp frq = polePairs * Encoder::GetFrq() + fslip;
  if (frq > fmax)
      fslip = 0;
  slipAngle += FP TOINT((fslip << SineCore::BITS) / pwmfrq);</pre>
  if (frq < 0) frq = 0;
  angle = polePairs * motorAngle + slipAngle;
  uint32_t amp = MotorVoltage::GetAmpPerc(frq, ampnom);
  SineCore::SetAmp(amp);
  parm_SetDig(VALUE_amp, amp);
  parm SetFlt(VALUE fstat, frq);
}
```

Code:

SineCore
void SineCore::Calc(uint16_t angle)
{
 int32_t Ofs;
 uint32_t Idx;
 int32 t sine[3];

/* 1. Calculate sine */
sine[0] = SineLookup(angle);
sine[1] = SineLookup((angle + PHASE_SHIFT120) & 0xFFFF);
sine[2] = SineLookup((angle + PHASE_SHIFT240) & 0xFFFF);

when i develop rpm everything is good. No more motor jumping and oclimit throwing.

OB-07-2015, 01:31 AM
A #919 A CA A A

A Bib Control

Senior Member

A

Posts: 782

Posts: 782

Posts: 782

Posts: 782

I johannes

I am now driving normally at 90km/h in 3rd O. It is not explosive acceleration like with lower voltage, but

	car takes cca 5kW, at 60	km/h cca 6kW and at 80km	n/h cca 9kW. So consumption seem					
	I will try to go on the highway later this month, but first i have to turn my brake discs. During 5 months of inaction rust gathered on disks and now brakes are ineffective.							
Can you tell how to set up pedal braking? I see in software that signal is good, but i dont have any effect in regen. I have brknompedal set to 30%. Should i give it more?								
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			📝 Quote 📴 🏹 👔					
■ 08-07-2015, 07:57 AM			# <u>920</u> ∢∰ <mark>≬</mark>					
	Onegreenev Å Senior Member Å Join Date: May 2012 Location: Marysville, CA Posts: 3,796							
📳 Re: Another homet	orew AC-controller							
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Originally Posted <i>Hi johannes</i>	by arber333 							
voltage, but whe I checked at 50k consumption see I will try to go or	n i develop rpm everythin m/h car takes cca 5kW, a ms legitimate. n the highway later this m	t 60km/h cca 6kW and at	jumping and oclimit throwing. 80km/h cca 9kW. So rn my brake discs. During 5					
		I see in software that sign 30%. Should i give it mor	al is good, but i dont have any e?					
A								
Currently the brake p	edal regen is preset at 30	%. Fixed.						
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Change comes, one conversion at a time. <u>http://onegreenev.blogspot.com/</u>								
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Quote:

Originally Posted by arber333 53 Hi johannes

I am now driving normally at 90km/h in 3rd 😷. It is not explosive acceleration like with lower voltage, but when i develop rpm everything is good. No more motor jumping and oclimit throwing. I checked at 50km/h car takes cca 5kW, at 60km/h cca 6kW and at 80km/h cca 9kW. So consumption seems legitimate.

I will try to go on the highway later this month, but first i have to turn my brake discs. During 5 months of inaction rust gathered on disks and now brakes are ineffective.

Can you tell how to set up pedal braking? I see in software that signal is good, but i dont have any effect in regen. I have brknompedal set to 30%. Should i give it more?

Thats great news!

Do you mean to use the second pot input for braking? Haven't programmed that yet. In my polo I set brknompedal to 80%, I hardly ever have to use the disk brakes that way. 30% doesn't do much on my motor.

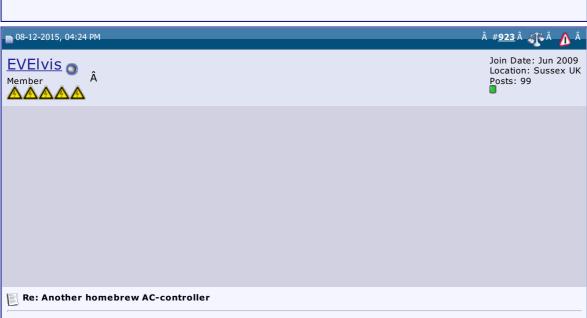
Quote:

Originally Posted by EVElvis 5

First thing is that when the inverter is started via web interface all bottom PWM signals go high 3.3V. Once started by changing ampnom to 1 etc they fluctuate as expected with top signals and you can see the deadtime around 1.5 micro seconds at 63 as per instructions. Wondering why all bottom PWM subscriptions with the signal second set of the second se
bottom PWM outputs go high on start of inverter? Edit - I think that this is to ensure all IGBTs are set the same prior to start? Second thing, deadtime set from 63 to 255 clearly makes a huge difference. I stopped then restarted the inverter via web interface and then saw the change occur, however, I could not go
back to deadtime 63 without powering inverter down. Looking good so far. cheers Tim
Alles ist gut When the inverter is in stop mode, the timer is disconnected from the output pins, thus all 6 outputs are low. As soon as you start, the timer is connected and generates the complementary output. Thus, all low side switches are on, all high side switches are off. By default you'd see a 50/50 signal in that case, but I have changed it to what you observe because "empty" pulsing (i.e. not generating current) generates a lot of EMI noise. I mean more than when actually doing useful work. Not sure why.
I noticed the deadtime behavior as well. Must be some hardware security feature.

📝 Quote 🕎 📝 🖉

VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit



Thanks Johannes

Good to hear. I have just played with actual gate driver board outputs, when outputs. This time I noticed noise that you mention and what looked like volt off/on. Glad you mentioned it as I can never be sure if its my scope, probe, s temporary wiring connections with my little experience. One of my drivers only provides half of the voltage on one side, not sure why caps is slightly damaged (I recall that when I damaged it making up the boar note in your instruction video that your gate drivers do not have the diodes I think I had only 5V output for the gate drivers? Had it in my mind they wen components, so I guess this is scope user error. Cant believe I build 3 gate of play tomorrow. cheers Tim	age spikes at point of turn scope user error or my dodgy y but I notice one of the small rd) I have a spare ill use. Also I fitted, is there any reason why? e 15V outputs via DC1 & DC2
■ 08-12-2015, 04:27 PM	# <u>924</u> ∡∏ ê <u>∧</u> Â
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by EVEIvis Also I note in your instruction video that your gate drivers do not have any reason why?	the diodes fitted, is there
Well spotted 🙂 The diodes are on the IGBT board itself.	
Quote:	
Originally Posted by EVEIvis I think I had only 5V output for the gate drivers? Had it in my mind they & DC2 components, so I guess this is scope user error. Cant believe I be have another play tomorrow. cheers Tim	
Very unlikely, maybe use a voltmeter for those kind of tests. The INPUT to t must be -15V or +15V.	he gate drivers is 5V, The output
VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	📝 Quote 📴 🏹 🎤
■ 08-13-2015, 02:07 AM	# <u>925</u> ⋌ №Â <mark>∧</mark> Â
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782
Re: Another homebrew AC-controller	
I am in croatia now. Far from my car. Last time i was experimenting with sett happened. Controller wouldnt start. I tried many timesnothing. Then i start from + battery pole towards gnd!!! I tought it was BMS but it wasnt. Then i measurement. Finally i found out main contactor relay starts as soon as i sw precharge I tried to move it a little and BANG! I saw sparks to my right wh burned SOC PCB board. I guess full cap voltage was draining trough precharge though i made protection underneath it contacts still found alu metal	ted to measure, i got 140VDC suspected controller voltage itch controller on! No ere main contact box is. I found
The good news is controller still works. First thing when I come home i will charge :=).	
A	Vuote 🕎 🌠 🔗
■ 08-15-2015, 04:41 AM	â # <u>926</u> â 🕂 Â \Lambda â
jackbauer Senior Member Â	Join Date: Jan 2008 Location: Ireland Posts: 2,147

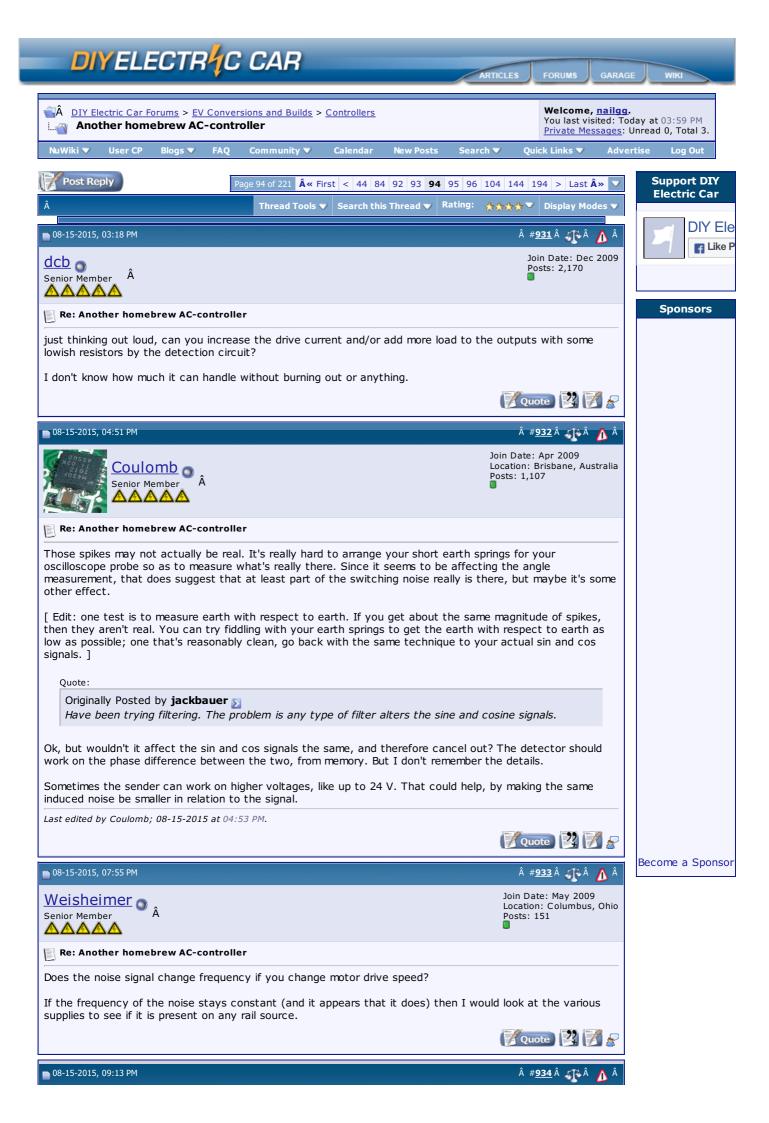


	-					
Re: Another homeb	rew AC-controller					
Have been trying filtering. The problem is any type of filter alters the sine and cosine signals. Also very little info seems to be available for resolver application circuits.						
Amps, that's bad.	shift the gear and that lit	tle needle on the ammete	r goes into the red and reads	1000		
www.evbmw.com			Vuote 2	1		
Post Reply	Page 93 of 221	Â « First < 43 83 91 92	93 94 95 103 143 193 > La	st » 🔍		
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Join Date: Jul 2009 Posts: 168

Re: Another homebrew AC-controller

Quote:

Originally Posted by jackbauer 🔊

Sorry I should have stated the clean signal on the left is with the inverter not operating. One on the right is with the inverter pumping current into the motor. The spikes have a ringing frequency of 8.8MHz.

If the circuit receiver and wiring is balanced differentially and noise spikes are at inverter switching points, then its most likely common mode noise induced by current circulating in the grounds between your motor/resolver case ground and resolver receiver circuit ground due to parasitic winding to case capacitance within the resolver and motor.Try a common mode choke by winding your wires (twisted triplet of sin, cos, rtn) around a high mu toroidal core.

If that does not help enough make sure you have low impedance ac ground path from your motor case back to your inverter ground? Play around with grounding the motor case to inverter ground through a high frequency capacitor or directly to see if that helps. Your goal here is to provide a lower impedance path back for circulating currents and use the common mode chock to increase the common mode impedance back through your resolver interface.





to digital convert rotor moving. Wh gears in the 'box Attached are sco	Moron of the week award goes to : Damien! Guess what? I don't have a noise problem! The resolver to digital converter couldn't give a damn about the inverter noise what it does car about is the rotor moving. When I inject current into the stator what happens? The rotor moves! The lash in the gears in the 'box mean i dont see the output flange more but the damn resolver does and tells me. Attached are scope shots of the encoder emulation channel running in open loop and 2.5Hz , 5Hz and 10Hz. Crystal clear. Big thanks to Michal Elias for spotting this ::						
Glad to help 🙂 Our new webpage th	Glad to help Our new webpage that will soon contain useful stuff about our projects: advantics.fr						
			Quote 2	18			
Post Reply	Page 94 of 22	1 « First < 44 84 92 93	94 95 96 104 144 194 > Last Â	» 🗸			
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Join Date: Apr 2010 Location: Germany Posts: 927

🛐 Re: Another homebrew AC-controller

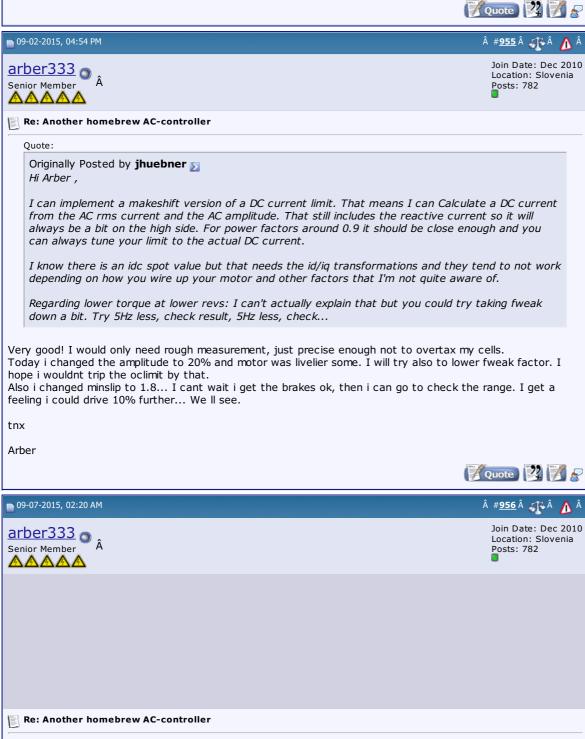
Hi Arber,

I can implement a makeshift version of a DC current limit. That means I can Calculate a DC current from the AC rms current and the AC amplitude. That still includes the reactive current so it will always be a bit on the high side. For power factors around 0.9 it should be close enough and you can always tune your limit to the actual DC current.

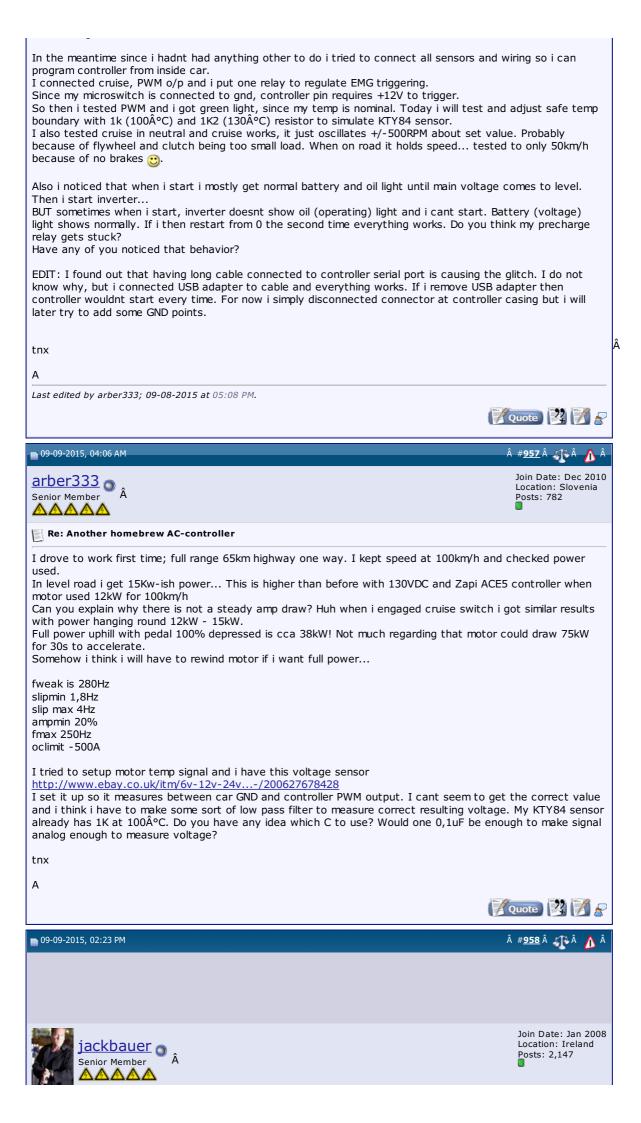
I know there is an idc spot value but that needs the id/iq transformations and they tend to not work depending on how you wire up your motor and other factors that I'm not quite aware of.

Regarding lower torque at lower revs: I can't actually explain that but you could try taking fweak down a bit. Try 5Hz less, check result, 5Hz less, check...

VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit



Still waiting for new brake discs DOH !!!



Re: Another homebrew	AC-controller		
Arber , if I remember corre 1k.	ectly it is an open colle	ector output so you will need a resis	stor pullup to 12v. Try a
Now, Cole, when you shift Amps, that's bad. www.evbmw.com	the gear and that litt	tle needle on the ammeter goes into	the red and reads 1000
			VQuote 🕎 📝 🔗
■ 09-09-2015, 06:25 PM			â # <u>959</u> â 📣 â 🧥 â
Arber333			Join Date: Dec 2010 Location: Slovenia Posts: 782
Re: Another homebrew	AC-controller		
Quote:			
Originally Posted by ja Arber , if I remember 12v. Try a 1k.		n collector output so you will need a	a resistor pullup to
DOH! you are right. I antic on GND!!! i will change		as its own pullup and i connected jus	st +12V and towards signal
tnx			
А			
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■ 09-10-2015, 12:24 PM			â # <u>960</u> â 🐠 â <u> â</u>
Dep-10-2015, 12:24 PM	Â		# <u>960</u> ∰ M Â Join Date: Apr 2010 Location: Germany Posts: 927
jhuebner Senior Member			Join Date: Apr 2010 Location: Germany
jhuebner Senior Member			Join Date: Apr 2010 Location: Germany
Re: Another homebrew A Argh, quote not working. So concerning the control I reckon that is down to t	AC-controller ler hang with the seria he boot loader. It poll	al cable connected: s the serial port right after startup a t wait for new software forever.	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew A Argh, quote not working. So concerning the control I reckon that is down to the other than 0 it starts the	AC-controller ler hang with the seria he boot loader. It poll update process, i.e. it oblem we need more d	s the serial port right after startup a	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew Argh, quote not working. So concerning the controll I reckon that is down to t to ther than 0 it starts the Concerning your power pro"	AC-controller ler hang with the seria he boot loader. It poll update process, i.e. it oblem we need more d elerating and cruising.	s the serial port right after startup a t wait for new software forever.	Join Date: Apr 2010 Location: Germany Posts: 927 and if it finds anything and plot "fstat", "il1rms",
Re: Another homebrew A Argh, quote not working. So concerning the control I reckon that is down to t other than 0 it starts the Concerning your power pro "udc" and "uac" while acce How did you arrive at the I'm not yet sure that rewin	AC-controller ler hang with the seria he boot loader. It poll update process, i.e. it oblem we need more d elerating and cruising. value for "fmin"? That nding the motor is the	is the serial port right after startup a t wait for new software forever. data. Please use the plot function ar	Join Date: Apr 2010 Location: Germany Posts: 927 and if it finds anything and plot "fstat", "il1rms", y. you don't want to spin
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Re: Another homebrew A Argh, quote not working. So concerning the control I reckon that is down to the other than 0 it starts the Concerning your power pro- "udc" and "uac" while acce How did you arrive at the I'm not yet sure that rewin faster than 4000rpm. With Some basic questions: is y	AC-controller ler hang with the seria he boot loader. It poll update process, i.e. it oblem we need more d elerating and cruising. value for "fmin"? That nding the motor is the fweak=280Hz you rea your pot configured rig AC Conversion - AC N	is the serial port right after startup a t wait for new software forever. data. Please use the plot function ar c one is crucial for part load efficienc e #1 solution to your problem unless ach peak power at around 8000rpm. ght, i.e. do you get ampnom=100% a <u>Motor Inverter Kit</u>	Join Date: Apr 2010 Location: Germany Posts: 927 and if it finds anything and plot "fstat", "il1rms", y. you don't want to spin Ever been there? at full throttle?
Re: Another homebrew of Argh, quote not working. So concerning the controll I reckon that is down to t to other than 0 it starts the Concerning your power procude" and "uac" while access How did you arrive at the I'm not yet sure that rewing faster than 4000rpm. With Some basic questions: is y	AC-controller ler hang with the seria he boot loader. It poll update process, i.e. it oblem we need more d elerating and cruising. value for "fmin"? That nding the motor is the fweak=280Hz you rea your pot configured rig AC Conversion - AC N	is the serial port right after startup a t wait for new software forever. data. Please use the plot function ar c one is crucial for part load efficienc e #1 solution to your problem unless ach peak power at around 8000rpm. ght, i.e. do you get ampnom=100% a <u>Motor Inverter Kit</u>	Join Date: Apr 2010 Location: Germany Posts: 927 and if it finds anything and plot "fstat", "il1rms", y. you don't want to spin Ever been there?
Re: Another homebrew of Argh, quote not working. So concerning the controll I reckon that is down to t to other than 0 it starts the Concerning your power procude" and "uac" while access How did you arrive at the I'm not yet sure that rewing faster than 4000rpm. With Some basic questions: is y	AC-controller ler hang with the seria he boot loader. It poll update process, i.e. it oblem we need more d elerating and cruising. value for "fmin"? That nding the motor is the fweak=280Hz you rea your pot configured rig AC Conversion - AC N	s the serial port right after startup a t wait for new software forever. data. Please use the plot function ar c one is crucial for part load efficience e #1 solution to your problem unless ach peak power at around 8000rpm. ght, i.e. do you get ampnom=100% a <u>Motor Inverter Kit</u> son: More questions	Join Date: Apr 2010 Location: Germany Posts: 927 and if it finds anything ad plot "fstat", "il1rms", y. you don't want to spin Ever been there? at full throttle?
ihuebner Senior Member Senior Member Re: Another homebrew Argh, quote not working. So concerning the control I reckon that is down to the other than 0 it starts the Concerning your power pro "udc" and "uac" while acce How did you arrive at the I'm not yet sure that rewin faster than 4000rpm. With Some basic questions: is y <u>VW Polo 86C High Voltage</u> Last edited by jhuebner; 09-10	AC-controller ler hang with the seria he boot loader. It poll update process, i.e. it oblem we need more d elerating and cruising. value for "fmin"? That nding the motor is the fweak=280Hz you reis your pot configured rig AC Conversion - AC N 0-2015 at 12:29 PM. Reas	s the serial port right after startup a t wait for new software forever. data. Please use the plot function ar c one is crucial for part load efficience e #1 solution to your problem unless ach peak power at around 8000rpm. ght, i.e. do you get ampnom=100% a <u>Motor Inverter Kit</u> son: More questions	Join Date: Apr 2010 Location: Germany Posts: 927 and if it finds anything ad plot "fstat", "il1rms", y. you don't want to spin Ever been there? at full throttle?
	AC-controller ler hang with the seria he boot loader. It poll update process, i.e. it oblem we need more d elerating and cruising. value for "fmin"? That nding the motor is the fweak=280Hz you reis your pot configured rig AC Conversion - AC N 0-2015 at 12:29 PM. Reas	s the serial port right after startup a t wait for new software forever. data. Please use the plot function ar one is crucial for part load efficience e #1 solution to your problem unless ach peak power at around 8000rpm. ght, i.e. do you get ampnom=100% a <u>Motor Inverter Kit</u> son: More questions < First < 46 86 94 95 96 97 98	Join Date: Apr 2010 Location: Germany Posts: 927 and if it finds anything ad plot "fstat", "il1rms", y. you don't want to spin Ever been there? at full throttle?

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09-10-2015, 12:46 PM		# <u>.</u>	961 Â 🐠 Â 🧥 Â	
Tomdb Senior Member Â			: Jan 2013 Warwickshire, UK 18	
Re: Another homebrew AC-co	ntroller			Sponsors
	H103's so i can get building on new cor	ntroller boards. 😁		
Wondering how its going with th I will start working on creating a	ne writing of code? a new " main" board to include new feat	ures:		
1. Preparation for an resolve				
 Canbus transciever Dual throttle input Prake pot input 				
Ofcourse changing a few conne to show this weekend.	ctors and switching to smd, for smaller	form factor. Hope to ha	ive something	
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■ 09-10-2015, 05:08 PM		# <u>:</u>	962 Â 🐠 Â 🧥 Â	
arber333 Senior Member Â		Lo	in Date: Dec 2010 cation: Slovenia osts: 782	
				Become a Sponso

Quote:

Originally Posted by **jhuebner** *Argh, quote not working.*

So concerning the controller hang with the serial cable connected: I reckon that is down to the boot loader. It polls the serial port right after startup and if it finds anything other than 0 it starts the update process, i.e. it wait for new software forever.

Yes i figured it is something like that. Could i connect GND on the other side of cable to chassis and use 10K pulldown resistors from TX RX towards GND. How is ttl connected there?

Quote:

Originally Posted by **jhuebner**

Concerning your power problem we need more data. Please use the plot function and plot "fstat", "il1rms", "udc" and "uac" while accelerating and cruising.

I took the motor out for rewinding. When i went trough 6000RPM i heard some strange noise like flutter of thin metal... In any case it is difficult to upshift at that speed but downshift is strange, sometimes motor just stops and i am stuck with 0RPM on motor and 2500RPM on transmission side. I will took those measurements when i put motor back in 😁 maybe next week...

Quote:

Originally Posted by jhuebner

How did you arrive at the value for "fmin"? That one is crucial for part load efficiency.

Huh i tried changing single parameter and suddenly motor took off smoothly with 1.8Hz. With ZAPI controller i had it set at fslipmin 3.2Hz and fmin 3Hz. also fslipmax was 6.4Hz. Today when i tried setting fslipmax 6Hz and ampmin 30% motor also worked very good above 2000RPM. I got to 50kW draw at 120km/h.

But below 2000rpm i had to be carefull with pedal or oclimit would activate.

Quote:

Originally Posted by jhuebner

I'm not yet sure that rewinding the motor is the #1 solution to your problem unless you don't want to spin faster than 4000rpm. With fweak=280Hz you reach peak power at around 8000rpm. Ever been there?

6500RPM, but when i bought motor they said not to spin more than 240Hz because of g forces on rotor.

Quote:

Originally Posted by jhuebner

Some basic questions: is your pot configured right, i.e. do you get ampnom=100% at full throttle?

[/QUOTE]

I tried static value and i get full throttle travel. I havent checked the ampnom value yet... I will get my motor rewound. This guy also said he could make wiring for 100Hz and will probably get 30Kw nominal at 120Hz out of motor and better efficiency.

Now it is wound for 90Hz operation with 28kW at 120Hz and weakening at cca 140Hz - 150Hz...

I think i will also put axial taper front bearing in because my clutch exerts some 7kg of pressure along motor axis...

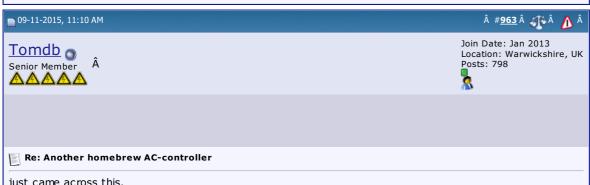
say which version of software is now latest? I use 2.87 now and it works quite good.

tnx

Arber

Last edited by arber333; 09-11-2015 at 06:14 AM.







ΔΑΔΑΑ	7
E Re: Another homebrew AC-controller	(A)
My first SMD design just came in, its for my bms slave boards. Happy with then i can finish the controller board layout.	the look, now just some testing,
	Â
I	VQuote 🕎 📝 🔗
● 09-24-2015, 03:02 РМ	# <u>968</u> 🐠 🥼
Tomdb Senior Member Â	Join Date: Jan 2013 Location: Warwickshire, UK Posts: 798
Re: Another homebrew AC-controller	
The smd design of the main board will take a little more time, starting over make the routing more clean to the micro controller. Last 20 traces needed	
Got some free time the coming days so after my reflow oven is done i can s	sink some time into it.
How is the testing coming along guys?	
	Â
Last edited by Tomdb; 09-24-2015 at 03:13 PM.	VQuote 🕎 🏹 😞
р 09-27-2015, 05:33 АМ	â # <u>969</u> â 🕂 â <u>Å</u> â
EVElvis Member Â	Join Date: Jun 2009 Location: Sussex UK Posts: 99
🛐 Re: Another homebrew AC-controller	
Hi All	
I have been testing the gate drive outputs. I have nice clean square PWM outputs from driver boards GTOP etc are rather varied. Some show half th 15V between each GTOP & ETOP. I have not connected the IGBTs, so I do wonder whether a difference in th better? Anyone else see similar outputs? I plan to test again asap with drivers connected to IGBTs.	ne amplitude, although I measure
Edit - Built two more drivers up. Half of each are not right, so suspect temp driver chips. My solder melts 184 degC and use iron set at 300degC to quic what everyone else uses?	
cheers Tim	
Attached Thumbnails	
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Last edited by EVElvis; 09-28-2015 at 02:48 PM.	
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р 09-29-2015, 03:50 РМ	# <u>970</u> ∢ ∰ <mark>∧</mark> Â
Tomdb Senior Member Â	Join Date: Jan 2013 Location: Warwickshire, UK Posts: 798

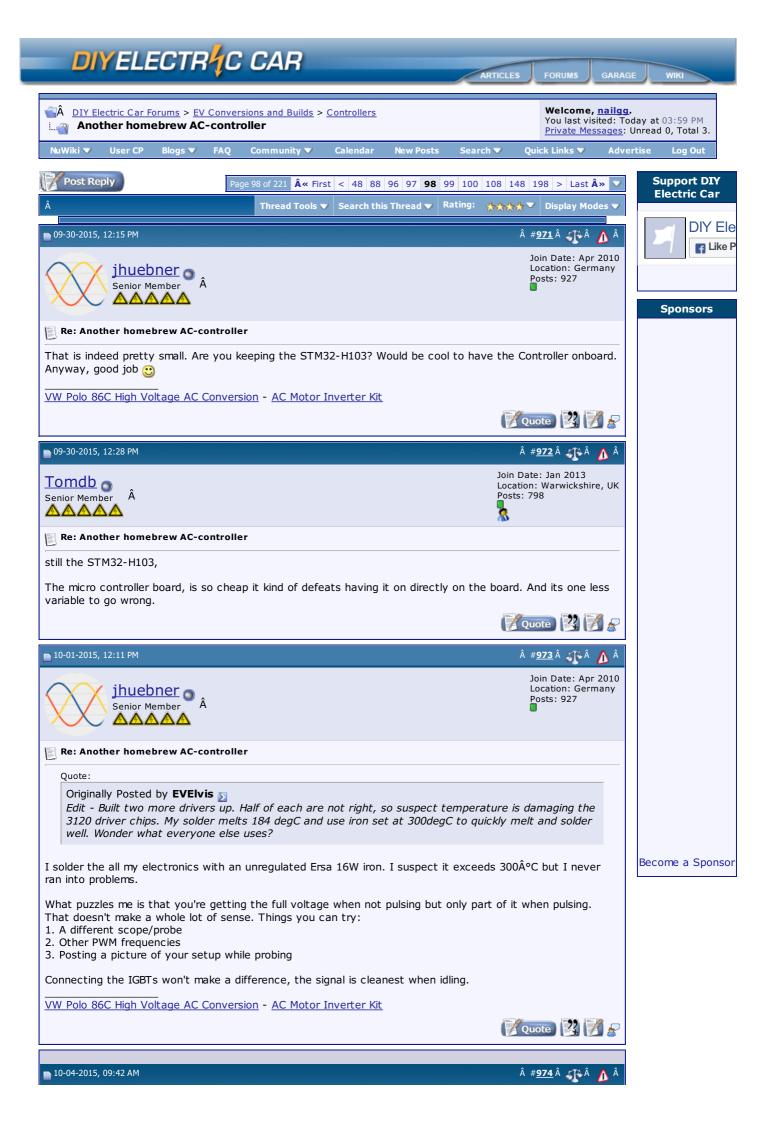
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w i wonder if this design wil even work, need to give it a once over end of the week before ordering lit: Dammit just realized, have not hooked up the "top" trigger for the resolver decoder. lit 2: Looks like our Chinese friends have a holiday so I have a week to check my board and order the resion and the "original". A Atached Thumbals A st edited by Tomby 09-29-2015 at 04:36 PM. Post Reply Post Reply Page 97 of 221 Å ≪ First < 47 87 95 96 97 98 99 107 147 197 > La Post Reply Page 97 of 221 Å ≪ First < 47 87 95 96 97 98 99 107 147 197 > La Post Reply Page 97 of 221 Å ≪ First < 47 87 95 96 97 98 99 107 147 197 > La Procebook StumbleUpon Coogle Wessage: Message: Please click one of the Quick Reply icons in the posts above to activate Quick Reply. Post Quick Reply Post Quick Reply Co Advanced	Re: Another homebr	ew AC-controller			
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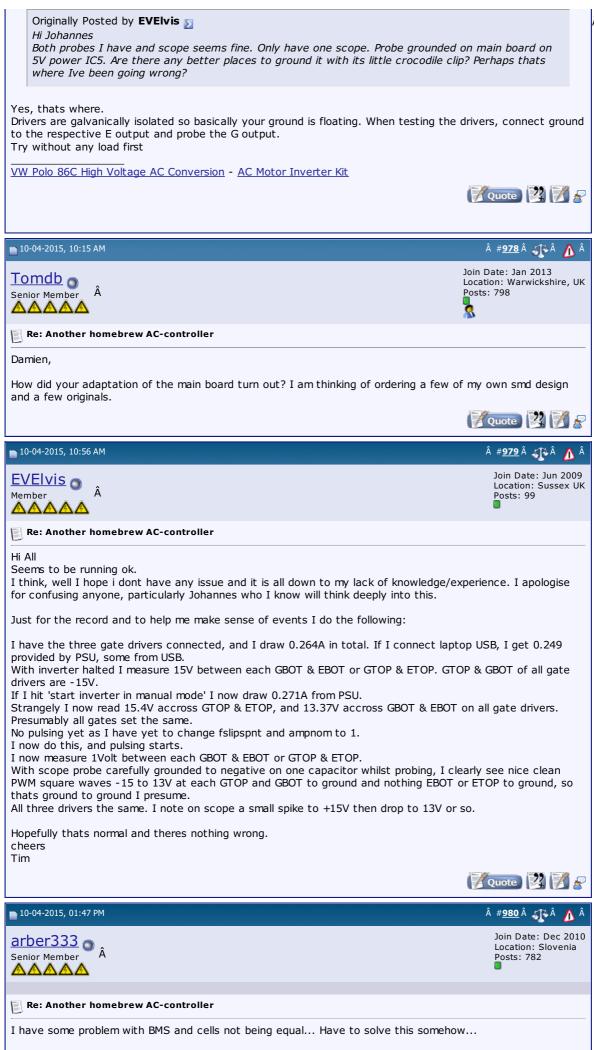
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Athenwise inverter works and surprisingly it seems to have even lower consumption than my mosfet Zani

Wervise. Interferent works good, subplicingly is seens to have even hore: consumption than ny moster Lapin showed 15% more. I still havent found the best compromise between acceleration and amps, but iam close. I set fslipmin 0.6Hz just out of curiosity and it works good. Also i set fmin 0.5Hz. fmaxslip is 6.4Hz still. I varied boost value a bit and came to conclusion that this variable also applies when motor transitions from regen to drive mode. Johannes please comment me here? So when i use 2200 motor surges against clutch, but when i set 1300 motor is very benign. I opted for 1600 to have good takeoff and tolerable acceleration on crossroads. ampmin though is a bit elusive. I have it set at 28%. It seems 35% is too much and again motor surges from 0 load. Lower than that it seems there isnt much effect. How can i best set and try different versions of this? There is still something i cant handle though. The cruise mode works by pushbutton yes? Well when i push the button everything starts to rock violently. It doesnt seem to matter how i set speedkp parameter, car still jumps around Tell me what works for you? I had it set from 1 to 25, do you think i should set more? I noticed that when i use 25 motor is steadier at transition from steady state to acceleration. tnx Arber Image 98 of 221 A ** First < 48 88 96 97 98 99 100 108 148 198 > Last A > Image Share or Bookmark this Image 99 002 10 A** First < 48 88 96 97 98 99 100 108 148 198 > Last A > Image Share or Bookmark this Image 99 01 02 08 148 198 > Last A > Image Facebook Image 99 01 221 A ** First < 48 88 96 97 98 99 100 108 148 198 > Last A > Image I face					
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Ok, so I have some interesting findings, and for once I took some videos	which I have uploaded. Today is the
first time i connected my IGBTs. Not all great findings, and I have something wrong, but not sure what. I my IGBTs as I have blown a couple of 10A auto fuses on my dc bus line.	must end up with shoot through of
As I have seen before, I note that on each gate driver between each an GBOT & EBOT = $13.4V$. No idea why and $3.3V$ driving PWM signal seems of	
https://www.youtube.com/watch?v=-AIe66-mJJc	
With drivers connected to main board I did see a spike to 30V, then mean issue somewhere, but all gate drivers are the same as shown here:	sure around 28.4V. Seems to be an
https://www.youtube.com/watch?v=juvZqt6Eb9M	
After connecting IGBTs, I first had deadtime set to 63 and it did not apprivideo:	ear to be enough as shown in this
https://www.youtube.com/watch?v=Ams6EYoFNrQ	
So I changed it to 200 and could see plenty of deadtime with no overlap to 12V battery via 10A fuse. Started the inverter and I got some smoke exactly what fizzed and I thought it was the main board. It looks all ok, a understand how the main board can get damaged. I did notice my scope connection, having left those in the position shown in my video. I do wor and prevented the switching off of a gate?	and a fizz noise. I cannot see and it still seems to work. I also dont ground was sparking on one ground
Any pointers would be greatly appreciated? Feeling so very green, but er	njoying the learning.
Ill have another play tmw. Really want to get a motor spinning.	
cheers	
Tim	
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■ 10-11-2015, 04:50 AM	# <u>986</u> 🌾 🔥 Â
<u>EVElvis</u>	Join Date: Jun 2009
a a a a a a a a a a a a a a a a a a a	Location: Sussex UK
Member A	Posts: 99
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Re: Another homebrew AC-controller	d fully, but must be shoot through? e the IGBT pins have got hot as they e even see the copper in the PCB has
Re: Another homebrew AC-controller Hi All In good light I have now seen what got hot yesterday. I dont understand The ETOP and EBOT connections on one IGBT have got hot. You can see are discoloured and the smoke I saw was the solder having melted. I can got hot and changed colour.	d fully, but must be shoot through? e the IGBT pins have got hot as they e even see the copper in the PCB has
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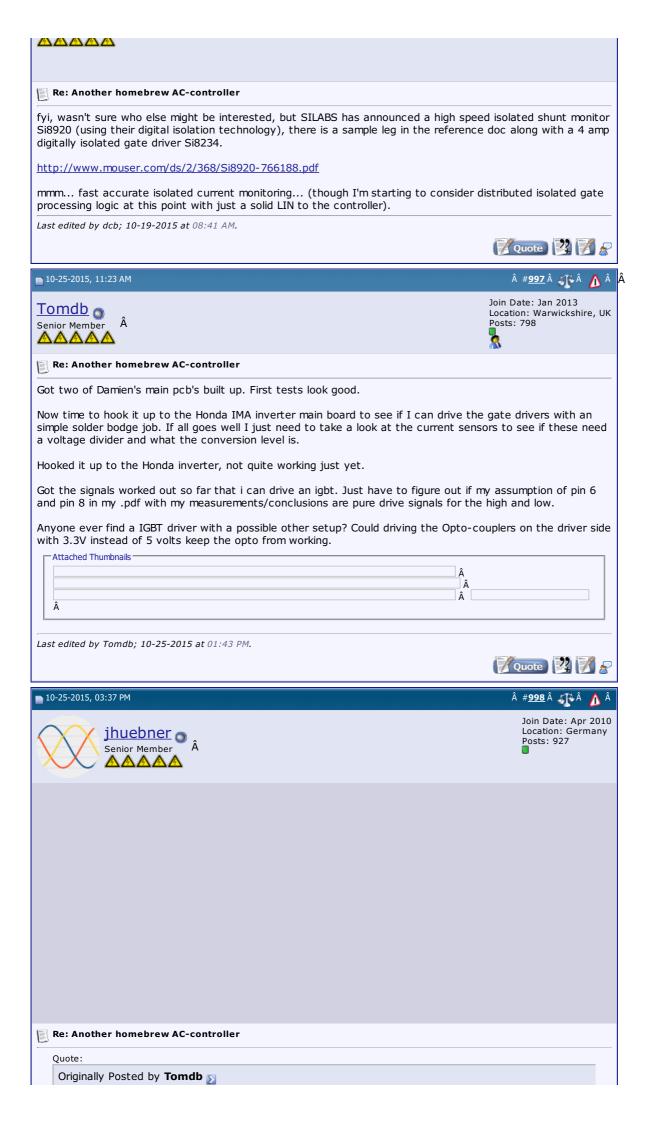
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got it all in a box, unfortunately could not find a shorter one, i need 35mm in height f could only find 60mm tall ones.	for the connector. But i
The black box (on top), contains the main board +h103, is 113mmx190mmx61mm. I n management and an extra relay to switch the Honda Ima inverter on and off.	eed the 190mm for cable
For testing this is fine. If there is enough interest, I could look into redesigning the n the existing Cover of the Honda inverter. This is tricky due to the fact the large lump cap which is part of the cover.	
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■ 10-28-2015, 06:17 PM	â # <u>1005</u> â 🐢â <u>۸</u> â
coleasterling A	Join Date: Feb 2012
Member Â	Location: Bryan, TX Posts: 82
Re: Another homebrew AC-controller	
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	Join Date: Apr 2010
jhuebner Â	Location: Germany <u>P</u> osts: 927
Senior Member A	•
E Re: Another homebrew AC-controller	
Thats a great source for a compatible power stage!	
You are using the existing gate drivers, so in effect you only need the main board?	
W Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
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Tomdb Senior Member Â	Location: Warwickshire, UK Posts: 798
	8
E Re: Another homebrew AC-controller	
only the main board hooked up to the mainboard of the IMA inverter.	
Just one resistor divider for the current sensor. 5v range to 3.3v range.	
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■ 10-29-2015, 12:37 PM	# <u>1008</u> ∧ĩ≩ <mark>∧</mark>Â
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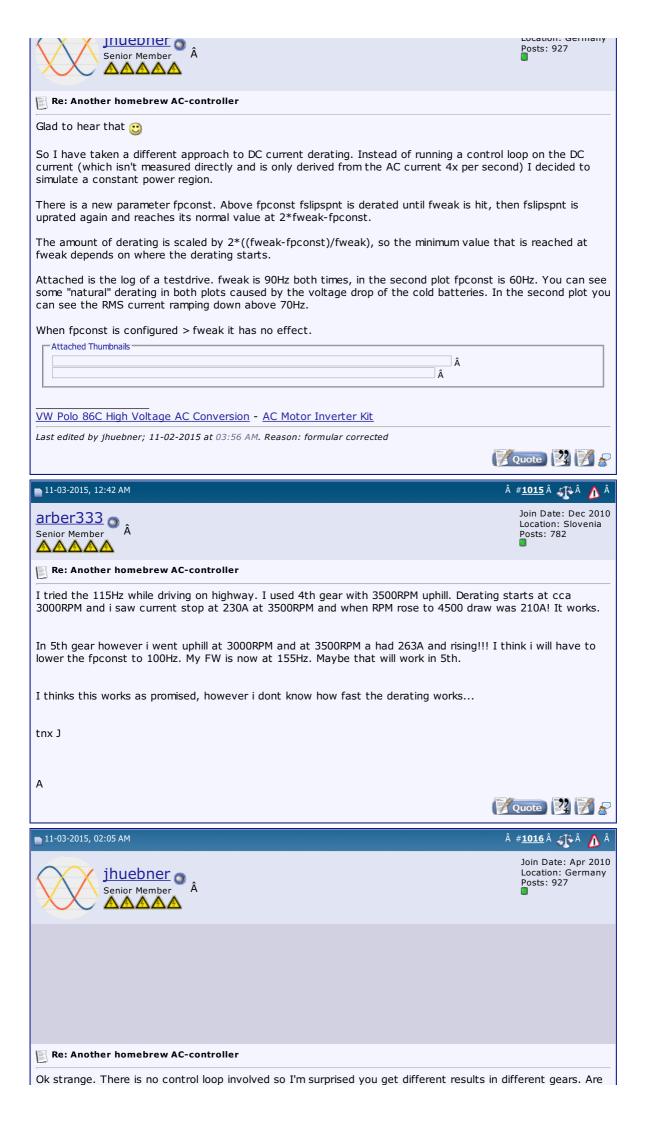
For fear of sounding dumb, I'm interested to see how this works at high currents. I read a few references to

hardware over-currer ready signals to the o		l up in a way that allows the	e main board to still control the
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■ 10-29-2015, 12:40 PM			# <u>1009</u> 🐢 <u> Â</u> Â
Tomdb Senior Member Â			Join Date: Jan 2013 Location: Warwickshire, UK Posts: 798
Re: Another homeb	rew AC-controller		
Quote:			
For fear of sound references to ha	by coleasterling ling dumb, I'm interested rdware over-current prot trol the ready signals to a	to see how this works at h ection. Is it hooked up in a the gate drivers?	igh currents. I read a few way that allows the main
		e overcurrent protection is b reaching the gate drivers.	ased on the main board (added on
	gate comparing the feedb ceeds the max it stops th		to a level set by the micro. So if
			VQuote 🕎 🎢 🔗
■ 10-29-2015, 12:59 PM			# <u>1010</u> ∰ <mark>∆</mark> Â
<u>coleasterling</u>	Â		Join Date: Feb 2012 Location: Bryan, TX <u>P</u> osts: 82
			•
Re: Another homeb			
Sorry for the confusion	on there, I realized it does	sn't make much sense, eithe	er.
		om Hitachi reference hardwa down the driver and throws	re over-current protection in the a fault.
			e (and the whole driver board). And with your new board on top?
			📝 Quote 🕎 🌠 🔗
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■ 11-08-2015, 09:32 AM			# <u>1020</u> ≼ ⊺∳Â	à 🔥 â
dcb Senior Member Â			Join Date: De Posts: 2,170	-
📃 Re: Another homeb	rew AC-controller			
bits to do it. http://www.vkingpub http://www.vkingpub	.com/VkUpload/20140616 .com/VkUpload/20140616	1627404039.pdf	oller *should* have the necessa	ary
Last edited by dcb; 11-08	8-2015 at 09:46 AM.		Quote	2
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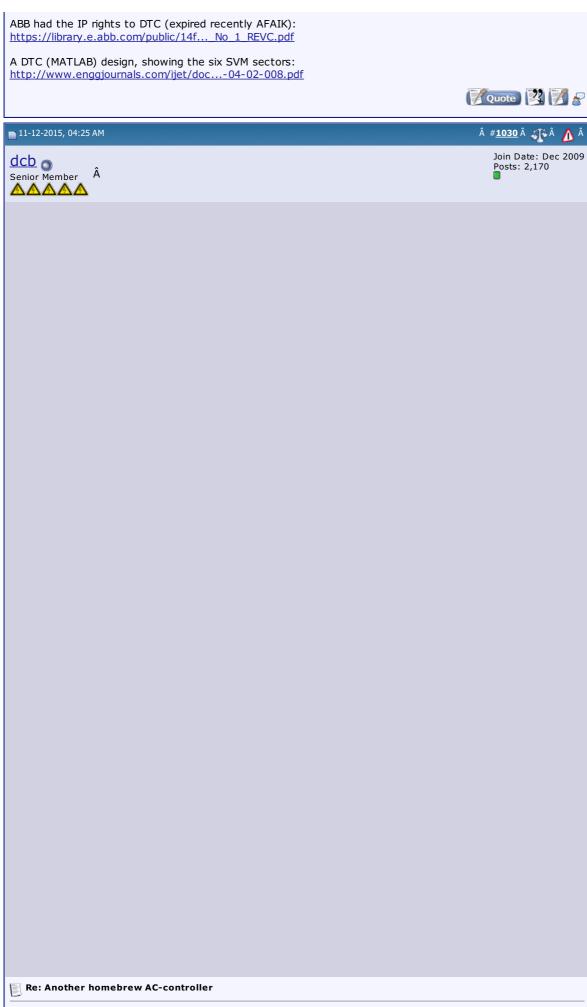
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That is sort- of what I'm getting at, everything I've read shows svm based DTC is fixed pwm frequency, even that first ABB link appears to be switching at 40khz.

" Torque and flux status signals are calculated

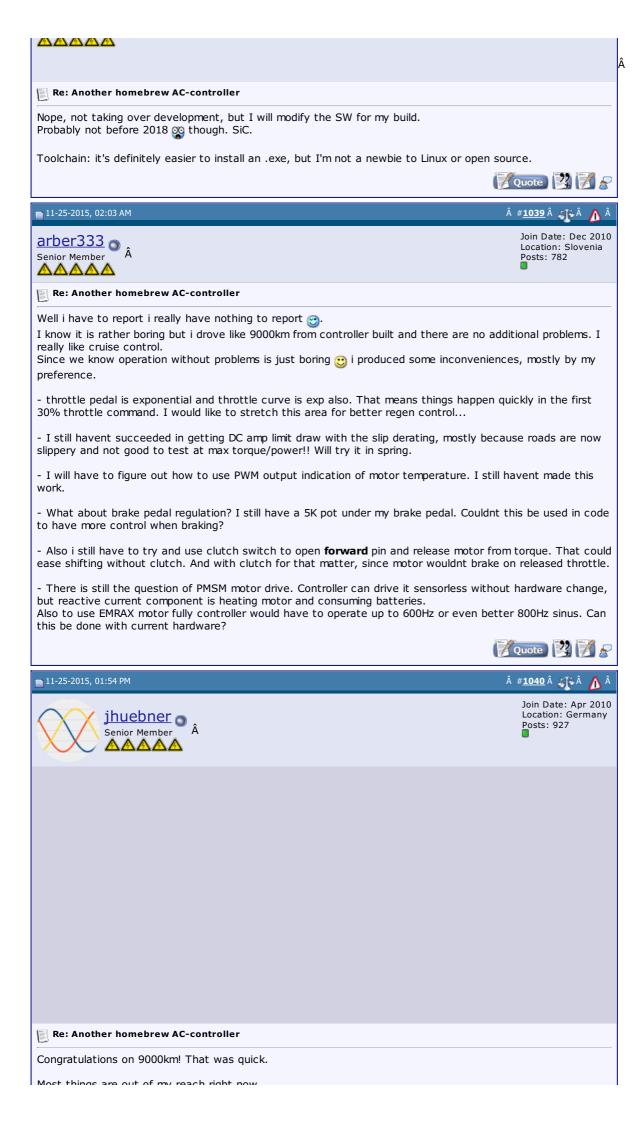
using a two level hysteresis control method.	
These signals are then fed to the optimum pulse selector"	
"This configuration brings immense processing speed such that every 25 microseconds the inverter's semiconductor switching devices are supplied with an optimum pulse for reaching, or maintaining, an accurate motor torque."	
So they implemented the sensing/logic with hysteresis, but the power control is fixed frequency.	
whereas in the other thread Stiives describes the DTC sound (spread spectrum) and mentions hysteresi control	S
Indeed: Quote:	
Originally Posted by Stiive <i>the hardware OTOH took about 2months and many hours!</i> <i>I had heard that DTC will make the motor sound awful, sounds alright to me at these lower powers</i> <i>so far.</i>	5
A hardware based high power variable band hysteresis controller would take a while to sort out, but you need any extra current limiting stuff either, current limiting is at the core of it.	ı don't
Quote:	
Originally Posted by Stiive DTC sound is starting to come through now though Decibels seem to vary with flux :s	
Quote:	
Originally Posted by Stiive 5	
Yeh, my hysteresis band is very small	
A comparison of DTC and DTC-SVM <u>http://ijartet.com/papers/ICAEECA-2015/V02S110203.pdf</u> Code:	
DTC uses hysteresis controller Controller output will be flux and torque Forward Euler Integrator Variable switching frequency	
DTC-SVM uses PI controller Controller output will be voltages of d-q Trapezoidal Integrator Constant switching frequency	
Then there is the obligatory million papers upgrading the pi controller to an estimator to an observer (estimator w/feedback) to fuzzy logic (hardcode some educated guesses), etc	
But stiives implementation doesn't sound like the DTC-SVM I am familiar with, which *should* be within of the huebner controller, though 40khz might be asking a bit much of it.	reach
Last edited by dcb; 11-12-2015 at 07:48 AM.	7
	Â.
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but this one:
Quote: Originally Posted by arber333 - What about brake pedal regulation? I still have a 5K pot under my brake pedal. Couldnt this be used in code to have more control when braking?
You can connect the pots in series:
 GND: brake pot "positive" pole, i.e. as the brake pedal is pressed, the wiper moves closer to that pole Brake pot wiper to "negative" pole of throttle throttle pot wiper to inverter input throttle "positive" pole to 3.3V
So when you press the brake pedal the voltage is drawn towards GND. Full brake is potmin. When you press the accelerator pedal the voltage is drawn towards Vcc and full throttle is potmax.
Of course that also means that pressing both throttle and brake gives a weird combination of the two.
Don't forget to disconnect the brake switch, as it sets the regen torque to a fixed value.
<u>VW Polo 86C High Voltage AC Conversion</u> - <u>AC Motor Inverter Kit</u>
Quote 22 Ma
Page 104 of 221 Â « First < 4 54 94 102 103 104 105 106 114 154 204 > Last » Y
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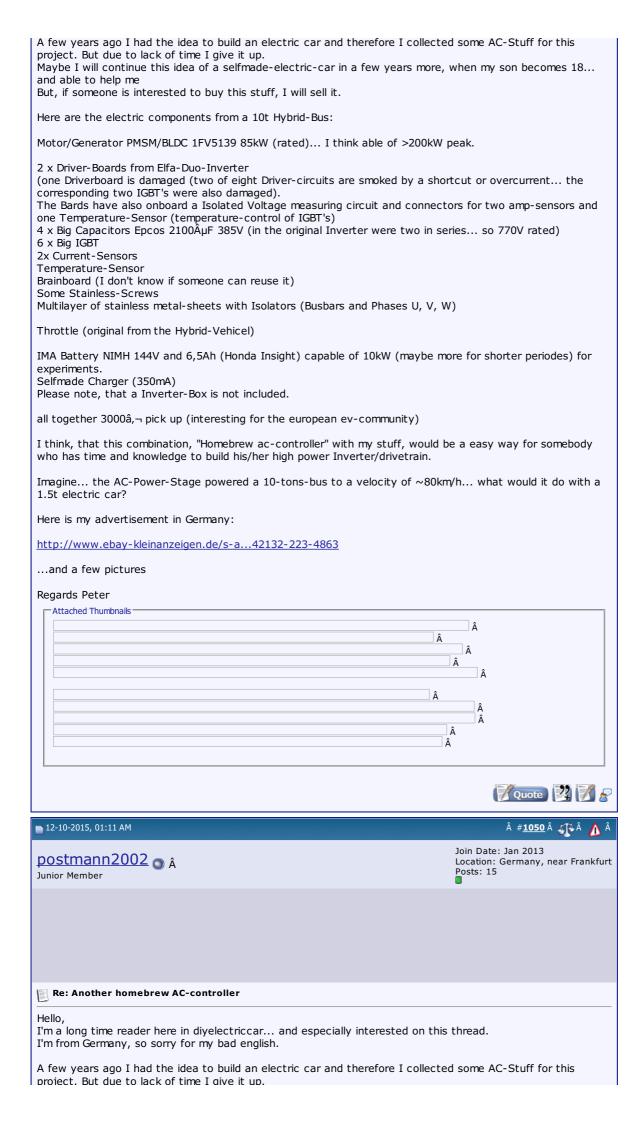
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■ 11-25-2015, 03:10 PM	# <u>1041</u> "	<u> </u> Â	DIY Ele
arber333	Join Date: D Location: SI Posts: 782		
Re: Another homebre	w AC-controller		Sponsors
Quote:			
Originally Posted by Congratulations on S	jhuebner 🛐 9000km! That was quick.		
Most things are out	of my reach right now.		
but this one:			
You	a nota in action.		
You can connect th	e pots in series: ositive" pole, i.e. as the brake pedal is pressed, the wiper moves closer to tha	+	
pole	o "negative" pole of throttle	L	
- throttle pot wiper - throttle pot wiper - throttle "positive"	to inverter input		
So when you press	the brake pedal the voltage is drawn towards GND. Full brake is potmin. When erator pedal the voltage is drawn towards Vcc and full throttle is potmax.		
Of course that also two.	means that pressing both throttle and brake gives a weird combination of the		
Don't forget to disc	onnect the brake switch, as it sets the regen torque to a fixed value.		
powered by 5V and it pu	ool idea. However i forgot to say that i use hall sensor for my throttle pedal. It uts out 0.8V - 4.2V. Then i use resistor divider to get this down to 0V - 3V. I d n if i connected 5K pot in series. I am not sure i want to find out the results	ont	
I vote for separate brak	e pot seting in software later on. Whenever you are available J.		
	Quote	1	
■ 11-25-2015, 06:48 PM	# <u>1042</u> 4	<u> </u>	
dcb 💿 🔒	Join Date: D Posts: 2,170		
Senior Member Ä	· · · · · · · · · · · · · · · · · · ·		
		ſ	Become a Sponsor

Quote:	
Originally Posted by arber333 - I will have to figure out how to use PWM output indication of motor temp made this work.	perature. I still havent
a while ago I used a pwm signal to drive a cheap low power analog meter (for a experimented with the duty cycle and set the max duty cycle to 100%fsd, and might be able to feed a potentiometer and have the wiper drive the meter for a I do now, I might add a "freewheel" diode and/or drive it with a transistor, but y voltmeter can probably be scaled with a pot and very small capacitor to give a 1.00 v = 100 degrees (C or F, whatever floats your boat)	half of that was %50 fsd. You adjustment too. knowing what you get the idea. A <u>digital</u>
edit, I assume the max output from the pwm is \sim 3.2v so keep that in mind whe \Box Attached Thumbnails	en scaling for C/F.
Â	
Last edited by dcb; 11-25-2015 at 07:13 PM.	
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■ 11-26-2015, 12:03 AM	â # <u>1043</u> â 🐠 â <u> Å</u> â
ibuobnor -	Join Date: Apr 2010 Location: Germany
jhuebner Senior Member Â	Posts: 927
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by arber333 Originally Posted by arber333 Originally Posted by arber333 <i>its powered by 5V and it puts out 0.8V - 4.2V. Then i use resistor divider t</i> <i>3V. I dont know what would happen if i connected 5K pot in series. I am no</i> <i>the results</i>	to get this down to OV - ot sure i want to find out
Ok sure.	
Quote: Originally Posted by dcb <i>a while ago I used a pwm signal to drive a cheap low power analog meter experimented with the duty cycle and set the max duty cycle to 100%fsd, fsd. You might be able to feed a potentiometer and have the wiper drive t too. knowing what I do now, I might add a "freewheel" diode and/or drive you get the idea. A <u>digital voltmeter</u> can probably be scaled with a pot and give a meaningful result too (i.e. 1.00 v = 100 degrees (C or F, whatever f</i>	and half of that was %50 he meter for adjustment it with a transistor, but d very small capacitor to
edit, I assume the max output from the pwm is ~3.2v so keep that in mind	d when scaling for C/F.
The PWM is open collector (BC549) and his indicator only has two wires. But it 12V, GND to the PWM output that has been filtered with an RC like your scheme	
VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	Quote 🕎 🏹 🔎
■ 11-26-2015, 12:28 PM	# <u>1044</u> 🕀 🧥 Â
dcb Senior Member Â	Join Date: Dec 2009 Posts: 2,170
🔄 Re: Another homebrew AC-controller	
Quote:	



Cant recall what fweak was, seem to think it is 124 Hz, set for the larger motor in the car? Fortunately the motor in my car already has a suitable encoder HEDS-5605-FB fitted, as described in the attached. Just ordered a KTY83 temp sensor, as the one fitted to the motor is much like that provided for the inverter temperature.		
Hopefully next video is spinning the 90kW peak 25 kW contin	uous motor installed. 🥶	
Attached Thumbnails		
	Â	
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■ 12-10-2015, 01:00 AM	# <u>1049</u> ∰ <mark>∕</mark> Â	
postmann2002 o Â Junior Member	Join Date: Jan 2013 Location: Germany, near Frankfurt Posts: 15	
Re: Another homebrew AC-controller		
Hello, I'm a long time reader here in diyelectriccar and especially I'm from Germany, so sorry for my bad english.	interested on this thread.	

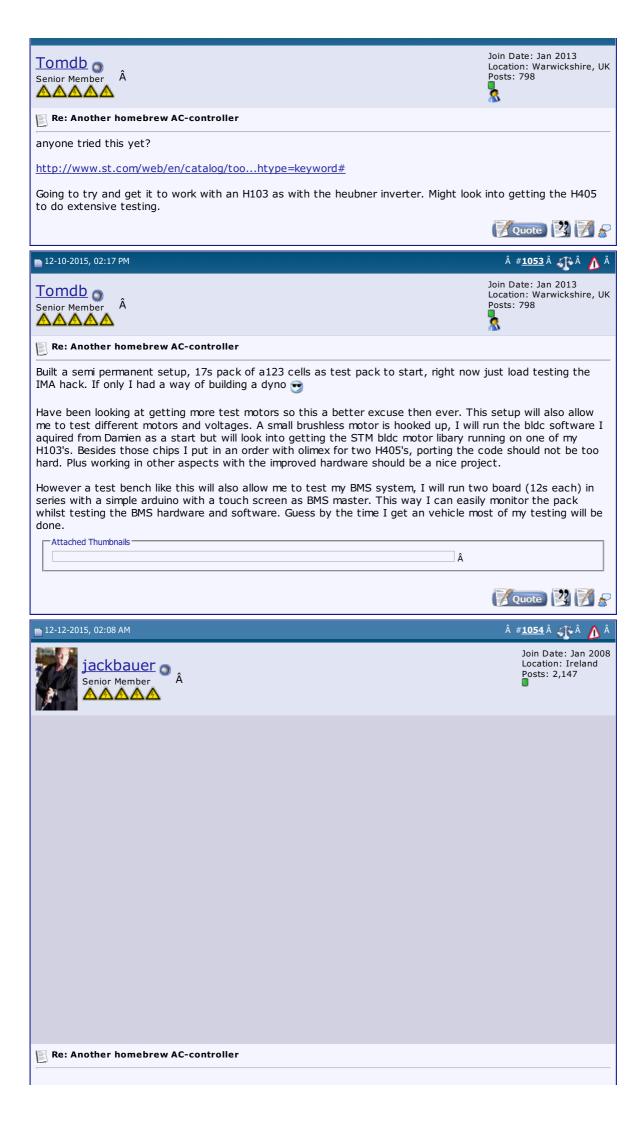


Maybe I will continue this and able to help me But, if someone is interes			more, when my son become	es 18
Here are the electric corr				
Motor/Generator PMSM/B	LDC 1FV5139 85kW (1	rated) I think able of >2	200kW peak.	
corresponding two IGBT's The Bards have also onbo one Temperature-Sensor 4 x Big Capacitors Epcos 6 x Big IGBT 2x Current-Sensors Temperature-Sensor Brainboard (I don't know Some Stainless-Screws	ged (two of eight Driv were also damaged). bard a Isolated Voltag (temperature-contro 2100µF 385V (in the if someone can reuse	ge measuring circuit and c l of IGBT's) e original Inverter were tw	v a shortcut or overcurrent onnectors for two amp-sens vo in series so 770V rated) U, V, W)	ors and
Throttle (original from the	e Hybrid-Vehicel)			
	nd 6,5Ah (Honda Insi		aybe more for shorter periode	es) for
all together 3000â,¬ pick	up (interesting for th	e european ev-community	')	
		controller" with my stuff, v igh power Inverter/drivetr	would be a easy way for som ain.	nebody
Imagine the AC-Power- 1.5t electric car?	Stage powered a 10-	-tons-bus to a velocity of	\sim 80km/h what would it do	o with a
Here is my advertisement	in Germany on "ebay	-kleinanzeigen":		
http://www.ebay-kleinan	zeigen.de/s-a4213	2-223-4863		
and a pictures				
More informations here in	diyelectriccar market	tplace:		
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Regards Peter				
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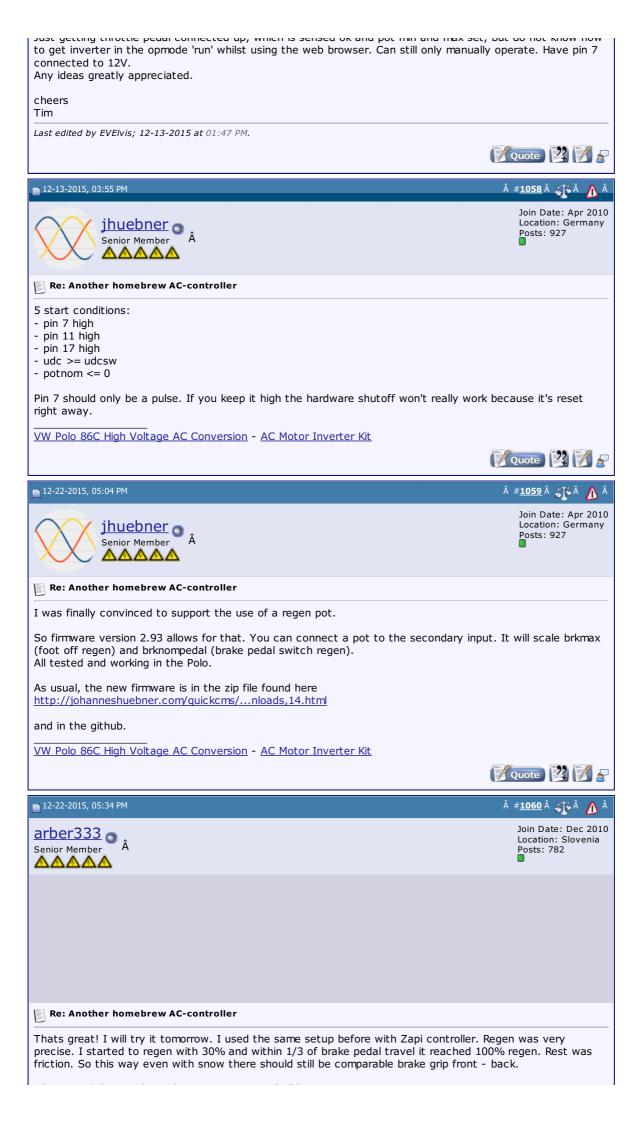
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12-10-2015, 01:47 AM			# <u>1</u>	051 Â 🐠 Â	<mark>∕∆</mark> Â	
postmann2002 o p	Â		Join Date: Jan 20 Location: Germa Posts: 15		ankfurt	
Re: Another homebrew	AC-controller					Sponsors
Hello, I'm a long time reader here I'm from Germany, so sorry	e in diyelectriccar and es y for my bad english.	specially interested on this	thread.			
project. But due to lack of Maybe I will continue this and able to help me	e idea to build an electric ca of time I give it up. idea of a selfmade-electric ted to buy this stuff, I will s	-car in a few years more, w				
Here are the electric comp	ponents from a 10t Hybrid-	Bus:				
Motor/Generator PMSM/BL	LDC 1FV5139 85kW (rated).	I think able of >200kW p	eak.			
corresponding two IGBT's The Bards have also onboo one Temperature-Sensor (4 x Big Capacitors Epcos 2 6 x Big IGBT 2x Current-Sensors Temperature-Sensor Brainboard (I don't know if Some Stainless-Screws	ged (two of eight Driver-circ were also damaged). pard a Isolated Voltage mea (temperature-control of IGF 2100µF 385V (in the origin	suring circuit and connecto BT's) nal Inverter were two in ser	ors for two amp ies so 770V i	-sensors a		
Throttle (original from the	Hybrid-Vehicel)					
IMA Battery NIMH 144V ar experiments. Selfmade Charger (350mA) Please note, that a Invert		apable of 10kW (maybe mo	re for shorter p	periodes) f	or	
all together 3000â,¬ pick u	up (interesting for the euro	pean ev-community)				
	tion, (UMC or Homebrew ac as time and knowledge to b				easy	
Imagine the AC-Power-S 1.5t electric car?	Stage powered a 10-tons-b	bus to a velocity of ~80km,	/h what wou	ld it do wit	:h a	
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or here on "marketplace":						
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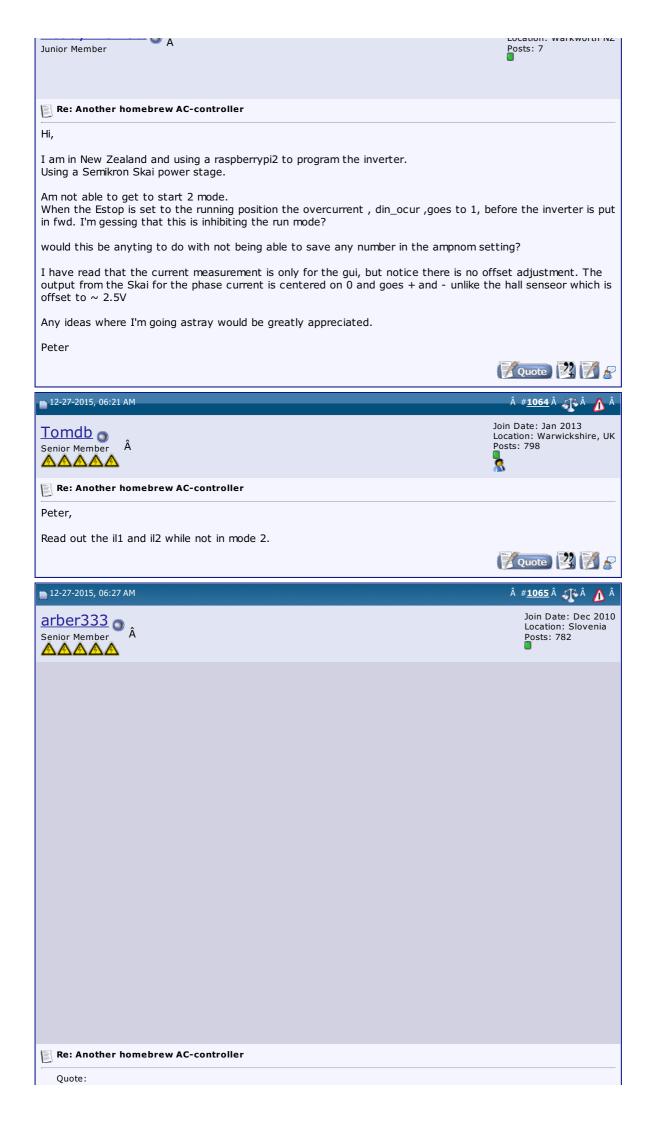


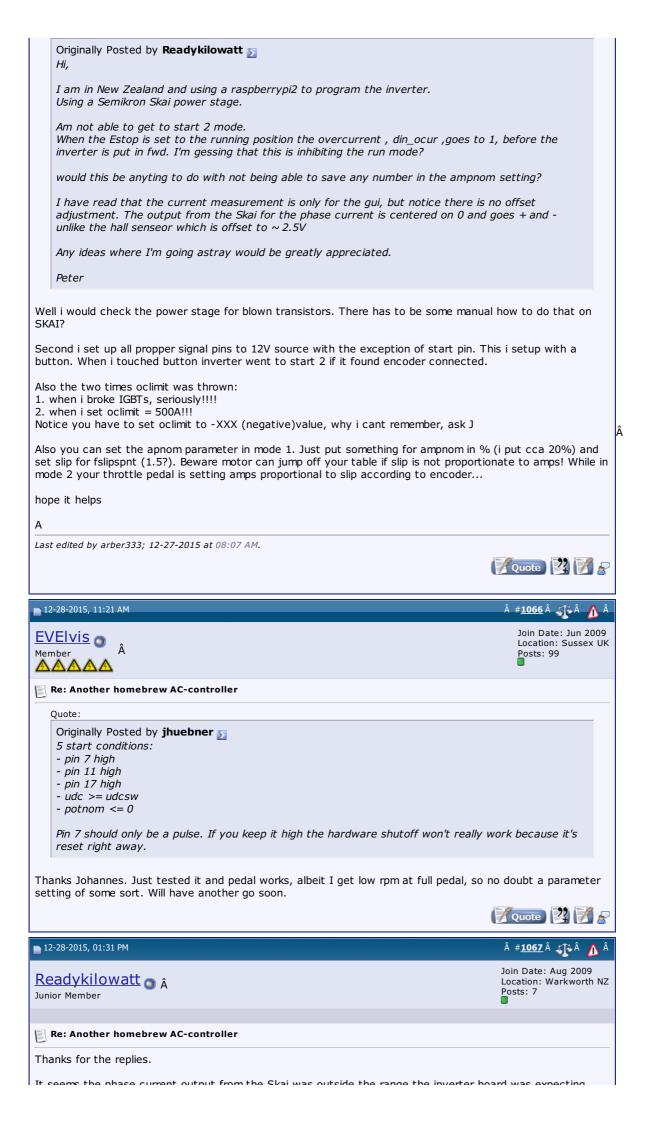
	al pot. Expensive as hell but press.com/201/regenerac	, , , ,	etup.
Around new year i will hav something	e 10KKm on your controller	without any significant prot	plems. That gets to show
I spend cca 75Ah for my d consumption also. Cells sh	laily trip. Thats some 23kWh ould last good time.	n out of 24kWh planned so i	math shows good
tnx			
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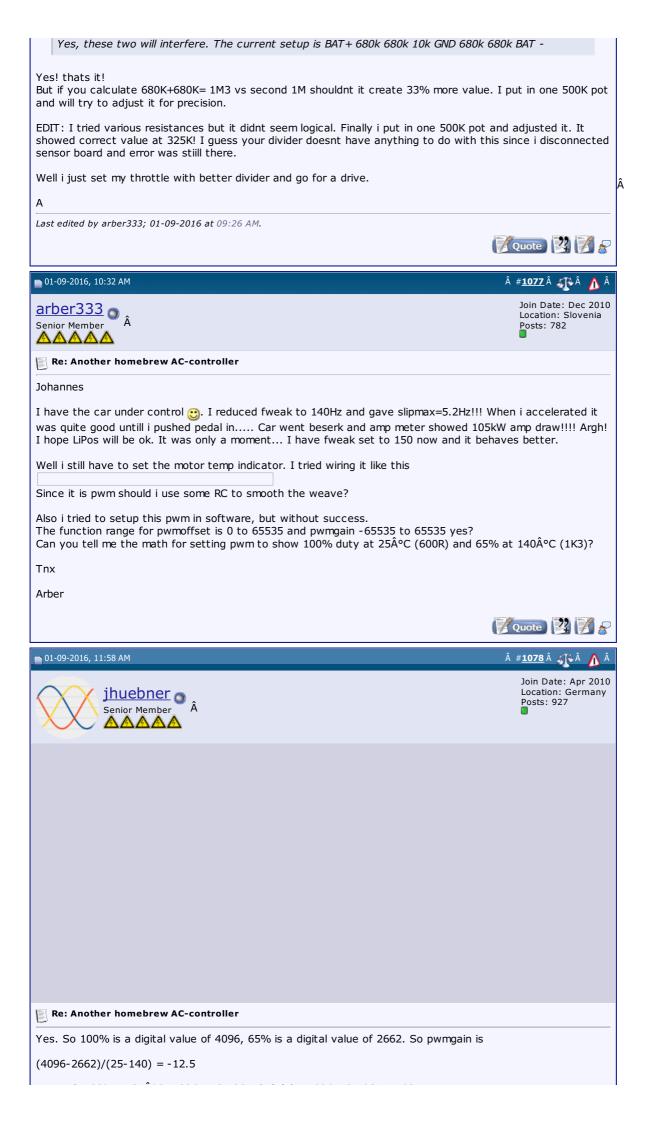
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	Originally Posted by arber333 There is also a side issue i want to discuss.
	I am using pedal hall sensor as throttle. It is 0.8V - 4.2V signal and runs on 5V. I used voltage divider that made 0.5V - 3.3V. Now when i connected to throttle i only got digital value from 580 to
	3500! Why would that be?
	Resistor values are 6K8 signal to gnd and 1k8 throttle to signal out. Did you use some pullup resistors in circuit. Should i add it to this divider?
Ye	s, there is a 47k pull down resistor on both pot channels.
	Quote:
	Originally Posted by arber333 \sum Also i tried to wire second 5K pot (resistive potentiometer) to brake pedal and i got marginal results.
	I connected 5K resistor from 3V3 to signal then wire to pot wiper and one wire to gnd. I get digital
	value from 150 to 3000. This wiring works but i get some anomalies while driving.
So	unds good so far.
	Quote:
	Originally Posted by arber333 p
	E.g. when i push brake switch even throttle regen goes to 0. When i press further regen is applied
	from 0 to some 4kW. By then car is at halt by friction. Normally that would work very good in winter, but since brake regen does not go from throttle
	regen it gets a little jerky when i alternate from brake to throttle pedal while driving. Is it possible that throttle divider interferes with brake pot and vs?
	is a possible that throttle divider interferes with brake pot and vs:
Wh	at are your settings for brknom, brkmax and brknompedal? Currently, the brake pod scales both, brkmax
and	d brknompedal. When the brake pot goes out of range, no scaling is done at all to allow operation without it pot. So you should add some leeway to pot2min and pot2max.
LIIC	
	Quote:
	Originally Posted by arber333 <i>I installed a new firmware on my EVdisplay to extend the sensing area to 450V and put 1M resistor</i>
	inline with battery + as per instructions. Woa it showes 237V!!! I schratched my head for a
	minute but i figured only electronic part left in my car that uses resistor divider is controller. That must be interfeering with EVdisplay probe
	Johannes how much total resistance is there from +B to -B in your sensing circuit? I may have to recalculate sense resistor for EVdisplay.
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to reach 100% at 25A°C: 4096=-12.5*25+b (=) b= 4096+12.5*25=4408	
so, pwmofs=4408	
And use a small R and large C to get rid of the ripple and not have to much loss over the relike 47R and 470ŵF.	esistor. Something
Your drawing is wrong, the indicator must be tied to 12V and the cathode to Pin 18.	
EDIT: you can test digital values by setting pwmgain to 0 and then try values between 0 a pwmofs	nd 4096 for
Attached Thumbnails	
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VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
Last edited by jhuebner; 01-09-2016 at 12:50 PM. Reason: Added drawing	
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■ 01-10-2016, 04:42 PM Â	# <u>1079</u> Â 🅀Â <u>A</u> Â
arber333	Join Date: Dec 2010 Location: Slovenia
Senior Member Â	Posts: 782
	-
Re: Another homebrew AC-controller	
Well sht i connected it wrong. Yes positive is on pin18 and negative to gnd. I taught to pin18 and +12V but it didnt work well. I will have to take my dash out tomorrow and rewire it.	make a pullup on
Meanwhile i figured the power reduction. It works. I had to set fslipmax to 5.2Hz and fpcor matter what i do with throttle now it allways ends at 230A!!! I guess 6.2Hz was too much, motor didnt complain. I will stretch this a bit to 250A.	
Also i set the brake pedal sensor. I set pot2min to start reading BEFORE brake switch is on allways have larger "brake" than "release". Also i measured brake position and set pot2max pedal travel. It works great!	
I cant wait when you have time to put your mind to PMSM control. That should be somethic controller running ANY motor available \bigcirc . Er aside from multiphase SRM but we can get	
tnx	
A	
	Quote 🕎 📝 🔗
01-13-2016, 05:37 PM Â	# <u>1080</u> Â 🎊 Â 🧥 Â
	Join Date: Apr 2010
jhuebner Senior Member Â	Location: Germany Posts: 927
Re: Another homebrew AC-controller	
Just wanted to introduce a project that I started back in 2014 whilst driving through Austr	alia.
It's the missing link from making the inverter kit a full inverter kit. Due to a lack of time I ha project for a while. Now I wanted to at least show it off.	ad to ditch the

 A dual layer PCB with mo A digital isolator and a D 3 4A dual bootstrap drive 6 100µF film capacitors 12 600V/160A (@125°C 	C/DC converter for is ers with a total 120A RN	olation 1S ripple current rating		
The IGBTs where designed	l for unipolar gate driv	ve.		
	sm on a solid aluminur	m plate. Also the ringing o	ts, just general heating becau on the DC bus is really minima	
So I reckon this power statesting it though.	ige can be used up to	o 450V and 250A (~100k)	W). I currently have no mean	s of
The BOM adds up to about	t 300â,¬.			
Attached Thumbnails				
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VW Polo 86C High Voltage	AC Conversion - AC	Motor Inverter Kit		
Last edited by jhuebner; 01-13				
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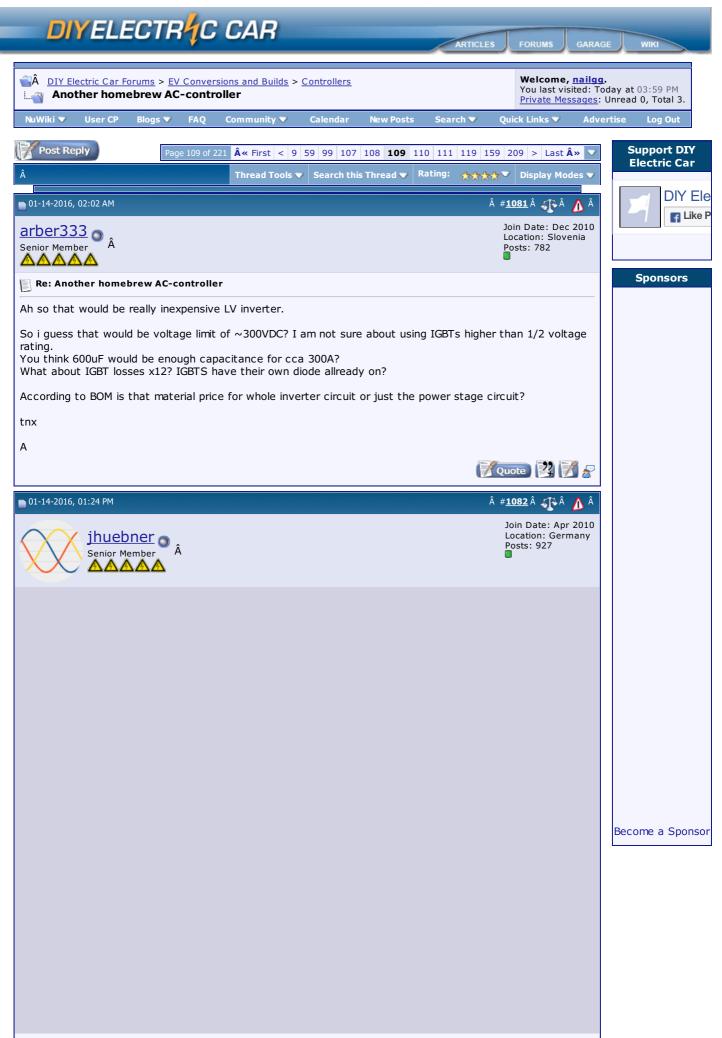
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I don't know if I am supposed to post here but I got my controller running my leaf motor in my Honda CRX...



Re: Another homebre	w AC-controller		
Quote:			
Originally Posted by So din_bms goes hig		verse? You set bmslimhigh t	o 35?
Thats the setup I'm	using as well. There's	s no mechanism that should	prevent this from working.
Huh, then i will set it evision is lower than 35 yes?	en lower. When i reve	rse car wants to lurch back	if i am not careful with pedal 25
A			
			📝 Quote) 🕎 🌠 🏾
01-17-2016, 10:22 AM			â # <u>1090</u> â 🐢 â <u>۸</u> â
jhuebne Senior Memb	er Â		Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebre	w AC-controller		
Quote:			
Originally Posted by 25 is lower than 35			
Yes <u>VW Polo 86C High Voltac</u>	<u>je AC Conversion</u> - <u>AC</u>	<u>C Motor Inverter Kit</u>	
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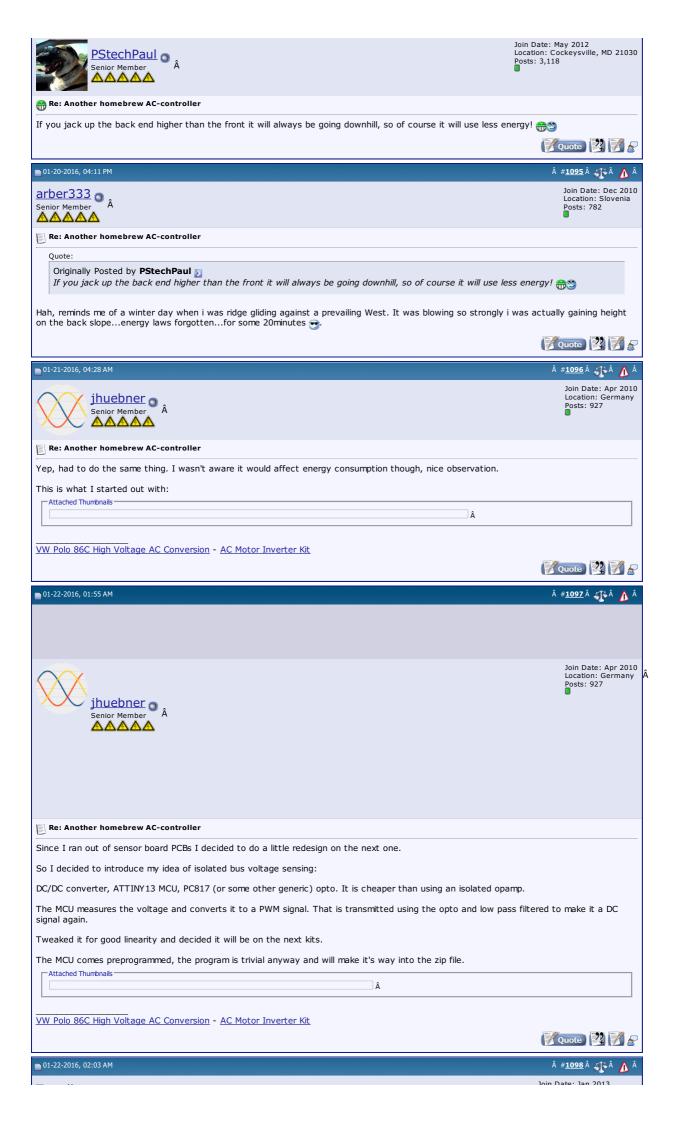
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💼 01-17-2016, 03:49 PM Â # <u>1091</u> Â 🎝 Â 🧘 Â	
arber333 Join Date: Dec 2010 Senior Member Â A A A A Posts: 782	
Re: Another homebrew AC-controller	Sponsors
Well BMS(actually it is reverse) limit works somewhat better now.	
How does value -1 affect regen? What would -5 do?	
Also i set the RC divider and propper polarity of my temp indicator like you suggested. I had to adjust values some due to my 13.8V workng voltage. It works very good. I simulated KTY84 reading using resistors. At 85ŰC indicator is yellow, at 110ŰC and 120ŰC it is blinking yellow amd at 145ŰC it turns red. Over 150ŰC it blinks fast and beyond 160ŰC it goes out. I will check tomorrow how this works. Later i will maybe add 12V stable regulator if i find voltage drop	
For anyone who would need this kind of (voltage) sensor http://www.ebay.co.uk/itm/6v-12v-24v8AAMXQVT9S2Hr5	
EDIT: I have set gain to -22.5 and offset to 3550. Those values were most accurate from 85°C to 140°C where my motor would run. Today in the morning i drove to work at 100km/h and watched. LED wouldnt even go past green. So cooling is very effective, even though it was -5°C outside :.	
Last edited by arber333; 01-18-2016 at 02:35 AM.	1
n 01-17-2016, 03:54 PM Â #1092 Â 🖓 Â 🏠	
jhuebner Senior Member Â	
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by arber333 Well BMS(actually it is reverse) limit works somewhat better now. How does value -1 affect regen? What would -5 do?	
-1 is pretty much no regen at all. Try what works best for you. I think my setting is -20. More negative value - more regen - more braking force.	
Quote:	Become a Sponsor
Originally Posted by arber333 Also i set the RC divider and propper polarity of my temp indicator like you suggested	
Great 🙂	
VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
	1
n 01-20-2016, 05:48 AM Â # 1093 Â 🌾 Â 🏠 Â	
arber333 Join Date: Dec 2010 Senior Member Â A A A A Posts: 782	
E Re: Another homebrew AC-controller	
Some info. I added 25mm alu standoffs over rear shocks to lift the rear part of car to acceptable height. It wasnt difficult. Now car is at somewhat level ride again.	
Now i noticed something weird Cca 1kW less consumption at 100km/h on level roadhuh!? I guess suspension geometry changed when i put 150kg of cells in the trunk. Now that i returned (as much as i could) to default again i see	
improvement That goes to show good alignment is mandatory when converting EVs.	1



Tomdb Senior Member Â			Location: Warwickshire, UK Posts: 798
Re: Another homeb	rew AC-controller		
Does the PWM get re	duced to an linear signal again, or does	the H103 convert the PWM based on duty c	ycle?
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n 01-22-2016, 02:25 AM			# <u>1099</u> ∢ ∰ <mark>∕</mark> Â
			Join Date: Apr 2010
Senior Me	ner A Amber Â		Location: Germany Posts: 927
Re: Another homeb	orew AC-controller		
Quote: Originally Posted Does the PWM ge		does the H103 convert the PWM based on du	ty cycle?
Quote:			
Originally Posted The MCU measure a DC signal again.	es the voltage and converts it to a PW	M signal. That is transmitted using the opto	and low pass filtered to make it
So yes, linear signal.			
The new board has e	xactly the same electrical interface as	the previous.	
VW Polo 86C High Vol	- Itage AC Conversion - <u>AC Motor Inverte</u>	er Kit	
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n 01-22-2016, 12:29 PM			# <u>1100</u> ∡∰ <mark>∆</mark> Â
arber333 Senior Member Â			Join Date: Dec 2010 Location: Slovenia Posts: 782
Re: Another homeb	orew AC-controller		
Good thinking J!			
I found it annoying to	have to add so many DCDC converter	s for each thing that misbehave when i rev m	ıy motor.
I will order one board	of course 🙂		
EDIT: I also found our one 12V nonisolated F		car and today motor temp light was blinking (orange for some time I will add
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Last edited by arber333;	01-22-2016 at 12:37 PM.		
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Does FOC use th	e bus voltage?			
		voltage if it is trying to be	accurate when sorting out t	the
slowly, then the resu	Ilts are not as good as if it			
Last edited by dcb; 01-2	2 3-2016 at 02:30 PM .		Quote	2 📝 🖉
01-26-2016, 10:33 PM	Di6, 10:33 PM ember Â inother homebrew AC-controller uls FOC controller doesn't require bus voltage, so maybe not critical for that appliout DTC, but that is a whole 'nuther. with DTC, but that is a whole 'nuther. Reply Page 111 of 221 Å < First < 11 61 101 109 110 111 112 113 121 1	# <u>1110</u> 🎸	🏹 Â <u> </u> Â	
dcb Senior Member Â			Join Date: Posts: 2,1	: Dec 2009 .70
Re: Another home	brew AC-controller			
		oltage, so maybe not crit	ical for that application. you	might be
nght about Die, but	that is a whole mather.		Quote) 📝 🖕
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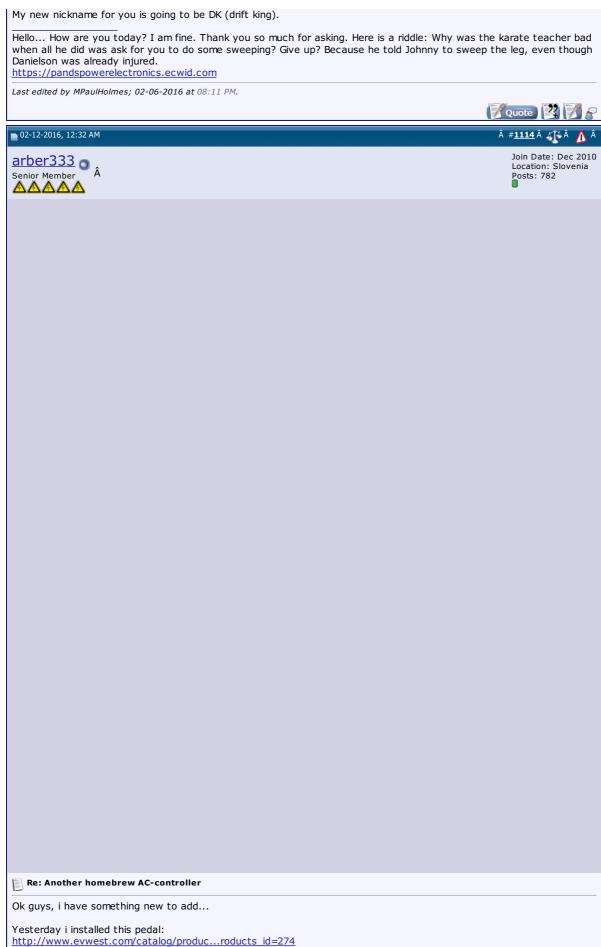
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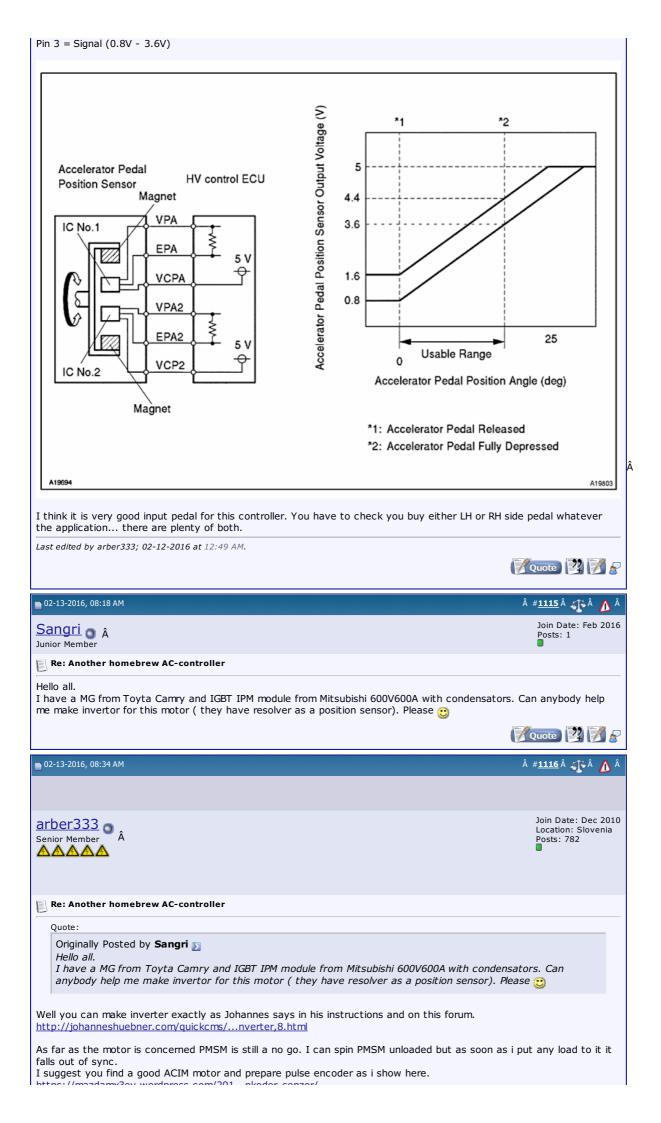
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E Re: Another homebrew AC-controller			
The inverter spinning up a big Siemens 1PV5138 for my drift car project			
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iackbauer 💊 🗠	oin Date: Ja ocation: Irel osts: 2,147		
E Re: Another homebrew AC-controller			
For those people using my version of the PCBs please see the attached photo for a wire link that needs New boards will not need this.	to be fitte	d.	
Attached Thumbnails			
Now, Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 10 that's bad. www.evbmw.com			
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■ 02-06-2016, 09:04 AM Â # 1	<u>113</u> Â 🐠 Â	Â	
	oin Date: Fe osts: 153 		Become a Spons
Re: Another homebrew AC-controller			
Re: Another homebrew AC-controller			
Quote: Originally Posted by jackbauer The inverter spinning up a big Siemens 1PV5138 for my drift car project			



I bought it from ebay for $60\hat{a},\neg$ and it was in very good condition. It is Toyota Prius II pedal that works from 5V BUT can create 2 outputs. One is 1,6V to 5V and second from 0,8V to 3,6V. I used second o/p and behold... very smooth start but firm throttle response all the way to 100%. Electrical stop ends a little sooner than mechanical stop but that can be arranged 😲

Connection is straightforward. It has 6 pins that can accept 2.8mm female faston crimp. I simply connected lower three pins.





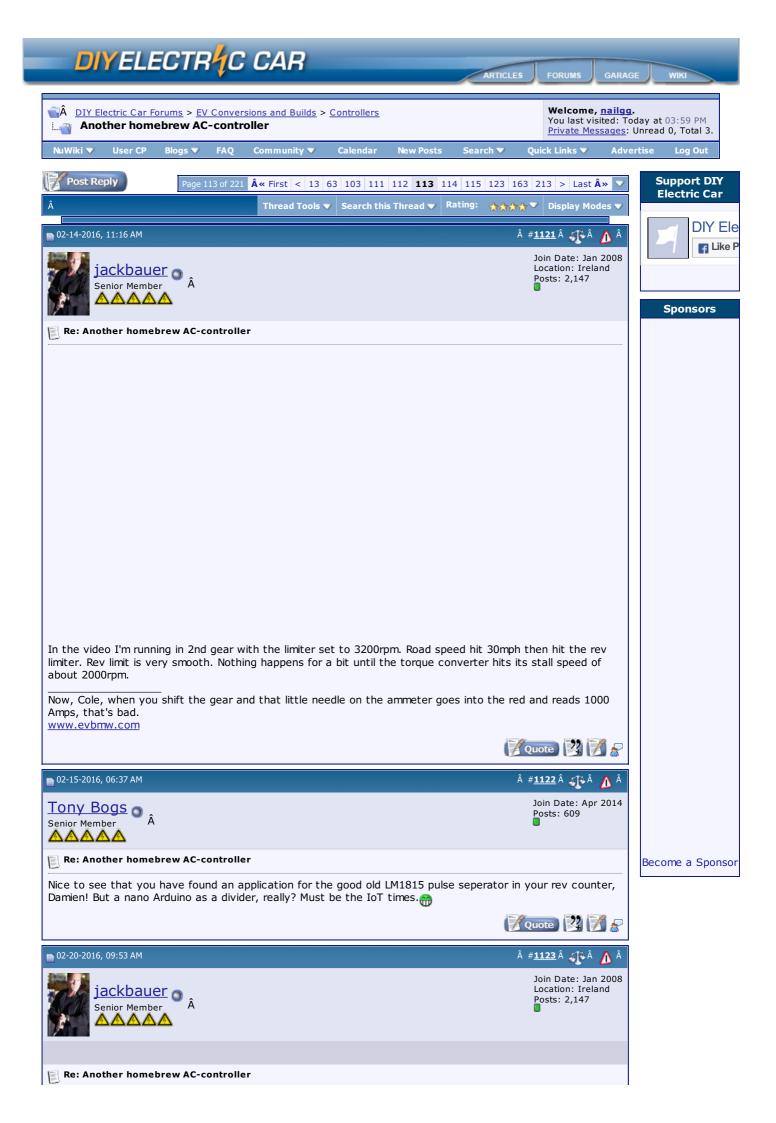
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Originally Posted by j Controller power tes			
Apparently, with no need	for that fire extinguisher	•	
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	olver to encoder converter. Works so much better then the luck getting the motor to run in torque mode as yet
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low, Cole, when you shift the gear and that little mps, that's bad. www.evbmw.com	e needle on the ammeter goes into the red and reads 1000
02-20-2016, 02:53 PM	# <u>1124</u> 👫 🧥
enior Member Â	Join Date: Sep 2008 Location: San Francisco Peninsula, CA, US Posts: 262
Re: Another homebrew AC-controller	
Quote:	
	e limiter set to 3200rpm. Road speed hit 30mph then hit thing happens for a bit until the torque converter hits its
	ng. I'm expecting similar results with my E46, so will hopefull
001 BMW 330ci conversion (Chevy Volt batterie	
02-25-2016, 03:23 PM	# <u>1125</u> J ⁱ A A
jackbauer Senior Member Â	Join Date: Jan 200 Location: Ireland Posts: 2,147
Re: Another homebrew AC-controller	
-	

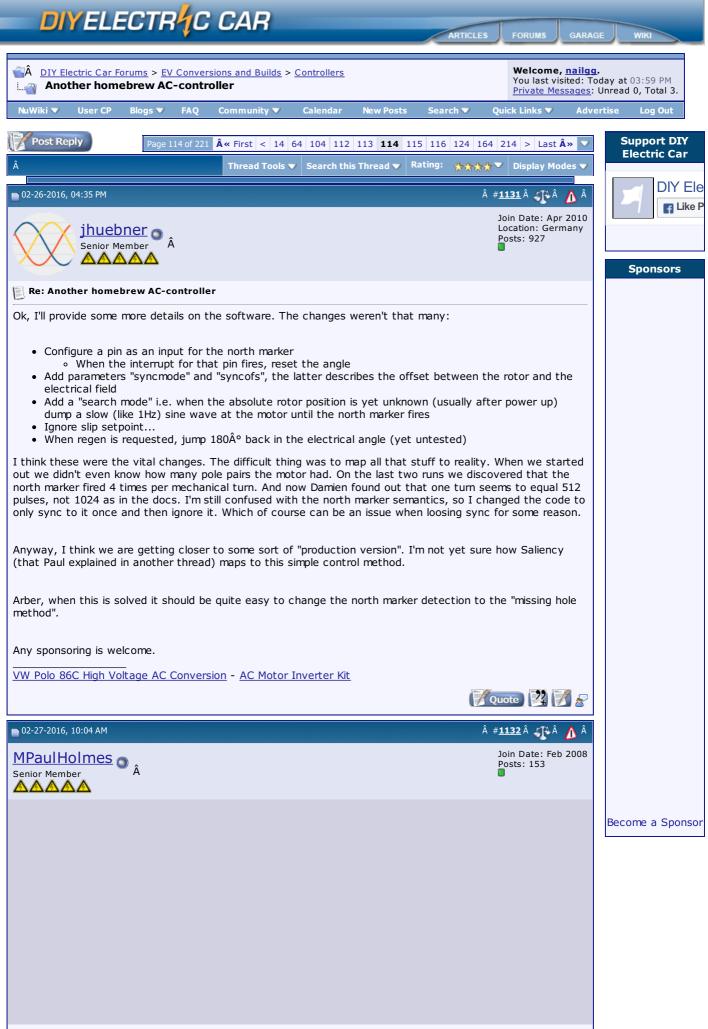
control tonight :	
	Ä
Now, Cole, when you shift the gear and that little needle on the amm Amps, that's bad. www.evbmw.com	neter goes into the red and reads 1000
	Vuote 🕎 📝 🔗
■ 02-25-2016, 03:24 PM	# <u>1126</u> ∰ <mark>≬</mark> Â
Tomdb Senior Member Â	Join Date: Jan 2013 Location: Warwickshire, UK Posts: 798
Re: Another homebrew AC-controller	
Wonder what changed, and what is the starting sequence/mode?	Vuote 🕎 📝 🔗
■ 02-25-2016, 03:27 PM	â # <u>1127</u> â 🕂 â <u> â</u> â
jackbauer Senior Member Â	Join Date: Jan 2008 Location: Ireland Posts: 2,147
Re: Another homebrew AC-controller	
Still lots more to do as it is still a bit flaky but was great to get it run I'll let Johannes explain the software	ning. Went through so many dead ends!
Now, Cole, when you shift the gear and that little needle on the amm Amps, that's bad. <u>www.evbmw.com</u>	neter goes into the red and reads 1000
	Quote 🕎 🖉 🔗
■ 02-25-2016, 03:41 PM	# <u>1128</u> ∰ Â
A A A A A A A A A A	Join Date: May 2012 Location: Cockeysville, MD 21030 Posts: 3,118
Are: Another homebrew AC-controller	
It looks like there is only a small range of throttle position from zero t the torque control needing a load to operate properly. But otherwise	



Quick Reply	8
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Senior Me	ember A			
🛐 Re: Another homeb	rew AC-controller			
I wonder why it jumps a low frequency.	s back and forth so much.	. For this one rotation it ba	sically runs in open loop mod	le with
Quote:				
Originally Posted Ever taught about	it just sending a pulse and	d measuring the currents? at is used in the Lebowski	Should give you rotor positic starting sequence.	on,
	'd like to keep the current go wrong or can be misco		rol as long as possible to elin	ninate a
VW Polo 86C High Vol	tage AC Conversion - AC	<u>Motor Inverter Kit</u>		
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03-24-2016, 04:33 PM			# <u>1140</u> 🍕	🏹 Â 🧘 Â
jackbaue			Join Date: Location: I	
Senior Member			Posts: 2,14	
Re: Another homeb	prew AC-controller			
		nom is too low for a set fr	eauencv.	
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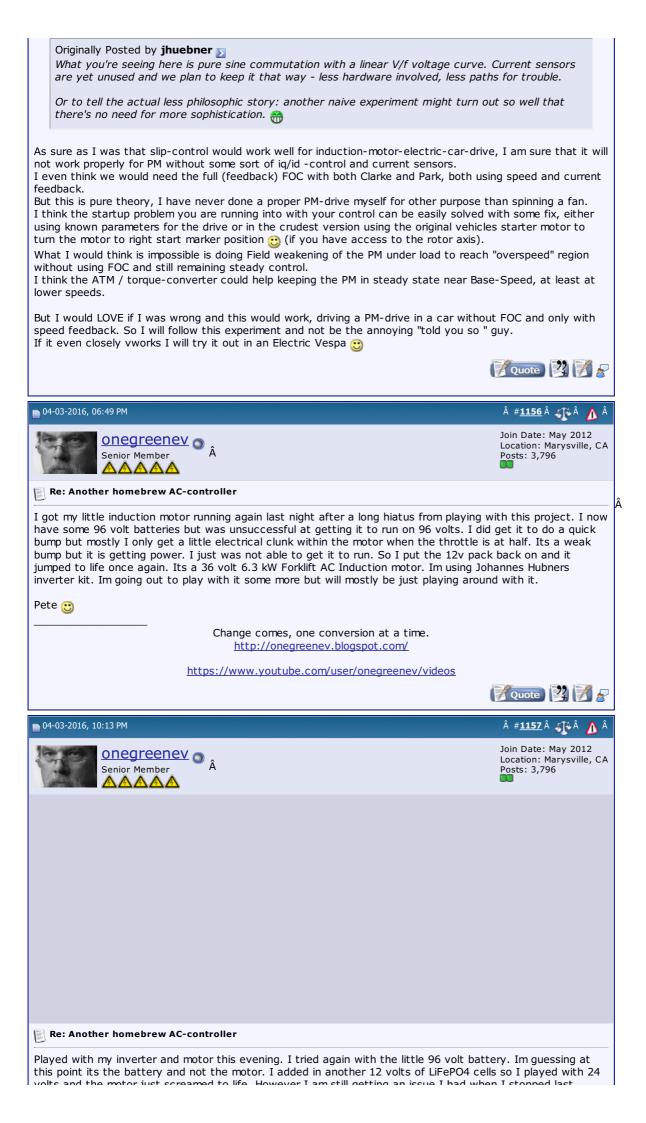
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Looks pretty smooth if the startup is not being filmed 😇 No seriously glad to see this some months after we'd started out with this jerky bumping around.







	Ocurlimit is suppose to be negative so you start at 24V 100A maybe that is the reason it is heating up. If the battery is good try 200A.
	You have sensor on your shaft? If not you have to start manually. So start manually! Put say 30Hz in fslipspnt and 20A in ampnom! Now you will run motor sensorless. You vary speed by putting different fslipspnt but you have to account for change of ampnom when you spin it up. Fweak is only for sensor operation. In sensorless you deal with fslipspnt and ampnom.
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Some small progress from my side.	
Got distracted from this setup due to wanting to run the big Remy core from controller for that and will have just mechanicals there I decide to tackle con something i could mount in a small bike.	
Dismantled the motor for its rotor, it just fit my lathe. dialed it in and drilled a encoder shaft that has a piece of friction material on it. (aka tape) Then reb fitted the encoder. A bench test confirms I spin the sprocket the encode giv volts. So it should work.	ouilt the motor, painted it and
Going to test it soon with the DIY inverter I built using all of the Huebner commonitoring setup sorted first though, some baking left to do.	mponents. Got to get my battery
Attached Thumbnails	Â
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■ 04-04-2016, 11:46 PM	â # <u>1165</u> â 🐢 â 🧴 â
A Senior Member	Join Date: May 2012 Location: Marysville, CA Posts: 3,796
Re: Another homebrew AC-controller	
Did a few software adjustments and got the motor to spin up nice and smood bit the motor shaft still got warm but not like before and not like last evening regen so I suspect that that is causing the induction heating of the shaft. S its not going to be much of an issue. Nothing that the fan can't handle I'm su ironed out, I can now move to the next portion. Putting a load on the motor that. Im going to connect up another motor to this one first. Here is a quick tonight. Just a quickie. The video I did was not so good so I'll try later for a Video is in 4k. But real short in duration. Pete 😳	g. This is still doing off throttle o if its on a load Im suspecting ure. Now that I have some things then see how well it handles flick of the motor running
Change comes, one conversion at a time.	
<u>http://onegreenev.blogspot.com/</u> https://www.youtube.com/user/onegreenev/vid	teos
https://www.youtube.com/user/onegreenev/vic	<u>Jeos</u> Quote 🕎 🏹 🎤
• 04-05-2016, 02:37 PM	# <u>1166</u> 👔 🧥 Â
	Join Date: Jan 2008 Location: Ireland Posts: 2,147



Re: Another homebrew AC-controller

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rig up some switches so i can fire the shift solenoids. Now, Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. www.evbmw.com Quote 🕺 📝 🖉 ■ 04-05-2016, 03:<u>29 PM</u> #<u>1167</u>Â 🍂 Â Δ Join Date: Jan 2013 Location: Warwickshire, UK Tomdb 👩 Â Posts: 798 Senior Member 8 Re: Another homebrew AC-controller Nice. However, does this mean that you cant run mg1 to give you daul motor drive? But this gives you a good target for an oil pump pressure. plus a blanking plate aint too bad. Probally internal regulator which is a good thing. A powersteering pump will most likely be overkill, wonder if an diesel fuel pump might work (ones used as low pressure feed that is) Last edited by Tomdb; 04-05-2016 at 03:35 PM. AQuote 22 A 💭 â #<u>1168</u> â 🌆 Â ■ 04-05-2016, 08:52 PM Λ Join Date: Dec 2015 dima 👩 Location: British Columbia, Canada Posts: 69 Â Member AAAARe: Another homebrew AC-controller

First time spinning the GS450h gearbox with oil pressure. Still need to do some tweaking on the inverter and

Made some progress, figured I post some inspirational photos 🥶

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15.47

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copper right.			
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			Quote 😰 🌠
04-06-2016, 12:05 PM			# <u>1169</u> $ { { { $
opegr			Join Date: May 2012
			Location: Marysville, Posts: 3,796
Re: Another home			
	brew AC-controller		
Quote:	hy dima =		
Originally Posted Made some prog	ress, figured I post some	inspirational photos 🙂	
		<u> </u>	uld not be proud, but hey -
copper is copper		oreakiastgranuma wo	ula not be produ, but ney -
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low are you connect	ting those caps? Looks gre	eat. make the inverter skir	nny. Great idea.
		es, one conversion at a ti negreenev.blogspot.com/	
		tube.com/user/onegreene	
	<u></u>		Quote 2
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04-06-2016, 12:56 PM			# <u>1170</u> 🌇 💋
dima 👩			Join Date: Dec 2015 Location: British Columbia, Can
And			Posts: 69
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Re: Another home	brew AC-controller		
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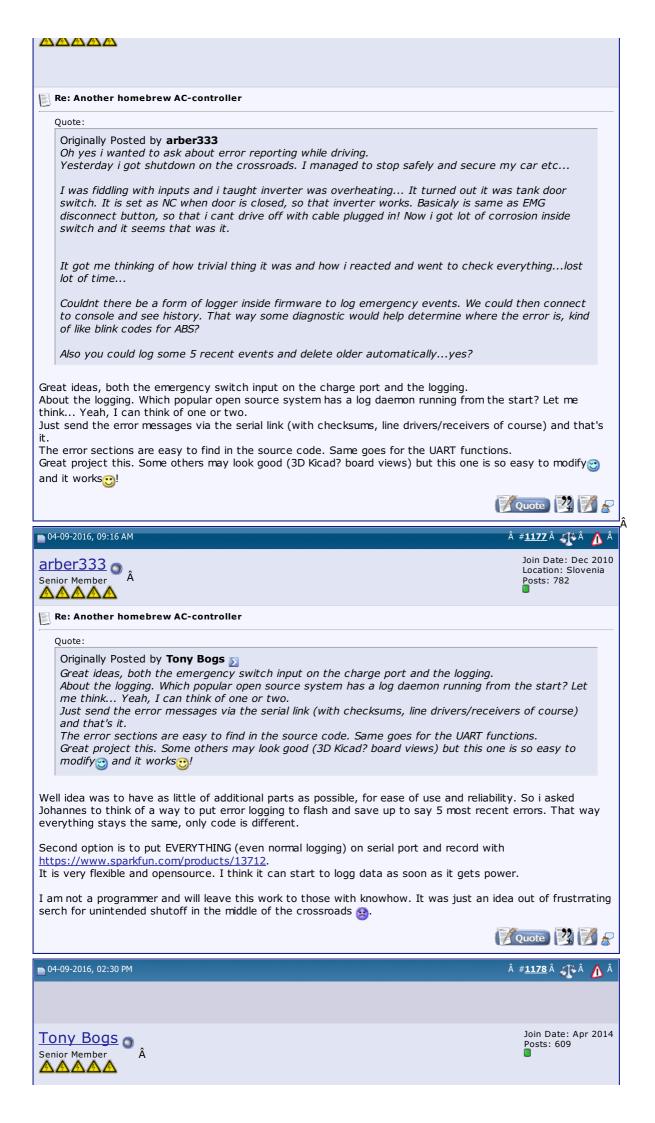
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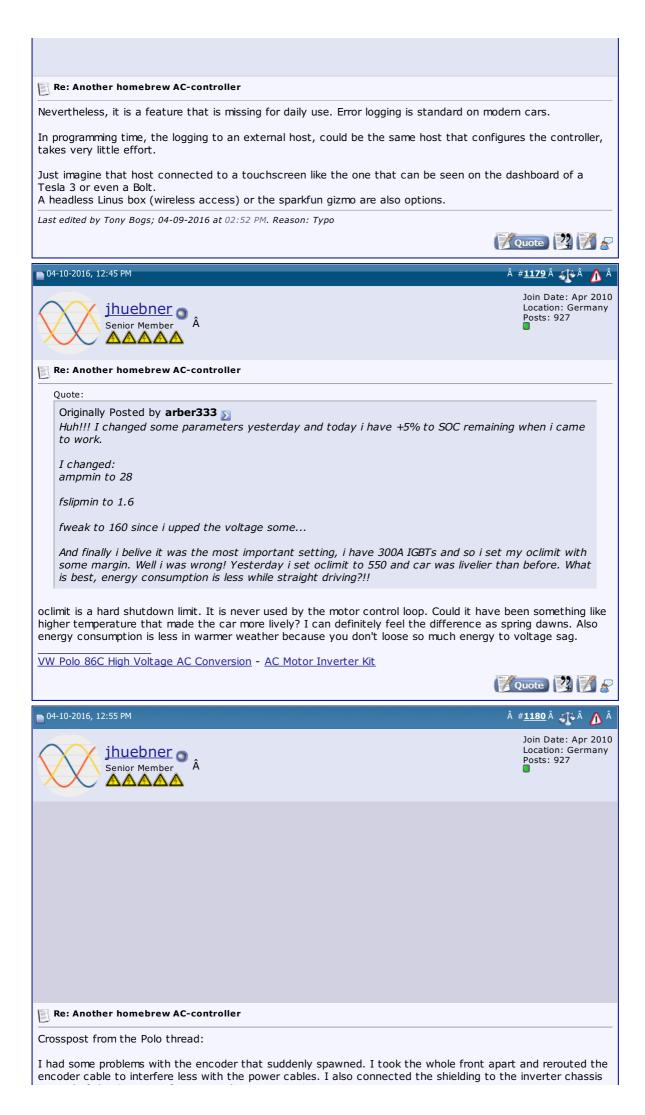
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	Quote:
	Originally Posted by dima \geq I suppose it will only work with certain fat capacitors. Tight fit - makes for precise cuts and drills with a 3mm gap. I plan to bolt those last with a small hex wrench (of course use a thinner head hex bolts than in the picture)
fou	Il i cant see why you couldnt use a small file to make the gap larger. maybe even sheet metal shears. I Ind out the hard way that 3mm gap is too small with voltages over 300VDC. The bch jumps across like Intning and you can get blown IGBT return diode. I suggest 4 to 5mm gap when applying over 300VDC.
my	2c
the	IT: I didnt use one wide rail for +/- but several thin 12mm wide strips of copper stacked together. Over m i put 2uF snubber caps. It works, period! I think i will just replace Rg 10ohm with 6R8 to get faster IGBT sing.
Las	t edited by arber333; 04-08-2016 at 06:55 AM.
0	4-08-2016, 11:14 PM Â # <u>1174</u> Â 🕀 Â 🏠 Â
	Join Date: Dec 2015 nber Â A Posts: 69
B	Re: Another homebrew AC-controller
On	e heck of a tight fit, does anyone think this is a bad idea placing snubber cap so close to driver board? 🥸
	anks <u>arber333</u> I will try to widen the gap and maybe coat the copper with some insulating lacquer.
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0	4-09-2016, 05:22 AM Â # <u>1175</u> Â 👔 Â 🏠 Â
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ar Ser	Der333 Join Date: Dec 2010 Join Date: Dec 2010 Location: Slovenia Posts: 782 Posts: 782 Quote: Quote: Originally Posted by dima ∑ One heck of a tight fit, does anyone think this is a bad idea placing snubber cap so close to driver
ar Ser E	Doin Date: Dec 2010 Location: Slovenia Posts: 782 Re: Another homebrew AC-controller Quote: Originally Posted by dima One heck of a tight fit, does anyone think this is a bad idea placing snubber cap so close to driver board? Thanks <u>arber333</u> I will try to widen the gap and maybe coat the copper with some insulating
Arr Ser A E Hrr Sni Dri	Der333 Join Date: Dec 2010 Location: Slovenia Posts: 782 Re: Another homebrew AC-controller Posts: 782 Quote: Originally Posted by dima ≥ One heck of a tight fit, does anyone think this is a bad idea placing snubber cap so close to driver board? Thanks arber333 I will try to widen the gap and maybe coat the copper with some insulating lacquer. I tried coting it but it doesnt help alone. If you have sufficient gap that is usually enough.
Arr Ser A Hrr Sni Driv Try I si	Der333 A Join Date: Dec 2010 Location: Slovenia Posts: 782 Re: Another homebrew AC-controller Quote: Originally Posted by dima ∑ One heck of a tight fit, does anyone think this is a bad idea placing snubber cap so close to driver board? ☺ Thanks arber333 I will try to widen the gap and maybe coat the copper with some insulating lacquer. I tried coting it but it doesnt help alone. If you have sufficient gap that is usually enough. ubbers are usually 1uF per 100A but i use 2,5uF for 300A and it is good. vers should be good, if you dont feel good put some thin pertinax board between as isolation ☺.
Arr Ser A Hrr Sni Driv Try I si	ber333 Join Date: Dec 2010 location: Slovenia Posts: 782 Posts: 782 Posts: 782 Quote: Originally Posted by dima > One heck of a tight fit, does anyone think this is a bad idea placing snubber cap so close to driver board? Thanks arber333 I will try to widen the gap and maybe coat the copper with some insulating lacquer. A tried coting it but it doesnt help alone. If you have sufficient gap that is usually enough. ubbers are usually 1uF per 100A but i use 2,5uF for 300A and it is good. vers should be good, if you dont feel good put some thin pertinax board between as isolation • fitting snubbers longitudinally so they clear driver board. till think you should use another layer of copper. Those caps are heavy and car is vibration enviroment. At st think how to fix caps together so they will not wobble when driving.
Hrr Ser M I I I I I I S I I S I I S	ber333 Join Date: Dec 2010 location: Slovenia Posts: 782 Posts: 782 Posts: 782 Quote: Originally Posted by dima > One heck of a tight fit, does anyone think this is a bad idea placing snubber cap so close to driver board? Thanks arber333 I will try to widen the gap and maybe coat the copper with some insulating lacquer. A tried coting it but it doesnt help alone. If you have sufficient gap that is usually enough. ubbers are usually 1uF per 100A but i use 2,5uF for 300A and it is good. vers should be good, if you dont feel good put some thin pertinax board between as isolation • fitting snubbers longitudinally so they clear driver board. till think you should use another layer of copper. Those caps are heavy and car is vibration enviroment. At st think how to fix caps together so they will not wobble when driving.
Arr Ser A E Hrr Sni Driv Try I si lea	ber333 Join Date: Dec 2010 location: Slovenia Posts: 782 Posts: 782 Posts: 782 Quote: Originally Posted by dima > One heck of a tight fit, does anyone think this is a bad idea placing snubber cap so close to driver board? Thanks arber333 I will try to widen the gap and maybe coat the copper with some insulating lacquer. At tried coting it but it doesnt help alone. If you have sufficient gap that is usually enough. ubbers are usually 1uF per 100A but i use 2,5uF for 300A and it is good. vers should be good, if you dont feel good put some thin pertinax board between as isolation . of fitting snubbers longitudinally so they clear driver board. till think you should use another layer of copper. Those caps are heavy and car is vibration enviroment. At st think how to fix caps together so they will not wobble when driving.
Arr Ser A E Hm Sni Driv Try I st lea tn> A	Doin Date: Dec 2010 Location: Slovenia Posts: 782 Re: Another homebrew AC-controller Quote: Originally Posted by dima One heck of a tight fit, does anyone think this is a bad idea placing snubber cap so close to driver board? Thanks arber333 I will try to widen the gap and maybe coat the copper with some insulating lacquer. It ried coting it but it doesnt help alone. If you have sufficient gap that is usually enough. ubbers are usually 1uF per 100A but i use 2,5uF for 300A and it is good. vers should be good, if you dont feel good put some thin pertinax board between as isolation of think you should use another layer of copper. Those caps are heavy and car is vibration enviroment. At st think how to fix caps together so they will not wobble when driving.
Arr Ser A E Hm Sni Driv Try I st lea tn> A	Der 333 Nor Member À Re: Another homebrew AC-controller Quote: Originally Posted by dima ∑ One heck of a tight fit, does anyone think this is a bad idea placing snubber cap so close to driver board? Thanks <u>arber333</u> I will try to widen the gap and maybe coat the copper with some insulating lacquer. It it ried coting it but it doesnt help alone. If you have sufficient gap that is usually enough. ubbers are usually 1uF per 100A but i use 2,5uF for 300A and it is good. vers should be good, if you dont feel good put some thin pertinax board between as isolation fitting snubbers longitudinaly so they clear driver board. cill think you should use another layer of copper. Those caps are heavy and car is vibration enviroment. At st think how to fix caps together so they will not wobble when driving.
Arrive Series Se	Der 333 Nor Member À Re: Another homebrew AC-controller Quote: Originally Posted by dima ∑ One heck of a tight fit, does anyone think this is a bad idea placing snubber cap so close to driver board? Thanks <u>arber333</u> I will try to widen the gap and maybe coat the copper with some insulating lacquer. It it ried coting it but it doesnt help alone. If you have sufficient gap that is usually enough. ubbers are usually 1uF per 100A but i use 2,5uF for 300A and it is good. vers should be good, if you dont feel good put some thin pertinax board between as isolation fitting snubbers longitudinaly so they clear driver board. cill think you should use another layer of copper. Those caps are heavy and car is vibration enviroment. At st think how to fix caps together so they will not wobble when driving.





instead of the GND Pin 1 f	or a more direct conn	ection.			
Maybe most importantly I results in a rising edge cut	changed the low pass t off frequency of 7.3	s filter. R3 and R4 are kHz and a falling edge	now 500R and C1 remains at 2 cut off frequency of 14.5kHz.	22nF. That	
Before it was 5.4KHz and (slowness of the 5.4kHz cu		mmetric with the spike	s that the 60kHz lets through	and the	
I have changed the BOM a	accordingly.				
Driving is now back to nor	mal.				
If you're having problems	with the encoder, tha	at is an easy fix.			
VW Polo 86C High Voltage	AC Conversion - AC I	<u>Motor Inverter Kit</u>			
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Post Reply	Page 118 of 221 Â « First	< 18 68 108 116 117	118 119 120 128 168 218 >	Last » 🔽	
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Quote:

Originally Posted by jhuebner 53

Looks pretty smooth if the startup is not being filmed 😁 No seriously glad to see this some months after we'd started out with this jerky bumping around.

What you're seeing here is pure sine commutation with a linear V/f voltage curve. Current sensors are yet unused and we plan to keep it that way - less hardware involved, less paths for trouble.

Or to tell the actual less philosophic story: another naive experiment might turn out so well that there's no need for more sophistication. 🚗

I agree with gunnarhs that current control is the way to go for these IPM motors based on my recent experience.

I am also all about naive experimentation but for a good experiment you almost really need the current sensors to prove that you don't need them.

My recent experiment showed me that just applying sinusoidal phase voltage relative to the rotor position (which I assume is V/f) resulted in very high reactive currents (Id currents) that I could not seem to avoid in all cases. My bus power supply didn't care either way and still showed low power draw which was misleading to me. The way to see the wasted currents is either by directly measuring the phase currents or indirectly by closly analyzing the IGBT temperature rise. In my case the currents were up to 10x what I wanted in some cases which could easily blow the IGBTs I am using.

I then designed an experiment to measure the accuracy of my sin/cos rotor sensor. I found a subtle nonlinear wobble in the position error depending on the actual shaft position. Relatively small error but could explain the higher Id currents I was seeing when the bemf is not precisely aligned with the applied voltage.

Adding in the current sensors and some FOC made the high currents go away. If I wanted to reduce complexity I would be inclined to remove the rotor sensor and go with a "sensorless" technique rather than go without the current sensors.

However I do encourage you not to take my word for it. Please experiment and share your conclusion.

JDDCircuit: Work in progress requiring a custom ECU for the Prius Inverter and Electric Transaxle.my MR2 conversion

Last edited by jddcircuit; 04-16-2016 at 12:32 PM.



🗖 04-16-2016, 05:54 PM



 #<u>1184</u>Â **∆**AÂÂ **A**

Join Date: May 2012 Location: Cockeysville, MD 21030 Posts: 3,118

🖲 Re: Another homebrew AC-controller

It seems to me that a simple V/f control should work as well as the same motor connected to three-phase

mains of the appropriate voltage and frequency according to the design. Under static load and speed conditions, I would expect the PF to be low with no load, but improve as the load is increased to rated value. But under dynamic conditions, such as start-up and rapid change of driven RPM, the motor could draw currents up to the locked rotor condition, as it would when starting conventionally without a VFD on a fixed AC source. By adding simple current sensors on the three low legs of the H-bridge, it should be possible to detect overcurrent and "short cycle" the PWM to keep the current within safe limits. Also, by simply monitoring the motor voltage on at least one phase, it should be possible to see if the voltage is less than it should be according to the V/f value, indicating a heavy load, or if greater, it would indicate regeneration. Perhaps the sensorless FOC or direct torque control algorithms do the same thing. But I like the idea of eliminating the rotor position transducer for reduced complexity and the need for additional components attached to the motor. If anything, perhaps a simple inductive proximity sensor and a one or two lobed shaft attachment could be used to read actual RPM. 📝 Quote 🕎 📝 💂 04-20-2016, 01:19 PM #<u>1185</u>Â **∭** Â Join Date: Apr 2010 Location: Germany jhuebner O Â Posts: 927 Senior Member Re: Another homebrew AC-controller Quote: Originally Posted by jddcircuit 5 Adding in the current sensors and some FOC made the high currents go away. If I wanted to reduce complexity I would be inclined to remove the rotor sensor and go with a "sensorless" technique rather than go without the current sensors. I'd also rather ditch the shaft encoder and just use the current sensors. I think eldis has achieved this I just don't know how. It's currently beyond my horizon. As long as the shaft encoder is there I want to avoid the extra complexity of current control. We'll take a closer look at the actual rotor currents next time. There is Clarke/Park in the current software and it does produce somewhat meaningful outputs. But only if you stick the current sensors to the right phases and get the spinning direction right. Two more things to go wrong on benchtop builds. VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit 🛛 🛛 Quote â #<u>1186</u> â 🎢 â 🧥 â n 04-20-2016, 01:42 PM arber333 O Â Join Date: Dec 2010 Location: Slovenia Senior Member Posts: 782 AAAAARe: Another homebrew AC-controller

Â

Quote:

Originally Posted by jhuebner 🔊

I'd also rather ditch the shaft encoder and just use the current sensors. I think eldis has achieved this I just don't know how. It's currently beyond my horizon.

As long as the shaft encoder is there I want to avoid the extra complexity of current control. We'll take a closer look at the actual rotor currents next time.

There is Clarke/Park in the current software and it does produce somewhat meaningful outputs. But only if you stick the current sensors to the right phases and get the spinning direction right. Two more things to go wrong on benchtop builds.

I think encoder drive is easier to use. Since it is only simple rotation no quadratur signals. However there is no reason you couldnt use current sensors to optimise slip/current relation. It would have to be faster response as well as calculating the sensorless phase... Hm maybe we could have flash lookup tables for comparing L1 L2 current to find L3 current.

Yes efficiency leaves somewhat to be desired...ramble ramble... but my motor is spinning regardless of super efficiency of some $10k\hat{a},\neg$ vector control inverters. And all for sub $1k\hat{a},\neg$!



#**1187** Â 🌆 Â

Λ A

04-20-2016, 04:42 PM



Join Date: Sep 2008 Location: San Francisco Peninsula, CA, USA Posts: 262

Re: Another homebrew AC-controller

I've been watching this conversation for a while now and trying my best to hold my tongue, but I feel it's necessary for me to provide my input.

Current sensors are absolutely required. Open loop control simply does not work in this sort of application. "Sensorless" control refers to lack of a rotor position sensor and normally uses current sensors and/or voltage sensors to infer the rotor position. There is no such thing as a truly sensorless inverter. You are simply replacing or inferring the information that a particular sensor would give you using OTHER sensors which you have. This interpretation is done in real time, in firmware, with very complex algorithms.

Leaving out current sensors does not improve ease of use or reliability. Quite the opposite.

If you want to reduce complexity, the best way to do this is to directly measure the things that you need to measure. Specifically, phase currents and rotor position. That's as simple as it gets.

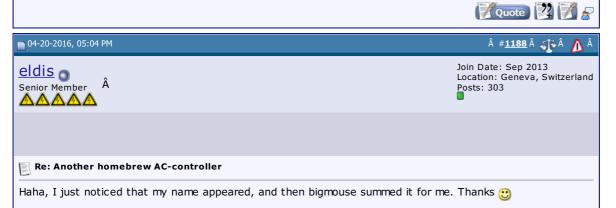
Hardware complexity is GREATLY overruled by firmware complexity. I've gone down this road several times before and have always found that the shortcuts I thought I was taking to make things easier/simpler/less complex actually had the opposite effect. Look at what happened when eldis tried to simplify things be using a resolver to encoder converter rather than reading the angle directly. Things got complicated, required information was missing, and he ended up redesigning it to do it the way it should have been done in the first place.

Open loop control is great for just getting a motor spinning with low voltage and low currents on the bench to make sure the PWMs are getting where they need to go. Anything beyond that, you absolutely need to close the loop. Benchtop or not, current sensors are required and worth putting in. V/Hz control doesn't work on permanent magnet motors, and barely works on induction motors.

In the future, if you want to go sensorless to save money because you're building thousands of these things, then tackle that project (and even then, you'll still need current sensors).

If you want to build a reliable, inverter that will provide good performance throughout the operating range with the simplest code (quickest path to a functioning inverter), then go with the proven, simple, methods that have been around for decades: Current sensors, rotor position, FOC.

2001 BMW 330ci conversion (Chevy Volt batteries, Lexus drivetrain)



Yup, the guy is right. Current sensors are always a must. You need at least two (most OEMs do it that way), or use three for redundancy fault handling) and slightly better accuracy.

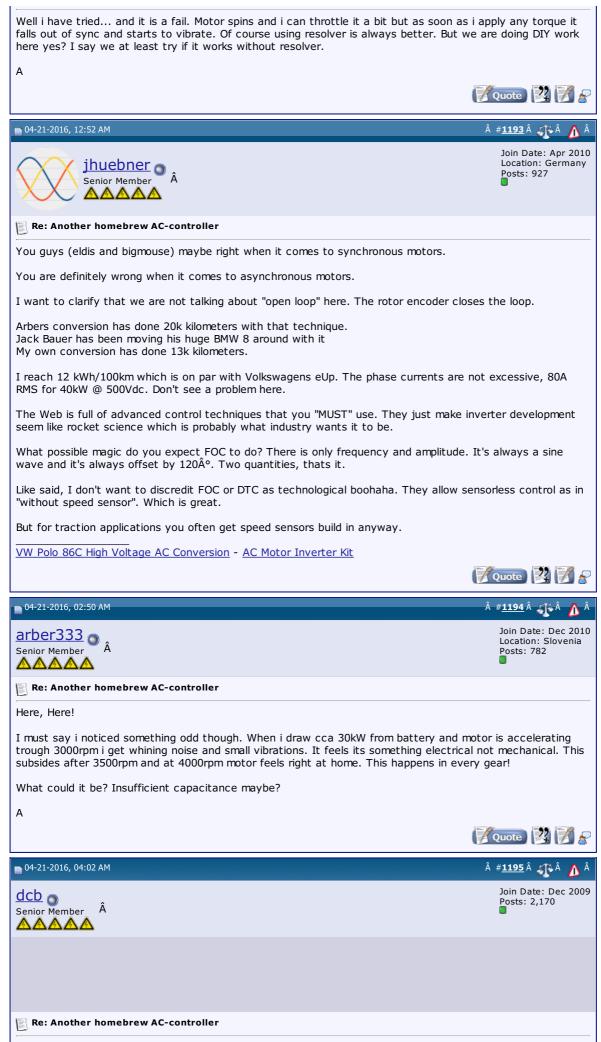
just means you sample three phase voltages and get the a There is sensorless and sensorless. The crude zero voltage 8bits, works just for RC airplanes. For good starting torque mode observers, saliency tracking, DTC. Important is that easy as reading encoder count.	crossing and similar usually implemented on AVR the sensorless starts to be a real science - sliding		
Our new webpage that will soon contain useful stuff about	our projects: advantics.fr		
04-20-2016, 05:43 PM	# <u>1189</u> 🕂 Â		
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782		
E Re: Another homebrew AC-controller			
Well i dont know if the car capable of running at 160km/h i sensors out inverter doesnt complain. It keeps on spinning 20K km on it, still going			
Since this is how cars have run for 100 years now i dont so complicate code, hardware and demand larger processor et Maybe only to improve effeciency but we have to check p	:c		
Johannes what you could try is expand master PCB and ad we could adapt other sensors or signals.	d the omitted ports for Olimex as inputs/outputs so		
I am still on to try PMSM motor with missing hole pulse and	current skew 🙂.		
	📝 Quote 📴 📝 🔗		
■ 04-20-2016, 05:46 PM	# <u>1190</u> 🕂 \Lambda Â		
MPaulHolmes A	Join Date: Feb 2008 <u>P</u> osts: 153		
Senior Member A	•		
Re: Another homebrew AC-controller			
What was the problem with the resolver to encoder? I'm using a dspic with a quadrature encoder interface, and haven't had any troubles with a resolver to encoder chip feeding the QEI with resolvers from leaf motors and toyota MGRs. To get the initial index pulse at turnon (which requires < 1/4 mechanical revolution for those motors), I just divided the circle into 8 pieces and let it cycle through each of those 8 candidate rotor flux angles. If a rotor flux angle candidate produced movement when the throttle was applied, I kept it there. Then, in < 1/4 of a turn, the true rotor flux angle is known, and everything is wonderful until you turn the controller off again.			
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DIYELECTR CAR	ARTICLES FORUMS GARAGE WIKI	
<u>DIY Electric Car Forums</u> > <u>EV Conversions and Builds</u> > <u>Controllers</u> Another homebrew AC-controller	Welcome, <u>nailgg</u> . You last visited: Today at 03:59 <u>Private Messages</u> : Unread 0, To	
NuWiki ♥ User CP Blogs ♥ FAQ Community ♥ Calendar New Posts So	earch 🔻 Quick Links 🔻 Advertise Log) Out
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■ 04-20-2016, 11:12 PM	# <u>1191</u> √ î ∕ û Â	DIY Ele
	: Sep 2008 San Francisco Peninsula, CA, USA 2	
E Re: Another homebrew AC-controller	Spor	nsors
Quote:		
Originally Posted by MPaulHoImes What was the problem with the resolver to encoder? I'm using a dspic with a interface, and haven't had any troubles with a resolver to encoder chip feed resolvers from leaf motors and toyota MGRs. To get the initial index pulse at < 1/4 mechanical revolution for those motors), I just divided the circle into through each of those 8 candidate rotor flux angles. If a rotor flux angle can movement when the throttle was applied, I kept it there. Then, in < 1/4 of a flux angle is known, and everything is wonderful until you turn the controller	ling the QEI with t turnon (which requires 8 pieces and let it cycle ndidate produced a turn, the true rotor	
In many applications (arguably, including a car), a 1/4 turn of the motor to "find" unacceptable. When you first apply current, you don't know which way the motor may align itself with the field by rotating backwards before "catching" and moving you've probably experienced this, based on your description). Depending on the p gear lash, 1/4 turn may not even show up as motion at the wheel, but the clunk undesireable at the very least. I'm not arguing that it can't work, my point is that there's a better way. If you h	or is going to turn. The rotor g forwards again (I expect pole count and amount of would be unsettling and	
emulator, then you have a resolver to digital converter. You already have the ha directly without the guesswork of an encoder index, so why wouldn't you use it? using can be configured for either parallel data output or encoder emulation, as w imagine your DSPic has a SPI interface or enough pins to read the parallel data a	The Tamagawa part I ['] m well as a SPI interface. I s well.	
Aside from rotor position sensing, for which there are indeed established viable of (with added complexity elsewhere to compensate and the associated performance remarks were aimed more at the proposed lack of current sensing which had been	e compromises), my initial	
I'm not aware of any control method which allows full utilization of a motor witho doesn't mean they don't exist, but I suspect they're confined to academic resear	rch, not practical application.	
Without current sensors, you are, by definition, open loop. Open loop control wor motors for reasons described by others earlier in this thread (see comments com on-line operation of induction motors). You just have to make sure your power st handle the peak currents and be willing to accept falling off the back side of the electrical frequency diverges too much from your mechanical frequency (without have no idea what your slip frequency is).	paring V/Hz control to direct- tage is over-rated enough to torque curve if your	
For permanent magnet motors without current sensors, you might get it to spin, make torque (if the load is small enough with low enough inertia), but without clo control, you'll never maximize the performance potential of the system as you ha angle of the flux relative to the rotor. The voltage vector alone only aligns with t low speeds.	osed loop control current ve no way of optimizing the	a Sponsor
I'm going to assume that nobody here is actually intending to run a permanent m current sensors nor rotor position and expect to get any usability from it.	agnet motor with neither	
2001 BMW 330ci conversion (Chevy Volt batteries, Lexus drivetrain)		
	📝 Quote 📴 🌠 🔗	
04-21-2016, 12:47 AM	# <u>1192</u> 🕂 🛕 Â	
arber333	Join Date: Dec 2010 Location: Slovenia	
Senior Member A	Posts: 782	
Re: Another homebrew AC-controller		



This link compares the two pretty nicely.

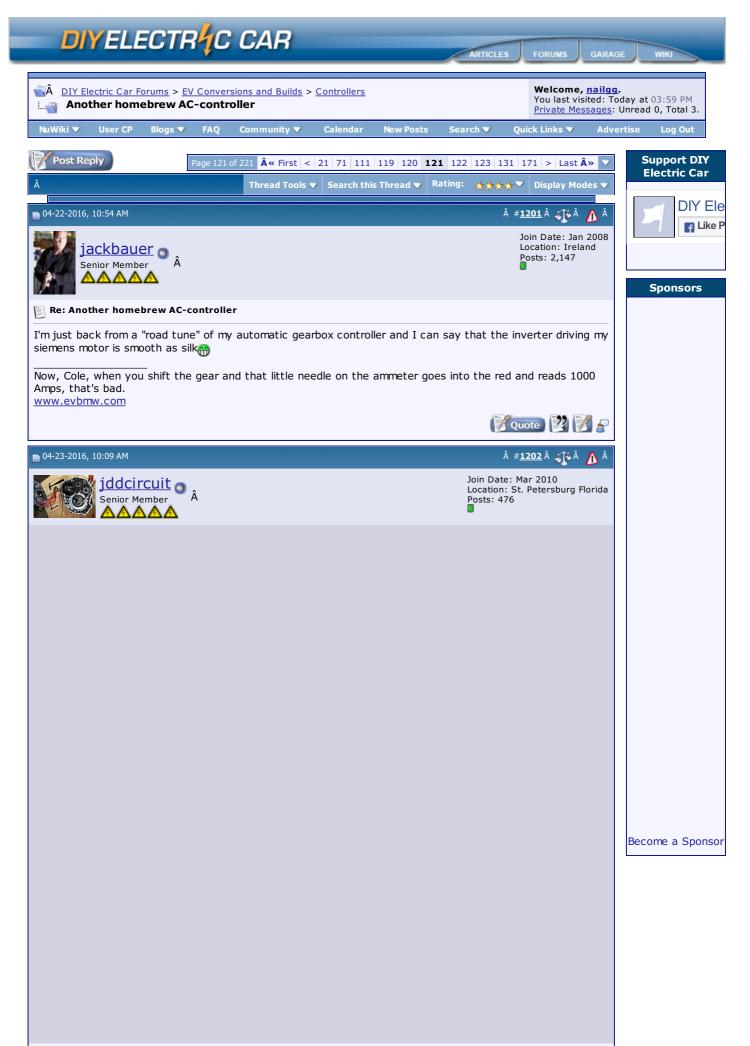
http://mkweb.uni-pannon.hu/hjic/indewnload/422/390	
COMPARISON OF SCALAR AND VECTOR CONTROL STRATEGIES OF INDUCTION MOTORS	
with scalar control and feedback, you essentially get torque control but not flux co control)	ntrol (basically slip
so as near an analogy as I can make, closed loop scalar is like a shunt wound moto But of course this is just software so it is fairly trivial to tweak your scalar routine t mappings than a hardwired shunt motor.	
but speed feedback is cheap compared to magnets and both techniques need it for operation in an induction motor, where a synchronous motor needs absolute positio operation across the entire speed range.	
and foc needs no-load and locked rotor tests to quantify the motor parameters, an resistance doesn't vary too wildly, and somewhat complicated maths, and there is a refinement.	
but in figure 8 and 9, in practical terms, closed loop scalar is perfectly driveable. th sluggish is all (without other optimizations), and dtc has better response yet if you w/performance (though the open source controllers don't have suitable current sen	are concerned
IIRC the huebner will *automatically* go into field weakening when it runs out of vo \ensuremath{vc}	oltage.
Last edited by dcb; 04-21-2016 at 04:46 AM.	
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04-21-2016, 04:12 AM	â # <u>1196</u> â 🐢 â 🧥 â
, ihushnar	Join Date: Apr 2010 Location: Germany
jhuebner Senior Member Â	Posts: 927
Re: Another homebrew AC-controller	
The comparison is pretty good but it assumes scalar control to only vary the slip free while keeping a constant V/Hz ratio.	equency to adjust torque
As soon as you lower the V/Hz ratio you decrease torque AND flux. Which is what ${\sf v}$	ve're doing here.
I think Paul Holmes does the same in his FOC controller. The throttle controls Iq AN	D Id.
Arber, does the vibration change if you change fweak?	
VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
	Quote 🕎 📝 🦻
■ 04-21-2016, 04:55 AM	â # <u>1197</u> â 🐠 â <u> </u> Â
MPaulHolmes Senior Member Â	Join Date: Feb 2008 Posts: 153
I meant to say that if you get forward motion, not just motion, then you keep it the backwards like 1/1024 of 1/4 of a mechanical revolution. The chip does have paralle both speed and angle, but it wasnt necessary.	
	📝 Quote 😰 📝 🔗
■ 04-21-2016, 05:00 AM	â # <u>1198</u> â 👫 â <u>۸</u> â
dcb Senior Member Â	Join Date: Dec 2009 Posts: 2,170
Re: Another homebrew AC-controller	
Re: Another homebrew AC-controller Quote:	

	keeping a constant V/Hz	es scalar control to only vary t ratio.	he slip frequency to
		ate from scalar to get the rotor oltage (field weakening) plus th	
■ 04-21-2016, 05:03 AM			â # <u>1199</u> â 🐠 â 🔥
arber333 Senior Member Â			Join Date: Dec 2010 Location: Slovenia Posts: 782
Re: Another homebrev	v AC-controller		
Quote: Originally Posted by : Arber, does the vibra	jhuebner ∑ ation change if you cha	nge fweak?	
Hm	l less voltage and lower en but at lower RPM!	put the final 32V in but i think I fweak i noticed vibrations in sar	-
		eed that we have to pass quick r turbine 😁. Maybe here lives a	
Last edited by arber333; 04-	21-2016 at 05:13 AM.		VQuote 🕎 🖉
04-21-2016, 05:10 AM			# <u>1200</u> 🐠 🏠 Â
dcb			Join Date: Dec 2009
Senior Member Â			Posts: 2,170
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Senior Member Â A A A A A Re: Another homebrew the gear train is also sus Post Reply Share or Bookmark this	pect for rpm specific no	20 70 110 118 119 120 121	Posts: 2,170
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Senior Member Â A A A A A Re: Another homebrew the gear train is also sus Post Reply Share or Bookmark this Facebook StumbleUpon Tags	Page 120 of 221 Â « First <	20 70 110 118 119 120 121	Posts: 2,170
Senior Member Â Re: Another homebrew the gear train is also sus Post Reply Share or Bookmark this Facebook StumbleUpon Tags None Quick Reply Message:	Page 120 of 221 Â « First <	20 70 110 118 119 120 121	Posts: 2,170 Posts: 2,170 Po

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I wanted to share a project I am working on. It may be	e relevant to some of the discussions.
With rotor position sensor and phase current sensors the relatively straight forward. I would not call it overly count the first time I hook things up but a couple of tries and	mplex. I do always get the polarity of things backwards
I am learning quite a bit during this inverter build. For each sensor I inadvertently induced some delay in the rotor speeds the phase current did not match phase voltage compensation which would maintain power factor. Some compensating for something else I did incorrectly. I dee delay instead of just overcompensating in software.	position that increased at higher speeds. At higher (phase duty cycle). I could fix this with software etimes two wrongs make a right when I am
I would probably give up the rotor position before I give can at least manage the power factor.	e up the current sensors. With the current sensors I
JDDCircuit: Work in progress requiring a custom ECU for conversion	r the Prius Inverter and Electric Transaxle.my MR2
	m. 10. 10. m. 10.
	📝 Quote 🕎 🎽 🎤
■ 05-02-2016, 01:49 PM	# <u>1203</u> 💦 Â
05-02-2016, 01:49 PM <u>gunnarhs</u> Senior Member Â	
gunnarhs Senior Member Â	# <u>1203</u> 🏹 Â Join Date: Apr 2012 Location: Iceland
gunnarhs Senior Member Â	# <u>1203</u> 💦 Â Join Date: Apr 2012 Location: Iceland
gunnarhs Senior Member Â A A B Re: Another homebrew AC-controller	# <u>1203</u> T Â Join Date: Apr 2012 Location: Iceland Posts: 292
gunnarhs Â Senior Member Â Markowski Senior Member Â Quote: Quote: Originally Posted by jhuebner As soon as you lower the V/Hz ratio you decrease I think Paul Holmes does the same in his FOC control	# <u>1203</u> ♠ Â Join Date: Apr 2012 Location: Iceland Posts: 292 torque AND flux. Which is what we're doing here. roller. The throttle controls Iq AND Id. I did tive control)
gunnarhs Â Senior Member Â Market Action A Quote: Originally Posted by jhuebner Originally Posted by jhuebner A As soon as you lower the V/Hz ratio you decrease I think Paul Holmes does the same in his FOC contract Induction-Motors: Yes that is basicly how it is done with slip control for in though add a current control model for two reasons 1) To keep eye on the currents and power factor (read 2) To improve dynamic behaviour if asked for (progress)	#1203 ↔ ▲ À ▲ À ▲ À ▲ À ▲ À ▲ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓
gunnarhs Â Senior Member Â Image: Senior Member Â Quote: Quote: Originally Posted by jhuebner As soon as you lower the V/Hz ratio you decrease I think Paul Holmes does the same in his FOC contr Induction-Motors: Yes that is basicly how it is done with slip control for in though add a current control model for two reasons 1) To keep eye on the currents and power factor (readors) 2) To improve dynamic behaviour if asked for (progress) So I had both speed sensor and current sensors. PM-motors: Have not done a EV-drive with PM but from the theory Id-compoment without current model in a PM.	A #1203 A A A A A A A A A A A A A A A A A A A

Re: Another homebrew AC-controller

Quote:

Originally Posted by gunnarhs 🔊

Induction-Motors:

Yes that is basicly how it is done with slip control for induction motor in a vehicle it works for me too: I did though add a current control model for two reasons

1) To keep eye on the currents and power factor (reactive control)

2) To improve dynamic behaviour if asked for (progressive control)

So I had both speed sensor and current sensors.

I also use the transformations to monitor power factor. A few (maybe 100 3) pages back I posted the results. While driving power factor is steadily above 0.9. On regen I think it went down to 0.7 for whatever reason.

Quote:

Originally Posted by gunnarhs 5

PM-motors:

Have not done a EV-drive with PM but from the theory I can not understand how one is going to control the Id-compoment without current model in a PM. (which must be set negative for overspeed driving under load to weaken the PM-field in a PM-motor)

First, I don't want to claim that I actually KNOW anything.

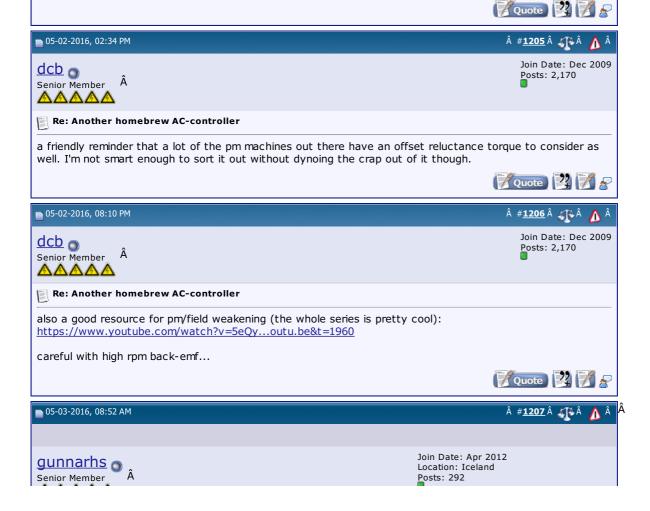
What I think is, that Id is not an actual physical quantity. It's virtual for ease of computing. The actual physical quantities in the PM motor would be V/f (again) and the angular difference between rotor current (not voltage!) and stator. Or to be more precise, V/f and a given angular difference result in a certain phase current.

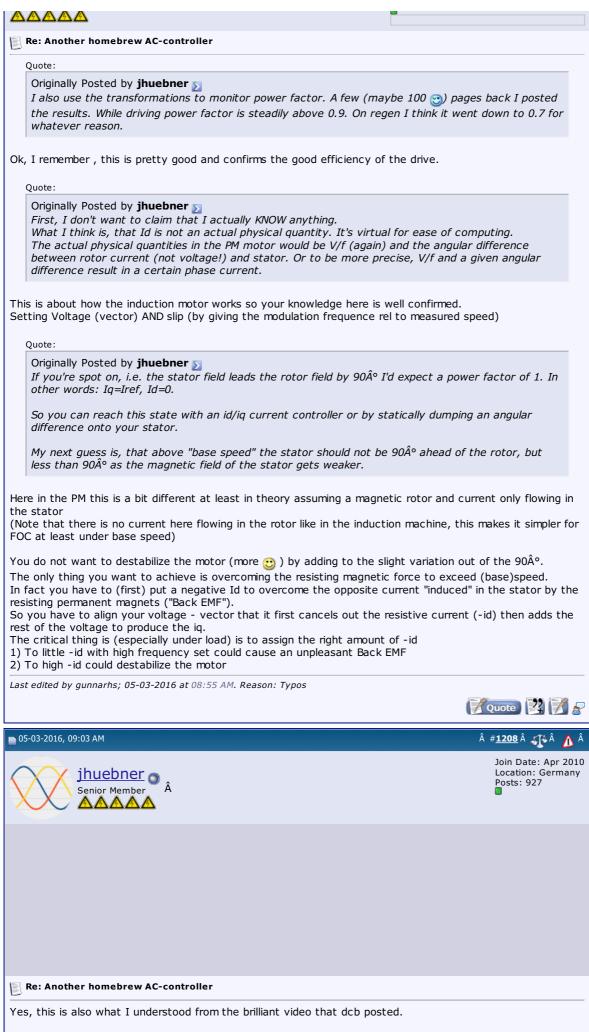
If you're spot on, i.e. the stator field leads the rotor field by $90\hat{A}^{\circ}$ I'd expect a power factor of 1. In other words: Iq=Iref, Id=0.

So you can reach this state with an id/iq current controller or by statically dumping an angular difference onto your stator.

My next guess is, that above "base speed" the stator should not be $90\hat{A}^{\circ}$ ahead of the rotor, but less than $90\hat{A}^{\circ}$ as the magnetic field of the stator gets weaker.

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Like he says, you can not weaken the actual rotor field but you can weaken it's effect (BEMF) on the stator. It is also good to know that once you fail to provide the negative id the BEMF rises back to the value at that

speed. It will cause uncontrollable high current into the inverter and battery. Now the question to me is: what does negative id translate to in the physical world? It must be the phase shift as it is the only quantity left to be controlled. The amplitude is at it's maximum in the overspeed region. Same has to go for reluctance torque. At the end of the day every fancy calculation must result in amplitude and phase shift. (amplitude and slip for induction) VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit Last edited by jhuebner; 05-03-2016 at 04:15 PM. Reason: clearer wording Quote 🕺 📝 🖉 #**1209 ∡ĩ**≱Â 🖿 05-04-2016, 04:34 AM ΛÂ gunnarhs O _Â Join Date: Apr 2012 Location: Iceland Senior Member Posts: 292 <u>Α Α Α Α Α</u> Re: Another homebrew AC-controller Quote: Originally Posted by jhuebner 5 Yes, this is also what I understood from the brilliant video that dcb posted. This Video and all other sessions related are brilliant, they go well into every detail. Nothing to add from my part learnt a lot too 😁 Quote: Originally Posted by jhuebner 5 Now the question to me is: what does negative id translate to in the physical world? It must be the phase shift as it is the only quantity left to be controlled. The amplitude is at it's maximum in the overspeed region. Yes, usually the amplitude is at maximum. The phase shift (usually determined by Voltage Space-Vector - map of some kind) must be put so that it provides enough -id to overcome the Back-EMF AND enough torque to drive the load (iq). To do that I have either to have a exact map of Motor/Load/Voltage/Frequency situation. Or measure the currents and (pre)-calculate the (expected) id and iq. (In the induction motor is it sufficent to have slip info if dynamic response is in average demand) As you know with the Induction motor there it is easier to measure the slip, in the PM it is easier to measure currents and calculate from them 😁 Quote: Originally Posted by jhuebner 5 Same has to go for reluctance torque. At the end of the day every fancy calculation must result in amplitude and phase shift. (amplitude and slip for induction) This is easier, you just have to step up the voltage to produce enough iq and set the position that it is orthogonal to resident rotor magnetic field. You must though be aware of the direction (In the induction motor you step up voltage and frequency to find the right starting situation i.e. starting frequency). Last edited by gunnarhs; 05-04-2016 at 05:50 AM. Reason: Typo Quote 🕎 📝 ج #<u>1210</u>Â 🏠Â <u>۸</u>Â 🗖 05-04-2016, 06:36 AM Join Date: Dec 2009 dcb Posts: 2,170 Â Senior Member <u>Α Α Α Α</u> Α Re: Another homebrew AC-controller fwiw, wilson has Itspice simulations, I've run this http://e2e.ti.com/group/motor/m/spice/666381 "31 ACIM Digital FOC Speed Control with slip estimator.asc" (using wine on ubuntu), little slow but you can poke and prod various signals.

Though I am not sure if there is a difference between absolute maximum torque and maximum torque per amo

(i.e. is pullout torque so	mehow quantified in FOC	C? or just another fudge	factor).	I.
here is a list, but it appendix here is a list, but it appendix http://e2e.ti.com/group/	•			
so it takes a little ingenu "41 PMSM Digital FOC Sp or	peed control"			
"44 PRIUS IPM Motor wit	h Digital Speed Control"		100-1001 Int 100-10	
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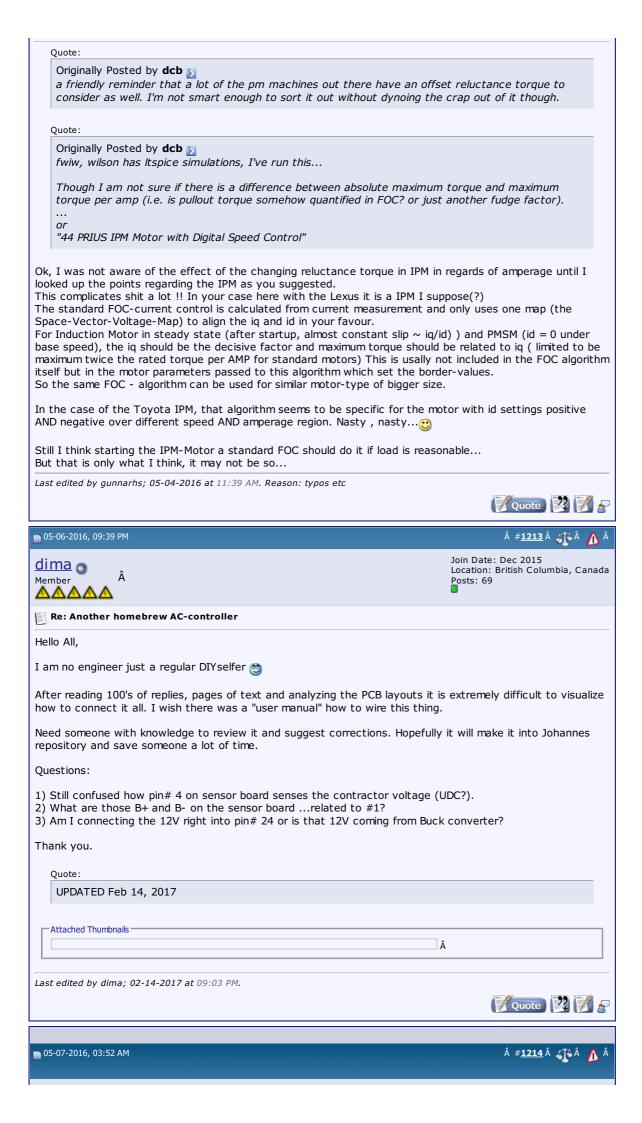
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D5-04-2016, 09:46 AM				# <u>1</u>	211 Â 🌆 Â	▲ Â	
dcb Senior Member Â					oin Date: Dec osts: 2,170	2009	
Re: Another homeb	rew AC-controller						Sponsors
here is a screenshot of that interesting in a c					oller which i	sn't	
I'm comparing slip vs s	slip_guess vs requ	uested load vs shaft	torque vs rpm here	2.			
The circuit at the bot	tom might look fa	imiliar 🙂					
It is interesting that a all the way to .5 seco				then the slip sta	rts creepin	g up	
Attached Thumbnails			Â				
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📄 05-04-2016, 11:19 AM				# <u>1</u>	212 Â 🐠 Â	Å Å	
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Join Date: Apr 2010 Location: Germany Posts: 927

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Re: Another homebrew AC-controller

Hi,

a piece of art 🙂

It seems you're not using Pin 12 to control your DC contactor, are you using a custom precharge logic instead?

Pin 24 is connected correctly, it is the main power input to the inverter.

B+ and B- may be connected directly to the DC bus. The value is displayed as "udc" and it is being used to control the precharge logic and the voltage warning light. It has no influence to the motor control.

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■ 05-07-2016, 12:35 РМ	# <u>1215</u> 🐢 🏠 Â
dima Member Â A A	Join Date: Dec 2015 Location: British Columbia, Canada Posts: 69
Re: Another homebrew AC-controller	
Hi	
Ah but it is a piece of art 🙂	
I have not connected anything yetmust visualize before I do.	
Thanks Johannes, I do have pin 12 (from J5) going to contactor (No I am not capturing your explanations)	re-inventing the wheel just
keeping the motivation alive for now.	
Attached Thumbnails	Â Â
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■ 05-11-2016, 03:54 PM	# <u>1216</u> 🚛 🔥 Â
	— 🐨 💋
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
jhuebner	Join Date: Apr 2010 Location: Germany
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany
jhuebner Å Senior Member Å Re: Another homebrew AC-controller	Join Date: Apr 2010 Location: Germany Posts: 927
ihuebner ihuebner Senior Member Â Re: Another homebrew AC-controller Cool housing and very creative way to not use the IDC headers : Just realized you updated the schematic above. The start key switch must put	Join Date: Apr 2010 Location: Germany Posts: 927
ihuebner Senior Member A A Re: Another homebrew AC-controller Cool housing and very creative way to not use the IDC headers : Just realized you updated the schematic above. The start key switch must pu Same goes for the brake switch. It doesn't need a ground connection.	Join Date: Apr 2010 Location: Germany Posts: 927
ihuebner Senior Member A A Re: Another homebrew AC-controller Cool housing and very creative way to not use the IDC headers : Just realized you updated the schematic above. The start key switch must pu Same goes for the brake switch. It doesn't need a ground connection.	Join Date: Apr 2010 Location: Germany Posts: 927 ull the start input up to 12V.
ihuebner ihuebner Senior Member ihuebner Re: Another homebrew AC-controller Cool housing and very creative way to not use the IDC headers : Just realized you updated the schematic above. The start key switch must pu Same goes for the brake switch. It doesn't need a ground connection. VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	Join Date: Apr 2010 Location: Germany Posts: 927 ull the start input up to 12V.
ihuebner Â	Join Date: Apr 2010 Location: Germany Posts: 927
ihuebner Â	Join Date: Apr 2010 Location: Germany Posts: 927



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Irdesigns O Â Junior Member		Join Date: May 2016 Location: South Africa Posts: 1			
Re: Another homebrew AC-c	ontroller				Sponsors
	t and build something with it, have fev	w question thouh, i require y	our help		
vhafuwi@gmail.com					
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05-16-2016, 12:06 AM		# <u>1</u>	<u>222</u> Â 🎢 Â	∧Â	
dima 🕤		Join Date: Dec 2	015		
Member Â		Location: British Posts: 69	Columbia, Ca	nada	
Re: Another homebrew AC-c	ontroller	-			
Re: Another homebrew AC-co					
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05-16-2016, 03:25 AM		# <u>1</u>	223 Â 🐠 Â	ΛÂ	
arber333		Jo	in Date: Dec	2010	
arber333 Senior Member Â			ocation: Slove osts: 782	nia	
				В	ecome a Sponsor
Re: Another homebrew AC-c	ontroller				
While helping my friend with hi	s inverter we made V/Hz work manual	y and later with EK not			

While helping my friend with his inverter we made V/Hz work manually and later with 5K pot.

But when we connected encoder we had problems. His encoder is optical quadrature with each at 90Ű. First we simply put 3V on and tried output with LED. It worked! LED was blinking when w 3V on pulse. So we connected signal line. When encoder started it was in V/Hz mode. No Hm When i tried to measure voltage signal to GND i got 0.8V! Signal was not changing wi barely alight. The other signal was at 3V unconnected, but if we put the line on it would Do you think something happened to input transistor? How could i check? Did you encounter anything like this?	e spun wheels. We got o sensor was detected. ith RPM and LED was
A	Vuote 2 7
05-16-2016, 04:06 PM	# <u>1224</u> ∢ T≩ ∧ Â
	Join Date: Apr 2010
	Location: Germany Posts: 927
Re: Another homebrew AC-controller	
The 0.8V is normal, it is the Vbe of any bipolar transistor. Maybe you encoder output is r sort of input.	not compatible to that
Look at the input circuit. You could remove R1, R3 and T1 and bridge the base to the co two pins of T1 that are NOT connected to the ground plane.	llector i.e. bridge the
That way you get a high impedance, low-pass filtered digital input.	
Attached Images	
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■ 05-17-2016, 04:44 PM	â # <u>1225</u> â 🌾 â 🏠 â
	Join Date: Dec 2010
arher333 🕳	Join Date: Dec 2010
arber333 Senior Member Â Â	Location: Slovenia Posts: 782
	Location: Slovenia
Senior Member Â	Location: Slovenia
Senior Member Â	Location: Slovenia Posts: 782
Senior Member Â A A A A A Re: Another homebrew AC-controller Quote: Originally Posted by jhuebner The 0.8V is normal, it is the Vbe of any bipolar transistor. Maybe you encoder output	Location: Slovenia Posts: 782
Senior Member Â Re: Another homebrew AC-controller Quote: Originally Posted by jhuebner The 0.8V is normal, it is the Vbe of any bipolar transistor. Maybe you encoder output to that sort of input. Look at the input circuit. You could remove R1, R3 and T1 and bridge the base to th	Location: Slovenia Posts: 782
 Senior Member Â Re: Another homebrew AC-controller Quote: Originally Posted by jhuebner The 0.8V is normal, it is the Vbe of any bipolar transistor. Maybe you encoder output to that sort of input. Look at the input circuit. You could remove R1, R3 and T1 and bridge the base to the bridge the two pins of T1 that are NOT connected to the ground plane. That way you get a high impedance, low-pass filtered digital input. Well we tried and setup the port directly, but it was a failure. Inverter wouldnt start in s After that i rewired resistors back to original schematic. We went to check voltage drop. got 2.5V when encoder was connected. Then we used on Liion battery at 3.4V and put inverter 3V3 supply. Hah! Motor started in torque/slip mode. So it was the sensor current. 	Location: Slovenia Posts: 782 ut is not compatible the collector i.e. slip mode. . It was substantial, we it in paralel with
 Senior Member Â Re: Another homebrew AC-controller Quote: Originally Posted by jhuebner The 0.8V is normal, it is the Vbe of any bipolar transistor. Maybe you encoder output to that sort of input. Look at the input circuit. You could remove R1, R3 and T1 and bridge the base to the bridge the two pins of T1 that are NOT connected to the ground plane. That way you get a high impedance, low-pass filtered digital input. Well we tried and setup the port directly, but it was a failure. Inverter wouldnt start in s After that i rewired resistors back to original schematic. We went to check voltage drop. got 2.5V when encoder was connected. Then we used on Liion battery at 3.4V and put it 	Location: Slovenia Posts: 782 ut is not compatible the collector i.e. slip mode. . It was substantial, we it in paralel with t demand that caused
Senior Member Â Re: Another homebrew AC-controller Quote: Originally Posted by jhuebner The 0.8V is normal, it is the Vbe of any bipolar transistor. Maybe you encoder output to that sort of input. Look at the input circuit. You could remove R1, R3 and T1 and bridge the base to the bridge the two pins of T1 that are NOT connected to the ground plane. That way you get a high impedance, low-pass filtered digital input. Well we tried and setup the port directly, but it was a failure. Inverter wouldnt start in s After that i rewired resistors back to original schematic. We went to check voltage drop. Got 2.5V when encoder was connected. Then we used on Liion battery at 3.4V and put inverter 3V3 supply. Hah! Motor started in torque/slip mode. So it was the sensor current voltage drop. Since we cant have Liion battery connected all the time we put 5V from sensor pins directed and setup.	Location: Slovenia Posts: 782 ut is not compatible the collector i.e. Slip mode. It was substantial, we it in paralel with t demand that caused ctly to encoder supply. SV as encoder supply a 2,7V. Could you
Senior Member Â	Location: Slovenia Posts: 782 ut is not compatible the collector i.e. Slip mode. It was substantial, we it in paralel with t demand that caused ctly to encoder supply. SV as encoder supply a 2,7V. Could you
Senior Member Â	Location: Slovenia Posts: 782 ut is not compatible the collector i.e. Slip mode. It was substantial, we it in paralel with t demand that caused ctly to encoder supply. SV as encoder supply a 2,7V. Could you
Senior Member Â	Location: Slovenia Posts: 782 ut is not compatible the collector i.e. Slip mode. It was substantial, we it in paralel with t demand that caused ctly to encoder supply. SV as encoder supply a 2,7V. Could you dnt work right away.
Senior Member Â Re: Another homebrew AC-controller Quote: Originally Posted by jhuebner The 0.8V is normal, it is the Vbe of any bipolar transistor. Maybe you encoder output to that sort of input. Look at the input circuit. You could remove R1, R3 and T1 and bridge the base to the bridge the two pins of T1 that are NOT connected to the ground plane. That way you get a high impedance, low-pass filtered digital input. Well we tried and setup the port directly, but it was a failure. Inverter wouldnt start in s After that i rewired resistors back to original schematic. We went to check voltage drop. got 2.5V when encoder was connected. Then we used on Liion battery at 3.4V and put i inverter 3V3 supply. Hah! Motor started in torque/slip mode. So it was the sensor curren voltage drop. Since we cant have Liion battery connected all the time we put 5V from sensor pins direct Again motor worked in slip mode Johannes, since signal from encoder is translated by BC547 transistor, i dont think using will hurt olimex sensor port. Or would it? Voltage difference from +5V to signal pin is cccar confirm this and write it to your instructions page so it is clear why some encoders would A	Location: Slovenia Posts: 782 ut is not compatible the collector i.e. Slip mode. It was substantial, we it in paralel with t demand that caused ctly to encoder supply. SV as encoder supply a 2,7V. Could you dnt work right away.

Quote:	
Originally Posted by arber333 Well we tried and setup the port directly, but it was a failure. Inverter wo After that i rewired resistors back to original schematic. We went to check substantial, we got 2.5V when encoder was connected. Then we used on it in paralel with inverter 3V3 supply. Hah! Motor started in torque/slip mo current demand that caused voltage drop. Since we cant have Liion battery connected all the time we put 5V from s encoder supply. Again motor worked in slip mode	k voltage drop. It was Liion battery at 3.4V and put ode. So it was the sensor
Johannes, since signal from encoder is translated by BC547 transistor, i d supply will hurt olimex sensor port. Or would it? Voltage difference from + Could you confirm this and write it to your instructions page so it is clear work right away. A	-5V to signal pin is ccca 2,7V.
Yes, well spotted! 5V supply is ok, the Olimex will not see the 5V. Will add it to	o the instructions
VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
	Quote 🕎 📝 🔗
05-29-2016, 01:21 AM	â # <u>1227</u> â 🕂 â <u> â</u> â
dima Member Â	Join Date: Dec 2015 Location: British Columbia, Canada Posts: 69
Re: Another homebrew AC-controller	
Could not compile the source code until changed anian.cpp line 48 from Code:	
<pre>adc_off(ADC1);</pre>	
Code:	
<pre>adc_power_off(ADC1);</pre>	
using <u>latest libopencm3</u>	
	(💆 Quote) 🔀 📝 🔗
05-29-2016, 05:06 AM	# <u>1228</u> ∢ T ▲ Â
arber333 Â	Join Date: Dec 2010 Location: Slovenia Posts: 782
	•
Re: Another homebrew AC-controller	0
	•••••
Re: Another homebrew AC-controller	ped a bit when throttle went er at drive-off BUT I eventually spring heat. Motor overheated
Re: Another homebrew AC-controller About pairing inverter and motor Last week i tried to smooth motor some more. I got the feeling that motor jum through 0%. So i lowered slipmin from 1.3Hz to 1Hz. Things went a lot smoothe noticed that motor started to overheat sooner. This is now amplified more by s driving over some hill where it used to hold temperature normaly, even with ax	ped a bit when throttle went er at drive-off BUT I eventually spring heat. Motor overheated
Re: Another homebrew AC-controller About pairing inverter and motor Last week i tried to smooth motor some more. I got the feeling that motor jum through 0%. So i lowered slipmin from 1.3Hz to 1Hz. Things went a lot smoothe noticed that motor started to overheat sooner. This is now amplified more by s driving over some hill where it used to hold temperature normaly, even with ax I do you think too small slipmin parameter can cause overheating?	ped a bit when throttle went er at drive-off BUT I eventually spring heat. Motor overheated
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Action Action Action Action and Matter Action Actio	ped a bit when throttle went er at drive-off BUT I eventually spring heat. Motor overheated ial impeler turning at 4000RPM. $\widehat{\mathbb{C}} \ \widehat{\mathbb{C}} \ \widehat$
Re: Another homebrew AC-controller About pairing inverter and motor Last week i tried to smooth motor some more. I got the feeling that motor jum through 0%. So i lowered slipmin from 1.3Hz to 1Hz. Things went a lot smoothe noticed that motor started to overheat sooner. This is now amplified more by s driving over some hill where it used to hold temperature normaly, even with ax J do you think too small slipmin parameter can cause overheating? Today i will change this to previous and drive again.	ped a bit when throttle went er at drive-off BUT I eventually spring heat. Motor overheated ial impeler turning at 4000RPM.

Quote:	
Originally Posted by dima Could not compile the source code until changed anian.cpp line 48 from	
Code:	
<pre>adc_off(ADC1);</pre>	
to Code:	
adc power off(ADC1);	
using <u>latest libopencm3</u>	
anka for pointing it out. Will also not a port commit	
anks for pointing it out. Will change it on next commit.	
Quote:	
Originally Posted by arber333 D	
About pairing inverter and motor	
Last week i tried to smooth motor some more. I got the feeling that motor is went through 0%. So i lowered slipmin from 1.3Hz to 1Hz. Things went a lot I eventually noticed that motor started to overheat sooner. This is now amp Motor overheated driving over some hill where it used to hold temperature mimpeler turning at 4000RPM.	smoother at drive-off BUT blified more by spring heat.
J do you think too small slipmin parameter can cause overheating?	
Today i will change this to previous and drive again.	
o little slip causes lower power factor and thus more ohmic losses and thus mo	re heat.
you want smoother start, try lowering ampmin.	
Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
	Quote
5-29-2016, 04:05 PM	# <u>1230</u> 🍂 🖊
	Join Date: Apr 2
jhuebner o	
	Location: Germa
Senior Member A	
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Re: Another homebrew AC-controller	Location: Germa
Re: Another homebrew AC-controller	Location: Germa
Re: Another homebrew AC-controller updated to the latest opencm3 version.	Location: Germa
Senior Member A	Location: Germa
Re: Another homebrew AC-controller updated to the latest opencm ³ version. much testing yet, will do that tomorrow.	Location: Germ

Only record each inc	ident once after si	tarting (I.e. key switch start	ing)	
The latter means for exam When you start the inverte	. ,	goes out of range you will re receive it once again.	eceive that message ONCE.	
The error codes are textua	I, i.e. no cryptic e	rror numbers.		
There are 4 errors right no	w:			
 Emergency stop -> 9 Motor protection -> Over Current -> STC Throttle out of range 	STOP)P			
More to come.				
The last 4 errors can be di <u>VW Polo 86C High Voltage</u>		"errors" . The web interface <u>C Motor Inverter Kit</u>	does not support this yet.	3 🛛 8
Post Reply	Page 123 of 221	« First < 23 73 113 121	122 123 124 125 133 173 >	Last » 🔽
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Â Controllers

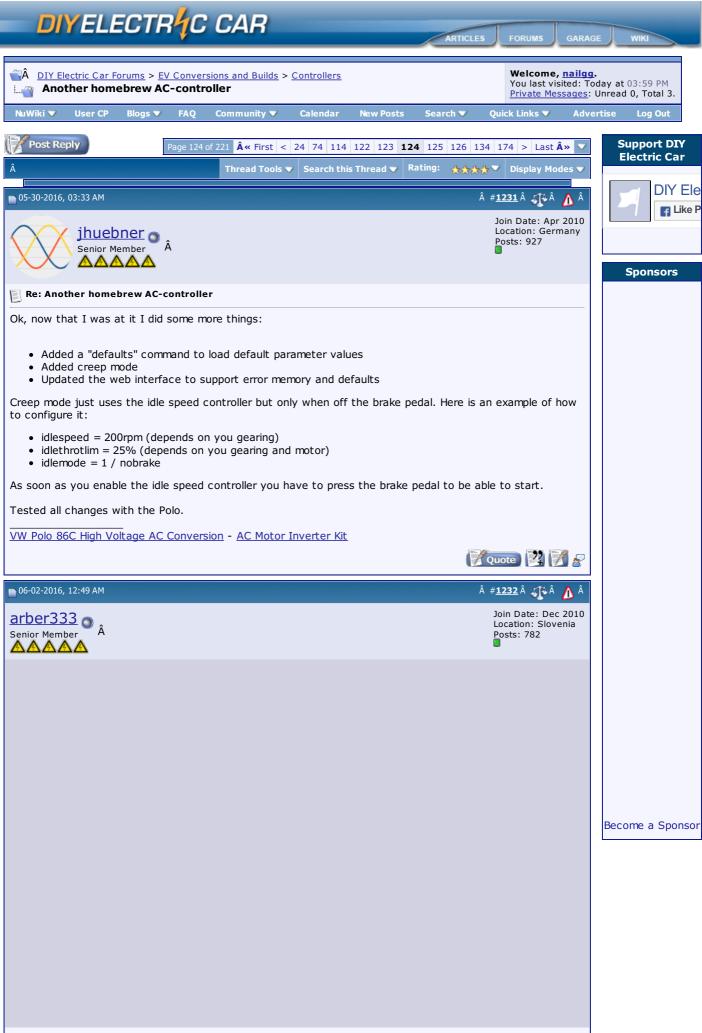
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Originally Posted by jhuebner Too little slip causes lower power factor and thus more ohmic losses and thus If you want smoother start, try lowering ampmin.	more heat.
Well before i set up my motor initially i tried various options. I found some settings actually havent used results from your slip equasions. Your last comment got me the old calculations from before motor rewiring. I put in as calculated slipmin 3Hz, slipmax 5,4Hz and i lowered ampmin to 10%. Difference was humongous! Car can accelerate to 100km/h in 3rd gear linearly! I ca 5th and motor doesnt overheat. And it can take off quite smoothly. Consumption is before. Problem i am dealing now is regen effect is very strong in 2nd gear. If i lower brkma back. Braking effect however remains very strong still. On highway that is not a pri can get very jittery if i alternate throttle around 0% position. You have any idea what to do? Could it be helped or is this just my motors constru-	hinking I searched for my an now run at 130km/h in s on the same level as ax i only get less amps oblem, but in city driving it
I had idea that could be done in software. Could you somehow put hysteresis filter it wouldnt oscillate when i alternate from throttle to regen? Maybe averaging samp	
tnx	
A	
EDIT: I also noticed in web interface i have only -25% throttle travel available for since i set it to 35%?	regen. Why would that be,
Last edited by arber333; 06-02-2016 at 12:54 AM.	
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■ 06-02-2016, 01:03 AM	â # <u>1233</u> â 🐠 â 🧥 â
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782

Quote:

T.

		_
	Originally Posted by jhuebner <i>Ok, updated to the latest opencm3 version.</i>	
	Not much testing yet, will do that tomorrow.	
	While I was at it I also added a very basic error log functionality:	
	 Record the time of the error (ms since inverter start) Output error code and consequence of error (Stop, Derate, Display) Remember the last 4 errors in RAM, i.e. they are lost at each "reboot" Only record each incident once after starting (i.e. key switch starting) 	
	The latter means for example if your throttle goes out of range you will receive that message ONCE.	
	When you start the inverter again, you may receive it once again.	
	The error codes are textual, i.e. no cryptic error numbers.	
	There are 4 errors right now:	
	 Emergency stop -> STOP Motor protection -> STOP Over Current -> STOP Throttle out of range -> DISPLAY 	
	More to come.	
	The last 4 errors can be displayed by typing "errors" . The web interface does not support this yet.	
Exc pos	cellent! I will try new software ASAP and simulate some "OClimit errors", "EMG stop" and "throttle out of sition" errors.	
1. ' 2. '	u could add errors "inverter hot"> derate "motor hot"> derate "encoder input error"> Stop	
А		
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	6-08-2016, 01:52 AM Â # <u>1234</u> Â 🛵 Â	
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■ 00 ar Sen	6-08-2016, 01:52 AM A () ber333 Nor Member A A A A A A A A A A A A A	Â 2010
■ 00 ar Sen	6-08-2016, 01:52 AM Â #1234 Â A Â ber333 nior Member Ĵoin Date: Dec 2 Location: Slover Posts: 782	Â 2010

A Last edited by arber333; 06-08-2016 at 03:10 AM.	 boost calculate cca 15V boost at first to overcome motor winding resistance at start fweak calculate it acc. to johannes equasion, in general something around 130Hz works unless motor is industry specific fslipmin either calculate it like Johannes showed or set it so that you can take off without motor jitter fslipmax just set it 2x fslipmin initially ampmin 5 i set it at this and try to set fslipmin. I later reduce it if neccesary. fmin 0.5 or 0.25 it is slip resolution. I have minslip 3Hz and at such high minimal freq. motor doesnt wor good, so i set it lower. brknom 55 throttle braking action in % brknom 55 throttle braking action in % brknom 55 throttle braking action in % brknom 50 throttle pedal braking torgue set low initially brknom 50 throttle pedal braking torgue set low initially brknom 50 throttle pedal braking torgue set low initially brknom 50 throttle pedal braking torgue set low initially brknom 50 throttle pedal braking torgue set low initially brknom 50 th toron parameter at a time and save settings that work! 1. set fslipmin so that you feel car taking off smoothly and try to change it by +/-0,1Hz and check differences in starting. Save when satisfied. 2. lower boost value in 100pts untill motor jitters at start. Then return it to last good value. 3. try lowering ampmin in 0,1 increments and observe throttle travel. When throttle is not just smooth becomes sluggish return some previous increments untill throttle reaction is acceptable. 4. change fweak value in +/-10Hz increments from starting point and observe torque in starting. This v very dependent on battery voltage and is very subjective. Now you find a hill or ramp and set car on it. You want to hold car in position on slope just using thrott pedal. If there parameters are not good motor will jump or will feel sluggish 1. add boost if motor is oscillating if i	ring k affic. affic. but value is tle . Then lue raffic! full
Image: Control of the sec of the se	A	
06-16-2016, 01:51 M		
arber333 Senior Member Â Join Date: Dec 2010 Location: Slovenia Posts: 782 P Re: Another homebrew AC-controller Johannes can you tell me if your software has provision for reducing power under load in case of inverter overheating? If so, how does it start to reduce power and what are the limits? Is there also something to reduce power in case of motor overheating? Image: Control of the second secon		V
A Location: Slovenia Senior Member Â Posts: 782 Posts: 782 Dohannes can you tell me if your software has provision for reducing power under load in case of inverter overheating? If so, how does it start to reduce power and what are the limits? Is there also something to reduce power in case of motor overheating? Inv Oc-16-2016, 12:44 PM A #1236 Å C Å Â Din Date: Apr 2010 Location: Germany Posts: 927	■ 06-16-2016, 01:51 AM Â # <u>1235</u> Â €	<u> </u> Â
Johannes can you tell me if your software has provision for reducing power under load in case of inverter overheating? If so, how does it start to reduce power and what are the limits? Is there also something to reduce power in case of motor overheating? tnx	A Location: Slo Senior Member Â Posts: 782	
overheating? If so, how does it start to reduce power and what are the limits? Is there also something to reduce power in case of motor overheating? tnx $06-16-2016, 12:44 \text{ PM} \qquad \hat{A} \# 1236 \hat{A} \bigoplus \hat{A} \hat{A} \hat{A} \hat{A} \hat{A} \hat{A} \hat{A} \hat{A}$	Re: Another homebrew AC-controller	
tnx 06-16-2016, 12:44 PM #1236 I À Â Join Date: Apr 2010 Location: Germany Posts: 927 Posts: 927		er
06-16-2016, 12:44 PM #1236 ↓ ▲ Â O-16-2016, 12:44 PM #1236 ↓ ▲ Â #1236 ↓ ▲ Â Independent of the second sec	Is there also something to reduce power in case of motor overheating?	
■ 06-16-2016, 12:44 PM À #1236 À TA A A Join Date: Apr 2010 Location: Germany Posts: 927	tnx	
Join Date: Apr 2010 Location: Germany Posts: 927	Quote 2	1
jhuebner	■ 06-16-2016, 12:44 PM	<u> </u> Â
jhuebner		
	jhuebner	



Quote:

Originally Posted by arber333 🔊

Johannes can you tell me if your software has provision for reducing power under load in case of inverter overheating? If so, how does it start to reduce power and what are the limits?

Yes, it will derate above 85°C and reach 0 power at 88°C.

Quote:

Originally Posted by **arber333** *Is there also something to reduce power in case of motor overheating?*

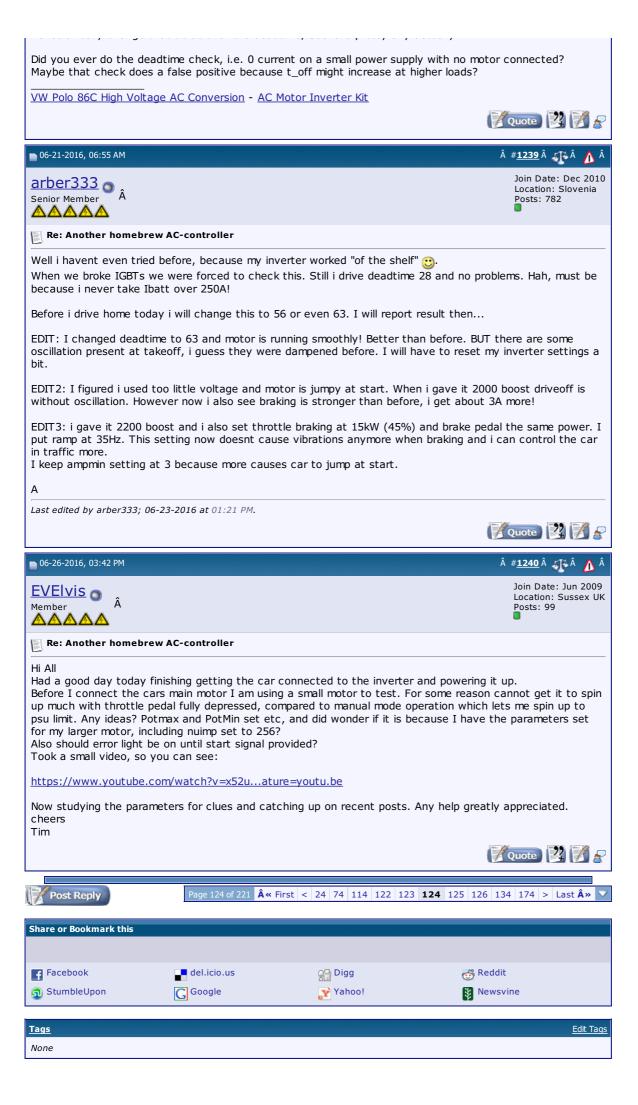
No, just the mprot input

BTW thanks for the guide, I will link to it.

VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit



I should really change that default for the deadtime. 800ns is pretty silly actually.



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You got a nice collection building up there. How about a simple load bench? You know for testing controllers



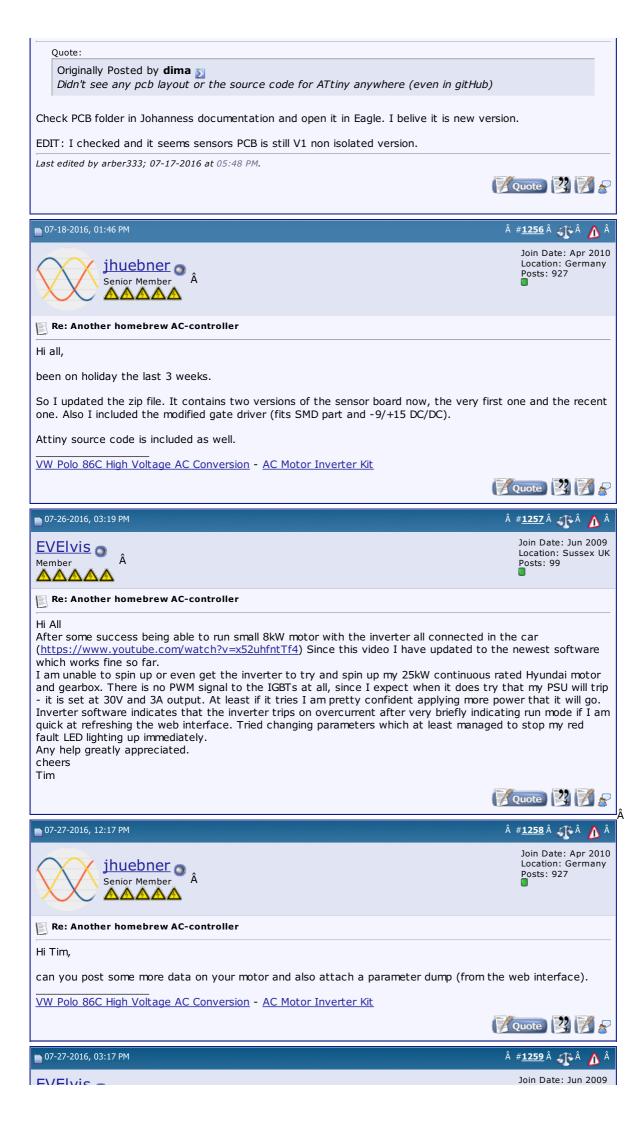
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Member Â	Location: Sussex UK Posts: 99 ■
🛐 Re: Another homebrew AC-controller	
Hi Johannes Motor plate attached. I will get a parameter dump asap, probably tomorrow now. Most parameters are set to default. From memory changes made were as fslipmin/fslipmax, fweak - all left at default believing it would make no diffe im wrong. Happy calculating what they should be based on rating plate. boost dig - tried 1700 - 5000 fweak - tried 10. deadtime dig 193 numimp 256 potmin dig 500 potmax dig 3400 udcsw V 15 udcmax V 30 ocurlim put this up to 1000 as error was overcurrent. il1gain,il2gain I played with these a bit as current readings were high. cheers!	
	Â
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■ 07-28-2016, 12:43 AM	# <u>1260</u> ∢ ♪ Â
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782
Re: Another homebrew AC-controller	
Well	
first dont try to run your motor sensored on 30V if you will later run it at 2 to run it manualy in V/F and it worked. That is all you need for testing.	200V. As i gather you already tried
Now you should make your car move and you cant expect that from 30V! transmission! Since you are 1:1 you will need 5kW at least. Try upping the suitable corrections.	
For 100VDC boost try 8000 since it is very low voltage you may have problem with mo just to start my motor fweak - try 90Hz so you dont throw overcurrent so often and increase in off. Check my post #1232 for procedure. deadtime i use 63 with 9Khz potmin/potmax have to see pedal travel to set. ocurlim i set at -550 since i have 300A IGBTs il1gain,il2gain just adjust so they get very close.	-
A	
Last edited by arber333; 07-28-2016 at 05:10 AM.	Quote 🕎 📝 🔗
Page 126 of 221 Â « First < 26 76 116 124 125	126 127 128 136 176 ≻ Last » ▼
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Join Date: Jun 2009 EVElvis 👩 Location: Sussex UK Posts: 99 Â Member AAARe: Another homebrew AC-controller Thanks Arber333 Only just seen your post so will have another go tomorrow, but I have just had a quick play, but still no go with overcurrent error. Got parameter list though, as follows: "boost": "1700", "fweak": "5", "fpconst": "400", "fslipmin": "1", "fslipmax": "3", "polepairs": "2", "ampmin": "10", "encflt": "4", "fmin": "1", "fmax": "150", "pwmfrq": "2", "pwmpol": "0" "deadtime": "193", "numimp": "256", "potmin": "540", "potmax": "3500", "pot2min": "4095", "pot2max": "4095", "idlespeed": "-100", "idlethrotlim": "50", "idlemode": "0" "speedkp": "0.25", "speedflt": "1", "cruisemode": "0", "bmslimhigh": "50", "bmslimlow": "-1", "brknompedal": "-50", "brknom": "30", "brkmax": "30", "brkrampstr": "10", "udcsw": "10", "udcmin": "10", "udcmin": "12", "udcmax": "24", "udclim": "25", "ocurlim": "1000" "minpulse": "1000", "il1gain": "0.5", "il2gain": "0.5", "udcgain": "6", "pwmfunc": "0" "pwmgain": "100", "pwmofs": "0", "speedgain": "6000", "snshs": "0", "snsm": "2", "fslipspnt": "-1", "version": "3", "ampnom": "0", "opmode": "0", "udc": "18.81", "idc": "0", "il1": "0", "il2": "0", "uac": "Ó" "il1rms": "0", "il2rms": "0", "id": "-0.09", "iq": "0", "p": "0", "q": "0", "s": "0", "pf": "0", "t": "0", "fstat": "0", "speed": "0", "amp": "0", "pot": "576", "pot2": "61", "potnom": "-25", "dir": "0", "tmphs": "21.4",



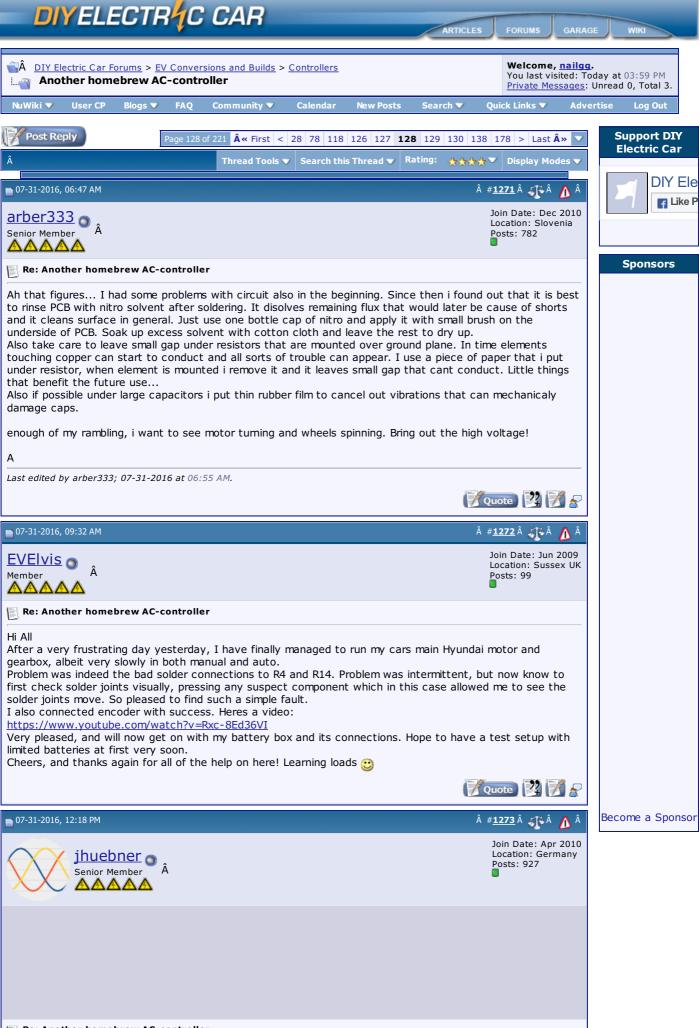


mode!:-)				
with no motor connected, overcurrent fault. I did start thinking that it testing off the car the gre 11, 13, 17, 24 to 12V and always provided enough p laptop. I did reflash it with I have a spare Olimex, so 836. I then thought there was IGBTs, so having a spare, which it was, but as soon so I am thinking a bad con	parameters, and agai or whilst off the car was the Olimex, since een LED was not flash 1 23 to GND now - I th ower to make the gree h the latest software just incase will have a a problem with a gate changed it to find it as the gate driver was nection somewhere of the IC5? At 12V pow	with separate test conne e I noticed that when it v ing, but seems ok now, a nink it may have been my een LED flash. Think it ma which it did just fine. a go at getting the softw e driver as I read 5V in bu made no difference. So c as connected (IGBT disco on the main board or com ter consumption was 0.19	d not even get manual mode workin ections. It always stopped on vas connected to the laptop during ind flashes when connected with p USB connection, which I thought ybe because I am using a different vare on it. Think I need to follow po ut no 15V out to one of the the hecked again that 5V was going in onnected) the voltage dropped to 0 nector, since I guess the 5V for the 7A, so less than 0.3A as it was during the state of the st) ins ost).2,
Tim				
Last edited by EVElvis; 07-31-	-2016 at 05:31 AM.			
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	Page 127 of 221 Â « I	First < 27 77 117 125 12	26 127 128 129 137 177 > Last Â	
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lever. I would use only a of spinning mass synchr	3 gears for easier actuat ros could be fooled by a	tor travel 2nd, 3rd and 4 oproximating shift RPM. Als	erpendicular to manage the shift th. Since motor doesnt have a k o i could use RPM sensor so i wo rs have troublesome downshift	ot uld
Now i could stop there a controler BMS input) an		h with a button to release	motor torque while shifting (
have controling mechan	nism to order gear chang	• •	e RPM output signal and i would d a driveshaft RPM sensor and	
hysteresis cca 800rpm o	difference involved. Of c	either to upshift or downsh ourse comparator would di elay when shiftingrobotic	isable motor torque when shifting	J
	ld natuarly compensate PMSM would be more of a	-	rotor is reactive not magneticaly	
What do you think?				
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The Panzer is rolling Attached parameter file from latest test run. Very smooth on startup and plenty of



https://www.diyelectricca Arber, that is awesome! ii					CIM	ļ				Ó	7 Q	uote		2 7	8
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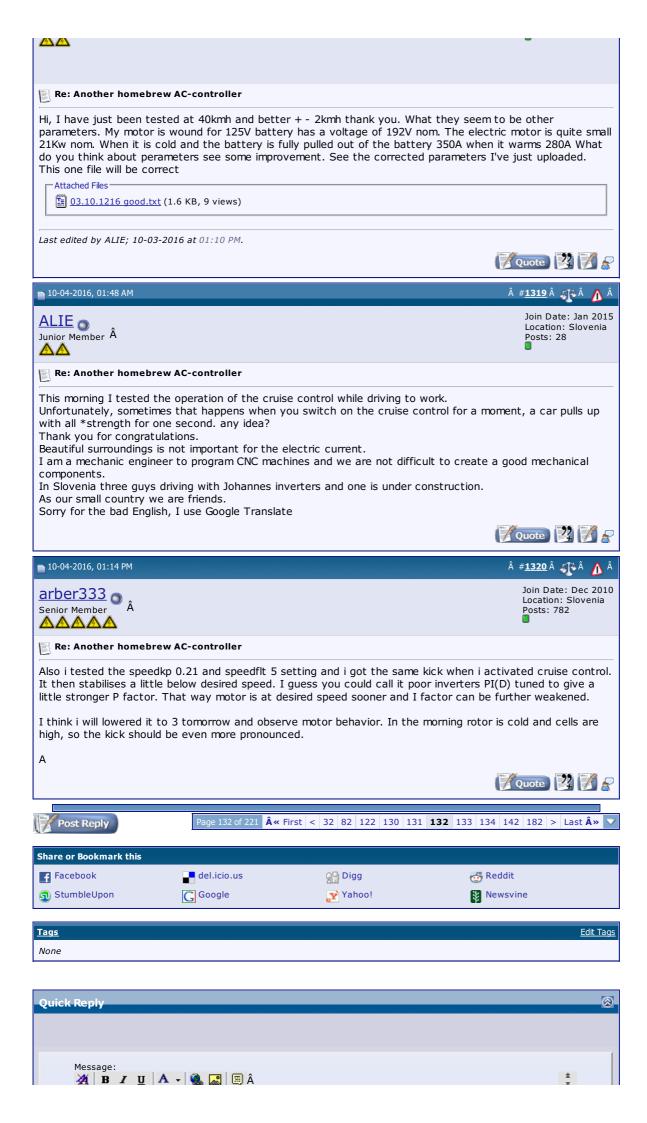
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	Posts: 28	
Re: Another homebrew AC-controller All connections are protected by varnish all unprotected gaps is min 7mm. I already drive 10,000 km in three months and work perfectly .		
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Last edited by ALIE; 09-24-2016 at 06:19 AM.	uote) 🕎 🍞 🔗	
09-24-2016, 01:46 PM Â #	<u>1315</u> â 🐠 â <u>۸</u> â	
	oin Date: May 2014 .ocation: Russia Posts: 73	
Re: Another homebrew AC-controller		
looks very nice and clean! Very very good work!		
The only way to do the best is knowledge that someone will always be better than You, ever		
	uote 😰 📝 🔗	
■ 10-03-2016, 12:17 PM Â #	1316 Â 🐠 Â 🧥 Â	
	Join Date: Jan 2015 Location: Slovenia Posts: 28	
Re: Another homebrew AC-controller		
Inverter parameters Very good except for the cruise control speed fluctuate +8 -3 kmh		
Attached Files		
Last edited by ALIE; 10-03-2016 at 12:21 PM.	Jote) 🕎 📝 🧬	
■ 10-03-2016, 12:21 PM Â #;	1317 Â 🐢 Â 🔥 Â	
	Join Date: Apr 2010	
	Location: Germany Posts: 927	
Re: Another homebrew AC-controller		
Recently I retuned cruise control. I found it worked better with higher filter values. I'm now running speedkp 0.21 and speedflt 5. It might also allow you to set a higher value for speedkp if the filter is higher.		
Maybe it helps.		
Congrats again on your EV work. Much nicer than what I did 😇		
VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	uote) 🕎 🃝 🎤	
■ 10-03-2016 12:49 PM	<u>1318</u> Â ∭ Â ⚠Â	
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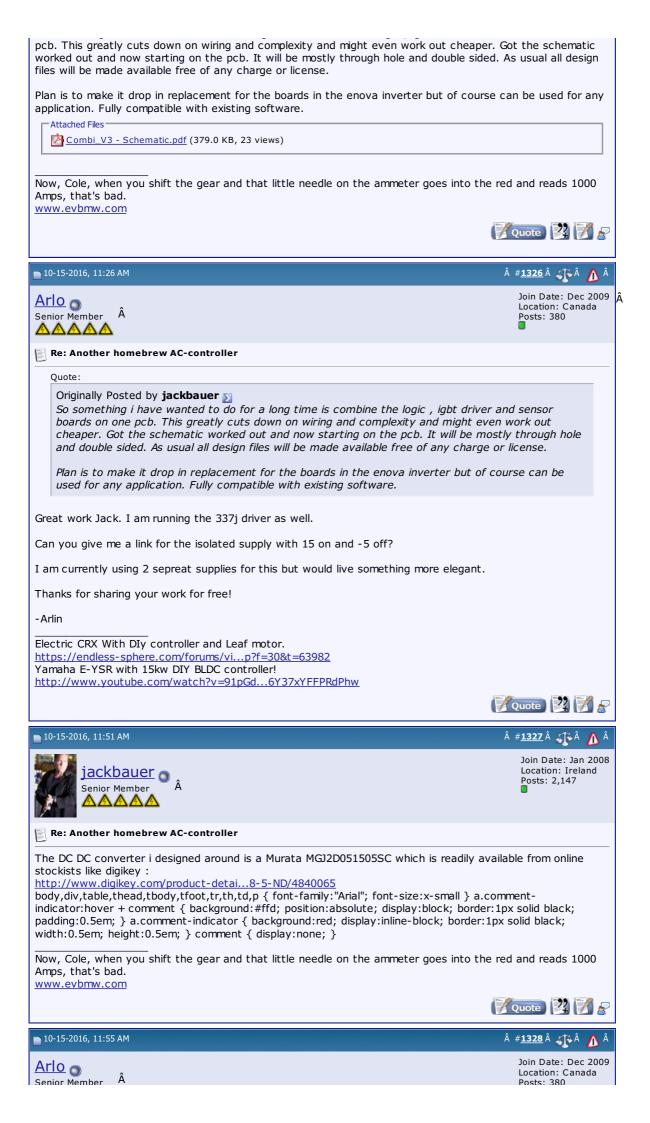
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So something i have wanted to do for a long time is combine the logic , igbt driver and sensor boards on one

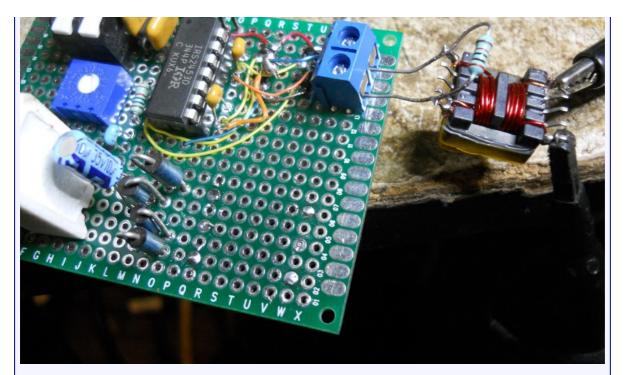




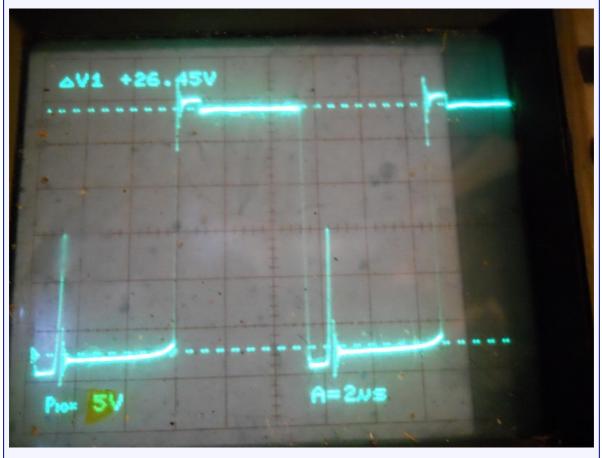
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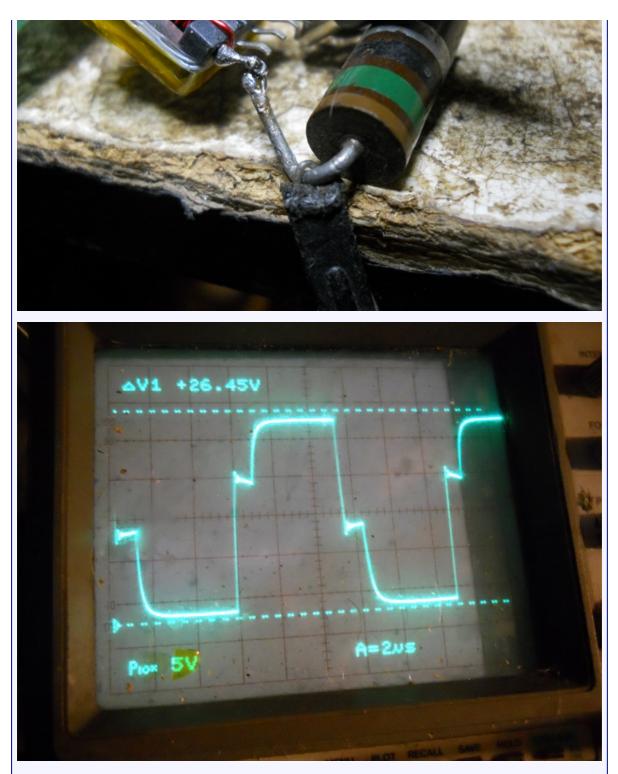
The output waveform with 13VDC input at about 30 mA:



The asymmetry is probably because of the ugly wiring. The IRS2453D has 1 uSec dead time, which you can see in the 90 kHz waveform. I added a 15 ohm (actually 17 ohm) 2W resistor to see how much the output dropped under load,

and I was surprised it didn't drop very much, and looks like about 10.5 VRMS, or 618 mA and 6.5 watts. Input was 13 VDC at 590 mA, or 7.67 watts, and 85% efficiency.





Then I connected the output to a FWB of 1N5818 Schottkys, a 20 uF 25V CM capacitor, and a 33 ohm resistor. Here

are the results at various input voltages:

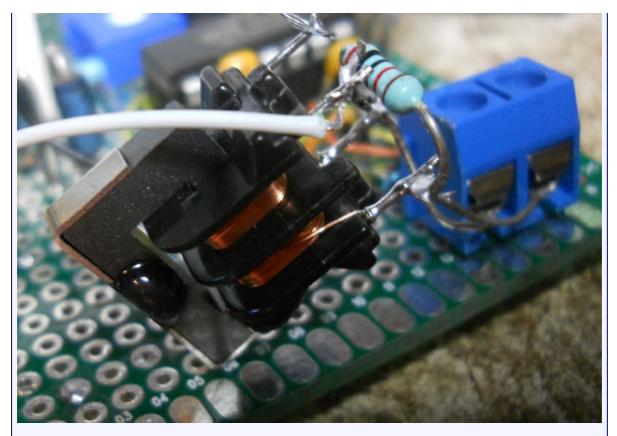
13V 0.37A 4.81W 11.77V 0.357A 4.20W 87% 15V 0.43A 6.45W 13.56V 0.411A 5.57W 86% 17V 0.55A 9.35W 15.08V 0.457A 6.89W 74% 18V 0.70A 12.6W 15.90V 0.482A 7.66W 61%

I am pleasantly surprised at the performance of this little transformer. The EPCOS catalog rates this size core at 5W for N27 at 25 kHz, but 28W for N87 at 100 kHz. I would have figured on 4x, but 5.6x is surprising. Probably because of greater surface area per watt for the smaller core.

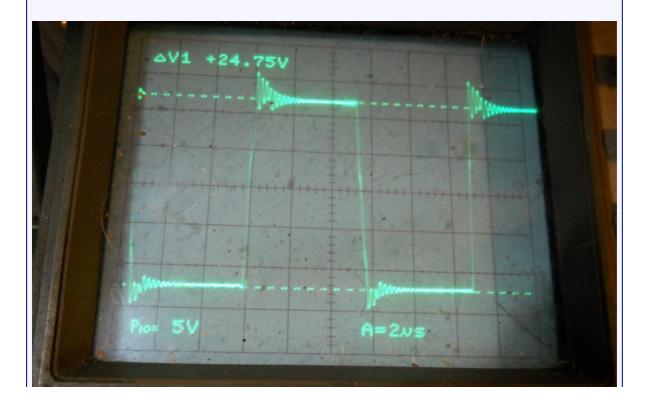
The output voltage for a gate driver does not need to be tightly regulated, if the input is known and solid. It would not be difficult to wind the output for any voltage you want, and perhaps even two windings for the +15 and -5 or whatever for IGBTs. You could use a 12V-20V and then a 15V zener on the output for the positive voltage (which is more critical).

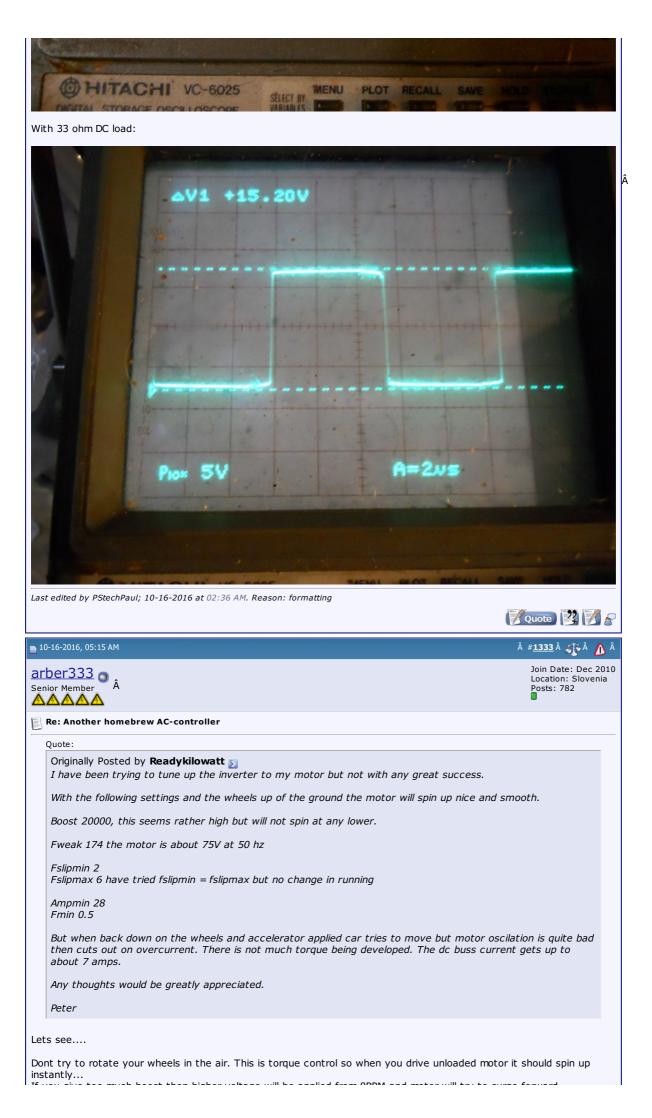
I also found that you can easily get 2 watts from a small common mode choke (less than \$1 each). They have dual windings with inherently high isolation but also high leakage inductance and poor regulation.

This is a TLF9UA202:



Waveform open circuit:





Also if you	too much boost then higher voltage will be applied from UKPM and motor will tr apply too much ampmin motor will oscillate from 0 RPM because of saturated w it, finally throw oclimit.	
	our fweak is too high. rocedure at post #1232	
What is the DC voltage In that case	IF DC voltage? AC voltage on the motor at 90Hz? If you have 75V at 50Hz than you may ass for that motor would be 220Vdc to account for voltage drop. e you would want to try motor from fweak 120Hz and use boost 4000 and amp at start but you still can apply 100% amp using throttle.	
If you use t	he motor with lesser voltage you must lower fweak so torque remains same.	
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10-16-2016 , 2	11:59 AM	â # <u>1334</u> â 🐠 â <u>۸</u> â
dima o Member	â	Join Date: Dec 2015 Location: British Columbia, Canada Posts: 69
Re: Anot	her homebrew AC-controller	
Fweak Fslipmii	ly Posted by Readykilowatt solution 174 the motor is about 75V at 50 hz n 2 x 6 have tried fslipmin = fslipmax but no change in running	
fweak:40	is too high for low voltage - you want to reach it sooner. t those two pole industrial motors slip is kind of "stretched out" try	
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Readyki Junior Membe	lowatt 💿 Â	Location: Warkworth NZ Posts: 7
Re: Anot	her homebrew AC-controller	
fweak:4	that those two pole industrial motors slip is kind of "stretched out" try :10	
We have be	en tring to use the procedure in post #1232	
The battery	voltage is 320 nominal.	
Will try with	n lower fweak.	
So I take it	that with a lower fweak it will not require so much boost to get the motor mov	ving?
Peter		
Peter		



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that's bad. www.evbmw.com				
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Readykilowatt O Â	ι,			e: Aug 2009 : Warkworth NZ
Re: Another homebrew	AC-controller			
Quote:				
2 pole motor you set	1!	f you have 4 pole motor you se ince rotor gets excited only 1/2		and if it is
Is anyone using a 360 pu	lse per rev encoder? t about 18000 to get any	g the encfit to 16 did help. y torque. This seems very high	?	
Peter			Quote	. 2 7 2
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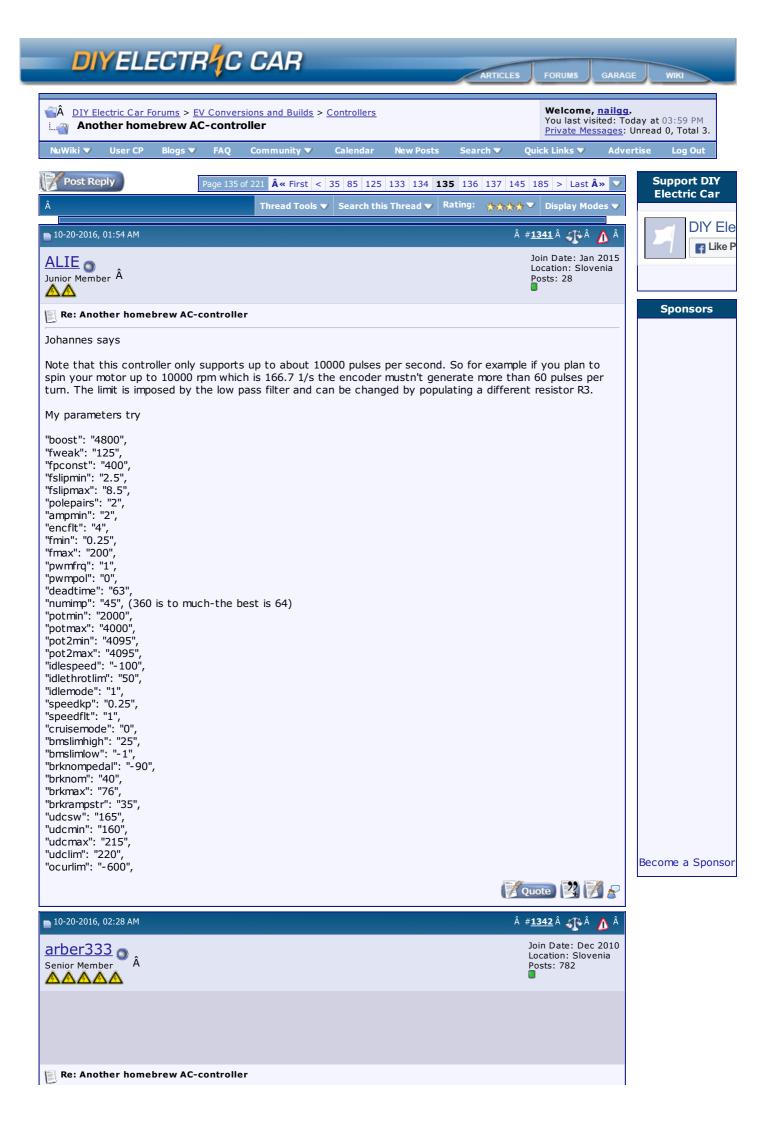
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Re: Another homebrew AC-controller Quote: Originally Posted by jackbauer Combi board now tracked out and checked. Going to check again tomorrow and order some boards Very good build! I still think we would need to make transformer power supply and totem pole drivers. Cca 10A at least! I th now we have the space. We could use one 24Vac transformer supply per driver and divide it to +15V and -with one 15V zener and one 24Z resistor. See attachment. I like the idea of remote LEM sensors. It is much easier to position the main board. I may order a board or two from you Co. Can you tell me what would be the use for CAN interface? Would it work as active part in a car or would it just transmit as serial interface? Attached Thumbnals
10:23:2016, 11:48 AM A #1346 Å (Å Å Join Date: Dec 2 Join Date: Dec 2 Dorginally Posted by jackbauer Controller Quote: Originally Posted by jackbauer Combi board now tracked out and checked. Going to check again tomorrow and order some boards Combi board now tracked out and checked. Going to check again tomorrow and order some boards Combi board now tracked out and checked. Going to check again tomorrow and order some boards Very good build! still think we would need to make transformer power supply and totem pole drivers. Cca 10A at least1 I throw we have the space. We could use one 24Vac transformer supply per driver and divide it to +15V and -with one 15V zener and one 242 resistor. See attachment. Like the idea of remote LEM sensors. It is much easier to position the main board. may order a board or two from you . Can you tell me what would be the use for CAN interface? Would it work as active part in a car or would it ust transmit as serial interface? Attached Thumbrake A
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Found a big problem.				
		v2" It is stretched out, pard and got confused	. I thought I ordered wrong	
Checked Eagle traces	looks like the same	component type but t	he pins are off by one.	
Been there. Got to watch	those isolated suppl	ies different manufactu	ires have different pin-outs.	
Electric CRX With DIy cont https://endless-sphere.co Yamaha E-YSR with 15kw http://www.youtube.com/	m/forums/vip?f=30 DIY BLDC controller!	<u>0&t=63982</u>	Quote) 🛂 🗹 🔗
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I believe our current STM32-H103 does not have CAN protocol handle in CPU. Don't know if this can be done through software emulation.							
So maybe when you	So maybe when you redesign your board next time have a surface mount ARM chip for soldering 奯						
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Well, I'm pushing some investors to put money in the vesc project so we can build an integrated TO247 IGBT

pack with TI IGBT drivers controlled by VESC MCU and firmware. The deal is to keep the whole thing open source just like vesc is. If I get funds, or a prototype -whatever comes first- I'll make a post. For now I just jumped in to say hi and to point out that the TO247 path seems to me like the best path. 📝 Quote 🕎 📝 🔎 ■ 11-01-2016, <u>11:24 PM</u> #<u>1377</u>Â 🎢 Â Λ Join Date: Dec 2009 dcb 👩 Posts: 2,170 Â Senior Member Re: Another homebrew AC-controller I think there is a reason igbt's aren't usually paralleled like mosfets, http://www.ixys.com/Documents/AppNotes/IXAN0058.pdf mpaulholmes even uses an extra 3' of lead to each igbt to add a bit of resistance in the 6 pack with dc logic version (and he has some experience paralleling things): https://www.diyelectriccar.com/forums...st-170938.html as an aside, there are a number of papers on paralleling mosfets WITH an igbt for faster turn on (though you are still stuck with tail current) and lower Vds, but that is probably overkill for now. so I would be wary of parallel TO247 IGBT implementations, perhaps the that is the "room for error", i.e. the ixys document says they have to be carefully matched in addition to a number of other criteria, and that means production expense vs modules. \$0.02 worth. edit: apparently tesla does use parallel to247 igbt's, but damn if they don't have a billion production controls in place too, and the margins to support it. http://www.pointthepower.com/on-tesl...tor-packaging/ Last edited by dcb: 11-01-2016 at 11:30 PM. Quote 🕎 🎢 🔎 ■ 11-02-2016, 02:53 AM #<u>1378</u>Â 🌆 Â Δ Join Date: Apr 2010 jhuebner O Â Location: Germany Posts: 927 Senior Member Re: Another homebrew AC-controller Quote: Originally Posted by nitrousnrg 🔊



- bugfix on throttle out o - Basic CAN functionality		the inverter at startup) c in fixed point format in h	igh word and low word)	
As usual here: <u>http://johanneshuebner.</u>	com/quickcms/nload	<u>s,14.html</u>		
and github				
VW Polo 86C High Voltag	e AC Conversion - AC	<u>Motor Inverter Kit</u>		
			Quote	21 📝 🖉
Post Reply	Page 138 of 221 «	First < 38 88 128 136 13	7 138 139 140 148 188 >	Last » 🔻
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It works for me, with some exceptions. The "Compile from source" and other local operations seem to be targeted at Win	dows.			
Just found you integrated the BOM with pictures and datasheets. Thats so cool				
Aha, replace "split" by "explode" in snapshot.php to be compatible with newer php	Ŭ			
Same in graph.php for the graph to work.				
VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit				
Last edited by jhuebner; 11-02-2016 at 05:33 PM. Reason: Debugging :)				
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11-03-2016, 02:09 PM	â # <u>1385</u> â 💦 â <u> â</u> â			
jackbauer Senior Member AAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAA	Join Date: Jan 2008 Location: Ireland Posts: 2,147			
Re: Another homebrew AC-controller				
Boards are here				
Attached Thumbnails	Â			
Now, Cole, when you shift the gear and that little needle on the ammeter goes in Amps, that's bad. www.evbmw.com	to the red and reads 1000			
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■ 11-03-2016, 02:11 PM	# <u>1386</u> ∢҈ ♣ 🔥 Â			
Senior Member Â	Join Date: Jan 2013 Location: Warwickshire, UK Posts: 798			
Re: Another homebrew AC-controller				
those look massive, outer size?				
If it works out good might be a good replacement for all the available engine and inverters				
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■ 11-03-2016, 02:38 РМ	â # <u>1387</u> â 🐢 â 🧥 â			
jackbauer Senior Member AAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAA	Join Date: Jan 2008 Location: Ireland Posts: 2,147			
Re: Another homebrew AC-controller				
290mm long x 135mm high. Being exhausted from a 12 hour day in work fault findiclearly the right time to tackle placing the smallest pitch parts on the board \widehat{m}	ng 0402 size boards is			
Attached Thumbnails	Â			
Now, Cole, when you shift the gear and that little needle on the ammeter goes in Amps, that's bad.	to the red and reads 1000			
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www.evbmw.com	Vuote 🕎 📝 🎤			
<u>www.evbmw.com</u> ■ 11-03-2016, 03:03 PM	# <u>1388</u> 💦 💧 Â			



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My intention is to make a standard power section and a small footprint so this inverter could also fit on airplane or in a small car and still drive 100kW EMRAX motor. Now you actually gave us a choise in flavor - Johannes STM brain for ACIM motor or Pauls FOC dsPIC brain for PMSM motor. Now both PCBs look very much the same and have all elements onboard. I should congratulate you Er do please position STM pins the correct way in future release \bigcirc .				
I too botched 40+ BMS boards when i forgot to enable a layer	for +/- battery contact plating DOH!			
A 				
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■ 11-06-2016, 09:30 PM	â # <u>1399</u> â 💦 â \Lambda			
dima Member Â	Join Date: Dec 2015 Location: British Columbia, Canada Posts: 69			
Re: Another homebrew AC-controller				
Ported new interface to Linux (Ubuntu distros). Tested with Mi will fix that in the future. <u>Download</u>	nt18. Security is slack requires sudo to run but			
Huebner Inverter - Console Management				
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■ 11-07-2016, 12:29 AM	â # <u>1400</u> â ∰Â <mark>♪</mark> Â			
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782			
Re: Another homebrew AC-controller				
Quote:				
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Quote: Originally Posted by dima <i>Ported new interface to Linux (Ubuntu distros). Tested wit</i> to run but will fix that in the future. <u>Download</u>	h Mint18. Security is slack requires sudo			
Originally Posted by dima <i>Ported new interface to Linux (Ubuntu distros). Tested wit</i> <i>to run but will fix that in the future. <u>Download</u></i>	h Mint18. Security is slack requires sudo			
Originally Posted by dima <i>Ported new interface to Linux (Ubuntu distros). Tested wit</i>	peautiful interface in Linux and Windows? I am			
Originally Posted by dima Ported new interface to Linux (Ubuntu distros). Tested with to run but will fix that in the future. <u>Download</u> Hi Dima Can you give some instructions on how to install and use this b	peautiful interface in Linux and Windows? I am			
Originally Posted by dima Ported new interface to Linux (Ubuntu distros). Tested with to run but will fix that in the future. <u>Download</u> Hi Dima Can you give some instructions on how to install and use this to not a programmer. Where to put your files and what command	peautiful interface in Linux and Windows? I am			
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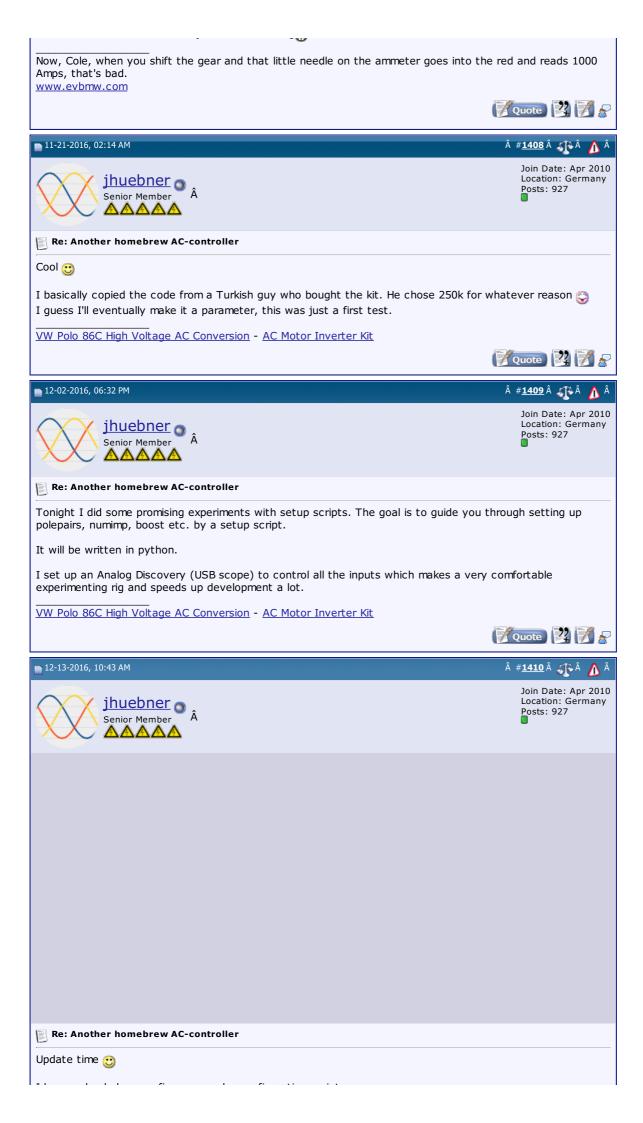
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I have uploaded a new firmware and a configuration script.

Changes in the new firmware:

- 1. Pure Sine mode (ignoring encoder feedback)
- Parameters are organized in categories (you also need to update the web interface to make use of that)
- 3. I have worked on the boost mode charger. It now has a current mode controller and according parameters. I will post a schematic on wiring it up soon.
- 4. I have added the experimental sync mode that I worked out with Jack Bauer (extra flying leads needed)5. In the tools I have added an auto-setup script that tries to find values for boost, fweak, polepairs and numimp. Those seemed to pose the biggest problem.

I would be happy to obtain some feedback on the setup script. Does it arrive at the same parameters you tuned by hand? No worries about messing up your config, the script doesn't save anything to flash unless you tell it to. So reset and your old config is back.

VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit

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Join Date: Apr 2010 Location: Germany Posts: 927

Re: Another homebrew AC-controller

Quote:

Originally Posted by **ALIE** *Hi Johannes*

Christmas is already here 音

I'm tested together with Arber

I putting together inverter for Letrika motor (tvizy) and I tested your accessories when I'm done.

Another inverter maniac 🙂 Very pretty. What car is it going to go into?

Quote:

Originally Posted by arber333 🔊

Will try the difference from autotuning and manual approximation soon. Let the better man (computer) win.

Otherwise i set the boost a little higher than usual together with fweak and i was shocked... motor took off smoothly, only in the begginning you can feel springs in the clutch and overall feel is better. I think boost and fweak have to be found together.

Well, they both influence the voltage curve, thus the current curve and thus the torque curve. See attachment.

Quote:

Originally Posted by arber333 55

On the other hand i can feel sudden twitch from the motor irregularly when accelerating from traffic light to speed. I now have 90KKm and 30K of those is with your controller, not bad! It seems my encoder has some problems, maybe moisture? Do you think i could see what is going on while driving? Which parameter i have to record to see if this is the case?

Try recording "speed". That should show sudden twitches when the encoder misses a pulse or something. My very exposed encoder has also been a source of trouble. First I had EMI issues which mostly showed at startup. Then the encoder wheel had moved and was scrubbing the encoder -> many pulses lost -> overcurrent error. The next time the encoder had gotten out of alignment -> overcurrent. Surprisingly I never had issues with dust or moisture.

I fixed everything more tightly, rerouted the cable (away from power cables) and fixed the low pass filter. The problems went away.

-Attached Thumbnails -

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 WW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit

 Image: Conversion

Quote:



Hi Johannes		
Christmas is already	/ here 🕋	
I'm tested together	with Arber	
Attachment 70098		
		· · · -
I putting together in	nverter for Letrika motor (tvizy) and I tested your accesso	ries when I'm done.
Clean, I like it.	Change comes, one conversion at a time. http://onegreenev.blogspot.com/ https://www.youtube.com/user/onegreenev/videos	
		Quote 🔡 📝 🔗
12-14-2016, 01:58 AM		# <u>1417</u> 🏠 🧥 Â
ALIE Junior Member Â AA		Join Date: Jan 2015 Location: Slovenia Posts: 28
💮 Re: Another homebre	w AC-controller	
72V maximum power is 4	ed T_KING . electric motor will be installed Letrika 15 kW motor but inste ЮkW.(already tested on several cars) dragrace car -street legal of corse 🌐	ad of 45V will operate at
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12-14-2016, 04:43 AM		# <u>1418</u> ∠ T ≜ ∧ Â
jhuebne Senior Memb	er Â	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebre	w AC-controller	
∽ ∵used to similar car, ver	ry fun to drive. It was only 20kW but quite angry because o Are there higher voltage versions?	of the low weight.



After I saw that	nat competition (not for b	eautiful) 😋	
phase board with (the prototype be	2 IGBTs. Drivers and bus pard at the upper right).	cap included. Galvanic iso	should give it a go. So I made a lation must take place off board
I tested with 1 po only 1W@17.8kHz		ns, no problems. All three	phase boards combined use
		d steel rods as DC bus are probably the second 20% .	crap 而 The last phase delivers less than the first.
	hreaded rod. Would be st anchored from one end.	ronger than copper and th	at way you could solder nuts on it
How do you drive two existing DCDC with la		Vouldnt you just make a pu	sh pull transistor driver and use
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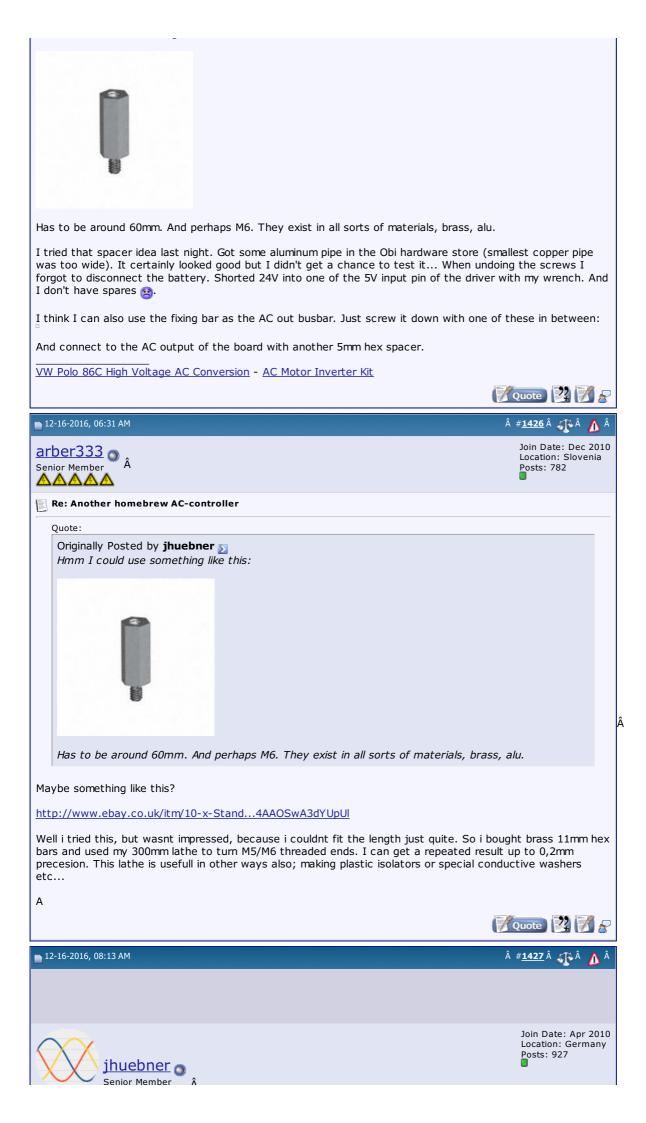
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12-15-2016, 04:26 AM			# <u>1</u>	421 Â 🏠 Â	∕Å 🛆	DIY Ele
jhuebner Senior Member			Le	oin Date: Ap ocation: Ger osts: 927		Sponsors
📃 Re: Another homebrew A	AC-controller					
Quote:						
	ber333) nreaded rod. Would be stro ked point anchored from or		at way you coul	ld solder		
Just checked a material tab copper: 0.017 aluminum: 0.027 brass: 0.07 steel: 0.1-0.2	ble for specific resistance:					
So brass would be about 2>	x better but aluminum wou	ld be an even better repl	acement (apart	from coppe	er)	
Quote:						
Originally Posted by art How do you drive two is and use existing DCDC	IGBTs with one driver? Wo	uldnt you just make a pu	sh pull transisto	or driver		
Each pair of parallel IGBTs I driver. Each IGBT has it's o The prototype board conta six drivers.	own gate resistor and TVS.			-		
WW Polo 86C High Voltage A	AC Conversion - AC Motor	Inverter Kit				
			Qu	ote 🙎	1	
■ 12-15-2016, 08:09 AM			# <u>1</u>	422 Â 🏠 Â	Â	
dcb Senior Member Â				oin Date: Dec osts: 2,170	2009	
📃 Re: Another homebrew A	C-controller					
the grommet discussion gav	ve me a quick fix idea, for	better or worse.				
You could use copper pipe nuts and washers in the mi their ends cleaned up nicely	iddle of the threaded rod. S	So 4 lengths of copper pi				Become a Sponsor
Also if you connect the blue without the pipe rig).	e lead where it is circled re	ed, it should help balance	out the resista	nce (even		
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Last edited by dcb; 12-15-2016	at 08:27 AM.		Row	ote 🙎	×	
■ 12-15-2016, 09:45 AM			# <u>1</u>	423 Â 🏠 Â	Â	
dcb 👩			Jo	oin Date: Deo	2009	

Senior Member Â	FUSIS. 2,170
Re: Another homebrew AC-controller	
Sorry, bored enough to dig into it more 🙄	
Anyway, the taps would have to be catercorner, but in \sim 3/10ths f as I can tell. (copper pipe standoffs or not).	rom the corners to get rms balance as far
I suppose you *could* fix balance in software too 🌚	
edit: here is a picture, the other attachment is straight catercorne to show balance ratio only.	r and straight endtap, resistances chosen
edit2: If you are using straight copper (or aluminum) bars, this still the battery leads.	looks like the optimum location to connect
Attached Thumbnails	Â
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Last edited by dcb; 12-15-2016 at 10:10 AM.	
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■ 12-16-2016, 02:25 AM	# <u>1424</u> 🌾 🧥 Â
	Join Date: Dec 2010
arber333 Senior Member Â	Location: Slovenia Posts: 782
	•
Re: Another homebrew AC-controller	
Quote: Originally Posted by jhuebner ∑ Just checked a material table for specific resistance: copper: 0.017 aluminum: 0.027 brass: 0.07 steel: 0.1-0.2 So brass would be about 2x better but aluminum would be an copper) I used aluminum for standoffs a lot in my charger. But in the end i for work with. I can solder threaded brass piece directly to PCB and us contacts etc Zinc ialso has very similar conductivity than brass. And research that aluminum some more. You will find that number i maybe 2xxx designation. I consider 2xxx too soft to work with in a electrical resistivity and besides Alu forms oxide layer that firther ir negligible difference from brass And in aluminum when you make because dry aluminum is more difficult to cut. I just use WD40. But brass material is more \$\$\$ yes? Also i wouldnt go with copper pipe for standoffs, due to copper core excellent standoff material, but if you use aluminum your choice. EDIT: Maybe you would just drill trough hex brass pieces and put t way through te path of least resistance My 2c Last edited by arber333; 12-16-2016 at 02:36 AM.	found out brass is just so much easier to se it instead of nut, or i can reinforce s relevant only for clean aluminum and lathe Every other designation is worse in npedes conductivity. In the end there is threads with hand tools, use lubricant,
■ 12-16-2016, 05:22 AM	# <u>1425</u> ∭ Â
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew AC-controller	
Hmm I could use something like this:	





Re: Another home	orew AC-controller			
Quote:				
Originally Posted is there a scheme	by jackbauer <u>></u> atic for how to connect c	charging mode?		
Not yet. For a basic t Make sure there is a		DC source to B- and Vcc	of your DC source to L3 or L1.	
Quote:				_
Originally Posted	· ·	uning scripts? Some proce	adura?	
		uning scripts? Some proce	2007 2 ?	
python tuning.py -d /	/dev/ttyUSB0			
.,	. ,			
Motor is connected a	s usual.			
VW Polo 86C High Vol	tage AC Conversion - AC	<u>Motor Inverter Kit</u>		
			Quote 2] 🖉
Post Reply	Page 143 of 221 «	First < 43 93 133 141 14	2 143 144 145 153 193 > Last Â	.» 🛡
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Forum Jump

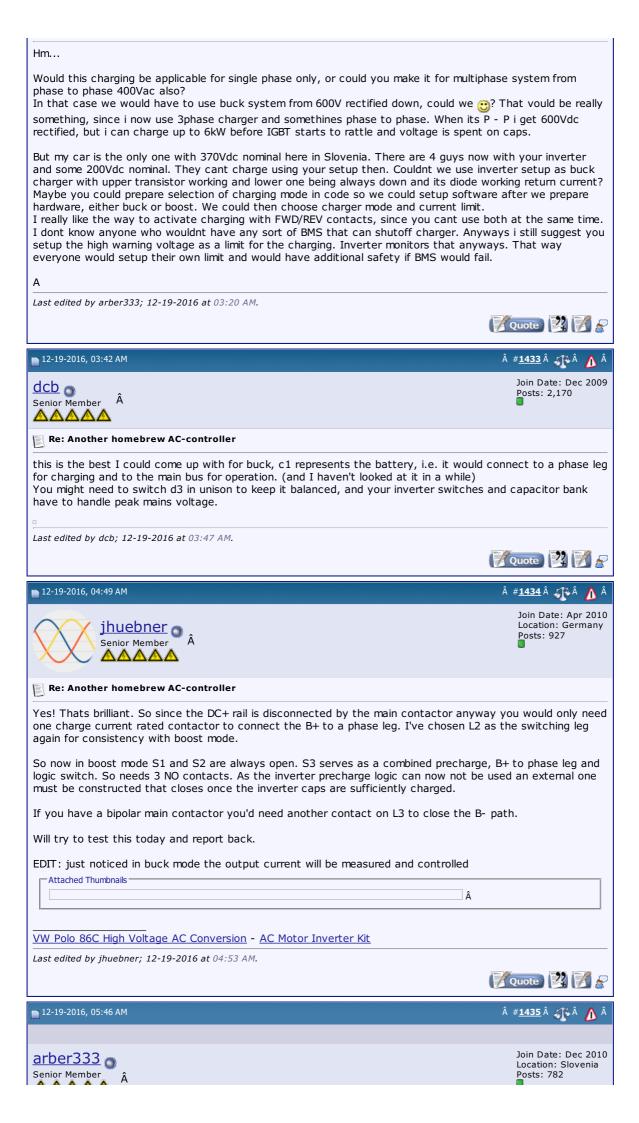
Â Controllers

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Post Reply Page 144 of 221 Â ≪ First < 44 94 134 142 143 144 145 146 154 194 > Last ≫ ▼	Support DIY Electric Car
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■ 12-18-2016, 04:22 PM Â # <u>1431</u> Â 👫 Â 🏠 Â	
jhuebner Senior Member Å Å Å	Sponsors
Re: Another homebrew AC-controller	Sponsors
Real engineering takes place on paper 😁	
So AC comes in, is being rectified and switches a contactor. The latter enables boost mode charging by a) supplying the inverter with 12V (instead of the key switch) b) Pulling FWD and REV high (you might need some extra diode magic to not obstruct normal operation. I constantly have it in FWD mode so no issue there) Then the rectified AC passes another switch that is controlled by the DCSW signal of the inverter (I have a 3-phase switch as main contactor and thus a free contact to use). Boost mode does the normal precharge sequence, closes the main contactor and starts charging.	
Charging will go on until you either cut power to the inverter or disable one of the hardware inhibit pins (mprot, emcystop). So you will need a BMS with a relay output.	
Of course you can also break the input into the rectifier instead of the output which would allow to place the rectifier inside the inverter.	
EDIT: bottom IGBT of L2 does the switching, top diode conducts the current upward. All other IGBTs are for illustration only and are constantly off. "Motor Phase" is basically L1 in parallel to (L2 in series with L3). Doesn't seem to pose a practical problem though.	
More edit: the parameter "chargecur" controls the input current INTO the inverter. So the charge current into the battery will taper off as voltage rises. I found that more practical than controlling the current into the battery as the wall outlet is usually the limit of the charge rate.	
Attached Thumbnails	
VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
Last edited by jhuebner; 12-18-2016 at 04:34 PM.	
Quote 🕎 🌌 🧞	
■ 12-19-2016, 01:45 AM # <u>1432</u> ∰ Â Â	
arber333 Join Date: Dec 2010 Senior Member Â A A A A Posts: 782	Become a Sponsor



Re: Another homebrew AC-controller

Quote:

Originally Posted by jhuebner 55

Yes! Thats brilliant. So since the DC+ rail is disconnected by the main contactor anyway you would only need one charge current rated contactor to connect the B+ to a phase leg. I've chosen L2 as the switching leg again for consistency with boost mode.

So now in boost mode S1 and S2 are always open. S3 serves as a combined precharge, B+ to phase leg and logic switch. So needs 3 NO contacts. As the inverter precharge logic can now not be used an external one must be constructed that closes once the inverter caps are sufficiently charged.

If you have a bipolar main contactor you'd need another contact on L3 to close the B- path.

Nice!!!

So now i think i could wire 3phase AC to have BUCK from 600Vdc.

I think outside precharge with arduino and 570R resistor would be good. 10s should do it.

Hm, i should use one 10mm2 wire from phase 3 to DC+ battery side BEHIND contactor. **DC contactor** (tyco EV200) would be off in case of charging. Another EV200 would be **phase contactor** to bring phase 3 to DC+. But for safety i would route gnd of **phase contactor** trough **DC contactor** wiring so that would be impossible to have both ON at the same time.

So if i wanted to have 3phase charging, this is how it would work... 1. presence of 400V (230V on AC contactor L1/N) sets on precharge (timer) relay 10s...

2. AC contactor is on, Phase contactor is on, inverter, water pump and cooling fans get 12V

3. Inverter charges with CC regulation.

4a. After BMS command, inverter shuts down softly, after that AC and Phase contactors go off

4b. Inverter reaches preset max voltage and stops softly. AC and Phase contactors go off!

Observe that all contactors could run trough existing precharge system allready in place. We would only have to remove GND from (main)DC contactor and precharge relay so that charger or drive functions couldnt mix. Precharge would be allways present on the AC side as 3x 570R 15W across AC contactor.

How would you manage boost circuit for single phase? How much current do you think we would get from single phase? PFC correction? I am still more for 3phase system!

Last edited by arber333; 12-19-2016 at 05:49 AM.

🖿 12-19-2016, 07:11 AM





Quote 🕎 🏹 🔎

#<u>1436</u>Â **∭** Â Â

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Re: Another homebrew AC-controller Of course 3-phase is better because there is much less ripple on the rectified DC. I will stick with 1-phase because you can find it anywhere. But thats your decision really, the software doesn't care where your DC

COLES HOLE	
With the EMW charger (no PFC) I can charge at 3kW from a 230V, 16A outlet. The power fact poor at 0.82 if I remember correctly.	tor is rather
Anyway, the good news is: it works! 💮	
It was only a minor software mod. I made a video which is currently uploading.	
I observed some unexpected things: 1. Efficiency drops as INPUT voltage rises 2. PWM frequency does not change efficiency (I tried 17.8kHz and 8.8)	
${\rm I}$ do remember there is a way to optimize power factor with only current measurement. That c step.	could be a next
Edit: once the video has uploaded:	
VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
Last edited by jhuebner; 12-19-2016 at 07:48 AM.	
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12-19-2016, 08:14 AM Â #1 arber333 Senior Member Â Re: Another homebrew AC-controller J how do you expect to control current power when this charger will be connected? Would you with a parameter in web interface? In that case i would suggest to measure caps voltage and control two parameters, limited and there is <320Vdc on caps system is on single phase, hence limit to 3kW. If there is >500Vdc on	437 Â A Â Â Din Date: Dec 2010 ocation: Slovenia osts: 782 u limit charging d full power. If
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Re: Another homebrew AC-controller A how do you expect to control current power when this charger will be connected? Would you with a parameter in web interface? In that case i would suggest to measure caps voltage and control two parameters, limited and there is <320Vdc on caps system is on single phase, hence limit to 3kW. If there is >500Vdc of apply full power of 11kW or 20kW example there is control two parameters. I think i will be happy to shed some 20kg of weight from my car AND have a faster charger! As i also use EMW charger, i find PWM at 8kHz is enough for IGBT comfort, winding lossess are we will have to see how this will play out. I have a large fan in front that i can trigger in case overtemperature You have another suggestion?	437 Â A Â Â bin Date: Dec 2010 ocation: Slovenia osts: 782 u limit charging d full power. If on caps then e greater but
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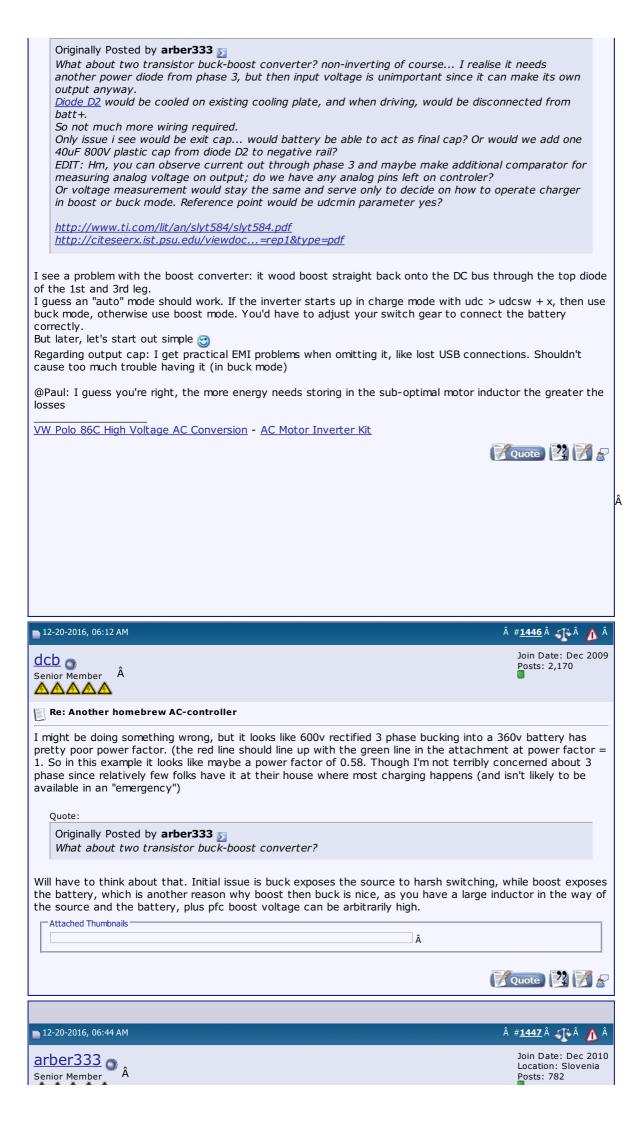
Re: Another homebrew	AC-controller			
fwiw, ideally you would have two motors and inverters (like the prius or volt) for charging, and one motor/inverter would be pfc/boost and the other buck. Then it would work with any input/output voltages and wouldn't be just for "emergencies" as it would be nice to the wall power 😳				
not considering 3 phase power though. You really need 3 separate boost converters to pfc that right, so "maybe* if you had 4 motors and inverters (unless 3 phase pfc boost is hidden in the standard topology somewhere)				
			📝 Quote 📴 🌠 🔗	
■ 12-19-2016, 10:05 AM			# <u>1439</u> ∡ [≩ <mark>∧</mark> Â	
jhuebne Senior Membe			Join Date: Apr 2010 Location: Germany Posts: 927	
🛐 Re: Another homebrew	AC-controller			
Not sure if you can take	the motor abuse tha	t far 😋		
			voltage measurement on the battery ed out all wrong and non-linear.	
It would be possible in bo	oost mode but I think	I'll just leave it to the BMS.		
you need high power cha	irging just take a sep		n replace a low power charger. If he respective trips or wait for DC / 😳	
VW Polo 86C High Voltag	e AC Conversion - AC	<u>C Motor Inverter Kit</u>		
Last edited by jhuebner; 12-	19-2016 at 10:12 AM.			
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📄 12-19-2016, 10:52 AM			# <u>1440</u> ∡∰ <u>∧</u> Â	
12-19-2016, 10:52 AM dcb Senior Member Â			# <u>1440</u> 📣 Â Join Date: Dec 2009 Posts: 2,170	
dcb o	v AC-controller		Join Date: Dec 2009	
dcb A Senior Member Â A A Re: Another homebrew Well, it is as complicated	as any "real" charge er setup then you ca	n accomplish it. I think this i	Join Date: Dec 2009	
A Senior Member A Re: Another homebrew well, it is as complicated have a two motor/inverted his prius charger experim conceptually pfc is real s	as any "real" charge er setup then you ca ents, and what the e imple (esp with a mic	n accomplish it. I think this i	Join Date: Dec 2009 Posts: 2,170 ge and a buck stage, and if you s what jdcircuit is working on with	
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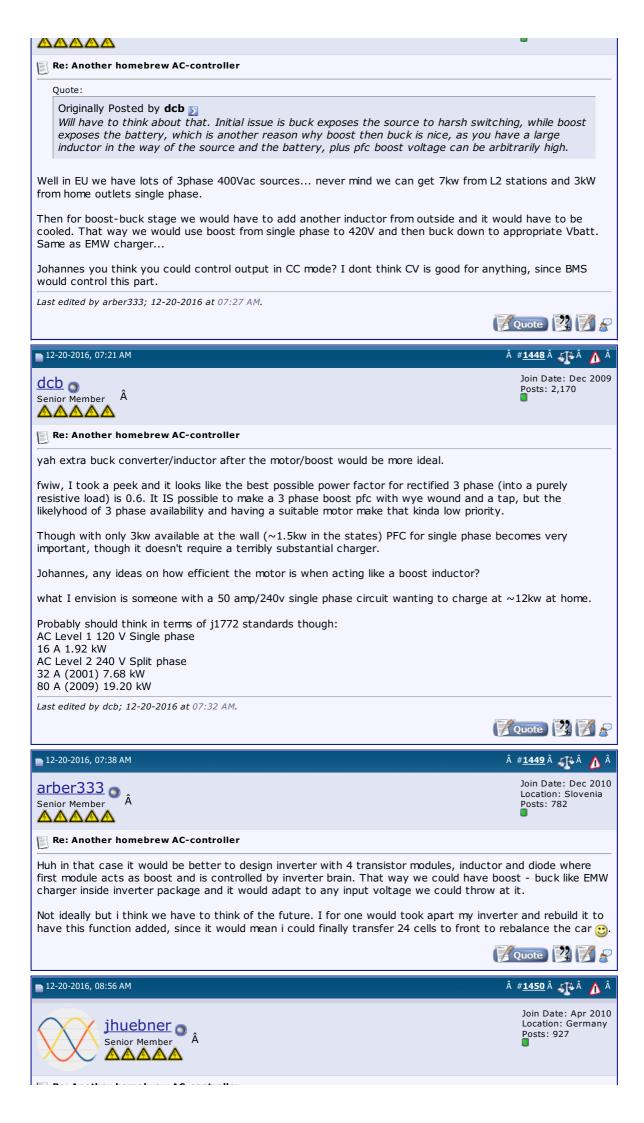
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E Ke: Another nomedrew AC-controller					
New firmware is up. Set chargemode to buck (4) to try it.					
As a little extra I figured I could use the voltage on the mprot pin to measure the aux (12V) voltage. See uaux and let me know the accuracy.					
I think before doing fancy things with extra transistors, PFC etc. let's try how well this goes.					
@dcb: watch the video 🤭 I do the efficiency calculation towards the end.					
VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit					
				Quote) 😰 🗹 🔗
Post Reply	Page 145 of 221 Â « Fi	irst < 45 95 135	i 143 144 145	146 147 155 195	> Last » 🔽
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	Google	💦 Yahoo!		Newsvine	
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Post Reply Page 146 of 221 Â « First < 46 96 136 144 145 146 147 148 Thread Tools ♥ Search this Thread ♥ Rating: Mathematical	B 156 196 > Last » ▼ Support Electric
2-20-2016, 01:48 PM	# <u>1451</u> 🎝 🛕 Â
	Join Date: Apr 2010 Location: Germany
jhuebner Senior Member Â	Posts: 927
	Spons
Re: Another homebrew AC-controller , about efficiency: I just noted that I measured at the wrong end of the cable. Some connections are made with 1.5mm² lab	cable. For example
output voltage of the power supply is 20V but the input voltage into the inverter is 19.26V.	
now • input voltage: 19.26V	
• input current: 14.3A • output voltage: 26.74V	
output current: 9.5A efficiency: 92,2% !	
ink thats not had considering the 2V ICPT voltage drop is already in them	
ink thats not bad considering the 2V IGBT voltage drop is already in there.	
In I did an experiment for the power factor. I have one of these energy meters which measure all kind of things. So I found m he basement and ran it at 14V@12A. So boosting to over twice the voltage. I got a power factor of 0.9. I'm quite happy with	
ver factor drops as the current is lowered.	
	1 Quote 2 7 8
-20-2016, 02:09 PM	# <u>1452</u> ∡ [≩ ∧ Â
	Join Date: Dec 2009 Posts: 2,170
Re: Another homebrew AC-controller	
Quote: Originally Posted by jhuebner s	
So boosting to over twice the voltage. I got a power factor of 0.9. I'm quite happy with that.	
nobably isn't. Back in the day they used simplifying rules of thumb such that they assumed current was linear (i.e. sinusoidal) unction of phase shift, or displacement. So something like change in zero crossing was sufficient.	and power factor was
it really doesn't work today, for non linear loads. You have to compare the input current waveform with the input voltage, m	noment by moment, at Become a s
lecent resolution, to get true power factor. e the "rant" section of the first comment here:	
p://electronics.stackexchange.comn-linear-loads	
	Quote 2 2 2
20-2016, 02:50 PM	# <u>1453</u> 🏹 🧥 Â Join Date: Apr 2010
jhuebner Senior Member	Location: Germany Posts: 927
Re: Another homebrew AC-controller	
: why would they use an algorithm in that power meter that is useless for most loads? Fluorescent lamps, switch mode power n-linear loads. I mean integrating the product of two values is not so hard	supplies etc. are all
so did a sanity check: DC current was 12A and AC current (into the rectifier) was 13.4A. 12/13.4A ~ 0.9 tadaa.	
e reason to care about power factor isn't academic. In the given case 13.4A would be the current that heats up the cable an only 12A are actually going somewhere, the remaining 1.4 amps are swinging back and forth. So you lose 1.4A that you coul	
only 12A are actually going somewhere, the remaining 1.4 amps are swinging back and forth. So you lose 1.4A that you coul a power factor of 1. 	u use for charging nau
/ Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
	V Quote 🔀 🖌 🔗
	â # <u>1454</u> â 📣 â 🧥 â
	Join Datas Data 2000
2-20-2016, 03:06 PM	Join Date: Dec 2009 Posts: 2,170



Re: Another homebrew AC-controller	
	ents, with surprising results in some cases. For the simulation below, I got 22.3 amps per
phase at 247 VRMS for 5518 VA, and 3.21 kW per phase for	·
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V(vU,neutral) V(bat)*([V], V[bat) V(vU,neutral) V[bat)*([V], V[bat) V(vU,neutral) V[bat)*([V], V[bat) V[neutral) V[v], V[bat) V[neutral) V[v], V[bat) V[v], neutral) V[v], V[bat) V[neutral) V[v], V[bat) V[neutral) V[v], Neutral V[neutral) V[neutral) 0KW 90V 0KW 90V -16KW -270V -28KW -360V -28KW -540V	
■ 12-21-2016, 08:15 AM	# <u>1459</u> 👔 Â
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by jhuebner New firmware is up. Set chargemode to buck (4) to try	it.
As a little extra I figured I could use the voltage on the accuracy.	mprot pin to measure the aux (12V) voltage. See uaux and let me know the
I think before doing fancy things with extra transistors,	PFC etc. let's try how well this goes.
@dcb: watch the video 😋 I do the efficiency calculation	towards the end.
Hmmmm	
(attiny) and opto needed with DCDC of course. We do need	sed it last. In that case you could use pot2 as voltage sensor. Only one comparator output voltage? You think it is wise to put any stuff to MPROT?
A Last edited by arber333; 12-21-2016 at 03:31 PM.	
	Quote 2 S
■ 12-21-2016, 12:13 PM	# <u>1460</u> 🏹 🧥

dcb Senior Member Â			Join Date: Dec Posts: 2,170
Re: Another homebrew	AC-controller		
Quote: Originally Posted by P 247 VRMS	'StechPaul 🗾		
	ase to phase is ~430v (600v peak),	, because apparently that is how it is	measured commonly.
Quote: Originally Posted by P for 58% power factor			
	d, "true" power factor, not displace	ment or harmonic shortcuts, just point	: by point integration.
Quote: Originally Posted by d So in this example it i	Icb ∑ looks like maybe a power factor of t	0.58.	
So if you replace everyth "proper" 3 phase pfc.	ing from the caps to the battery wi	th just a resistor, do you get pf=0.607	? This is why you need 3 boost converters for
			to the ripple current follows the peak voltages a so, not without messing up the other phases, n
Maybe "best" topology is), then use inverter/motor for buck? A r to boost the cap voltage initially via	is it could pfc single phase just fine and help with reverse buck possibly, maybe not).
Edit, oh and mind neutral	vs ground, here neutral is hundreds	of volts above ground.	
		Â	
Last edited by dcb; 12-21-201	16 at 01:06 PM.		
			Quote 2
Post Reply		Page 146 of 221 Â	96 136 144 145 146 147 148 156 196 > Last Â
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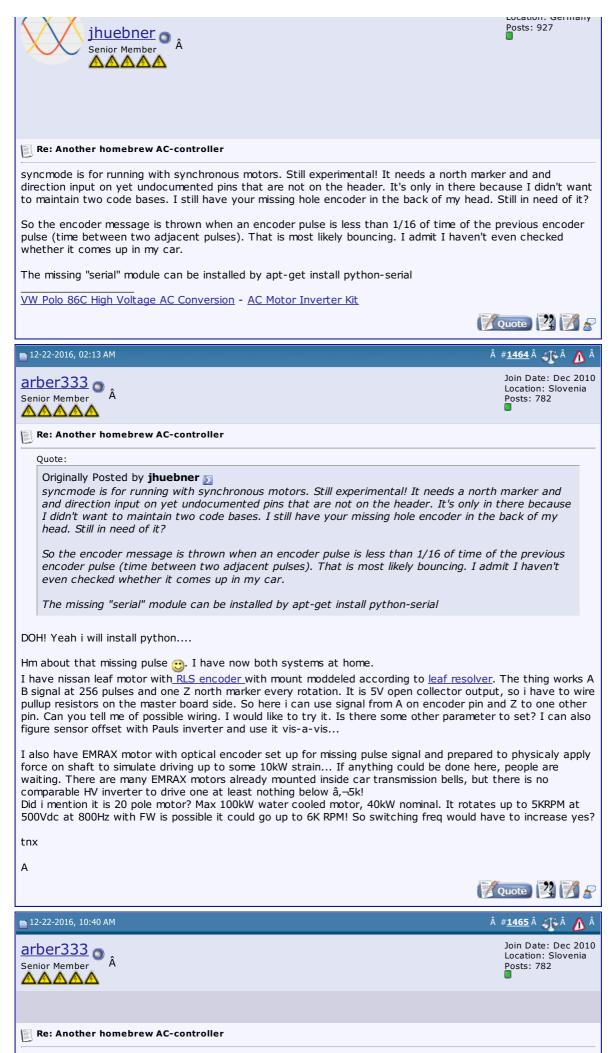
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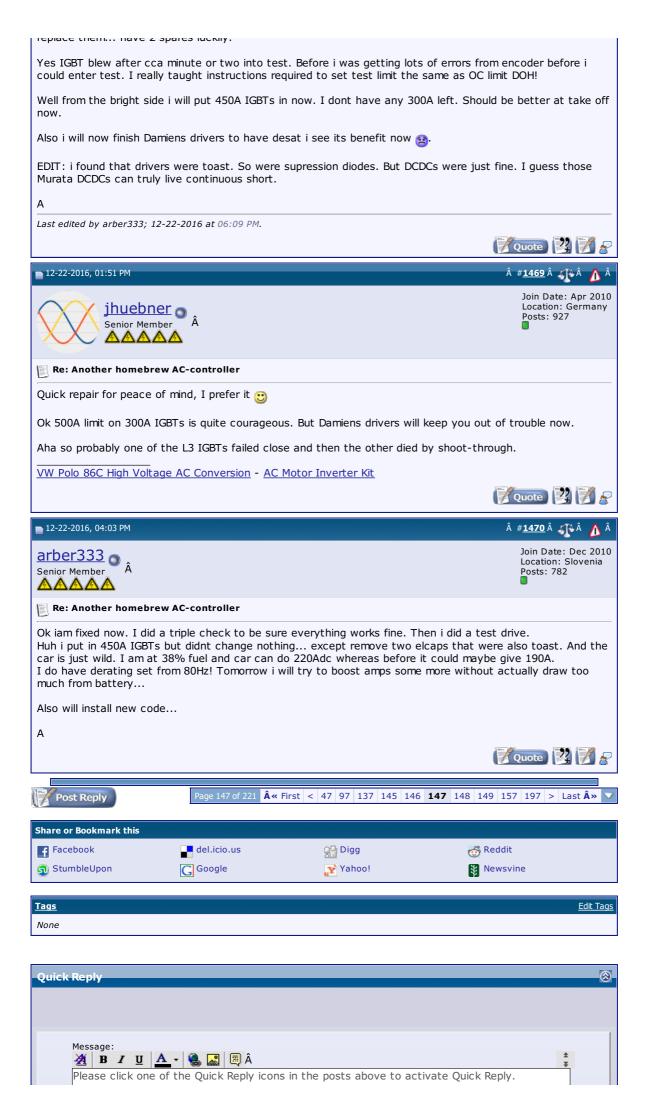
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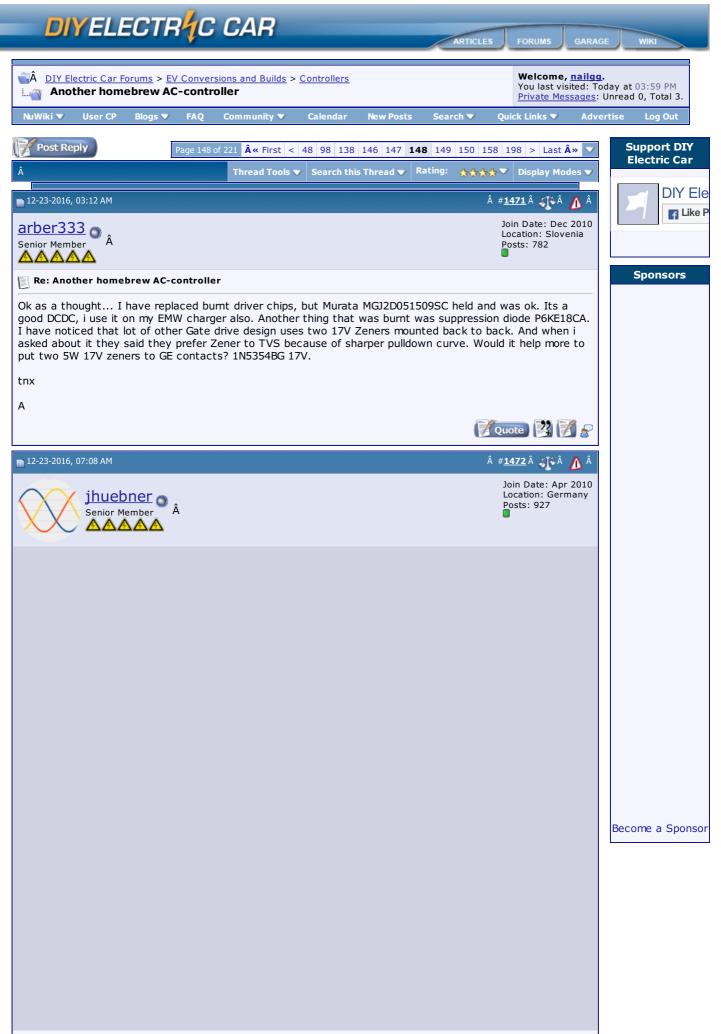
Grr... Johannes! I am angry at you!





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About Zener vs. TVS - I really don't know, hope someone else chimes in.

Now about the tuning script.

- It assumes that you have correctly calibrated your current sensor gain (il1gain, il2gain). So put a known DC current through the sensors (you use multiple windings, 10 windings with 10A result in 100A reading) and adjust the factors ilXgain until the reading matches your current
- It assumes a correctly configured over current limit. Over current limit relies on correctly calibrated sensors somehow it must convert A to the reference voltages for the comparator
- It assumes you correctly set up precharge, which includes correct calibration of udcgain

I can include this steps into the script later on. So far it concentrates on motor setup. The script then checks software version and key digital inputs and asks you to start the inverter with the start pin.

The following steps can be skipped if already set up

- boost calibration you enter your desired RMS motor current, meanwhile it checks your input against ocurlim - if its closer than 60% it will reject your input. It will then output a 2Hz sine wave and keep increasing the amplitude until your desired RMS current is reached. Keep in mind the peak current is higher - roughly 1.5 times the RMS current.
- 2. fweak calibration it requires boost to be correctly configured, either manually or by the script. The script will output fweak/2 and fweak at 10% amplitude assuming a locked rotor (it will hardly spin at that amplitude anyway). It will keep doing this until the current at fweak is 2x the current at fweak/2. Thats because the locked motor is a transformer with the secondary winding shorted and twice the frequency transfers twice the current into the short.
- 3. Next comes the polepairs test. It will spin the motor at 2Hz and 50% amplitude and instruct you to count the number of turns the motor does within 10s. From that it arrives at the number of polepairs
- Next up is finding the number of impulses per turn from the encoder. For that the motor is ramped up to 60Hz at 70% amplitude. That way the motor runs almost synchronous to the stator. numimp is set to 8. Now comparing the expected speed (assumed .1Hz lower due to slip) against the reported speed arrives at the actual number of impulses. Of course this test goes wrong if for some reason the slip is higher but at least it gets you in the right ball park. If it reports 63 than most likely it is actually 64.
 So far nothing has been saved to flash, you can do so in step 5

Long post today, because next up is CAN.

I was recently lent a CAN to USB adapter and decided I should play with it so attached pictures show you how to attach an MCP2562 transceiver to the current board.

- 1. Pin 1 is connected to Pin 3 of JP1/EXT1 (CANTX)
- 2. Pin 2 is bent soldered into the ground pad of former JP7
- 3. Pin 3, as opposed to pic 2, is connected to 5V
- 4. Pin 4 is connected to Pin 1 of JP1/EXT1 (CANRX)
- 5. Pin 5 is connected to 3.3V (can be found on the close by via)
- 6. Pin 6,7 is CANL, CANH
- 7. Pin 8 must be tied to ground

And HW wise you're done. Now tell me what the software should do. I'm thinking about uploading a JSON file or something that maps CAN-Id and the data bytes to certain parameters or spot values, as well as overriding the existing analog and digital IO.

Attached Thumbnails	Â Â Â
VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	Quote 🕎 🌠
■ 12-23-2016, 08:50 AM	â # 1473 â 🐠 â 💧
arber333 Senior Member Â	Join Date: Dec 20 Location: Slovenia Posts: 782
Re: Another homebrew AC-controller	
Now that is a good instruction, thank you!	



Started out by connecting my 60V lab power supply to B- and motor phase L3.

I took a couple of steps before actually applying full power

- 1. Disconnect battery from inverter by pulling fuses. Apply a very small (8V) voltage, set a small current set point and check the DC bus voltage: 60V > good
- Connect battery, apply 60V to input. Currently there are 162 LFP batteries in series in the car. I was surprised to see that the inverter managed to boost 60V to 550V -> boost working -> good
 Connected the mattifier with an additional 100 force. New L bad to be confident to math the input the second time.
- 3. Connected the rectifier with an additional 10A fuse. Now I had to be careful not to rush things:
- Turn key switch on -> precharge engages
- Make sure charge mode is boost and current set point is 0
- Connect fwd and rev to 12V -> main contactor closes, boost mode becomes active
- Make sure ampnom is <= 0
- Plug in rectifier into mains
- Now raise chargecur to whatever you feel comfortable with
- Above 8A setpoint the 10A fuse melted rather quickly

Now I repeated #3 but without the fuse (the line is protected by the house installation anyway). The maximum set point I tried was 14A which resulted in 17A being drawn from AC -> Power factor 0.82, this was displayed by the power meter as well.

Then I ran at 12A for about 30 minutes. I got an output current of 4.8A at 570V -> 2736W. The power meter displayed 2840W -> 96% efficiency

The inverter heated up to $2\hat{A}^{\circ}C$ during these 30 minutes ($7\hat{A}^{\circ}C$ above ambient) and the motor to $6\hat{A}^{\circ}C$. The rectifier on the small heatsink became warm to the touch, like $30\hat{A}^{\circ}C$ or $35\hat{A}^{\circ}C$ above ambient.

I'm very happy with these results. So the next step will be permanently wiring up the contactors and inverter for boost operation. The EMW charger has given up the ghost (probably my fault though) so it's a good time to remove it.

Attached Thumbnails Â VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit Quote 🕺 📝 💂 n 01-06-2017, 08:24 AM #**1476** Â 🎊 Â 🏠 Join Date: Jan 2008 jackbauer 👩 Location: Ireland Posts: 2,147 Â Senior Member Re: Another homebrew AC-controller That's amazing 😁 My next project lined up so! Now, Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. www.evbmw.com Quote 🕺 🕅 두 â #**1477** Â 🎢 Â 🧥 Â n 01-06-2017, 03:01 PM Join Date: Jan 2013 Tomdb Location: Warwickshire, UK Â Posts: 798 Senior Member AAAA 2 Re: Another homebrew AC-controller Mind creating a small diagram of the setup?

What parameters are used when charging? Provided any fancy regulations in terms of current taper/charge pause to observe sag?



I think this can do serious power. The inductance of those motor winds will be huge compared to small wound parts so no need to go very high with switching freg.

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Attached Thumbnails —			Â	
Now, Cole, when you Amps, that's bad. www.evbmw.com	shift the gear and that lit	tle needle on the ammete	_	nd reads 1000
🖻 01-07-2017, 03:20 PM			# <u>1</u>	<u>1480</u> Â 🎪 Â 🧥
jhueb Senior Me			L	loin Date: Apr 2010 Location: Germany Posts: 927
🛐 Re: Another homel	brew AC-controller			
Right, thats the idea discharged for it to w	. Of course in your example vork.	e if you have 400V input y	your pack needs to be	e >564V
	o handle the case when the first drawing would dump			
	ager testing: make very su or both buck and boost mo		un mode when applyi	ng charge
Currently the front of added a mains input	f my car is pretty much ta cable.	ken apart, I have bolted t	he rectifier into the in	nverter and
VW Polo 86C High Vo	Itage AC Conversion - AC	<u>Motor Inverter Kit</u>		
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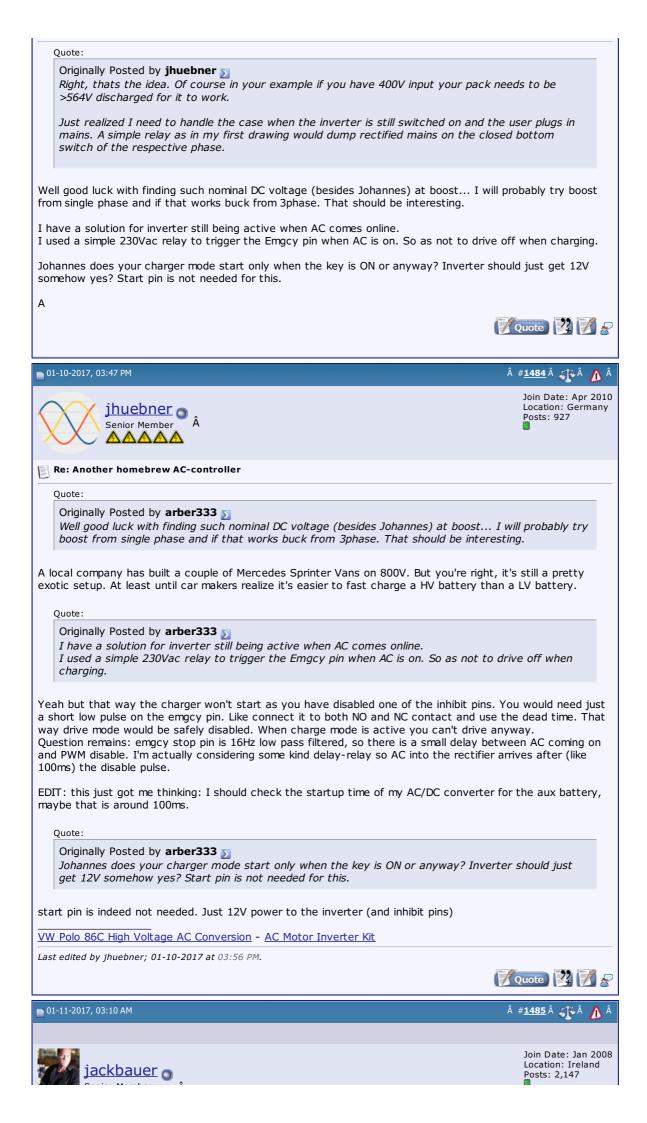
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	AC-controller		
Johannes, very clear updat components 💮	te. I need to get a c	car built so I can actually start	using my gathered EV
I wonder how much power 230v x 3). Should be 32 ar		one of these from a three phas	e charging station (EU one so
			📝 Quote 🕎 🌠 🔗
01-15-2017, 03:39 PM			â # <u>1490</u> â 🐢 â <u>۸</u> â
dima Member Â			Join Date: Dec 2015 Location: British Columbia, Canada Posts: 69
📃 Re: Another homebrew A	AC-controller		
Johannes your website say	vs Boost(4) Buck (5)	but the firmware description sa	ays:
"chargemode 0=Off, 3=Boo	ost, 4=Buck"		
not to confuse with opmod	le that is also needs	s to be set same?	
0=Off, 1=Run, 2=ManualRu	n, 3=Boost, 4=Buck	, 5=Sine, 6=AcHeat	
mistake somewhere on you	ır website or firmwaı	re?	
Huebner Inverter - Console	e Management		
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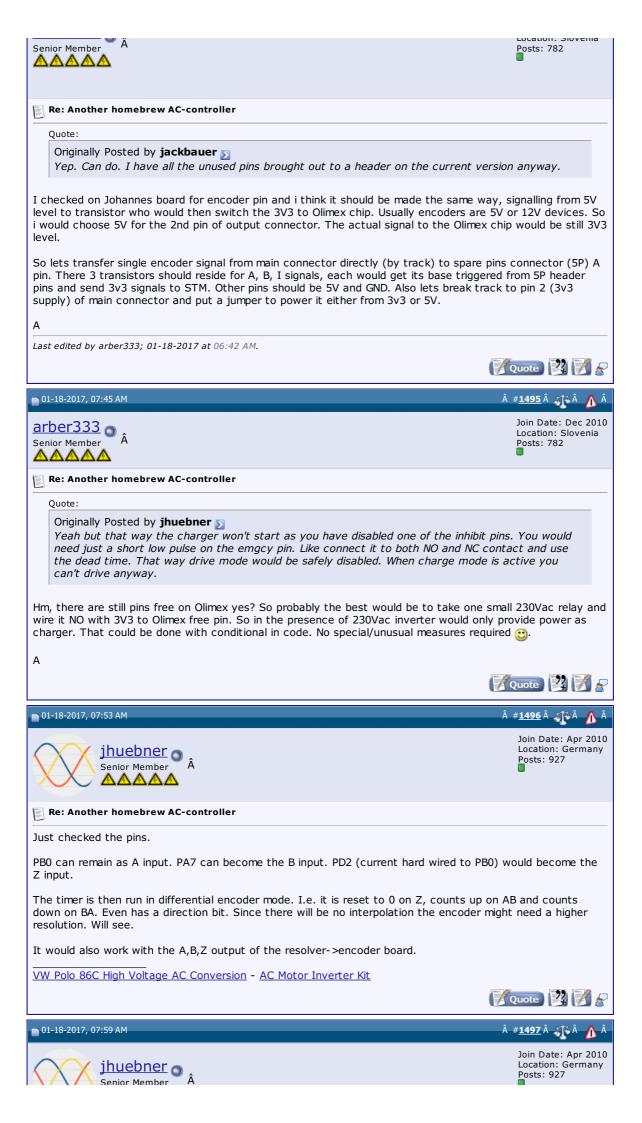
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a few posts back I	thought PA7 was dea	licated to "brkout" breaki	ng lights or something?
Also if the board will b	oe re-designed might	as well include that CAN	chip.
other does. Just to see if	it would be worth im en. It made a terrible	plementing. Same with va mess of my clutch, so i d	me curious but i am doing things none riable braking on brake pedal ont brake at 30A anymore. So this
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Last edited by arber333; 01-1	9-2017 at 02:29 AM.		VQuote 🕎 🌠 S
■ 01-19-2017, 02:25 AM			â # <u>1500</u> â 🐠 â 🔥
jhuebner Senior Member			Join Date: Apr 2010 Location: Germany Posts: 927
📳 Re: Another homebrew	AC-controller		
Quote:			
	thought PA7 was dea	licated to "brkout" breaki as well include that CAN	
			emp.
	so I will have a para tor.		move it to PC9. PC9 is also the speed the two. It will be brought to the pin
CAN will be on there.			
			, precharge etc.) by an ULN2001 dcsw output. Anyone have an issue
VW Polo 86C High Voltage	AC Conversion - AC	<u>Motor Inverter Kit</u>	
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I think what you want is more I/O pins 🧐

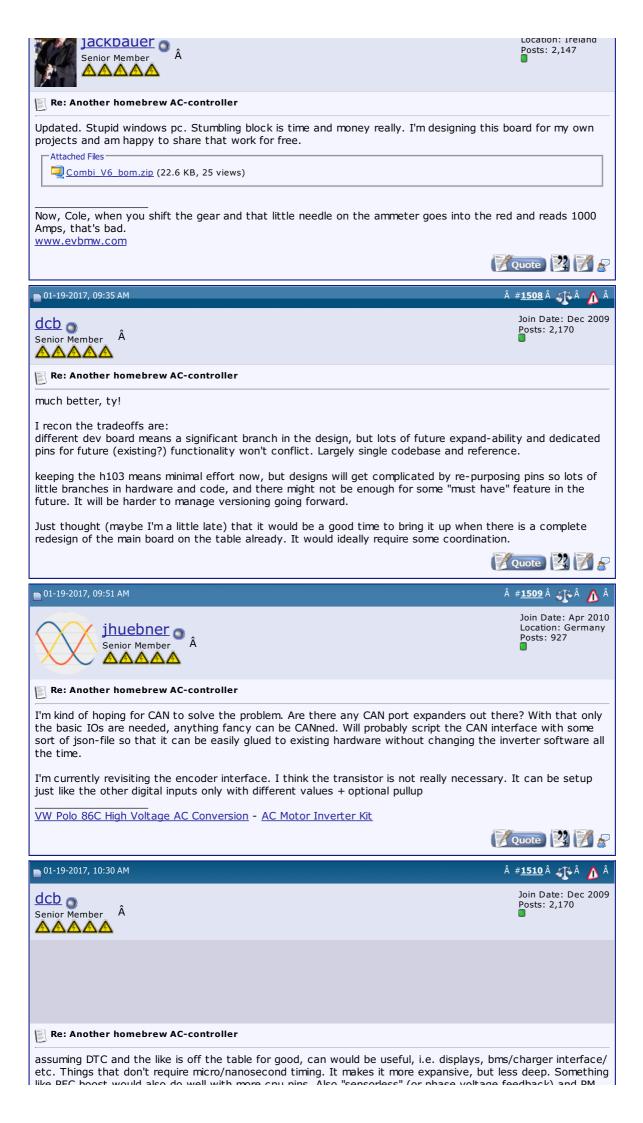
01-19-2017, 08:<u>28</u> AM





Location: Slovenia Posts: 782 Re: Another homebrew AC-controller Quote: Originally Posted by jackbauer S So what we want are three inputs with a transistor buffer and optional pullup for an encoder or encoder emulator type signal? Yes, currently i have push-pull type encoder so the signals would be direct 0 to 5V to transistor. Transistor would then switch 3V3 to Olimex. So if you leave mounts for 3x SMD pullups that would be great. 4K7 or 6K8 pullups would be sufficient. I agree with Johannes, you can use PA7 or PC0 brake input pin, as i dont actually use them to some great advantage. I dont even have PC0 connected. I would like to have CAN, also for future connection with car and arduino Due CAN module i have. You could anticipate another digital input to sense AC presence and/or one output with BC547 for starting charger relay. How many pins that leaves us with? I talked to Johannes about I2C port expander for digital ports, but i think he said serial pins are allready booked. А Quote 🕺 📝 ج ■ 01-19-2017, <u>08:42</u> AM #**1505** Â Λ Â Join Date: Jan 2008 jackbauer 🕥 Location: Ireland Posts: 2,147 Senior Member ◬◬◬◬ Re: Another homebrew AC-controller Here is the current state of the combi board including bom. Will work on modifications to encoder and charger functions as soon as i hear from Johannes. Attached Files Combi_V6 - PCB.pdf (502.5 KB, 38 views) Combi V6 bom.zip (22 Bytes, 15 views) Now, Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. www.evbmw.com 🛛 🛛 Quote #<u>1506</u>Â 🎻 Â 📄 01-19-2017, 09:13 AM ΔÂ Join Date: Dec 2009 dcb Posts: 2,170 Senior Member Â AAAAA Re: Another homebrew AC-controller combi.zip is empty btw so what do you think is the major stumbling block to a 100 or 144 pin code compatible cpu? There are quite a few dev board options out there. 🛛 🛛 Quote 📴 📝 🖉

n 01-19-2017, 09:17 AM #**1507** Â 🎢 A Λ Join Date: Jan 2008



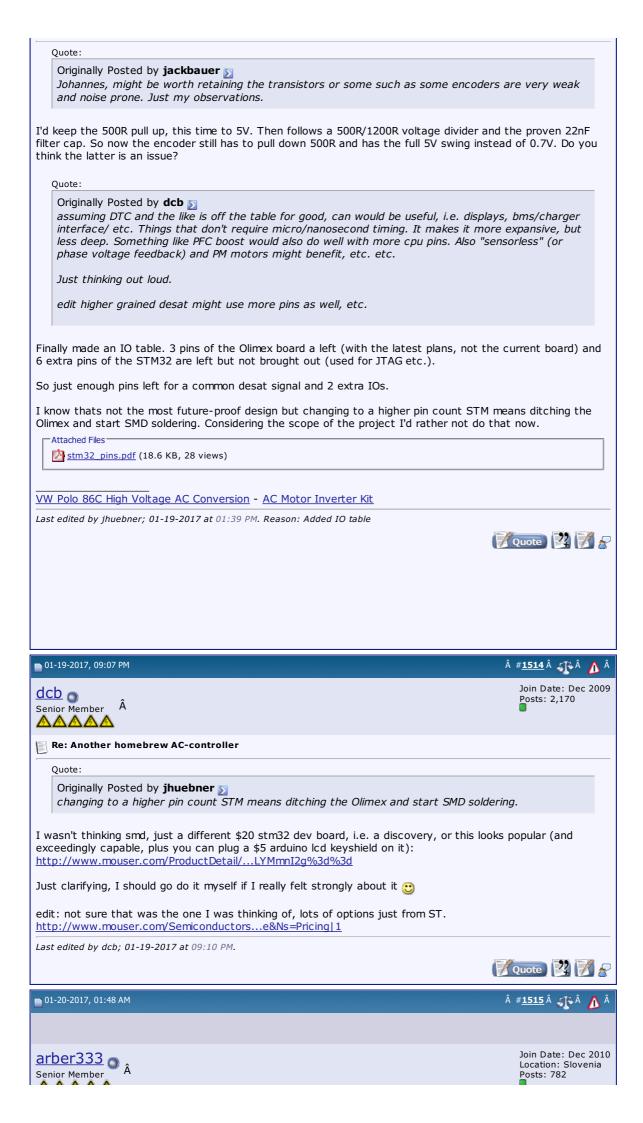
motors might benefit, etc		ט) בכשווטבוושב טבות ובווון עיט ב	i phase voltage recubaci	NJ and FM
Just thinking out loud.				
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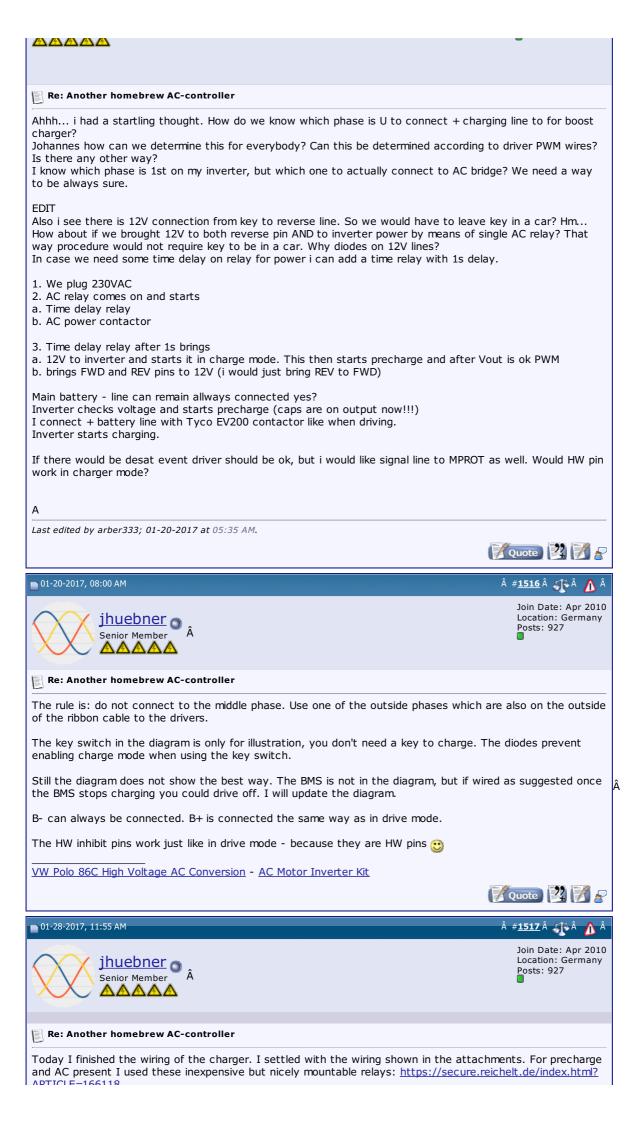
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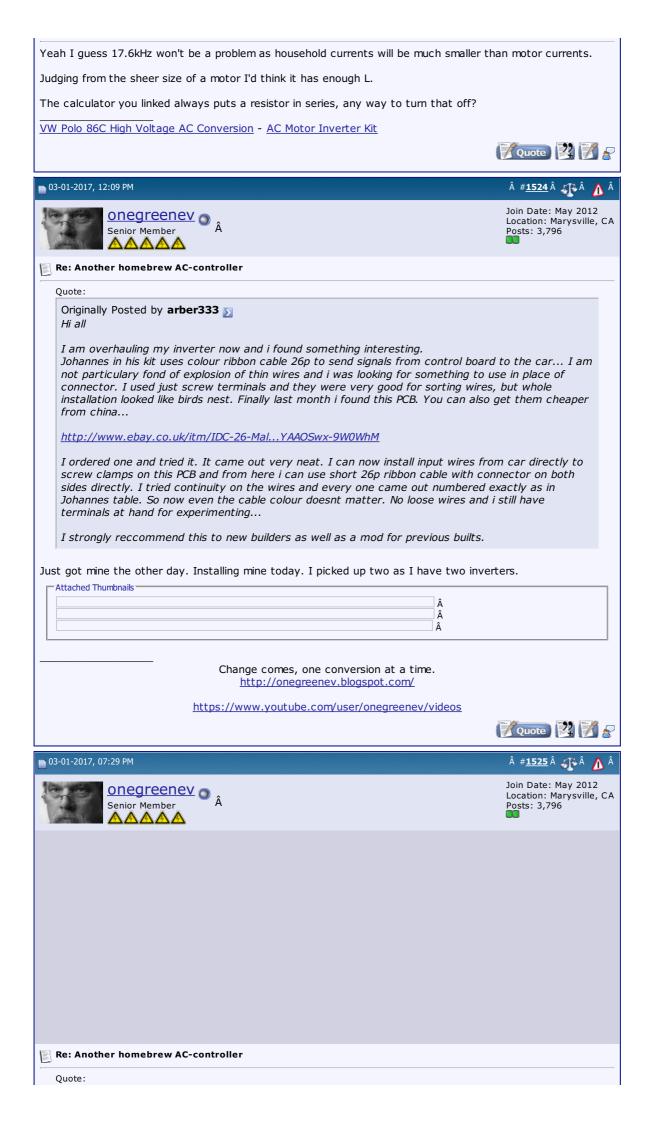
<u>AN10LL=100110</u>
So what happens:
 Plug in AC "AC present" relay K3 closes If inverter is still running, it is immobilized because FWD and REV are high. Charging does not start and no AC goes into the inverter because relay K1 only closes once the precharge relay did it's cycle. This way there are no issues with feeding current into the closed lower IGBT If inverter is not running it also gets the "start charge" input. Power is supplied via the BMS relay. (Issue here: if you leave the key in "on position" charging would never stop. It could be handled with another NC contact before the key switch but I couldn't be hardled.
 bothered) The inverter starts and closes the precharge relay K4. This leads to the AC disconnect relay closing Precharge is done, precharge relay opens. AC disconnect relay powers itself and stays closed Main contactor K2 closes and makes the final connection of AC into the rectifier
Works great and apparently the dials are on the same power as the inverter. So they power on and the state of charge is displayed.
Last week I tried charging at 17.6kHz which is a lot less noisy but it also produces a lot more heat. After 3 hours of charging the heat sink was at 40°C while ambient was -1°C. With 8.8kHz it stayed below 15°C at similar ambient.
Attached Thumbnails
A
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Last edited by jhuebner; 01-28-2017 at 12:00 PM. Reason: Added relay designators
Quote 🕺 🎢 ج
■ 02-14-2017, 07:26 AM Â # <u>1518</u> Â 🕵 Â
arber333 Join Date: Dec 2010 Senior Member Å A Posts: 782
💽 Re: Another homebrew AC-controller
Re: Another homebrew AC-controller Hi all I am overhauling my inverter now and i found something interesting. Johannes in his kit uses colour ribbon cable 26p to send signals from control board to the car I am not particulary fond of explosion of thin wires and i was looking for something to use in place of connector. I used just screw terminals and they were very good for sorting wires, but whole installation looked like birds nest. Finally last month i found this PCB. You can also get them cheaper from china
Hi all I am overhauling my inverter now and i found something interesting. Johannes in his kit uses colour ribbon cable 26p to send signals from control board to the car I am not particulary fond of explosion of thin wires and i was looking for something to use in place of connector. I used just screw terminals and they were very good for sorting wires, but whole installation looked like birds nest.
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Hi all I am overhauling my inverter now and i found something interesting. Johannes in his kit uses colour ribbon cable 26p to send signals from control board to the car I am not particulary fond of explosion of thin wires and i was looking for something to use in place of connector. I used just screw terminals and they were very good for sorting wires, but whole installation looked like birds nest. Finally last month i found this PCB. You can also get them cheaper from china http://www.ebay.co.uk/itm/IDC-26-MalYAAOSwx-9W0WhM I ordered one and tried it. It came out very neat. I can now install input wires from car directly to screw clamps on this PCB and from here i can use short 26p ribbon cable with connector on both sides directly. I tried continuity on the wires and every one came out numbered exactly as in Johannes table. So now even the cable colour doesnt matter. No loose wires and i still have terminals at hand for experimenting I strongly reccommend this to new builders as well as a mod for previous builts. Attached Thumbnails
Hi all I am overhauling my inverter now and i found something interesting. Johannes in his kit uses colour ribbon cable 26p to send signals from control board to the car I am not particulary fond of explosion of thin wires and i was looking for something to use in place of connector. I used just screw terminals and they were very good for sorting wires, but whole installation looked like birds nest. Finally last month i found this PCB. You can also get them cheaper from china http://www.ebay.co.uk/itm/IDC-26-MalYAAOSwx-9W0WhM I ordered one and tried it. It came out very neat. I can now install input wires from car directly to screw clamps on this PCB and from here i can use short 26p ribbon cable with connector on both sides directly. I tried continuity on the wires and every one came out numbered exactly as in Johannes table. So now even the cable colour doesnt matter. No loose wires and i still have terminals at hand for experimenting
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Hi all I am overhauling my inverter now and i found something interesting. Johannes in his kit uses colour ribbon cable 26p to send signals from control board to the car I am not particulary fond of explosion of thin wires and i was looking for something to use in place of connector. I used just screw terminals and they were very good for sorting wires, but whole installation looked like birds nest. Finally last month i found this PCB. You can also get them cheaper from china http://www.ebay.co.uk/itm/IDC-26-MalYAAOSwx-9W0WhM I ordered one and tried it. It came out very neat. I can now install input wires from car directly to screw clamps on this PCB and from here i can use short 26p ribbon cable with connector on both sides directly. I tried continuity on the wires and every one came out numbered exactly as in Johannes table. So now even the cable colour doesnt matter. No loose wires and i still have terminals at hand for experimenting I strongly reccommend this to new builders as well as a mod for previous builts. Attached Thumbnals Last edited by arber333; 02-14-2017 at 07:32 AM.

	Anotner nomedi	rew AC-controller			
Seing t	his, I think I wi			Ampseal version is cool but nany applications it can't be	
I also t	erminated the i	ribbon cable asap with a r	ather oversized Harting co	nnector:	
Attack	hed Thumbnails			<u>^</u>	
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02-28-2	2017, 02:18 AM			# <u>1520</u> 4	ĵ€Â <u>∆</u> Â
Senior M	<u>1333</u>			Join Date Location: Posts: 78.	
📄 Re: A	Another homebi	rew AC-controller			
Hi Joha	nnes				
I was th 3phase I mean Purpose shortag battery	hinking since AC too? i have 380Vdc e would be to c ge. Of course m	nominal. Would it be poss connect car to house 3pha	sible to make like 3phase o ase so basic utilities would	onverter, can it be used to utput without motor conner be able to run in case of p would than be fed only fro	cted. ower
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03-02-2017, 03:51 PM	# <u>1529</u> <u>(</u> <u>A</u> Â
dima Member Â	Join Date: Dec 2015 Location: British Columbia, Canada Posts: 69
Re: Another homebrew AC-controller	
Quote: Originally Posted by onegreenev Still can't get my motor to run from the mac we command start1, it will let me throttle up. The command. I can however change parameters and the web app be set so we can bench test with a	web interface does not give a similar lar start1 nd upload new firmware from the mac web app. Can
Start 1? I thought "start 1" is a physical switch trigg nto the new interface recently, still buggy but gettir curning out.	er, "start 2" is manual run. Tones of work has been put ng there. I am happy with how the graph section is
Can't wait for the new board revision!	
Huebner Inverter - Console Management	
	VQuote 🕎 🥻
03-03-2017, 08:09 AM	# <u>1530</u> 🍊 \Lambda
Senior Member Â	Join Date: May 2012 Location: Marysville, C Posts: 3,796

see if I can get some bett will need to connect up a way I can use the web in interface I loose my ability pain yes but it works.	key switch so I can tu terface to do more two	urn it on and off without eeking. As it is now if I c	the computer being con change any parameter fro	nected. That om the web
Pete 🙂				
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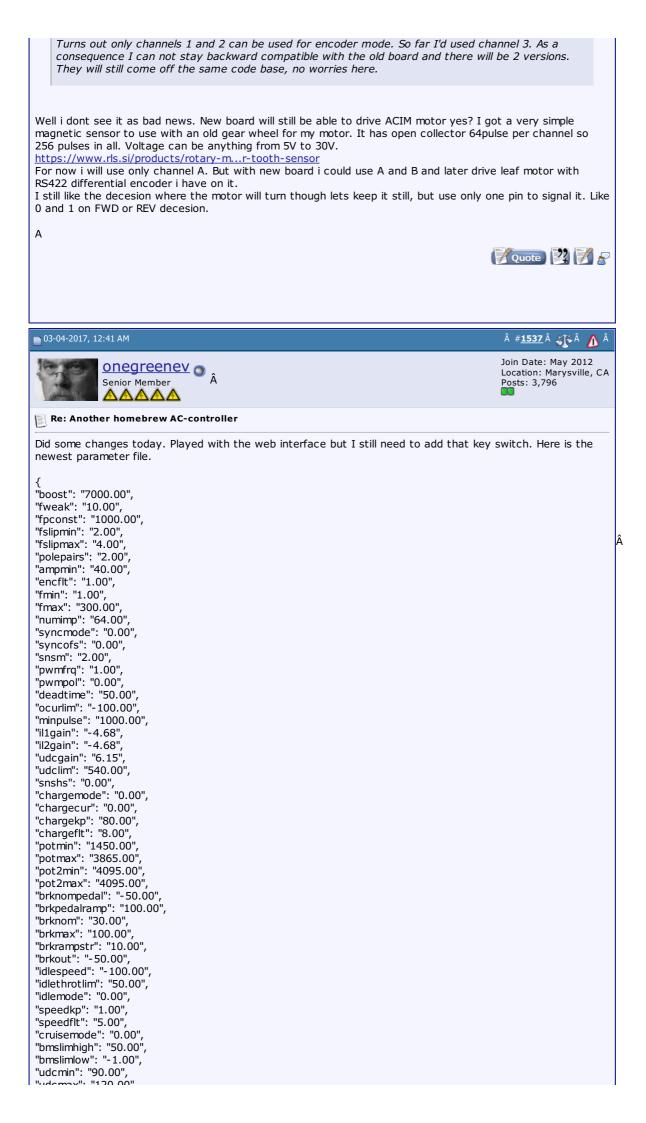
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🐚 03-03-2017, 01:50 PM
                                                                                                                     #<u>1533</u>Â ₄∰Â ∧ Â
                                                                                                                        Join Date: Apr 2010
                jhuebner A
                                                                                                                        Location: Germany
Posts: 927
                Senior Member
                    Re: Another homebrew AC-controller
I'd say your running pretty much open loop.
```

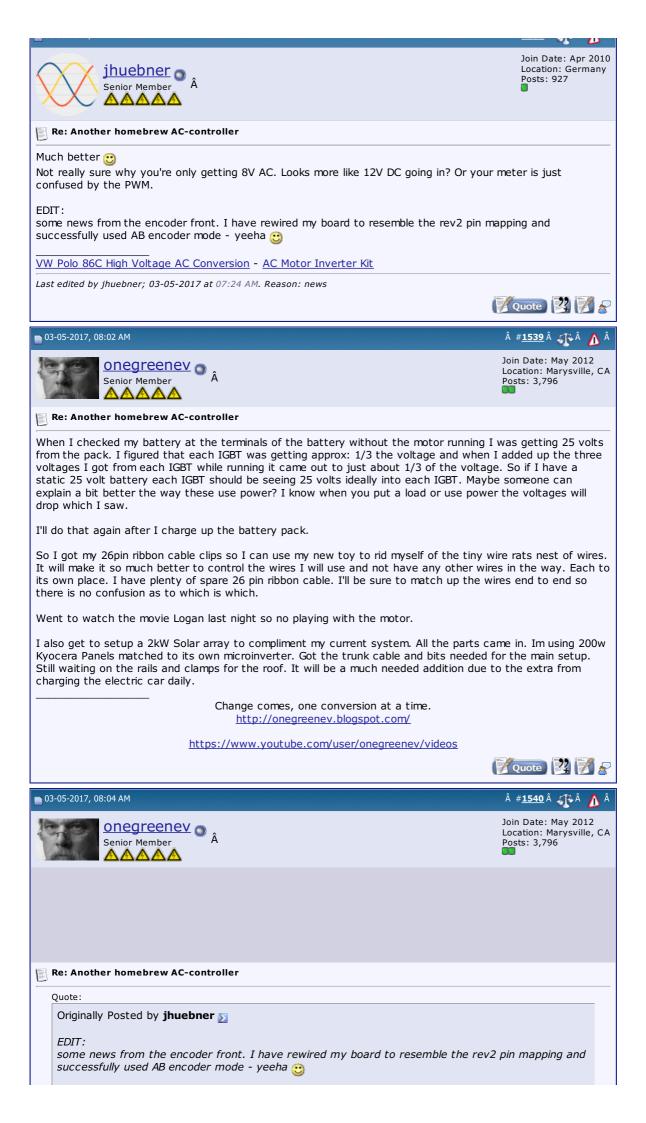






■ 03-05-2017, 07:22 AM

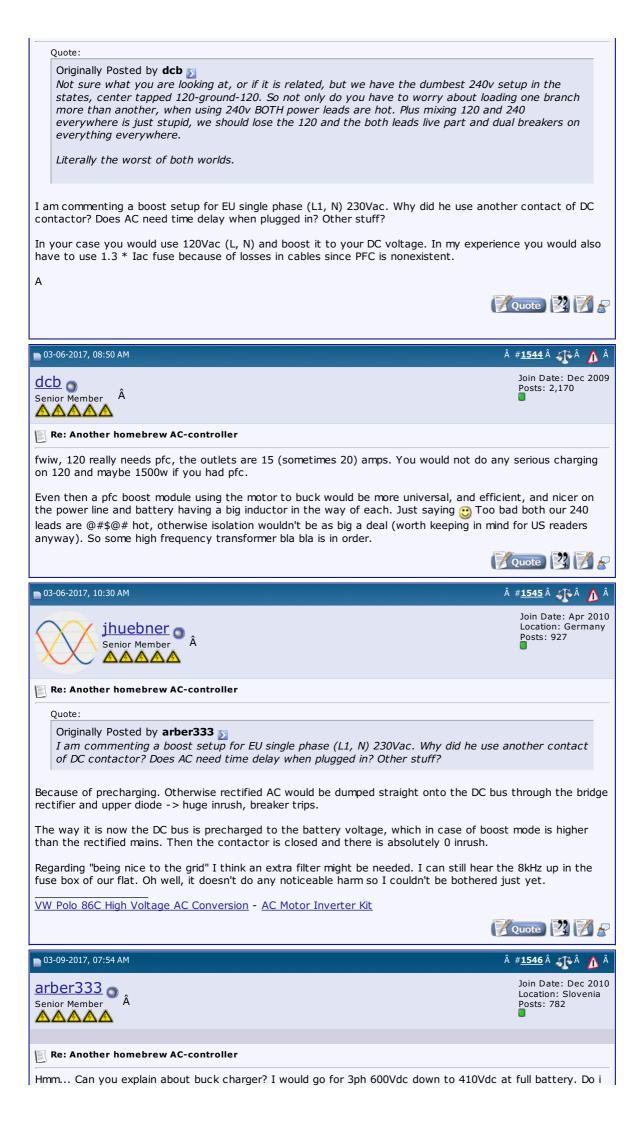
#1538 Â 🕅 Â Â



So what does this me	an for my setup?		
	way from one of the sense		e those tiny little original ones that e much better. Let me know what I
Pete 🙂			
		es, one conversion at a ti negreenev.blogspot.com/	me.
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need K4 to be true DC contactor or would a stronger AC contactor suffice? Do i have to us with current sensor?	se outside phase
Where to connect BMS? Is that covered by existing BMS pin?	
What would be appropriate precharge logic? A timer relay set for 5s? Hm i use DC film ca in 2s 😳.	ps so they are full
tnx	
A	
	Quote 🕎 🏹 🔗
■ 03-09-2017, 09:24 AM Â	à # <u>1547</u> â 🐠 â 💧 â
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by arber333 <i>Hmm Can you explain about buck charger? I would go for 3ph 600Vdc down to 410V battery. Do i need K4 to be true DC contactor or would a stronger AC contactor suffice</i>	
K4 will never interrupt DC current, so can be AC type.	
Quote:	
Originally Posted by arber333 Do i have to use outside phase with current sensor?	
No, the current sensor on L2 is always used. Just make sure you have a sensor on L2 (or s around at gate driver level until you do)	wap phases
Quote:	
Originally Posted by arber333 Where to connect BMS? Is that covered by existing BMS pin?	
Currently the BMS relay would interrupt the inverter 12V supply. But I will definitely tie in t	he BMS pin.
Quote:	
Originally Posted by arber333 <i>What would be appropriate precharge logic? A timer relay set for 5s? Hm… i use DC fi</i> <i>they are full in 2s</i>	ilm caps so
Yeah that should do. I think I have found a way to use the inverter precharge for buck as diagram and post it here.	well, will draw a
VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
	Quote 🕎 🌠 🔗
■ 03-12-2017, 12:08 AM Â	à # <u>1548</u> â 🕂 â 🧥 â
	bin Date: May 2012 ocation: Marysville, CA osts: 3,796
Re: Another homebrew AC-controller	
This evening I finally got my inverter re-wired with my little gadget I purchased on ebay. S one the other guy purchased was from the UK but they won't deliver to the US. You will no laid out different. I had assumed that it was the same layout but I was wrong. I wired it up	otice that mine is

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guys then put power to the inverter and got nothing. I checked and checked figured out what was wrong. I then re-labeled mine to match and checked co inverter and checked that they matched how the pinout is on the inverter. A won't power up. The light on the olimex is not coming on either and I checked was not my olimex. I can pretty much rest assured its not. When I had come the olimex connected to the computer. So Im thinking that because I had po have blown another cap. Did not have time to check the little caps on the bo good and connected properly as per the connections. So if you are going to check very carefully before connecting power and if you can get those from So remember that the outside pin is not pin 1 but pin 2. Im hoping I did not screwup the whole board. I have already replaced caps b	I and quadruple checked before I ontinuity of all the wires to the Il checks out great but now it d three of them to be sure it ected it to power I did not have wer switched around a bit I may bard yet. I know all the wires are go this route I'd suggest you the UK then you are good to go.
Pete 🙂	
Attached Thumbnails	Â
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Change comes, one conversion at a time. <u>http://onegreenev.blogspot.com/</u>	
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onegreenev o	Join Date: May 2012
Senior Member Â	Location: Marysville, CA Posts: 3,796
🛃 Re: Another homebrew AC-controller	
Good news. I had power to pin 7 and not pin 24. Once I changed that all was my rewireing. I had to re-label my little wire harness connector but after I did is the web interface with start 1 implimented works perfect. I tested with 12 with 24 volts. I checked battery voltage drain from the battery and it was m was like 7 plus amps and amperage to the motor was like 45amps testing sing IGBT module. So all seems rather well. Here are a couple graphs from the late Attached Thumbnais	d that all is well. The other thing volts and later I will go again inor. Amperage from the battery gle leads to the motor from the
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Change comes, one conversion at a time. <u>http://onegreenev.blogspot.com/</u>	
https://www.youtube.com/user/onegreenev/vid	leos
Onegreenev Senior Member Â	#1550 TA Â Join Date: May 2012 Location: Marysville, CA Posts: 3,796
Re: Another homebrew AC-controller	
Anyone here have a visual of their Pre-Charge Circuit?	
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elaborate pre-charge setups but wanted to see what others have done. I do fine off the real deal along with that. Combined it solidifies my understanding of how it all we rarely ever look the same. So visual and written are good.	
I have some good 24 volt contactors for low current applictions that might do well w	with the precharge setup.
Anyone with schematics and visual to back up the schematic would be very helpful.	
Thanks Pete 😳	
Change comes, one conversion at a time. <u>http://onegreenev.blogspot.com/</u>	
https://www.youtube.com/user/onegreenev/videos	
	VQuote 🕎 📝 🔗
■ 03-15-2017, 02:23 AM	# <u>1554</u> 🌾 🧥 Â
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by onegreenev When I did my first conversion I only put a resistor between the main contact p then turned on the key to position 1 then let it sit for a few seconds and then t This allowed pack voltage to trickle charge the caps before turning on the cont I have seen elaborate pre-charge setups but wanted to see what others have of schematics but like to see the real deal along with that. Combined it solidifies m all works out. Schematics and reality rarely ever look the same. So visual and v	rurned on the controller. roller. Worked like a champ. done. I do fine off of ny understanding of how it
I have some good 24 volt contactors for low current applictions that might do setup.	well with the precharge
Anyone with schematics and visual to back up the schematic would be very hel	pful.
Thanks Pete 🙂	
Well first i used 12V relay and 20W 470R resistor INSIDE inverter. That didnt work w had to deal with live 380Vdc wire!!! Try it in the evening when raining I decided to move relay and resistor in contact box near main contactor/fuse. That just 12V drain to trigger precharge relay. Mainly i looked up to this drawing, i just did got it somewhere on this forum	worked better. Now there is
Â	
Last edited by arber333; 03-15-2017 at 02:26 AM.	🛛 Quote 🕎 🏹 🔗
■ 03-16-2017, 02:40 PM	# <u>1555</u> € [♣ ∧ Â
	Join Date: Dec 2015
dima Member Â AAAA	Location: British Columbia, Canada Posts: 69 ■
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by onegreenev <i>Anyone with schematics and visual to back up the schematic would be very hel</i> <i>Thanks</i>	pful.
Pete 🙂	
1)	20

Here you go, ni-res images or my test/experimental setup. If you use those & CTRL are shorted and go to pin 20.	cneap 120V relays for pre-charge: GND
Attached Thumbnails	Â
	Â
Huebner Inverter - Console Management	
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03-19-2017, 01:02 PM	# <u>1556</u> 🕂 \Lambda Â
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew AC-controller	
I heard a very suspicious frequency from out TV today. So I unplugged the o Boost mode charging without any filtering really pollutes the grid!	-
I'll no order a netfilter like this (<u>http://www.ebay.de/itm/171978290699</u>) and	
The other day a public charging station shut down on me after 30 minutes.	
Also on an average 13A input current setting I see 38A peak. Not that the c don't like it and it's probably part of the pollution problem.	ircuit dreaker worries about it dut I
WW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
	Quote 🕎 👔
03-19-2017, 07:17 PM	# <u>1557</u> ∰ <mark>≬</mark> Â
dcb Senior Member Â	Join Date: Dec 2009 Posts: 2,170
E Re: Another homebrew AC-controller	
Quote: Originally Posted by jhuebner <i>I'll no order a netfilter like this</i> (<u>http://www.ebay.de/itm/171978290699</u>) and hope for improvement.
those R and C values look too small, won't be much attenuation at 10k or lea	SS.
i.e. 02DBAG5 has similiar values, peaks at 10MHZ, but only a couple db inser understanding it. <u>http://www.mouser.com/ProductDetail/a%252bSg%3d%3d</u>	tion loss at 10khz. maybe I'm not
Quote: Originally Posted by jhuebner 5	

Originally Posted by **jhuebner**

I ne otner day a public cnarging station snut down on me arte	er 30 minutes. Could that be a reason?
mebbe, what model was the charging station? any lights? could be else 🙂	e power factor, could be a gfci thing, or something
Note I don't think you want to ground it like they have it, it appea 120vrms above actual ground in europe (but still at ground in the	
maybe a rlc band stop if you want to keep component values low.	. You need a bit of R to make the LC branch more
appealing to the pwm current though. edit: i.e. <u>http://sim.okawa-denshi.jp/en/RLCbekeisan.htm</u> try 1 oh	
should see a 36db loss at ~10khz on the bode diagram (what pwn	n freq?)
Attached Thumbnails	Â
Last edited by dcb; 03-20-2017 at 07:49 AM.	Quote 🕎 📝 🧬
■ 03-20-2017, 11:28 AM	# <u>1558</u> ∡ ⊺ ≎ ∧ Â
	Join Date: Jan 2008
jackbauer 🕤 🔒	Location: Ireland Posts: 2,147
Senior Member A	•
Re: Another homebrew AC-controller	
Here is a first look at one of the combi boards back from the pcb	builder. Looks good. Let's hope it works 🍘
Attached Thumbnails	Â
	~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~
Now, Cole, when you shift the gear and that little needle on the a	immeter goes into the red and reads 1000 Amps,
that's bad. www.evbmw.com	5
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	V Quote V
03-20-2017, 02:37 PM	# <u>1559</u> ∢ } ▲
Tony Bogs	# <u>1559</u> 🚮 Â Join Date: Apr 2014 Posts: 609
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Tony Bogs	Join Date: Apr 2014
Senior Member	Join Date: Apr 2014
Fory Bogs Senior Member A Â Re: Another homebrew AC-controller Quote: Originally Posted by dcb	Join Date: Apr 2014 Posts: 609
Tony Bogs Senior Member Â A A A A Â Re: Another homebrew AC-controller Quote:	Join Date: Apr 2014 Posts: 609
For y Bogs Â Senior Member Â A A A Â A A A Â B A A A A Â A A A A Â A A A A Â A A A A Â A A A A Â B A A A A Â B A A A A Â B A A A A Â B A A A A Â B A A A A Â B A A A A Â B A A A A Â B A A A A B B A A A A B A A A A B A A A A A B A A A A B A A A A A B A A A A A B A A A A A A A A A A A A A A A A A A A	Join Date: Apr 2014 Posts: 609
For y Bogs Â Senior Member Â A A A Â Image: Construction of the second secon	Join Date: Apr 2014 Posts: 609
For y Bogs Â Senior Member Â AAAA Â Image: Construction of the second	Join Date: Apr 2014 Posts: 609
Fe: Another homebrew AC-controller Quote: Originally Posted by dcb i.e. 02DBAG5 has similiar values, peaks at 10MHZ, but only a of not understanding it. http://www.mouser.com/ProductDetail/a%252bSg%3d%3d I'm pretty sure you have got it right. Those small filters don't do r Let's assume that the fundamental is 3Arms (probably low value) a It takes two large inductors (think 1mH / 10A / 12cm diameter x 1 the 100 mA range at the plug.	Join Date: Apr 2014 Posts: 609
Fe: Another homebrew AC-controller Quote: Originally Posted by dcb i.e. 02DBAG5 has similiar values, peaks at 10MHZ, but only a of not understanding it. http://www.mouser.com/ProductDetail/a%252bSg%3d%3d I'm pretty sure you have got it right. Those small filters don't do r Let's assume that the fundamental is 3Arms (probably low value) a It takes two large inductors (think 1mH / 10A / 12cm diameter x 1	Join Date: Apr 2014 Posts: 609
Fe: Another homebrew AC-controller Quote: Originally Posted by dcb i.e. 02DBAG5 has similiar values, peaks at 10MHZ, but only a of not understanding it. http://www.mouser.com/ProductDetail/a%252bSg%3d%3d I'm pretty sure you have got it right. Those small filters don't do r Let's assume that the fundamental is 3Arms (probably low value) a It takes two large inductors (think 1mH / 10A / 12cm diameter x 1 the 100 mA range at the plug.	Join Date: Apr 2014 Posts: 609
Fe: Another homebrew AC-controller Quote: Originally Posted by dcb i.e. 02DBAG5 has similiar values, peaks at 10MHZ, but only a of not understanding it. http://www.mouser.com/ProductDetail/a%252bSg%3d%3d I'm pretty sure you have got it right. Those small filters don't do r Let's assume that the fundamental is 3Arms (probably low value) a It takes two large inductors (think 1mH / 10A / 12cm diameter x 1 the 100 mA range at the plug.	Join Date: Apr 2014 Posts: 609
Provide Bogs Â Provide Bogs Provide Bogs Quote: Originally Posted by dcb Originally Posted by dcb I.e. 02DBAG5 has similiar values, peaks at 10MHZ, but only a or not understanding it. http://www.mouser.com/ProductDetail/a%252bSg%3d%3d I'm pretty sure you have got it right. Those small filters don't do r Let's assume that the fundamental is 3Arms (probably low value) at takes two large inductors (think 1mH / 10A / 12cm diameter x 1 the 100 mA range at the plug. And a high value line filter capacitor: 0.47uF	Posts: 609 Doin Date: Apr 2014 Posts: 609 Couple db insertion loss at 10khz. maybe I'm nuch for the 8kHz base frequency. at the motor/transformer. Ocm each) to get the differential current down to Com each) to get the differential current down to Com each) to get the differential current down to Com each) to get the differential current down to Com each) to get the differential current down to Com each) to get the differential current down to Com each) to get the differential current down to Com each) to get the differential current down to Com each) to get the differential current down to Com each) to get the differential current down to
Re: Another homebrew AC-controller Quote: Originally Posted by dcb <i>i.e. 02DBAG5 has similiar values, peaks at 10MHZ, but only a onot understanding it.</i> http://www.mouser.com/ProductDetail/a%252bSg%3d%3d I'm pretty sure you have got it right. Those small filters don't do r Let's assume that the fundamental is 3Arms (probably low value) at takes two large inductors (think 1mH / 10A / 12cm diameter x 1 the 100 mA range at the plug. And a high value line filter capacitor: 0.47uF	Doin Date: Apr 2014 Posts: 609 In the set of the motor/transformer. In the motor/transformer. I com each) to get the differential current down to the set of the set of the differential current down to the set of the set of the differential current down to the set of the differential current down to the set of the set of the set of the set of the

	omebrew AC-controller		
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Quote:	sted by Tony Bogs Ŋ		
8kHz base fr			
	at do you think about a stop ban h and uf who's square root wher		nd some small resistance (or some
possibly your be	st bet in terms of hardware costs line has its benefits. Of course "	s/weight, again just specula	hz. If it is 60hz then active pfc is ting a bit, but making the load look like ustify it, but ya know people are gonna
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Originally Posted by jhuebner	
I have simulated a PFC that jut relies on the *current* to inverse sine wave to make the current at least more sinus	
did you mean to say voltage? would like to understand better o	otherwise how it stays in sync.
Quote:	
Originally Posted by jhuebner <i>Is it possible to replace the "R" of the stop band filter by a 20W.</i>	n "L"? Even though 20A@1R would only be
adding reactance mucks with the frequency, but you can re-ar diagram in the attached and lose the series resistor. But the co themselves FYI.	
Quote:	
Originally Posted by jhuebner Forgive my ignorance, but which side is grid input?	
right after the bridge, see right diagram. Keep in mind I am just about all this too.	a filter hack and might be completely clueless
Quote :	
Originally Posted by jhuebner @Damien: sweat piece of kit 🙂	
true that!	
Attached Thumbnails	
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Last edited by dcb; 03-20-2017 at 06:32 PM.	
	📝 Quote 🕎 🌠 🔗
■ 03-20-2017, 07:01 PM	# <u>1563</u> ൷ 🔥
03-20-2017, 07:01 РМ <u>dcb</u> Senior Member Â	
dcb Senior Member Â	# <u>1563</u> 🔂 Â Join Date: Dec 2009
dcb Senior Member Â	# <u>1563</u> A Â Join Date: Dec 2009 Posts: 2,170 ent values and turning it into a low pass filter
Cb A Senior Member Â Image: Another homebrew AC-controller fyi, looking at the line current profile, just doubling the componis a lot prettier (lower right), though there is about a 1.5khz peaks, so I dunno. edit: adding the 8khz notch downstream of the lowpass, makes might just be luck or maybe it is supposed to work like that :	#1563 ↓ ▲ ▲ ▲ ▲ ▲ ▲ Ĵoin Date: Dec 2009 Posts: 2,170 ent values and turning it into a low pass filter sine, still lower magnitude than the notch a HUGE difference fwiw (attachment 2),
dcb A Senior Member Â A A P Re: Another homebrew AC-controller fyi, looking at the line current profile, just doubling the componis a lot prettier (lower right), though there is about a 1.5khz peaks, so I dunno. edit: adding the 8khz notch downstream of the lowpass, makes might just be luck or maybe it is supposed to work like that 🙂 the phase reversals on the notch probably make it look like a 1	#1563 ↓ ▲ ▲ ▲ ▲ ▲ ▲ Ĵoin Date: Dec 2009 Posts: 2,170 ent values and turning it into a low pass filter sine, still lower magnitude than the notch a HUGE difference fwiw (attachment 2),
Cb A Senior Member Â Image: Another homebrew AC-controller fyi, looking at the line current profile, just doubling the componis a lot prettier (lower right), though there is about a 1.5khz peaks, so I dunno. edit: adding the 8khz notch downstream of the lowpass, makes might just be luck or maybe it is supposed to work like that :	#1563 ↓ ▲ ▲ ▲ ▲ ▲ ▲ Ĵoin Date: Dec 2009 Posts: 2,170 ent values and turning it into a low pass filter sine, still lower magnitude than the notch a HUGE difference fwiw (attachment 2),
dcb A Senior Member Â A A P Re: Another homebrew AC-controller fyi, looking at the line current profile, just doubling the componis a lot prettier (lower right), though there is about a 1.5khz peaks, so I dunno. edit: adding the 8khz notch downstream of the lowpass, makes might just be luck or maybe it is supposed to work like that 🙂 the phase reversals on the notch probably make it look like a 1	#1563 ↓ ▲ ▲ ▲ ▲ ▲ ▲ ▲ ▲ ▲
dcb A Senior Member Â A A P Re: Another homebrew AC-controller fyi, looking at the line current profile, just doubling the componis a lot prettier (lower right), though there is about a 1.5khz peaks, so I dunno. edit: adding the 8khz notch downstream of the lowpass, makes might just be luck or maybe it is supposed to work like that 🙂 the phase reversals on the notch probably make it look like a 1	<pre>Â #1563 Â ↔ Â ▲ Â</pre> Join Date: Dec 2009 Posts: 2,170 ent values and turning it into a low pass filter sine, still lower magnitude than the notch s a HUGE difference fwiw (attachment 2), 6khz+ signal to the lowpass.
Cb A Senior Member Â A A P Re: Another homebrew AC-controller fyi, looking at the line current profile, just doubling the compon is a lot prettier (lower right), though there is about a 1.5khz peaks, so I dunno. edit: adding the 8khz notch downstream of the lowpass, makes might just be luck or maybe it is supposed to work like that the phase reversals on the notch probably make it look like a 1 Attached Thumbnails	<pre>Â #1563 Â ↔ Â ▲ Â</pre> Join Date: Dec 2009 Posts: 2,170 ent values and turning it into a low pass filter sine, still lower magnitude than the notch s a HUGE difference fwiw (attachment 2), 6khz+ signal to the lowpass.
Cb A Senior Member Â P Re: Another homebrew AC-controller fyi, looking at the line current profile, just doubling the compon is a lot prettier (lower right), though there is about a 1.5khz peaks, so I dunno. edit: adding the 8khz notch downstream of the lowpass, makes might just be luck or maybe it is supposed to work like that is the phase reversals on the notch probably make it look like a 1 Attached Thumbnails Last edited by dcb; 03-20-2017 at 07:45 PM. O3-20-2017, 09:15 PM dcb Senior Member Â	
Cb A Senior Member Â P Re: Another homebrew AC-controller fyi, looking at the line current profile, just doubling the compon is a lot prettier (lower right), though there is about a 1.5khz peaks, so I dunno. edit: adding the 8khz notch downstream of the lowpass, makes might just be luck or maybe it is supposed to work like that is the phase reversals on the notch probably make it look like a 1 Attached Thumbnails Last edited by dcb; 03-20-2017 at 07:45 PM.	A #1563 À ↔ À À À Join Date: Dec 2009 Posts: 2,170 ent values and turning it into a low pass filter sine, still lower magnitude than the notch s a HUGE difference fwiw (attachment 2), 6khz+ signal to the lowpass.

ok, done w/filters for now. Sorted out bode for lowpass + notch + both, tolerance is a bit tight on notch. I

added the Itspice source if anyone wants to mess with it mo	re (remove .txt from filename).
	Â
bode.asc.txt (3.0 KB, 3 views)	
	Quote 🕎 📝
03-21-2017, 06:06 AM	# <u>1565</u> 🌾 <u>۸</u>
enior Member Â	Join Date: Dec 200 Posts: 2,170
Re: Another homebrew AC-controller	
< NOW I'm done w/filters 🙂	
o I made a shorthand boost converter (using time modulo be the bridge, and tried various filters, just to better emulate	
emulated the filter in a box, doesn't do much at 8khz.	
nd I emulated the other filters (on the AC side of the rectifi	er, to avoid dc offset vs UH rating issues).
ow it might be a simulation anomaly, or an unrealistic impler yan, lowpass + notch) are definitely far greater than their	
Quote:	
Originally Posted by jhuebner \sum Is it possible to replace the "R" of the stop band filter by	/ an "L"?
you throw in a cap too, to make a reactive divider, you ha _Attached Thumbnails	ve a lowpass filter.
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03-21-2017, 07:09 AM	# <u>1566</u> 🕂 \Lambda
ony Bogs A	Join Date: Apr 201
nior Member Â	Posts: 609
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by jhuebner	

Â



I have simulated a PFC that jut relies on the current to obtain the AC phase inverse sine wave to make the current at least more sinussoidal.	e and the modulates an
I took the term "emergency" from a magazine where they wrote about so "emergency" 3kW charger on board and using DC charging or a costly add charging. As for me, it's always emergency m	
<i>Is it possible to replace the "R" of the stop band filter by an "L"? Even thou 20W.</i>	gh 20A@1R would only be
Forgive my ignorance, but which side is grid input?	
@Damien: sweat piece of kit 🙂	
Hi I dont know enough about theoretic magnetism to attribute to debate here as	s long as it works 🙂.
Johannes, regarding boost mode charging. I use one 20A 230Vac contactor to b this i will use one 12V relay that would carry 230Vac to contactor. For inverter to one small 230Vac relay to switch on REV signal.	
Alternatively i can use one 12V 1A ACDC PSU to provide power for inverter when trigger other relais.	n car is not in operation and
Do you think 12V 1A would be enough power?	
Edit: DOH, i figured i will need power from car battery anyway to trigger DC con have to draw schematic first	tactor when key is out. I
A 	
	VQuote 😰 📝 🔗
03-30-2017, 03:01 PM	# <u>1569</u> "[À 🔥 Â
jackbauer Senior Member Â	Join Date: Jan 2008 Location: Ireland Posts: 2,147
Re: Another homebrew AC-controller	
So today I finally got a few hours to play with the combi board. Power up check and usb coms to the pc. Sadly the enova inverter uses a LEM HAL type current so I'll have to replace them with LEM HASS. Hopefully get a motor spinning at th	sensor that won't be usable
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Now, Cole, when you shift the gear and that little needle on the ammeter goes if Amps, that's bad. www.evbmw.com	into the red and reads 1000
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■ 03-30-2017, 04:02 PM	â # <u>1570</u> â 🐠 â
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
💽 Re: Another homebrew AC-controller	
This is looking extremely clean, nice job!	
As for the sensors, I replied to another builder: you can theoretically use the existing sensors. You need one isolated $\hat{A}\pm15$ V 2V 15V to sensor board ground. The sensors are supplied with $\hat{A}\pm15$ V and possibly the output of your current sensors to the input of the sensor board via a 47k re	ground. Then you connect

divider 15V -> 2.6V). The resolution won't be very good (like 2 A/digit) but sufficient for over current detection and diagnosis. Don't forget to calibrate via the ilXgain parameters.				
			Quote	1
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Re: Another homebrew AC-controller

Where to start...

I had quite an unfall couple months ago. One of the LiPo cells developed short to chasiss and it seems that caused catastrophic failure in IGBTs and drivers. I lost 2 of three half bridge modules while in regen downhill. When i tried to replace IGBTs and drivers i havent solved root cause and again one IGBT fell victim. That was it. I decided i wasnt going to suffer original drivers anymore. While they be simple and effective they havent got any protection at all.

I decided to try JackBauers desat drivers. I ordered some PCBs and materials and made them.

While i also converted my car - again! I put all the cells from the back to front. That way weight distribution is as close to original as possible. Handling is now better and tail feels lighter of course...

Well after drivers i decided to make a new master board. I got it from Johannes and i built it in one evening. Then i went on and test it. Idouble and triple checked and still i managed to burn precharge transistor... Everything then connected and i started car. Motor spun and everything seemed good. There was a bit more vibrations than i was used to though. I tried to take off... ARGH!!! Car rocked violently and tried to go forward half a turn and than in reverse... When i pushed brake motor started to rotate backwards....!

It took me 1 month of tests and scoping to figure what was wrong. I even took motor out as i suspected that there could be intermittent failure in stator wiring. Then i used different sensors. I even borrowed old drivers from a friend and still problem persisted.

Finally friend lent me his master board. I tried and motor ran good. So the failure was isolated there. I went element by element and i found wrong cap in C1. BOM shows 22nF but i guess i used 22pF? Cap was the same form, the same colour etc... When i found it i replaced it and presto motor rotated smoothly.

Now in my wisdom i used 6R8 Rg on new driver boards. I tought not to strain IGBTs too much. Well i was wrong again. When hard pushed inverter generated sound out of tune and desat kicked in. Then i replaced Rg with originals 4R7 and put small schottky diodes to suppress fake desat effect as datasheet suggest.

Difference is in order of magnitude. With the same settings i can run the car normally and shift gears up/down... Desat still kicks in if you push throttle very hard. I will try to tune up blanking time a bit.

I reccommend new drivers very much. They are consistent and predictable in action. I can see higher regen with new Rg resulting in stronger driving current. I even decided to try and expand on them, to build half bridge transistors in to have some 8A driver capability, which would allow to drive 600A IGBTs.

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Last edited by arber333; 04-12-2017 at 05:08 AM.







was tremendous. Both and putting 3x in place with my 230A meagre There is still a matter inspection everything regen is banging on sp conclusion EVs likes to Is there something to	in tone and in response of current 100uF 800Vo current. of clutch. Since i had to was ok, but i also found orings from the other sup o eat clutch springs be done here? Maybe in lelay and 35% brake i sti	n reality when i put anothe to acceleration. I am think dc. 450uF of capacity will t dissassemble my motor i to springs inside were loose. port, which is not designed software? Johannes did pu ill feel clutch vibrating/osci	king of buying 150uF 700 be able to cover every vo bok off the clutch also. A When i asked my mechar I to carry load. We came t a function of delay to	Vdc caps oltage drop After nic he said e to a regen, but
A			Quote) 🛂 🗹 🔗
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Quote:	
Originally Posted by jhuebner 5	
I could add a ramp to off pedal regen, maybe it he	lps?
I am not sure it would help, since the same happens on deccelerate and motor skips a liittle and then springs re pronounced since brakeing is dampened by car mass as start of regen to some time after its application. I can feel this effect up to a second of regen when on But off nedal ramp will be very welcome. Please	lease disk back and cycle repeats. It is just less well. Maybe you could add a sort of PI function from
But off pedal ramp will be very welcome. Please.	
I am now using settings for same power on off pedal an negative torque can cause weird car behaviour on slipped	
A	
Last edited by arber333; 04-17-2017 at 03:35 PM.	
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■ 04-19-2017, 11:11 AM	# <u>1585</u> ≼ [≩ ∧ Â
04-19-2017, 11.11 AM	A # <u>1905</u> A \$\$\$A (1)/
gunnarhs 👩	Join Date: Apr 2012 Location: Iceland
Senior Member Â	Posts: 292
	•
Re: Another homebrew AC-controller	
5	
Quote:	
Originally Posted by arber333 I am not sure it would help, since the same happer deccelerate and motor skips a liittle and then sprin less pronounced since brakeing is dampened by car function from start of regen to some time after its I can feel this effect up to a second of regen when But off pedal ramp will be very welcome. Please.	gs release disk back and cycle repeats. It is just r mass as well. Maybe you could add a sort of PI s application.
I am now using settings for same power on off pea difference in negative torque can cause weird car l strange.	
Sorry I have not followed this thread for a time so I have	ve to ask first before answering to the question
 I assume you are using an Induction motor? Generally I would not not recommend a standard clut (or I would turn regen off if using a standard clutch cor Do you use clutch in connection with an inertia wheel o Do you use original ABS/ESP of the car? 	nnection).
	Quote 🛂 🌠 S
■ 04-20-2017, 02:27 AM	# <u>1586</u> 🐴 🧥 Â
A A A A A A A A A A A A A A A A A A A	Join Date: Dec 201 Location: Slovenia Posts: 782
Re: Another homebrew AC-controller	
Quote:	



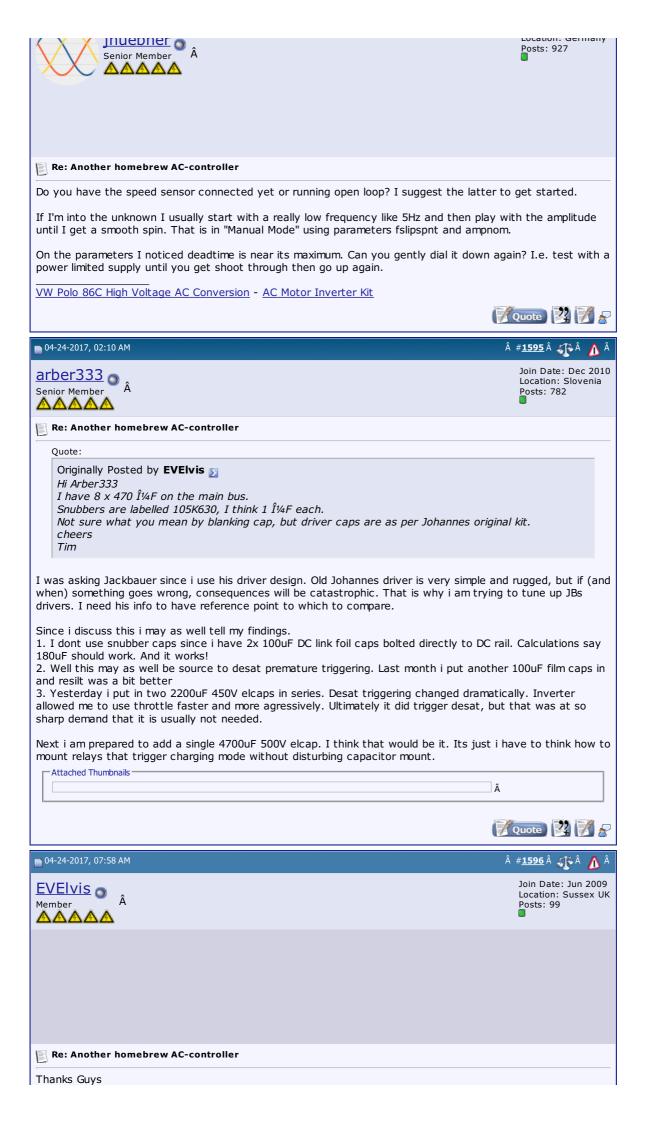
Just had a few days off work and made some good progress, but I do need some expert advice/help please.

Heres a video, including sho different values of fslipmin,	Irn smoothly in eithe owing the paramete fmin with no big im	er direction, and nor does n ers, which I know will not be aprovements:		se direction.
https://www.youtube.com/ I have successfully run a si so im hoping parameter valu Cheers Tim	maller motor with th	ne same parts before so cor	nfident the IGBTs and driv	vers are ok,
Last edited by EVElvis; 04-22-2	017 at 02:24 PM.		10- J	
			Quote	13 12 2
■ 04-22-2017, 02:26 PM			# <u>1589</u> Â	` € PÂ <u>∧</u> Â
jackbauer Senior Member	Â			ate: Jan 2008 on: Ireland 2,147
Re: Another homebrew A	C-controller			
I'll dig out my paramters to polepairs 2?	morrow but you wil	I need a lot more boost on s	such a low voltage and ha	ave you set
Now, Cole, when you shift Amps, that's bad. www.evbmw.com	the gear and that I	ittle needle on the ammeter	goes into the red and re	ads 1000
			Quote	2 🛛 🖉
■ 04-22-2017, 02:38 PM			# <u>1590</u> Â	🕂 🚺 Â
EVElvis Member Â				ate: Jun 2009 n: Sussex UK 99
🛐 Re: Another homebrew A	C-controller			
Thanks Jackbauer, yep pole cheers	epairs is 2.			
			Quote	2 2
Post Reply	Page 159 of 221 «	First < 59 109 149 157 158	159 160 161 169 209 >	> Last » 🔽
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Johannes, will try again with speed sensor both open and closed loop. It disconnected the speed sensing, but still pulsing strongly back and forth I tried in manual with 48VDC batteries via 25 Amp fuse with fslipspnt - f 50 then 100, and the motor did not spin afaik, but could hear the invert need to get better temporary cabling / fuse will blow. My cables got rat only rated for 10A or so being banana connector test leads. I think i can set deadtime down to about 70 or so, will try. Hopefully than not played with this parameter believing it was not possible for it to be Hopefully jackbauer will let me know his settings used (for the same mot Pleased you do not immediately think I have a driver or IGBT issue. I alm cheers	n Forward & Reverse. irst 1, then 2, then 3, and ampnom = er trying. Any higher fslipspnt and i her hot trying this - theyre probably at is the problem, most easy and I had the problem. cor and inverter)
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■ 04-24-2017, 08:03 AM	â # <u>1597</u> â 🐠 â 🧴 â
Tony Bogs Senior Member Â	Join Date: Apr 2014 Posts: 609
Re: Another homebrew AC-controller	
Quote: Originally Posted by arber333 I dont use snubber caps	
Great desat test. COOL! 📷	
	Quote 🕎 📝 🎤
■ 04-24-2017, 08:36 AM	â # <u>1598</u> â 🐠 â 🧄
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782 ■
Re: Another homebrew AC-controller	
Quote: Originally Posted by EVElvis D	

Thanks Guys Johannes, will try again with speed sensor both open and closed loop. It was a little better when I disconnected the speed sensing, but still pulsing strongly back and forth Forward & Reverse. I tried in manual with 48VDC batteries via 25 Amp fuse with fslipspnt - first 1, then 2, then 3, and ampnom = 50 then 100, and the motor did not spin afaik, but could hear the inverter trying. Any higher fslipspnt and i need to get better temporary cabling / fuse will blow. My cables got rather hot trying this - theyre probably only rated for 10A or so being banana connector test leads. I think i can set deadtime down to about 70 or so, will try. Hopefully that is the problem, most easy and I had not played with this parameter believing it was not possible for it to be the problem. Hopefully jackbauer will let me know his settings used (for the same motor and inverter) Pleased you do not immediately think I have a driver or IGBT issue. I already broke one IGBT. cheers

Ok, i had similar problem and it was a single defective cap on the encoder RC line. I also replaced caps and resistors on L1, L2 lines.

Before you try to go further with testing you check values of installed components against BOM. Check every resistor and cap. Time spent there will later ease your mind since you know you assembled correctly.

Then you connect driver boards to master board and sensors and power it up so you connect 12v to all required pins. You command "ampnom 1" and "fslipspnt 1" and inverter should give you nice 50% duty PWM on all driver GE contacts. You do have scope?

Drivers are good then. Now you assemble inverter and power it up as per instruction. You calculate boost and leave minslip and maxslip at 1. Leave encoder disconnected for this test. Then you command manual start. You then input fslipspnt 1 (enter) and ampnom 15 (enter).

Motor should move at 1tum per second. This is usefull so that you see smooth rotation at slow speed. In case IGBTs are bad you should see some jittering here. Remember encoder is not connected here, so it cant be blamed.

If this passes try to put fslipspnt 2 and then 4 and 6...8..10...15...30Hz. If motor stalls give it more ampnom.

If everything passes you connect encoder and start inverter true. Try to give it less boost than you calculate first. Have fslipmin at 1 and fslipmax at 3 ampmin at 2% and try to spin. Be sure to set fweak at large value motor will feel smooth but sluggish. Later you can use my procedure to tune up motor in post #1232.

Quote 🕎 🎢 🔎

Hope that helps

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■ 04-24-2017, 02:50 РМ	# <u>1599</u> ∡∰ <mark></mark> ∆ Â
EVElvis Member Â Â	Join Date: Jun 2009 Location: Sussex UK Posts: 99
Re: Another homebrew AC-controller	
Good news I just scoped the gate driver outputs to find one not working at all, so we connector to check input power supply from main board a wire broke free of connector fortunately the power lead. Resoldered and ok it seems, but do wonder why i only get all gates with the others giving 15V, but seem to recall I found this before in anycase. Poss feeding the new IGBT i got, will check - it was same part number as original and was not isn't a fake one. Thanks for all of your time helping me out, and thanks arber333, will follow your setup pr learning/experience exercise for me. cheers Tim	, which was bout 11V output to sible it is the one t cheap, just hope it
li l	VQuote 🕎 📝 🧬
■ 04-24-2017, 03:26 РМ	# <u>1600</u> 💦 <u> Â</u> Â
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782
🖹 Re: Another homebrew AC-controller	
Quote:	
Originally Posted by EVEIvis \sum Good news \bigcirc I just scoped the gate driver outputs to find one not working at all,	

fortunately the power output to gates with Possible it is the one and was not cheap, Thanks for all of you Was a good learning, cheers Tim You were lucky. If loose trough caps and that IGE I suggest you took the s check supply. Maybe TVS Id you only use 11V your and a sharp Rg is a must shorted so IGBT will not b	er lead. Resoldered and the others giving 15V, feeding the new IGBT just hope it isnt a fake r time helping me out, (experience exercise fo wire should come into of 3T gate would be buste ingle PCB off and desold 5 was defect and was of IGBT will never fully op . Si drivers are cheap i be destroyed.	and thanks arber333, will fo r me. contact while powering inve d. Watch out. der TVS diode from G or E c	r why i only get about 11 this before in anycase. me part number as origina ollow your setup procedur rter there would be power ontact. Try to power drive and a long time. That is w can replace them. They of	V al re. r surge er and vhy 15V ften fail
dead when i powered it f just 12V variety. I recom Driver SI8261BBC is 4A a giving PCB 50% PWM pub inductance and capacita 4R7 you have to change Well i hope your drivers a I have just started to dri schreech when PWM is d	irom 12V instead of 5V imend them very much. nd also tough but is mo se and scope GE for vo nce are true. With it yo DCDC to MGJ2D051505 are good. I will never go ive with JB drivers and istorted by high current whole inverter will shut	by mistake. In my EMW cha	rger i use exactly the san maybe yours is half dead put one old IGBT on so ga ster gate turn on. In case rivers 4A. d it too risky. ystem recovers from audit opto on the MPROT pin ar	ne DCDC . Try ite you use ble
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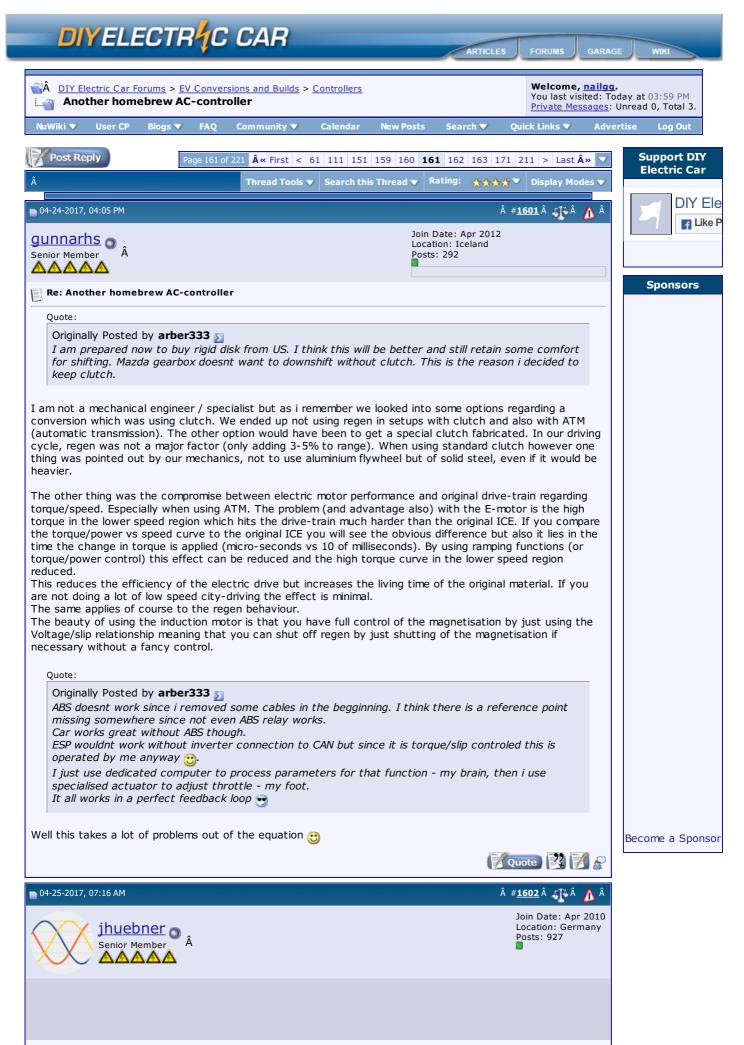
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■ 05-11-2017, 08:15 AM			# <u>1610</u> 🏠 🧥 Â
jhuebner Senior Member			Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew	AC-controller		
Quote:			
Originally Posted by A The project is coming Next weekend (May 2 Then the car will alree	g to a close. 20) we meet fans of	electric vehicles.	
Looking forward to seeing	it live 🙂		
Arber, how is the charging	g going? What mode	e do you use and how much	n power?
VW Polo 86C High Voltage	AC Conversion - A	<u>C Motor Inverter Kit</u>	
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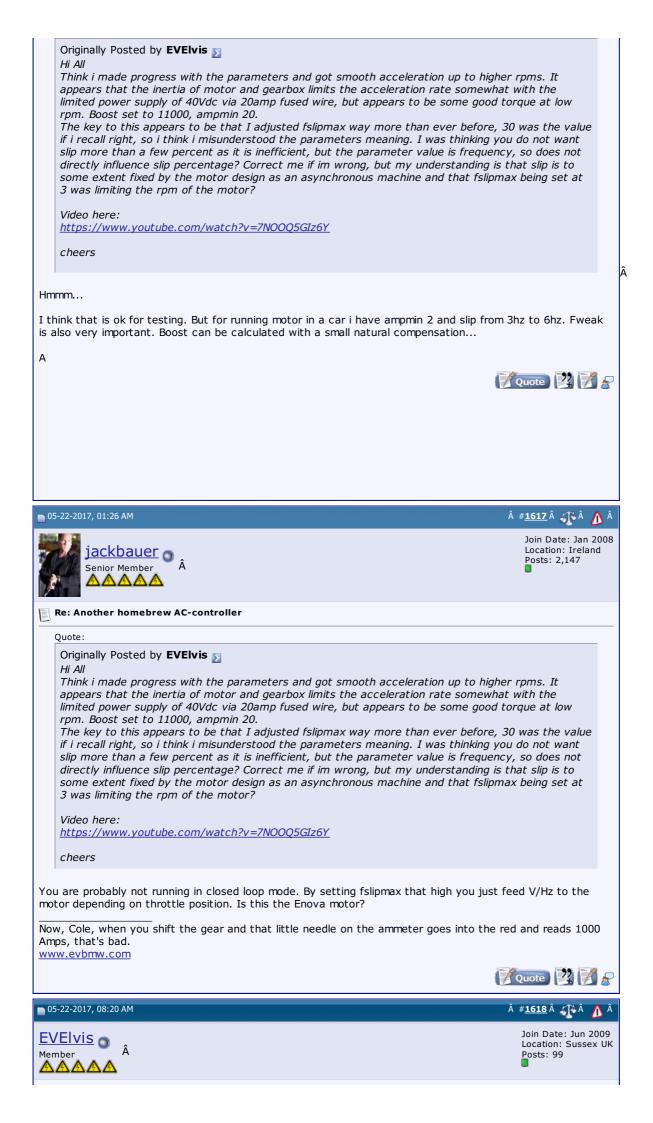
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Re: Another homebrew A	C-controller		
any difference? But good po	since I have encode pint, worth me chec the weekend with	cking.	ll right disconnecting it did not make battery, and make up some better
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■ 05-24-2017, 02:27 AM			â # <u>1619</u> â 🐠 â \Lambda â
arber333 Senior Member Â			Join Date: Dec 2010 Location: Slovenia Posts: 782
Re: Another homebrew A	C-controller		
not make any difference	notor. op since I have en e? But good point, ay at the weekend	worth me checking. with fully charged 50Vdc t	recall right disconnecting it did test battery, and make up some
Maybe you have different lo signal? I had this problem in http://www.ebay.co.uk/itm	the beginning and	i had to use encoder that	n powered with 3V3 it cant find worked on 3V3.
But since there is transistor problems. I stole 5V from se			to supply encoder without
А			
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■ 05-24-2017, 08:04 AM			# <u>1620</u> A ÂÂ
EVElvis Member Â			Join Date: Jun 2009 Location: Sussex UK Posts: 99
Re: Another homebrew A	C-controller		
	et for the encoder a watch?v=vEx4IIEsN	again. Just watching one o <u>4ZE</u>	
			Quote 😰 🕅 🔗
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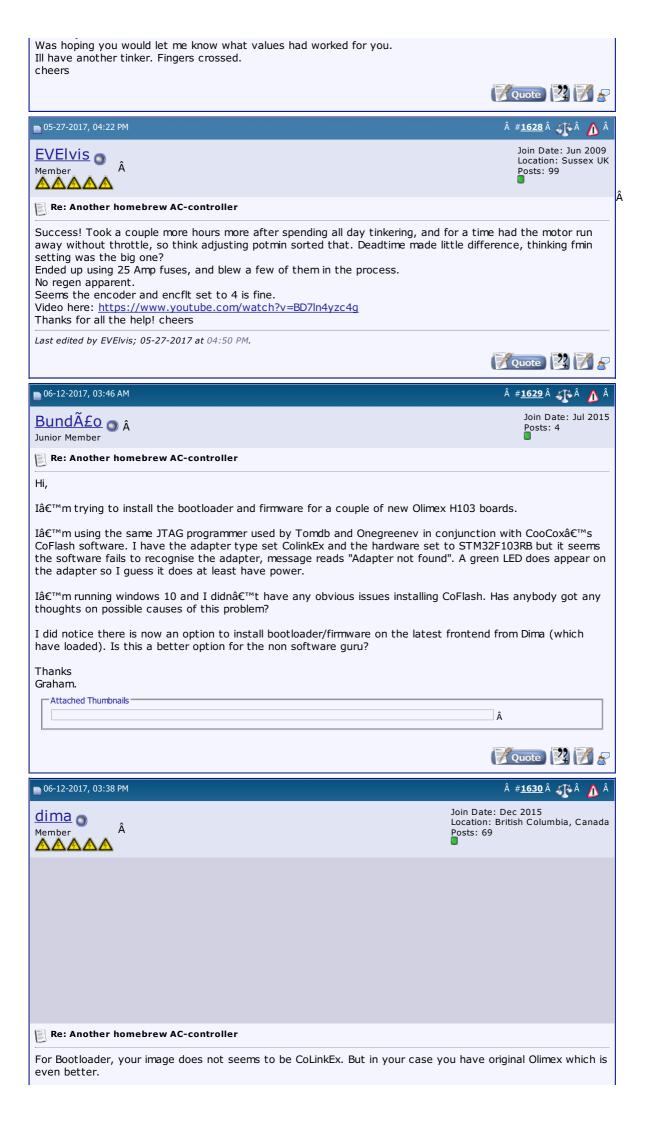
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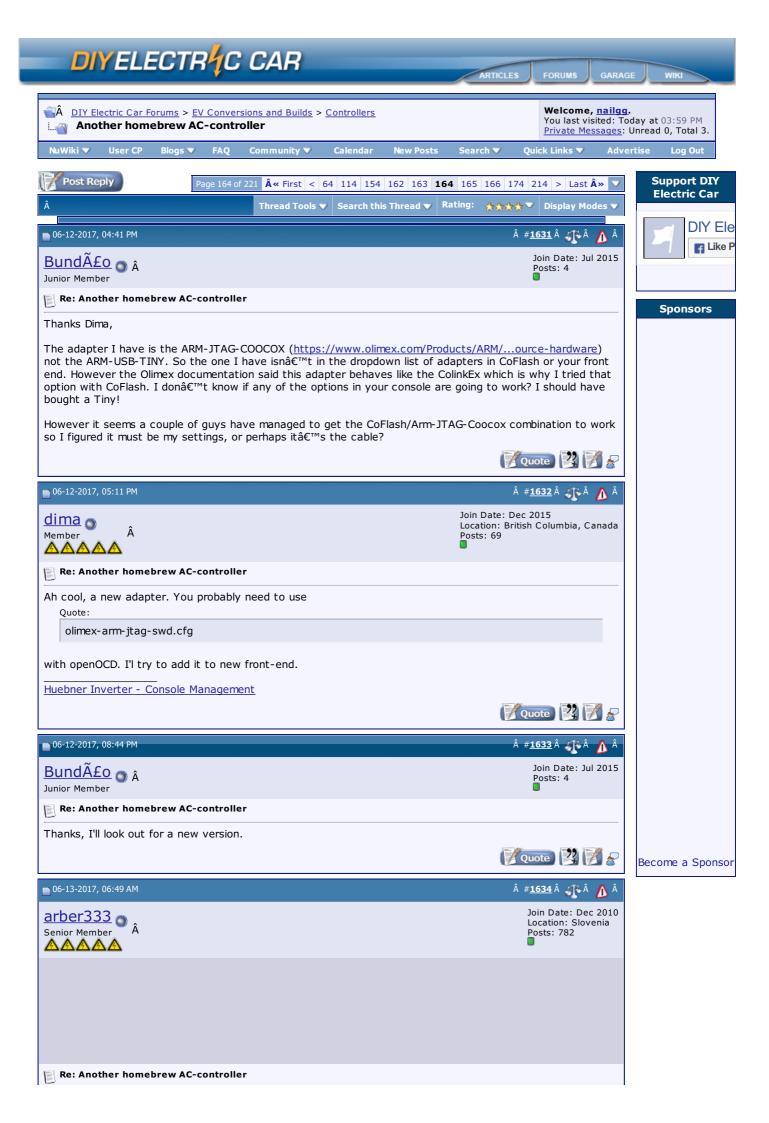
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I'm still working on flashing the bare Olimex board with the bootloader and firmware. I now have a Segger J-

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Link adapter which looks like it will flash the bootloader just fine but one thing I need to specify in the command line is the address to load it to. Can anyone help with that? Many thanks Bundao. 📝 Quote 🕎 📝 🖉 D6-20-2017, 09:19 AM #<u>1638</u>Â **∡™**Â ΛÂ Join Date: Dec 2015 dima 👩 Location: British Columbia, Canada Â Member Posts: 69 AAAAA Re: Another homebrew AC-controller Here is a full flash dump, you can start @ 0 Attached Files dump_original.bin.zip (19.8 KB, 9 views) Huebner Inverter - Console Management Quote 🕺 📝 💂 #<u>1639</u>Â 🌆 Â 🗖 06-26-2017, 10:05 AM ΛÂ Join Date: Apr 2010 jhuebner O Â Location: Germany Posts: 927 Senior Member Re: Another homebrew AC-controller So, back from holiday. As Arber keeps having problems with the drivers DESATing at surprisingly low current, I looked into the datasheet a bit On page 16 it says: Code: When t DESAT (MUTE) expires, LED input needs to be kept low for t DESAT (RESET) bef status will return to high. < > t DESAT(RESET) is about 4ms. Since the inverter does not know about the desat event it will keep sending PWM and the driver never recovers from the fault. The new main board has a desat input that would shut down the PWM and allows you to restart with the key switch. Next I calculated the blanking time. Also on page 16 it says: Code: $t_{BLANK} = C_{BLANK} \tilde{A}- (V_{DESAT} / I_{CHG}) + t_{DESAT} (BLANKING)$ $C_BLANK = 220pF$ V DESAT = 7V $I_CHG = 1mA$ t DESAT = $0.6 \hat{A} \mu s$ So: 220*10^â»â¶[µF]*(7/0.001)+0.6[µs]=0.60154µs So 220pF doesn't really change much even though it's the application circuits value. It only starts to take shape if you go to the upper nF region, e.g. 100nF: 100Â-10â»Â³[µF]Ã-(7/0001)+0,6=1.3µs Can someone please confirm that? Damien, whats your blanking caps value? VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit Quote 🕺 🕅 🖉 #<u>1640</u>Â 🐢Â <u>۸</u> Â 🗖 06-26-2017, 10:37 AM Join Date: Jan 2008 jackbauer 👩 Location: Ireland

Posts: 2,147

Senior Member	A		•	
Re: Another homebrew	/ AC-controller			
trips. The equation looks	right and keep in mind	when driving higher power	i boards shutdown the pwm i red igbts than the device is r r Cblank value would be requ	ated
Now, Cole, when you shin Amps, that's bad. www.evbmw.com	t the gear and that lit	tle needle on the ammeter	goes into the red and reads	
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Post Reply	Page 164 of 221 « Fi	rst < 64 114 154 162 163	164 165 166 174 214 > La	ist » 🔻
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Originally Posted by jhuebner wow, I really need to look into that!	
Was it GEHigh of all IGBTs or just one specific channel? If so, which one?	
The start sequence should be as follows:	
1. Power up - all 6 PWM signals low 2. Start - Close DC switch, open precharge switch 3. 500ms delay - start PWM generation, i.e. all lowside transistors on, on highside off	
I'll check for a glitch in that sequence tonight.	
I dont know if this is a glitch. It is too consistent to be an error. On every GEHigh channel voltage was +15V when i applied 12V and gnd. GELow channel was do When i turned the key and added 12V pulse to start pin of inverter all GEs were then pulled low time. Then DCswitch is thrown.	to -5V. Every
Is it possible driver channel signals would need pulldown resistors to keep them from going high unintentionally? Doesnt Olimex have internal pulldown resistors? I use like 200mm of wire from m drivers	
So there should be no damage, but i see this as a potential failure point. Remember, only two phases are protected by sensors. Third one has to pass trough motor wind igbts before it is detected Murphy says whatever can happen WILL happen.	ling and two
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■ 06-29-2017, 12:23 PM Â # <u>16:</u>	<u>56</u> Â 🐢Â 🔥 Â
	in Date: Jan 2015 cation: Slovenia sts: 28
E Re: Another homebrew AC-controller	
Who killed my inverter. I think I found it. R3 or R6 100hm resistor in the gate driver. (died without visible damage) I broke it and found oxidation under the covers on both sides I will replace all six for 4.70hm for minor losses on IGBT. I saw them in the new BOM Attached Thumbnails	
Â	
Last edited by ALIE; 06-29-2017 at 12:29 PM.	
■ 06-30-2017, 12:51 PM Â # 16 3	<u>57</u> Â∡ĩ∿Â ∧ Â
Join Loc	in Date: Jan 2008 cation: Ireland sts: 2,147
Re: Another homebrew AC-controller	
Spun up the Tesla motor with the Heubner inverter today. I will break off a new thread on this including reverse engineering the tesla inverter and a Heubner based logic board.	project
Attached Thumbnails Â	
Now, Cole, when you shift the gear and that little needle on the ammeter goes into the red and Amps, that's bad. www.evbmw.com	i reads 1000
Quot	• 🛛 🏹 🦻
● 06-30-2017, 01:00 PM Â # <u>16</u> :	<u>58</u> Â ∭ Â ∧ Â
arber333	n Date: Dec 2010 cation: Slovenia



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Great work on the Tesla inverter.

I have been informed that the reason my motor increased rpm up by itself in closed loop mode is to do with the way Torque control works. I do not fully understand, but without any or little resistance this is what can apparently happen and is normal, so thats good, because I could not understand why the throttle signal would be at fault.

I am also curious as to what everyone is using for insulation / isolation monitoring HV to chassis? I know of Bender units, but any other ways? I hear that some inverters incorporate this function.

cheers

Tim

🖿 07-03-2017, 11:54 AM



 #1664 Â A Â Â Join Date: Apr 2010 Location: Germany Posts: 927

Quote 🕎 🏹 🎤

Re: Another homebrew AC-controller

Originally Posted by arber333 5 It seemed like temp sensor was giving trouble also... I had to replace it too. I feel sorry for the thing. Its wires have to bare all sorts of strain. I noticed something i consider dangerous though. Couple of times now i got OClimit thrown just after i start inverter. At first i just reset and drove away. But yesterday it happened the fourth time now. I got really upset since i havent applied any throttle. I connected scope to GE and checked values at the moment of start. I noticed when i put 12V to inverter i got GElow at -5V and GEhigh at +15V!!! What! When i toggle start both values go to -5V. Is it possible that for a very short time High to Low transistor would be open and current would flow from precharge? Johannes i think maybe you should put a ms delay from all gates going low to DCswitch starting. What do you say? So I scoped all 6 gate outputs and they all looked perfectly low on power up with all signals in sane regions, i.e. emcy and mprot high etc. Is it only the gate drivers that you measured high or the 3.3V drive signals as well? Quote: Originally Posted by EVElvis 🔊 Great work on the Tesla inverter. I have been informed that the reason my motor increased rpm up by itself in closed loop mode is to do with the way Torque control works. I do not fully understand, but without any or little resistance this is what can apparently happen and is normal, so thats good, because I could not understand why the throttle signal would be at fault. I am also curious as to what everyone is using for insulation / isolation monitoring HV to chassis? I know of Bender units, but any other ways? I hear that some inverters incorporate this function. In fact the very first sensor board (non-isolated, non-differential) could tell when there was something wrong with insulation. As soon as some resistance lies in parallel to the 2M measure resistors the voltage reading would be too high accordingly. So thats what you could build, independently from the inverter, HV+--|\/\/|--- Chassis --|\/\/|-- HV-The two outer resistors (say R1, R3) should be in the megohm region and the inner one (call it R2) sized to drop 3V. Also put a capacitor in parallel to it to filter capacitively coupled stuff. Have an Arduino measure from Chassis over R2 and either just shine a light or do fancy math with the obtained value. Concerning torque control, yes thats how it works 😁 Even small torque values will deal with the rotor mass pretty quickly and accelerate it until the fmax limit is hit. VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit 📝 Quote 🕺 📝 🔗 07-04-2017, 03:11 PM #**1665** 🎢 Â ΛÂ Join Date: Apr 2010 jhuebner O _Â Location: Germany Posts: 927 Senior Member Re: Another homebrew AC-controller So, here is a first shot at some dynamic CAN programming There will be a new command set for CAN mapping. I did TX first:



	Re: Another homebrew AC-controller		
I'm No Ih tur Is	guys n driving again. w I've set up current sensors correctly. Iad to lower the bust from 6000 to 5000 and fslipmax fron rned off PWM. et the Oculim -600 (Infineon 400A 1200V -192V batery). Ie car is lazy, but it works.	n 8.5 to 7 because my curr	rent protection was
Las	st edited by ALIE; 07-06-2017 at 03:12 PM.		
			📝 Quote 🕎 📝 🔗
0	7-07-2017, 03:50 PM		â # <u>1670</u> â ∢ ॉ ∿â ∕ ∆ â
	VElvis mber Â A		Join Date: Jun 2009 Location: Sussex UK Posts: 99
	Re: Another homebrew AC-controller		
-	Quote:		
	In fact the very first sensor board (non-isolated, non-d something wrong with insulation. As soon as some resist resistors the voltage reading would be too high accordin	tance lies in parallel to the	
	So thats what you could build, independently from the i HV+ VV VV Chassis VV HV-	nverter,	
	The two outer resistors (say R1, R3) should be in the m sized to drop 3V. Also put a capacitor in parallel to it to Arduino measure from Chassis over R2 and either just sh value.	filter capacitively coupled	stuff. Have an
	Concerning torque control, yes thats how it works Even mass pretty quickly and accelerate it until the fmax limit		eal with the rotor
Thanks Johannes. Good to know there is some protection already, and I recall the Orion BMS i plan monitors this as well.			
	und the info attached today which may be of interest to it covering insulation. cheers $\underline{standard6235.pdf}$	some whilst researching ve	enicie standards, some
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jhuebner Senior Member Â	Posts: 927
Re: Another homebrew AC-controller	
Thanks 🙄	
I attached an Itspice file that lets you play with a grid simulator. (Page 3)	
So many limit out there, don't which one is right. <u>http://rfemcdevelopment.eu/index.php/en-55022-2010</u> This one actually ends at 150kHz.	
Here is a converter db to dbµV <u>http://www.radiomar.net/convDBWen.htm</u>	
The image shows the FFT with a stop band filter and a 33mOhm series resistance on t there is a pronounced spike at around 3kHz.	he filter cap. Without it
Â	
Attached Files	
boost charge emc.asc.txt (3.3 KB, 5 views)	
<u>VW Polo 86C High Voltage AC Conversion</u> - <u>AC Motor Inverter Kit</u>	Quote 🕎 🎢 🔗
07-20-2017, 12:34 PM	â # <u>1675</u> â 🐢 â <u> â</u> â
	lain Datas Data 2000
dcb Senior Member Â	Join Date: Dec 2009 Posts: 2,170
Senior Member A	
Senior Member A A A Re: Another homebrew AC-controller	Posts: 2,170
Senior Member A Re: Another homebrew AC-controller using the home rolled modulo function, w00t might want to add a realistic amount of resistance to the components, getting ringing	on the input current.
Senior Member A Re: Another homebrew AC-controller using the home rolled modulo function, w00t might want to add a realistic amount of resistance to the components, getting ringing edit, doh, you already did.	Posts: 2,170
Senior Member A Re: Another homebrew AC-controller using the home rolled modulo function, w00t might want to add a realistic amount of resistance to the components, getting ringing edit, doh, you already did. Last edited by dcb; 07-20-2017 at 12:36 PM.	on the input current.
Senior Member A Re: Another homebrew AC-controller using the home rolled modulo function, w00t might want to add a realistic amount of resistance to the components, getting ringing edit, doh, you already did. Last edited by dcb; 07-20-2017 at 12:36 PM.	Posts: 2,170 on the input current.
Senior Member A Re: Another homebrew AC-controller using the home rolled modulo function, w00t might want to add a realistic amount of resistance to the components, getting ringing edit, doh, you already did. Last edited by dcb; 07-20-2017 at 12:36 PM. 07-21-2017, 10:22 AM Tony Bogs Senior Member Â	Posts: 2,170 on the input current. $\boxed{2} \boxed{2} \boxed{2} \boxed{2} \boxed{2} \boxed{2} \boxed{2} \boxed{2} $



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	lly Posted by E bin of the whee					
https:/	https://www.youtube.com/watch?v=yW_Qb6j_TKE					
	Still not the smoothest control, the rattle on startup you hear has been worse at times, so much so I thought the drive splines between motor and gearbox were knackered. Anyone else come across this?					
cheers						
I suspect r in the 1800 clutch plat Othervise i It is a 1001	ny clutch is bar Irpm region som e and there is s see a lot of no thz heartbeat.	netimes. The cure some peace for a lise on my lines co What do you use	of center a bit. Since is to put it in neut time :	ral and rev it to contactor ecor it have open col	llector output? You or inverter.	ters the
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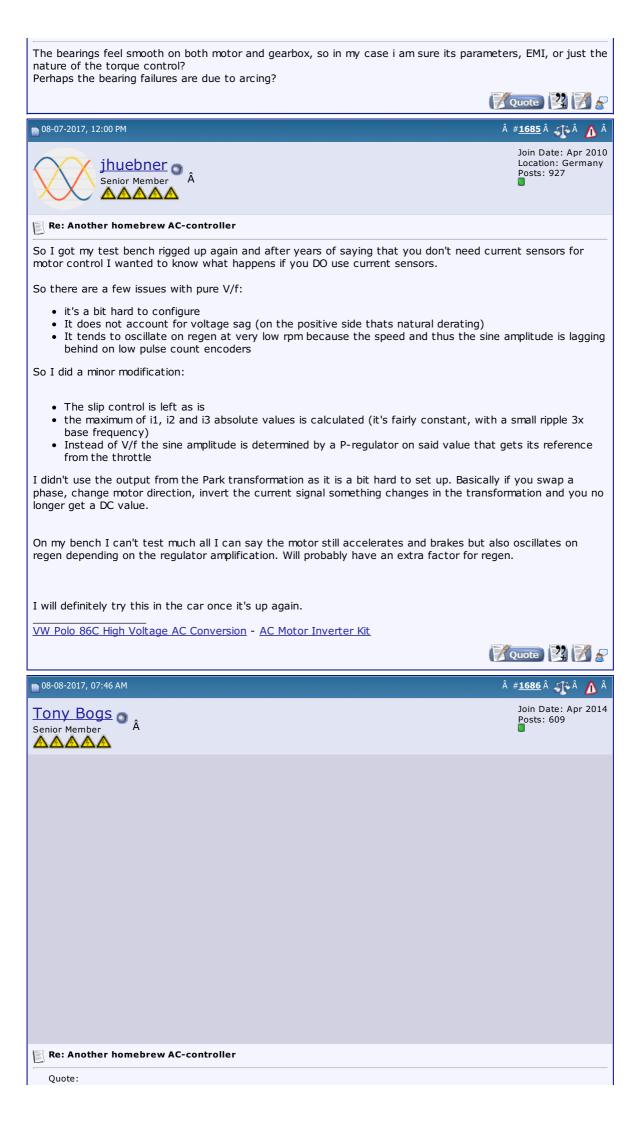
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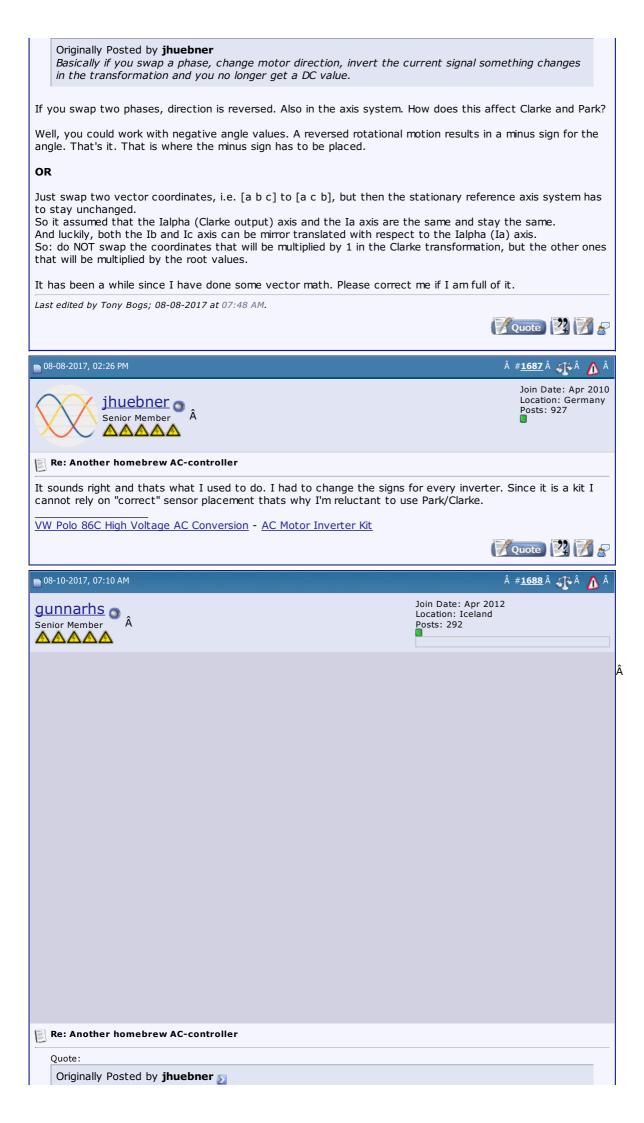


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	cult. Run the routine every tir may have changed (DIY!).	ne the system is restar	ted in case the physical	
Maybe I'll sub	mit a post about the method	in my SiC inverter thre	ad.	
			nagnetic field in an ACIM, Unlike · did you mean something else,	
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new f which sets speed) and we ne situation and we See an example h PMSM but I used I did long ago pro So the only use f efficiency and the current protection The advantage of calculation.	both voltage AND slip. Howeved to react again. So by mea can use this information directer in http://ww1.microchip.co it because of the good explarvide a code example for how or a current model transformate current overload situation (to n). f this model is the simplicity or	ver if load changes quick asuring the current we h tly for Sinusodial- or SV com/downloads/etes/C hation of the modulation to use this to "correct" ' tion (in this case only C the code previously post f the current sensor set	11299A.pdf, the paper is titled for	or ad wer
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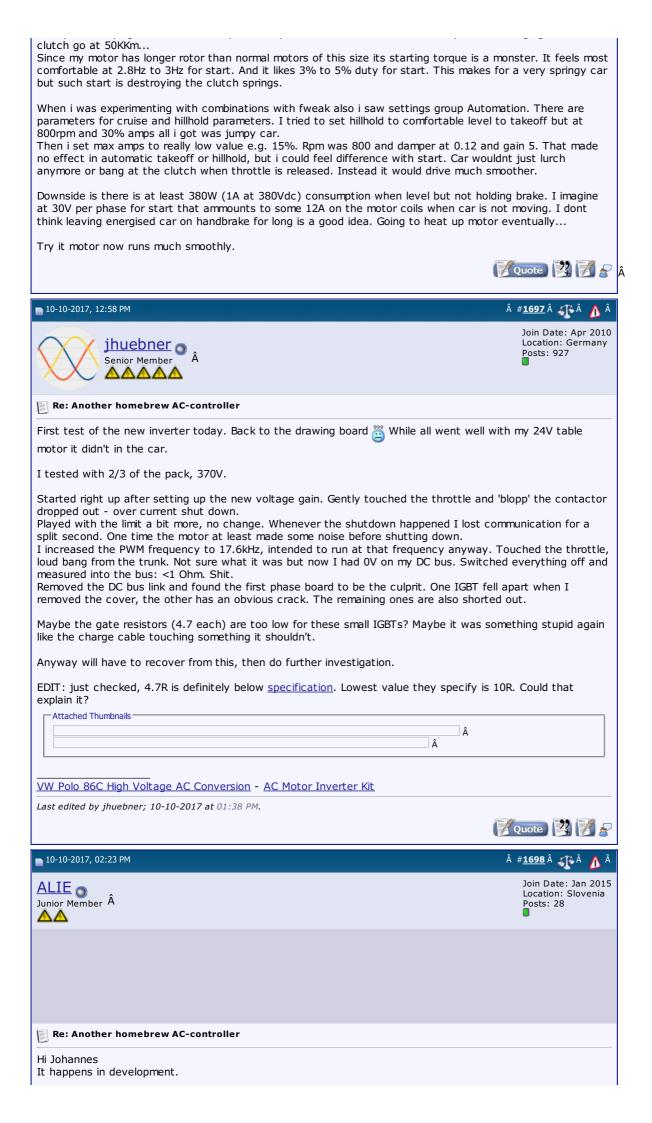
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jhuebner Senior Member Â			Join Date: Apr 2 Location: Germa Posts: 927		
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Re: Another homebrew AC-con	ntroller				
Some more hardware has arrived the Polo though).	d. Beefy 7A EiceDrivers driving 2 no	ot so beefy 1200V/40A IGB	Ts (enough fo	or	
The Melexis current sensors are	located on the other side under th	he AC bus bar and give reli	able readings.		
Can't wait to put it in place 🙂					
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jhuebner Senior Member Â			Location: Germa Posts: 927		
Re: Another homebrew AC-co	ntroller				
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dcb 💿			Join Date: Dec 2 Posts: 2,170	2009	
Senior Member Â					
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arber333 Senior Member Â			Join Date: Dec 2 Location: Slover Posts: 782		
Re: Another homebrew AC-con	ntroller				







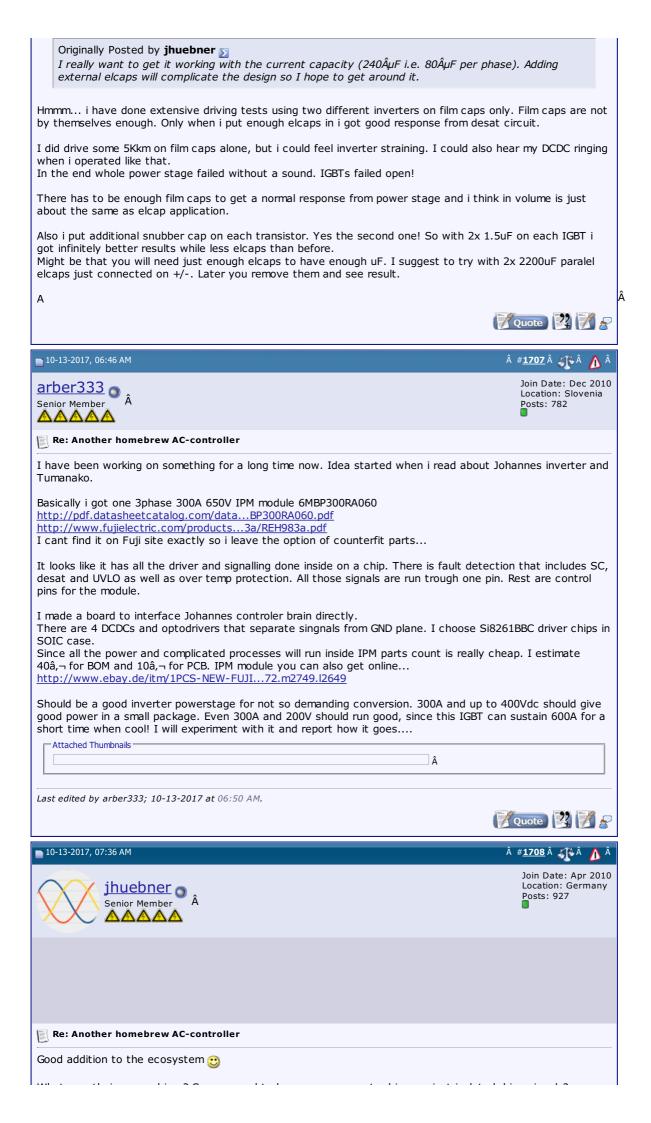
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What exactly is a pre	-driver? So you need to h	ave your own gate driver	or just isolated drive signals?
VW Polo 86C High Vol	ltage AC Conversion - AC	<u>Motor Inverter Kit</u>	
			Quote 😰 🎽
10-13-2017, 09:57 AM			# <u>1709</u> 🕂 <u>۸</u>
jhueb Senior Me			Join Date: Apr 20: Location: German Posts: 927
🛐 Re: Another homeb	orew AC-controller		
	nen I swapped all resistors		ne DC bus voltage when the gate off. I'm not posting the scope plot a
In both cases the DC overshoots by 30V i.e	bus shows some high free bus shows some high free bus spike is 70V for 40V	quency ringing (+-2V) and ' bus voltage.	d a positive spike of about 8V. Vce
The overshoot get ma 20A rms into the mot		rrent into the motor rises	. The picture shows the overshoot a
	ing behaviour or does it p	oint to a design problem?	
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VW Polo 86C High Vol	<u>Itage AC Conversion</u> - <u>AC</u>	Motor Inverter Kit	Quote 2 7
10-13-2017, 12:41 PM			# <u>1710</u> 📢 🔥
			Join Date: Apr 20:
Tony Bogs Senior Member Â			Posts: 609
Re: Another home	orew AC-controller		
l have seen similar sp	pikes with fast punch throu	ugh IGBTs in one of my m	otor controllers.
An avalanche rated n	would have lowered the F nosfet (gate shorted to so ween IGBT and mosfet we	ource) in parallel with eve	ry IGBT solved the IGBT popcom.
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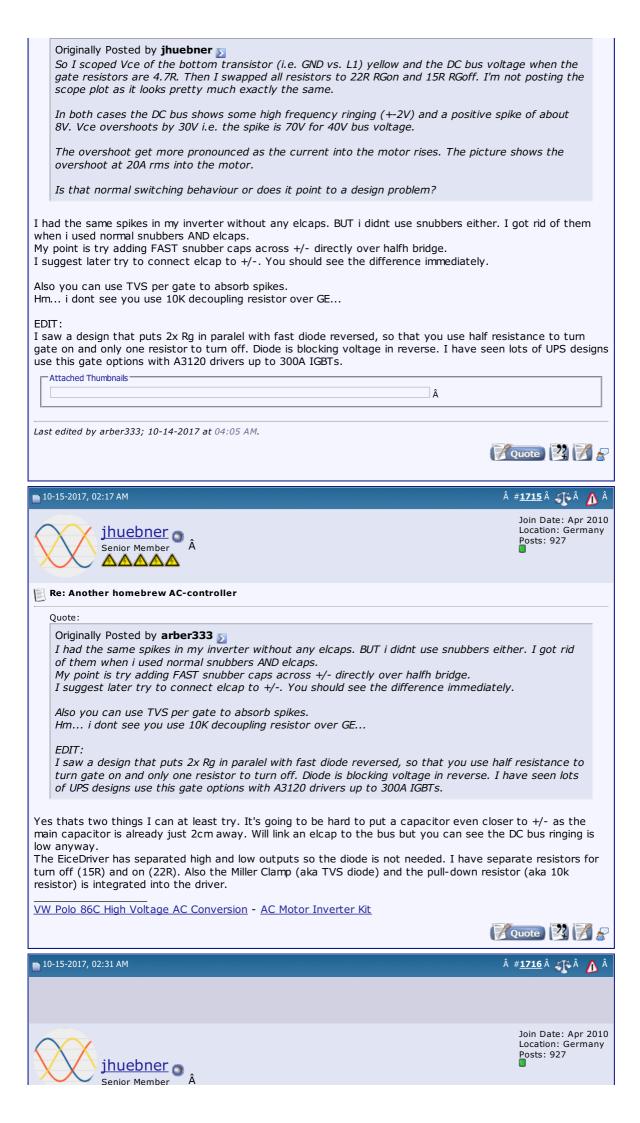
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jhuebner Senior Member Â		L	pin Date: Apr 2010 ocation: Germany osts: 927	
💽 Re: Another homebrew AC-co	ontroller			Sponsors
<u> </u>	unky. Where did you find that? I'm no	ot using punch through IGF	STs though.	
I observed something strange.	I disconnected 2 modules to see the both gate signals (directly on the pine	plain switching. Increased	the deadtime	
	s a small hump on the low side gate a at hump reaches 5V which is above t			
	ge with the generic driver and it didn' ge. I guess there is always some?	t show this hump. There w	as 4mA cross	
So does the collector gate cap +-200mV ringing.	bacity cause this? What is going on? /	All supply voltages are stal	ole with some	
EDIT: I read in some appnote t anyway because I thought the	hat you shouldn't use the ground pla distance was short enough.	ne as the gate return to t	he driver. I did	
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<u>VW Polo 86C High Voltage AC (</u>	<u> Conversion</u> - <u>AC Motor Inverter Kit</u>			
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■ 10-13-2017, 02:38 PM			<u>712</u> Â ∰Â <u>∧</u> Â	
Tony Bogs Senior Member			pin Date: Apr 2014 osts: 609	
				Become a Sponso







🛐 Re: Another homebrew AC-controller

Quote:

Originally Posted by Tony Bogs 🔊

I did not find the parallel mosfet solution anywhere. Funky? No way, I had to use IGBTs for the low Vcesat. Back then, that is, almost ten years ago. I'd go with mosfet now if I had to do it again. I know that you are using trench. Trench and PT are similar in a number of features. Both are fast, they don't avalanch nicely and they have low Vcesat.

So what sort of mosfet would I need in parallel? Small SOT23?

Quote:

Originally Posted by Tony Bogs 🔊

The hump is probably caused by feedback collector > gate. The IGBT is a switching very fast plus inductive load, resulting in high dV/dt > high capacitive current feedback in gate resistor. Guess a bit of snubber might be helpful. The trench has a very low output c at higher Vce(~60pF). Image two does not have the Miller plateau on the high side, could mean that the anti-parallel diode is already conducting.

No inductive load on these images because I'm only operating one half-bridge. Anyway, what do you mean by "a bit of snubber might be helpful"? Across +/-? Would it help to further increase the turn-on resistance?

Quote:

Originally Posted by Tony Bogs 🔊

Tracks to the gate: keep them as short as possible and and lay out the return line from the Kelvin pin on the opposite side of the PCB (without intermediate layers of course).

Edit: Ok, wait, just read that Ch1 is low side, Ch2 is high side. No, the other way around. Hmm, maybe not the collector - gate C. Not enough data to be sure.The trench has a much higher output c at low Vce. Might have something to do with it.

🛛 🛛 Quote 🕎 🏹 🔎

â #<u>1717</u> â 🌆 Â 🧥 â

Join Date: Apr 2014 Posts: 609

Yes, will have Kelvin connections on the next run.

Hopefully all this together will solve the problem.

VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit

n 10-15-2017, 04:40 AM

Tony Bogs Senior Member Â▲▲▲▲

Re: Another homebrew AC-controller

Quote:

Originally Posted by **jhuebner** So what sort of mosfet would I need in parallel? Small SOT23? <snip>



I also checked on the running circuit that it's not an inductance issue. The hump is there on the gate pin and

it's barely noticeable B Cgc capacity to build u		. So the resistor (I've low	ered it down to 10 Ohm) allows the
One obvious cure woul over the same 22 Ohm		ve on the low side. So I t	ried that. Biased the gate with -5V
Result looks promising,	just a minor hump in the	e negative voltage.	
Attached Thumbnails			
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		Motor Invortor Vit	
	age AC Conversion - <u>AC</u>	Motor Inverter Kit	
			Quote 24
📄 10-18-2017, 05:50 AM			â # <u>1720</u> â 🐠 â \Lambda â
Tony Bogs A			Join Date: Apr 2014 Posts: 609
Re: Another homebr	ew AC-controller		
That is as clear as it c	an be.		
Quote:			
Originally Posted by	y jhuebner		
	unication, quadrature e	ncoder support, IGBT driv	ver fault signaling and some minor
		ently you can get/set all p s/values to arbitrary CAN	parameters using the CANOpen frames.
CAN throttle contro	ol and IO is not yet supp	oorted, I'll wait for some	practical applications to spawn.
Wow, that looks very p	romicina		
	-		
If fault signaling include short circuit rating (SC		much use with 1200V trei	nch IBGTs. I haven't seen one with a
There are 600V trench	IBGTs that have a squa	re FBSOA + RBSOA and a	SCSOA rating. For instance the
Infineon IRGP4063D (50 https://www.infineon.co	com/dgdl/irgp4053565	<u>5ee0c2450</u> .	
	clamp @370V: for instar m/pub/Collateral/FQA65	nce two Onsemi FQA65N2	0 in series.
good 1200V match.	U (no anti-parallel diode) and Onsemi FDL100N50F	(diode is here) look like they are a
-			
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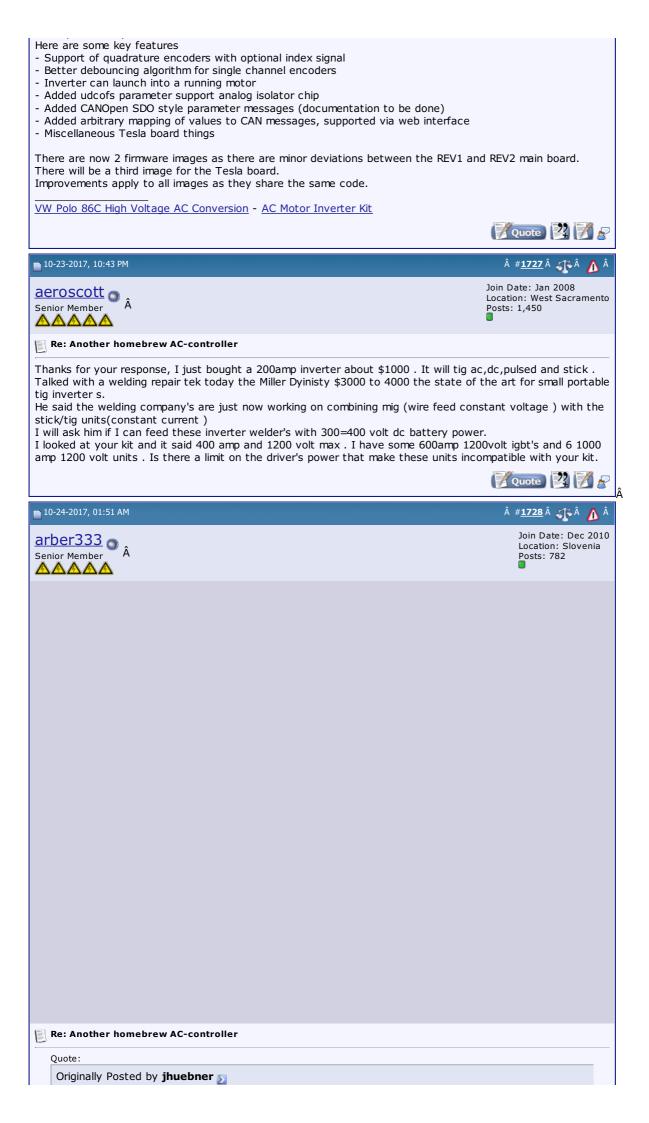
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The zip file on my website now contains a new firmware and web interface.



	The zip file on my website now contains a new firmware and web interface. Here are some key features	
	- Support of quadrature encoders with optional index signal	
	- Better debouncing algorithm for single channel encoders - Inverter can launch into a running motor	
	- Added udcofs parameter support analog isolator chip	
	 Added CANOpen SDO style parameter messages (documentation to be done) Added arbitrary mapping of values to CAN messages, supported via web interface 	
	- Miscellaneous Tesla board things	
	There are now 2 firmware images as there are miner deviations between the PEV/1 and PEV/2 main	
	There are now 2 firmware images as there are minor deviations between the REV1 and REV2 main board. There will be a third image for the Tesla board.	
	Improvements apply to all images as they share the same code.	
inv TIN I h I d rela I h wo 1. 2. 3. I th	have tested new code and i can attest it works very good on old main board. I had some instances wher verter threw OClimit due to low setting. I was able to restart my inverter while driving at 100km/h EVERY ME! I did use clutch to decouple motor from transmission, but i think it works even without this feature. have yet to test this on new revision of main board since i use my car every day \bigcirc . Id notice however that my web interface doesnt get data every time i have inverter started. I have to oad page a lot. But connection works when i order some parameter. have a plan to make inverter with 300A IPM module and driver interface so that everything we would nee buld be main board pcb sensor board cheap driver interface since IPM has drivers inside hink i will use air cooling for this one with 24V fans because of their speed and i can use 24V as supply a e to converter chip already present \bigcirc .	d
Sin Wo	hannes you said you use some new version of sensor interface. I am interested in seeing that in action. nee melexis chips would be a cheap alternative to LEM sensors. ould two melexis chips on parallel phase lines 10cm apart interfere with current reading from each other? nat is the distance from conduit you use them on?	
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5	jhuebner Senior Member Â Â	010
5	Join Date: Apr 2 Location: Germa Posts: 927	010
5	Join Date: Apr 2 Location: Germa Posts: 927 Re: Another homebrew AC-controller	010
So	Join Date: Apr 2 Location: Germa Posts: 927 Re: Another homebrew AC-controller Quote: Originally Posted by arber333 ≥ Johannes you said you use some new version of sensor interface. I am interested in seeing that in action. Since melexis chips would be a cheap alternative to LEM sensors. Would two melexis chips on parallel phase lines 10cm apart interfere with current reading from each other? What is the distance from conduit you use them on? Paral I'm impressed with the Melexis chips. Here you see it mounted about 3mm away from the bus bar (5 ud - chip height). Gives me 9 digits/A. 800A LEM sensors are more like 2 digit/A.	010 iny
So	Join Date: Apr 2 Location: Germa Posts: 927 Posts: 927 Re: Another homebrew AC-controller Quote: Originally Posted by arber333 ≥ Johannes you said you use some new version of sensor interface. I am interested in seeing that in action. Since melexis chips would be a cheap alternative to LEM sensors. Would two melexis chips on parallel phase lines 10cm apart interfere with current reading from each other? What is the distance from conduit you use them on? Posts: 10cm Posts: 2027	010 iny
So	Join Date: Apr 2 Location: Germa Posts: 927 Re: Another homebrew AC-controller Quote: Originally Posted by arber333 ≥ Johannes you said you use some new version of sensor interface. I am interested in seeing that in action. Since melexis chips would be a cheap alternative to LEM sensors. Would two melexis chips on parallel phase lines 10cm apart interfere with current reading from each other? What is the distance from conduit you use them on? Paral I'm impressed with the Melexis chips. Here you see it mounted about 3mm away from the bus bar (5 ud - chip height). Gives me 9 digits/A. 800A LEM sensors are more like 2 digit/A.	010 iny
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So stu Did	Join Date: Apr 2 Cocation: Germa Posts: 927 Posts: 927 Posts: 927 Posts: 927 Post: 921 <p< td=""><td>010 iny mm</td></p<>	010 iny mm
So stu Did	Join Date: Apr 2 Senior Member Senior Member A	010 iny mm

Re: Another homebre	w AC-controller			
Has anyone installed the	e pc software on a wi	ndoze machine? If so any p	ointers?	
Now, Cole, when you sh Amps, that's bad. <u>www.evbmw.com</u>	ift the gear and that	little needle on the ammete	er goes into the red and reads	1000
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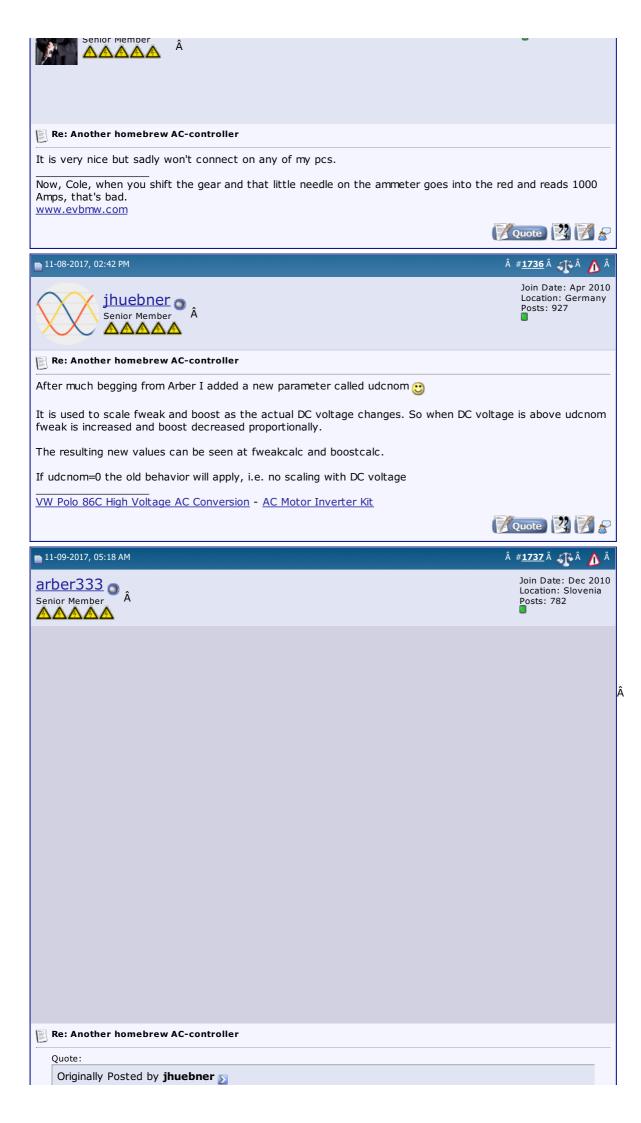
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	s a readme file: 	
CI	on Windows you need an apache+php stack. For example Easyphp (www.easy in addition you need the php_dio library: http://windows.php.net/downloads/pecl/releases/dio/0.0.7/php_dio-0.0.7	
С	Inpack the contents of the zipfile to your easyphp installation, typic ::\Program Files (x86)\EasyPHP-DevServer-13.1VC9\binaries\php\php_runr Don't copy and paste, as you'll have a different version of EasyPHP!)	ingversion\
	<pre>Open the file ::\Program Files (x86)\EasyPHP-DevServer-13.1VC9\binaries\conf_files\p</pre>	ohp.ini
A	and find the line that reads "extension=php_bz2.dll" add a new line: extension=php_dio.dll	
N	low unpack the web interface to	
с	::\Program Files (x86)\EasyPHP-DevServer-13.1VC9\data\localweb\inverte	er
a	und start EasyPHP.	
	Javigate to localhost/inverter and you should see the web interface.	
<		>
Thet		and mark also
	said, try to grab exactly the mentioned versions, as php_dio and the php version r	nust match.
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<u> </u>	iote:	
C	Driginally Posted by jhuebner <i>What PC software?</i>	
	en might be referring to <u>"the beautiful" interface</u> . Yes it went through many revisior e for PC.	ns and more less
Hueb	ner Inverter - Console Management	
		Quote 🕎 📝
11-0	6-2017, 12:36 PM	â # <u>1735</u> â 🕂 Â 💋
	jackbauer	Join Date: Jan 2 Location: Irelan Posts: 2,147





Then we tried and put heat on components while PWM was in operation. First drivers, then main board. The instant we started to heat Olimex chip PWM dropped out! We measured °C with laser temp and got 42°C. We tried several times. Each time chip dropped out above 40°C. When querried, error reporting stated "inverter overvoltage error". We replaced chip with a spare and heat this one. It held above 60ŰC and PWM was steady. It is still spitting out PWM for 20 hours now. I also replaced one Olimex when it started to throw OC limit into the blue with no power applied. I think that probably we would have to think about looking for a replacement for STM32H103 chip with a SIL chip in the future. What do you think Johannes? Would it be possible to port the code to STM32F4 SIL chip? Last edited by arber333; 11-13-2017 at 08:11 AM. Quote n 11-13-2017, 01:22 PM #**1740** 🎢 Â ∕∆ Join Date: Apr 2010 jhuebner 🕥 Location: Germany Posts: 927 Â Senior Member Re: Another homebrew AC-controller Do you think the STM32 is the problem or could it also be the 3.3V voltage regulator? Because spurious over voltage error could mean the ADC ref dips. Would you mind measuring the 3.3V line on your faulty board? VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit Quote 2 « First < 74 124 164 172 173 174 175 176 184 > Last » Post Reply Share or Bookmark this del.icio.us Facebook 骨 Digg 🚓 Reddit 🕤 StumbleUpon G Google 📝 Yahoo! Newsvine <u>Tags</u> Edit Tags None

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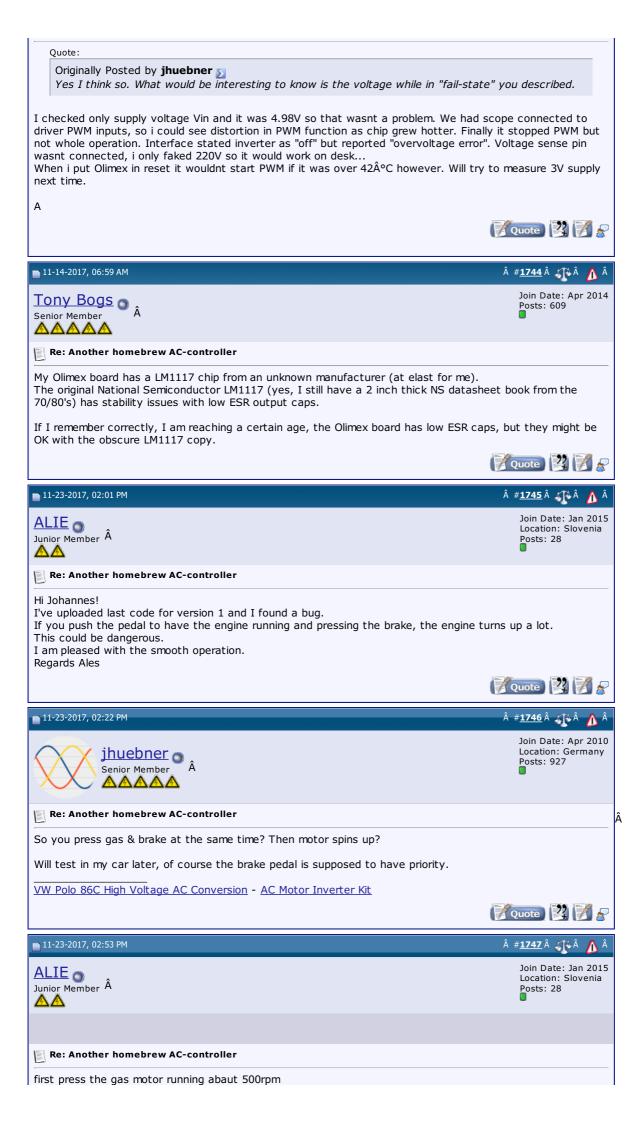
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	A A		•
Re: Another homebr	ew AC-controller		
Yes, the Miller plateau Would you suggest usi		very high gate turn-on res	sistor to reduce ringing, it's 22 Ohms.
10 Ohms is the lowest	gate resistor specified in	the <u>datasheet</u> . I use 10	Ohms for turn-off.
VW Polo 86C High Volt	age AC Conversion - AC	<u>Motor Inverter Kit</u>	
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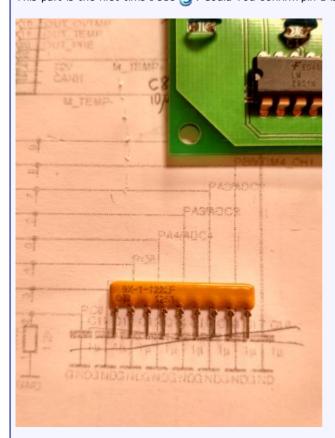
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arber333		Jo Lo	oin Date: Dec 2010 ocation: Slovenia osts: 782	Lik
Re: Another homebrev	v AC-controller			Sponsors
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prass washers to provide like i said i had much rin went down audibly and d amps on takeoff. Try add You could add 2x 17V 2V occurs. EDIT: What abour adding make some form of snub	ging with desat tripping on start. When i adde desat would trip later. When i added large elca ding some large cap there. V zeners back to back on GE so they would dr g a 1R resistor from - pole of film capacitor to	d 1.5uF snubbers acros ps instead of film caps rain excess voltage whe	s DC link ringing i could pull full n ringing	
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12-06-2017, 07:01 AM				
chentron Junior Member Â		Ja La	2762 Â T Â Â Â bin Date: Nov 2017 ocation: Spain osts: 20	
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Hi to all.

I received the kit from Johannes. My electronics is very limited and will be a big help if somebody can answer two questions: This part is the first time I see \bigotimes . Could You confirm pin 1 is in the left side ?



I am also planning what capacitors to choose. I see some people is using film cap + snubber. Other Elcap + snubber. Film cap are really expensive !! I found some good deals and want your advice what could be a good choice. option 1: 2 units **EPCOS (TDK) B43456A9158M000 + snubbers**

https://www.digikey.com/product-deta...235-ND/2269444

or

option 2: 1 unit FFLI6U0437K- - CAPACITOR PP FILM PP, 430UF, 10%, 1.15KV + snubbers

http://es.farnell.com/avx/ffli6u0437...-10/dp/1867543

option 2 is really big cap, 85x180 and 1.3kg so I like better option 1.

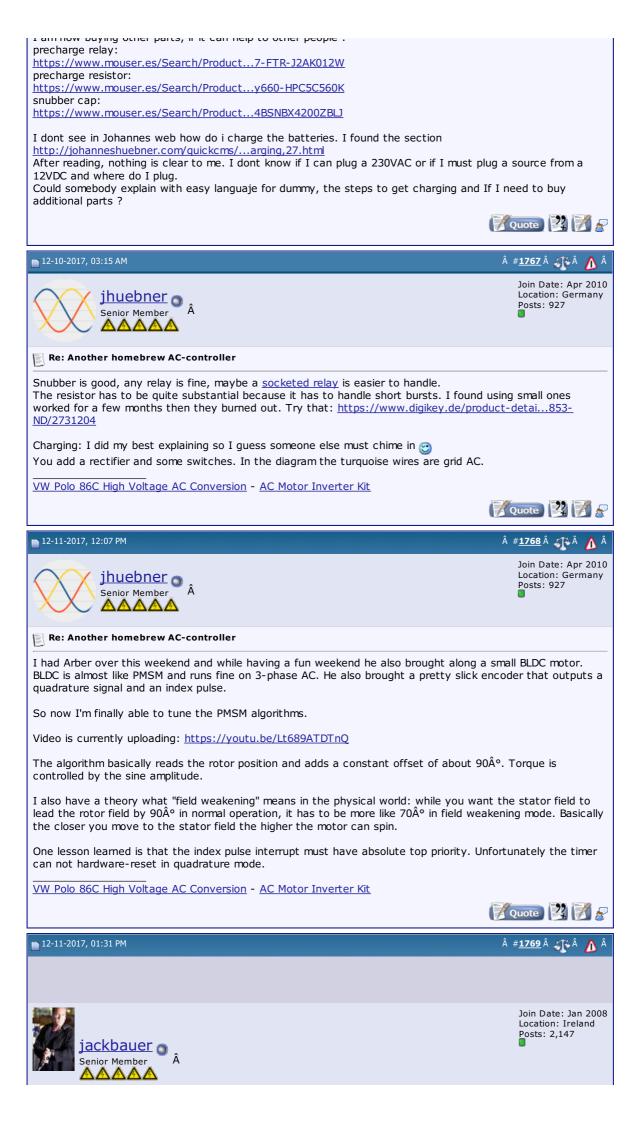
or maybe none of this is good option... I am hearing your conseil.

thanks









🛐 Re: Another homebrew	AC-controller		
So does this mean I can	run my BMW i3 motor	? 🙂	
Now, Cole, when you shif Amps, that's bad. www.evbmw.com	ft the gear and that lit	tle needle on the ammete	r goes into the red and reads 1000
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■ 12-11-2017, 01:34 PM			# <u>1770</u> 🕂 \Lambda Â
jhuebner Senior Member			Join Date: Apr 2010 Location: Germany Posts: 927
📳 Re: Another homebrew	AC-controller		
I think so 🙂			
Just some small issues to feeding back power.	resolve, like forward/	backward is still a little we	eird and I'm not sure if regen is really
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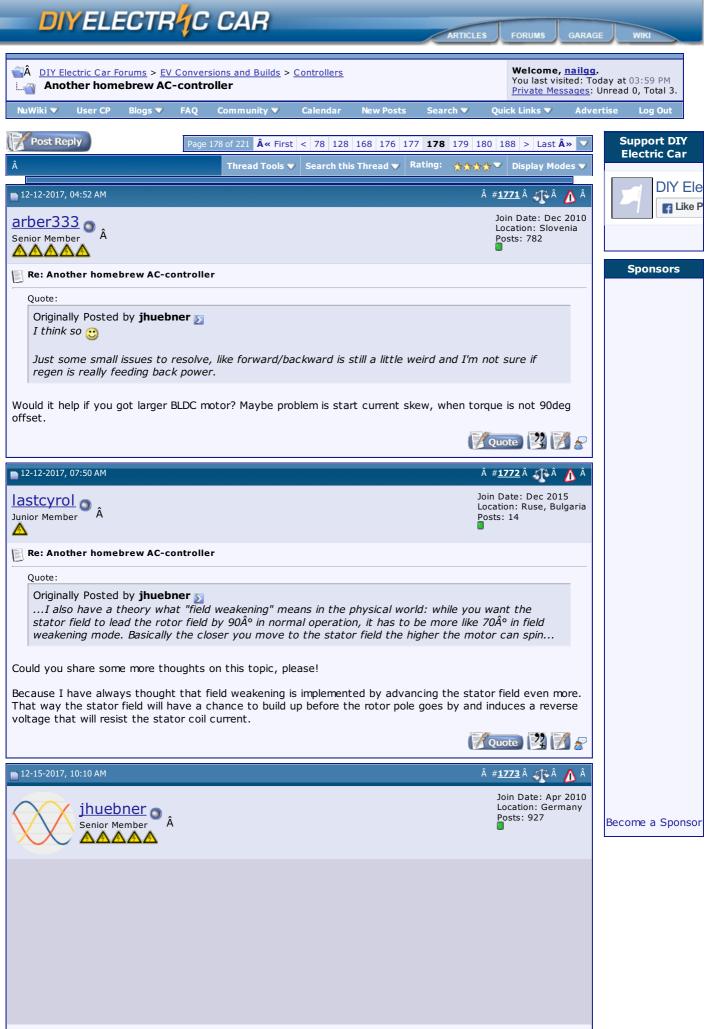
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I wale have to investigate further, maybe you're right. Currently I'm on to other things, namely the new power steeped ession. I testade in the car today and results were better than last time. Notor spins up ok with both 8.8 and 17.6642 MY frequency. I wale yet. It moves but with a lot of rocking back and forth. So will work on the shielding and see if I can get it running before Christmas. I wale better thaneose I work on the shielding and see if I can get it running before Christmas. I wale better thaneose I work on the shielding and see if I can get it running before Christmas. I wale better thaneose I work on the shielding and see if I can get it running before Christmas. I wale better thaneose I work on the shielding and see if I can get it running before Christmas. I wale better thaneose I work on the shielding and see if I can get it running before Christmas. I wale before the work of the Will adapter : http://ghtub.com/dameonrague/fiverter-Will Any contributions or modifications can get in there to keep things tidy. Now, Cole, when you shift the gear and that little needle on the armeter goes into the red and reads 1000 Armse, that's bad. www.ethma.com I wale the controller I have setup a Christing the gear and that little needle on the armeter goes into the red and reads 1000 Armse, that's bad. I wave were also a modifications can get in there to keep things tidy. Now. Cole, when you shift the gear and that little needle on the armeter goes into the red and reads 1000 Armse, that's bad. I wave were also a modifications can get in the red and reads 1000 Armse, that's bad. Will be the second bad were		
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La have setup a Github repo for the WiFi adapter : https://github.com/damenmaguire/Inverter-WiFi Any contributions or modifications can go in there to keep things tidy. Now, Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. www.evbmw.com Prove 2017 00:5344 12:08:007 Member A 12:08:007 Member A 12:08:07 Member A 12:08:07 Membe	Senior Member Â	Location: Ireland
https://github.com/damiennaguire/Inverter-WiFi Any contributions or modifications can go in there to keep things tidy. New, Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. www.evbmw.com Image: Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. Image: Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. Image: Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. Image: Cole, Wenty or Shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. Image: Cole, Wenty or Shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. Image: Cole, Wenty or Shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. Image: Cole, Wenty or Shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. Image: Cole, Wenty or Shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. Image: Cole, Wenty or Shift the gear and that little needle on the ammeter goes into the red and the shift the gear and that little needle on the ammeter goes into the red and the shift the gear and the s	Re: Another homebrew AC-controller	
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12:16:2017, 03:53 M Â #1275 Å () Å Å Senior Member Â Å Join Date: Dec 2010 Doin Date: Dec 2010 Posts: 782 Ø:Station Action Posts: 782 Ø:E Another homebrew AC-controller Posts: Postation	www.evbmw.com	
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<u> </u>	arber333	Join Date: Dec 2010 Location: Slovenia
	A A A A A A A A A A A A A A A A A A A	Join Date: Dec 2010 Location: Slovenia



Re: Another homebrew AC-controller
No problem running from the inverter 5v supply. Takes about 100mA when booting then settles to about 50- 60mA running. Also works perfectly on a generic android tablet.
Now, Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. www.evbmw.com
■ 12-18-2017, 01:37 PM Â # 1779 Â 🕵 Â 🚺
Join Date: Apr 201 Location: Germany Posts: 927
E Re: Another homebrew AC-controller
Yes will se about the firmware updates this week. In fact I think Dimas frontend already supports upgrading? Maybe it would be worthwhile to extend JP6 to 5 pins. Like GND, RX, RX, 3V3, 5V.
Now on to todays tests. I have moved most of the Polos signals to the superseal connector. Not so easy because of the variety of wire thicknesses.
I then found two design glitches: the ULN2003 has integrated freewheeling diodes all tied to pin 9. I connected it to the 12V input which does make sense. But if you're contactors happen to be connected to a permanent 12V source, current will make it's way through the diodes and half power on the inverter. That can lead to really strange effects. So, if the contactors are not on the same 12V source as the inverter you' need to cut pin 9 of the ULN2003 and take care of freewheeling yourself. Next glitch is on the not yet public isolator board: It ties the UVLO pin to 5V on a non-5V tolerant pin. Thankfully that did not lead to destruction of the STM32 but through the ESD diode it raises the supply voltage to 4V! Not good either. So I cut that pin as well.
I also installed a push-pull optical encoder but it needs more mechanical adjustment to work good I think. It conks out at higher speeds.
So I did some simple open-loop tests instead, 3Hz, 50% amplitude. Then came the bang and a cloud of smoke and the inverter looked like below.
Not sure what happened here but it seems the AC line filter which is supposed to be passive in inverter mode was not so passive after all. The trace towards the rectifier vaporized so for some reason current must have gone through it. The "epicenter" is the screw clamp, that even vaporized some of the heatsink below it.
One high side IGBT lost 2 legs, only the gate pin left. The one parallel to it might even still work, will see tomorrow. The drivers and the digital isolator are gone as well. All else is good including the other phase boards.
Attached Thumbnails Â Â Â
<u>VW Polo 86C High Voltage AC Conversion</u> - AC Motor Inverter Kit
Last edited by jhuebner; 12-18-2017 at 01:44 PM. Reason: typos
▲ 12-18-2017, 01:49 PM Â # <u>1780</u> Â 🏠 Â
Join Date: Jan 200 Location: Ireland Posts: 2,147

Re: Another homebr	ew AC-controller			
	the Dima frontend runn be wrong as I never gol		nly gives instructions on firm	ware
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So since weather was friendly today I decided to bolt the inverter in place and do an actual test drive.



So i would recommend water cooling block with 1mm recess cut for IGBT placement and a clamp to hold them down much like you have now. A clamp doesnt need to go trough IGBT center...

Though i seriously think those 40A IGBTs are worth up to 20A in the real automotive world. We have to solve the core issue here. Not just remove heat.

1. I think two of IGBTs are too close together to dissipate heat.

2. Copper under DC and AC outputs is too thin and is probably heating up IGBT contacts. Remember heat transfers and moves towards greatest sink... that are IGBTs. I suggest adding copper sheet under/over DC link PCB plating and soldering IGBT to this sheet directly while leaving holes to separate opposite connection. I would only use PCB traces for gate signaling.

The same with phase connection. I would put copper sheet there and solder only correct legs, rest i would drill out and separate with pressed silk or other isolator.

3. Also i think you should add more capacitance to DC rail. You can try next time, just add one large cap you have to +/-.

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■ 12-27-2017, 01:25 PM			# <u>1800</u> Æ	🚺 Â
jackbauer Senior Member	Â		Join Date: J Location: Ir Posts: 2,14	reland
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I am sure your answer has a sense but I dont know how to translate this info to the my IGBT semikron SKM400GB126D (470 A at $25 \hat{A}^{\circ}$)	ne amperes that will charge
I was trying to decide which bridge rectifier to buy for charger circuit. candidate we I dont want charge more than 20 amperes/hour in AC, \dots could this rectifier be the	
Quote:	
Originally Posted by jackbauer The pwm duty cycle of the IGBT.	
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■ 12-27-2017, 03:09 PM	# <u>1804</u> ∡∰ 🏠 Â
kennybobby Senior Member	Join Date: Aug 2012 Location: Heart of Dixie Posts: 1,054 Blog Entries: <u>1</u>
Re: Another homebrew AC-controller	
This is not likely the right thread for charger info, but language translation may be signal, that is the pwm duty cycle chart vs charge current in amps. Thru this signal charger how much current is available.	
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■ 12-27-2017, 03:31 PM	â # <u>1805</u> â 🕂 Â 🧥 Â
jackbauer Senior Member Â	Join Date: Jan 2008 Location: Ireland Posts: 2,147
Re: Another homebrew AC-controller	
Re: Another homebrew AC-controller You can set the desired charge current on the web interface when connected to t	he inverter.
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Senior Member	A		
Re: Another homebre	ew AC-controller		
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Regards the web interfa version.	ace I'm leaving it for a v	vhile. I don't think the Pi ha	s the horsepower to run Dima's
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■ 12-29-2017, 08:03 AM			# <u>1810</u> ∭ Â
Senior Mem	✓ ∧		Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebre	ew AC-controller		
Thats a good point, will	l consider it.		
I will put more work in t	the "Huebner" interface	then.	
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Can someone with a working inverter give this a test for me? https://github.com/damienmaguire/Tessh test v1.zip	
just go to localhost/index3.php	
Works on my desktop pc so far but I'm not able to test for changing values from the i	nverter.
Now, Cole, when you shift the gear and that little needle on the ammeter goes into the Amps, that's bad. www.evbmw.com	ne red and reads 1000
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■ 12-29-2017, 02:06 PM	â # <u>1814</u> â 🐠 â 🧥 â
jackbauer Senior Member Â	Join Date: Jan 2008 Location: Ireland Posts: 2,147
Re: Another homebrew AC-controller	
Up and running on the Pi Zero W and Android tablet 🙂	
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Now, Cole, when you shift the gear and that little needle on the ammeter goes into the Amps, that's bad. www.evbmw.com	ne red and reads 1000
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■ 12-30-2017, 02:01 AM	# <u>1815</u> ∡ ™ ⚠ Â
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew AC-controller	
Wow thats cool 🙂 Do you mind if I integrate your work using tchart? Just for the mat charting component?	tter of sticking to one
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■ 12-30-2017, 02:11 AM	# <u>1816</u> ∡∰ <u>∕</u> Â
jackbauer Senior Member Â	Join Date: Jan 2008 Location: Ireland Posts: 2,147
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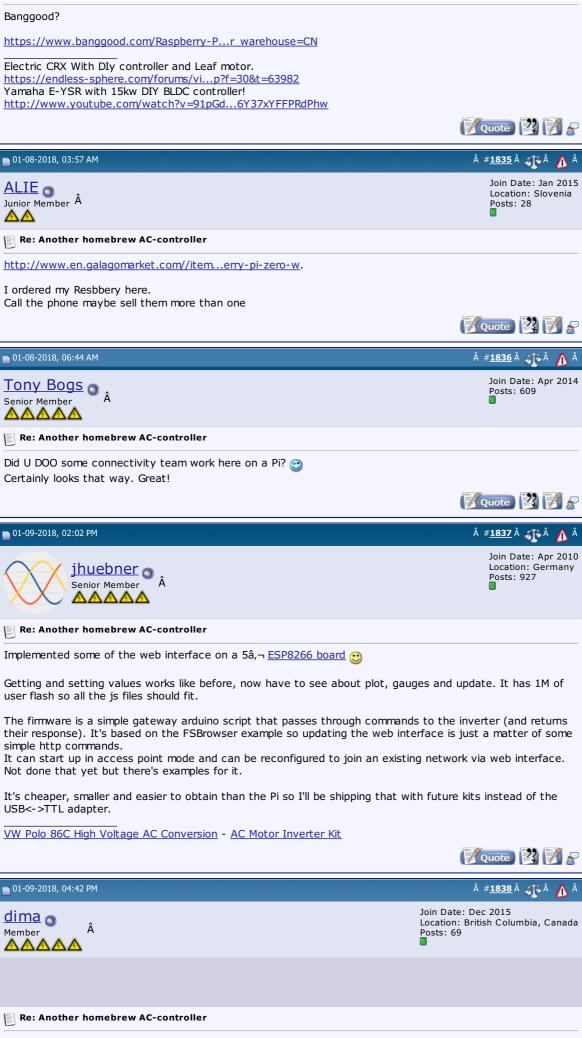






I have completely reworked the sensor board: - 1 voltage sense board with Si8920 iso opamp and dc/dc (much like Damien approach) - 2 Melexis boards that are fixed to the phase output cables with a cable tie and can be padded with some plastic to adjust the current scale.			ith some	
I do consider replacing bulk orders. Any hints?		y a Pi Zero but I haven't fo	ound a Pi Zero source that	accepts
With the Pi Zero kit pr	ice would stay the same,	, without it 10â,¬ less than	now.	
W Polo 86C High Volt	age AC Conversion - AC	<u>Motor Inverter Kit</u>		
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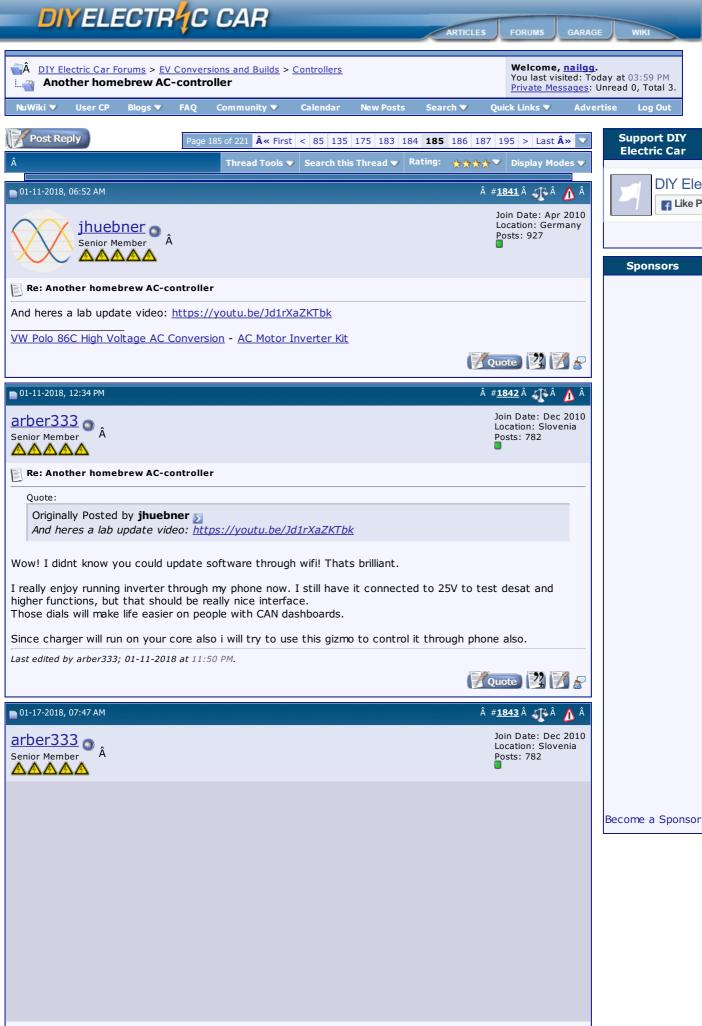
Very interesting ... so there is no PHP? it just passes the commands with http/ajax?

Huebner Inverter - Console Management		
		VQuote 😰 🕅 🔗
■ 01-10-2018, 04:19 AM		# <u>1839</u> 🐠 <u>۸</u> Â
jhuebner Senior Member Â		Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew AC-controller		
Yes exactly, most logic is now shifted to javascri Of course it could be done in C++ but thats more js/html files.		ne binary is harder to upgrade than the
The js/html/png etc. files reside on a small file sy command. I think even the form for upgrading firm		
If you want you can try porting your interface. T sketch into git once it's finished.	he firmware-update c	ode will be in C++. I will put the ino
W Polo 86C High Voltage AC Conversion - AC Mo	otor Inverter Kit	
		📝 Quote) 😰 🌠 🍃
■ 01-11-2018, 01:21 AM		# <u>1840</u> 🕂 <u> Â</u> Â
jhuebner Senior Member Â		Join Date: Apr 2010 Location: Germany Posts: 927
🖹 Re: Another homebrew AC-controller		
Some more hardware experiments with this isolate	or: <u>https://www.digi</u> k	ey.de/product-detai157-ND/2445486
It's some phase change material on a Kapton film	L	
Thermally I'm now very pleased, heat now transfe	ers almost immediatel	y to the heat sink.
But because the isolator is so thin it gets punctu at first, as soon as I heat stuff up and the phase to work on that.	red very easily and the change material mell	nen no longer isolates. Even if it isolates s I get isolation break down. Still have
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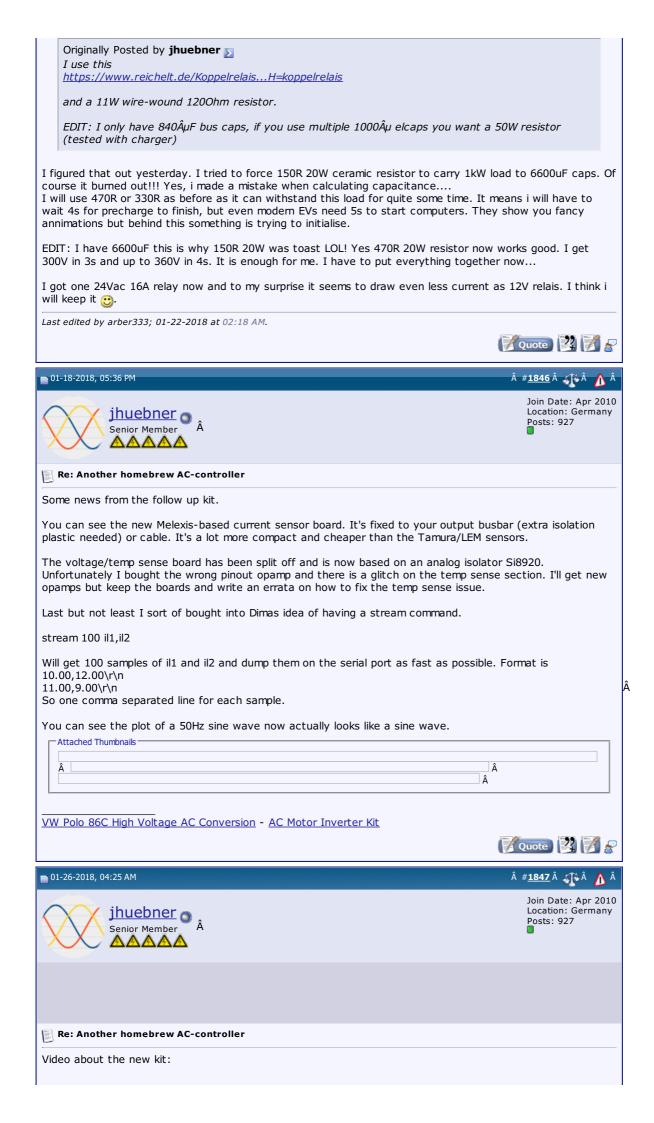
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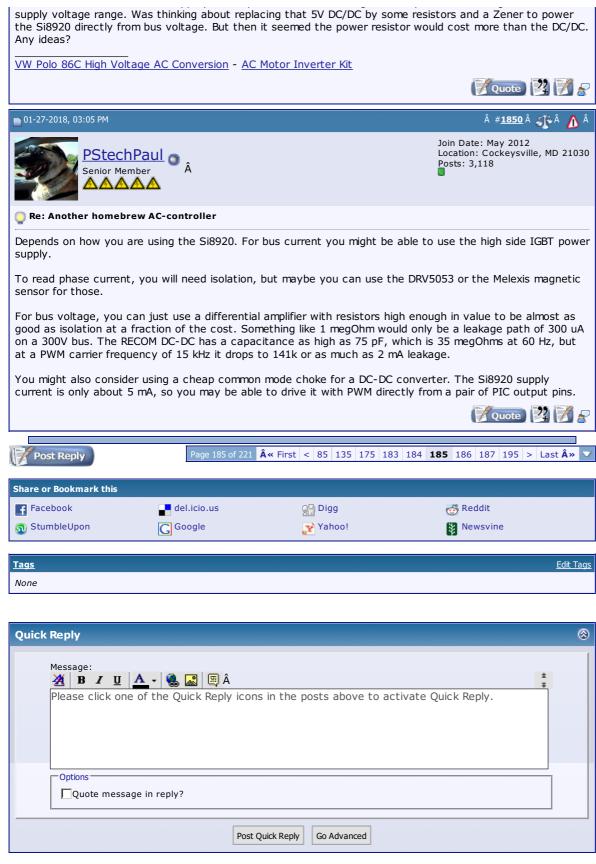








I don't think the HV7801 is an appropriate replacement as it's not galvanically isolated. Though I do like their



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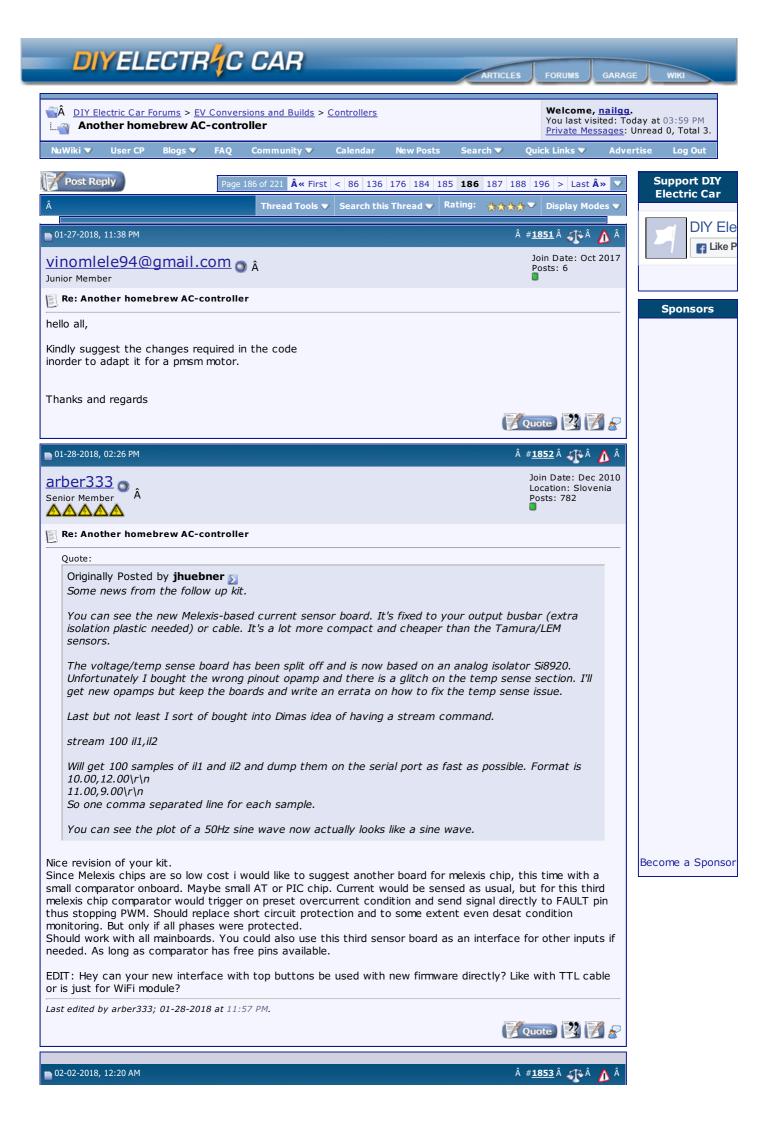
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Join Date: Dec 2010 Location: Slovenia Posts: 782

Re: Another homebrew AC-controller

Hi Johannes

I finally got all IGBTs home. I assembled it together and now inverter works on manual and on throttle command with 25V. Current draw is reasonable.

I use new Revision 2 board with rev. 3 sensor board. I made driver interface board and i am using skyper32pro drivers. Firmware is for Rev2. Wifi interface is such a relief, i no longer have to rely on TTL and Linux.

Wifi even works trough sheet metal covering and car hood! And i just use my phone and configure inverter.

But wait! While inverter works with V/Hz on manual, i could only get encoder working on "single" channel setting. ABZ mode is causing motor to strain, but no movement. I did populate all channels for ABZ like from the plans. I am using AB induction pickup encoder with toothed

wheel 64 teeth and on scope i see it work.

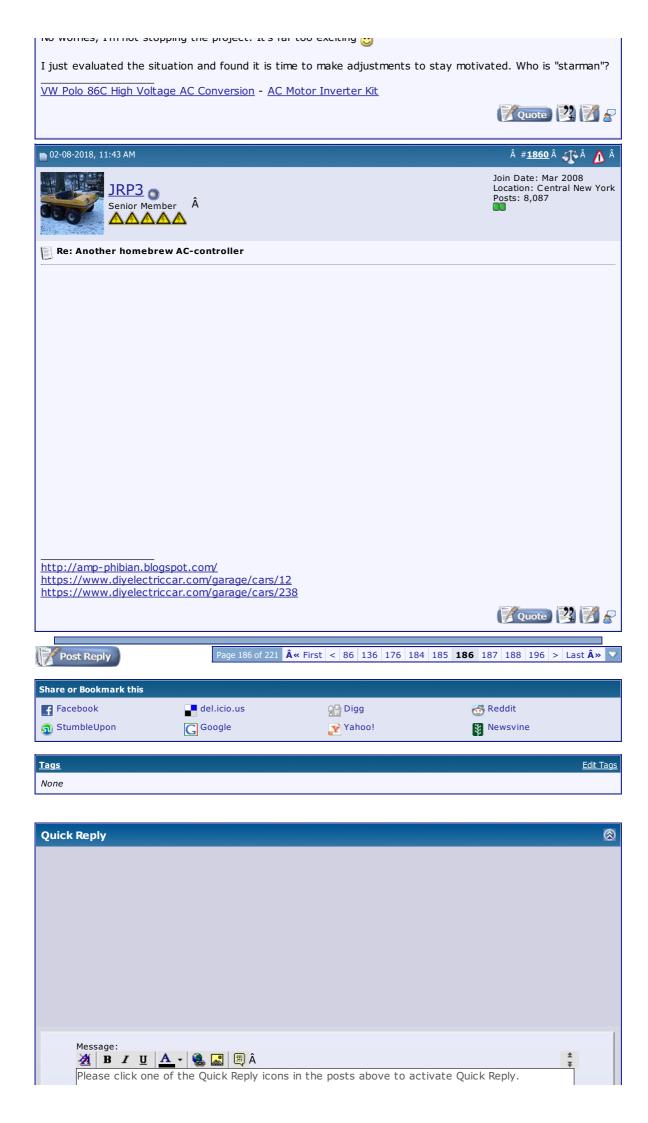
Should i delete Z channel components for AB channels to work together? Any suggestions? What does the code says?

А Quote 🕎 🏹 🖉 n 02-04-2018, 01:07 PM #**1854** Â ⁄ 🏠 Â ΛÂ Join Date: Jan 2008 jackbauer 🗿 _Â Location: Ireland Posts: 2,147 Senior Member ◬◬◬◬ Re: Another homebrew AC-controller Did you try swapping the A and B channels? Don't forget that AB mode now gives the cpu direction. If the motor is turning forward but the encoder says it's going in reverse then it won't run. Don't ask me how i know Now, Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 Amps, that's bad. www.evbmw.com Quote 🕺 📝 ج n 02-05-2018, 06:06 AM #<u>1855</u>Â 🎢 Â ΔÂ arber333 O Â Join Date: Dec 2010 Location: Slovenia Senior Member Posts: 782 DOH! If this is the only thing to do, i feel very lucky. I havent tried to swap them back since direction is now good. I will just try and change A and B. Hope that would be it... Last edited by arber333; 02-06-2018 at 09:33 AM. Quote 🕎 🎢 🔎 🗖 02-08-2018, 09:15 AM #<u>1856</u>Â 🎢 Â 🔥 Join Date: Apr 2010 jhuebner 💿 _Â Location: Germany Posts: 927 Senior Member

Re: Another homebrew AC-controller

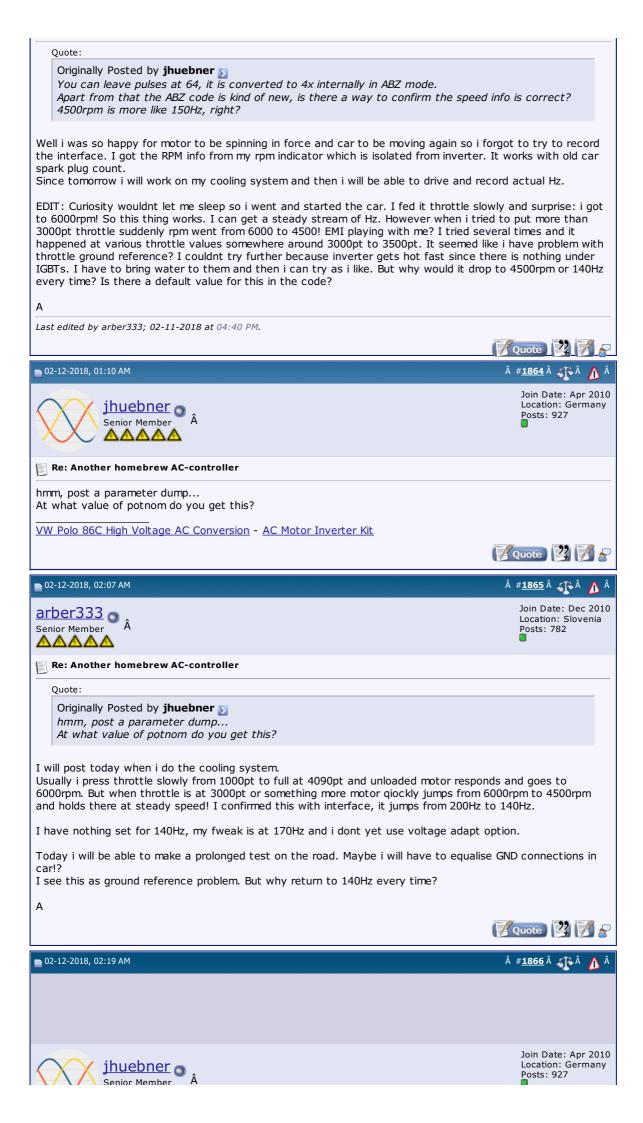
I've been in touch with people using Damiens Tesla version of the logic board. In the process I was sent a





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amplitude has re	ached it's full value and th	max in your post). All I can he slip starts to increase wi ns to brake your motor. Hoj	hen you go further. Can you
There is certainly	y no constant of 140Hz ar	nywhere.	
Hm so it could just be EMI of unloaded motor. I will have to go on the road to see that, it is a torque mode after all.			
isolate electricity too	I will add one cable to t	on rubber blocks that supp he case so it can be on the shielding for DC cables and p	
			📝 Quote 🕎 🌠 🍃
D2-12-2018, 02:42 PM			# <u>1870</u> 🕂 Â
arber333 Senior Member Â			Join Date: Dec 2010 Location: Slovenia Posts: 782
🛐 Re: Another homel	brew AC-controller		
	ome pedal travel RPM is re		I could use throttle and reach f i reduced throttle inverter offered
		graphs of throttle travel vs hing is just so easy now	s motor speed. Sure enough over
	330V as i calculate my mo		voltage adapting parameters. So i nen my motor is turning under full
This must have been worked.	something inside code th	at was calculating final Hz c	output. When i satisfied input it
I didnt go for a drive water inside	I didnt go for a drive though since snow is falling and inverter cover is not done yet. Wouldnt want to get water inside		
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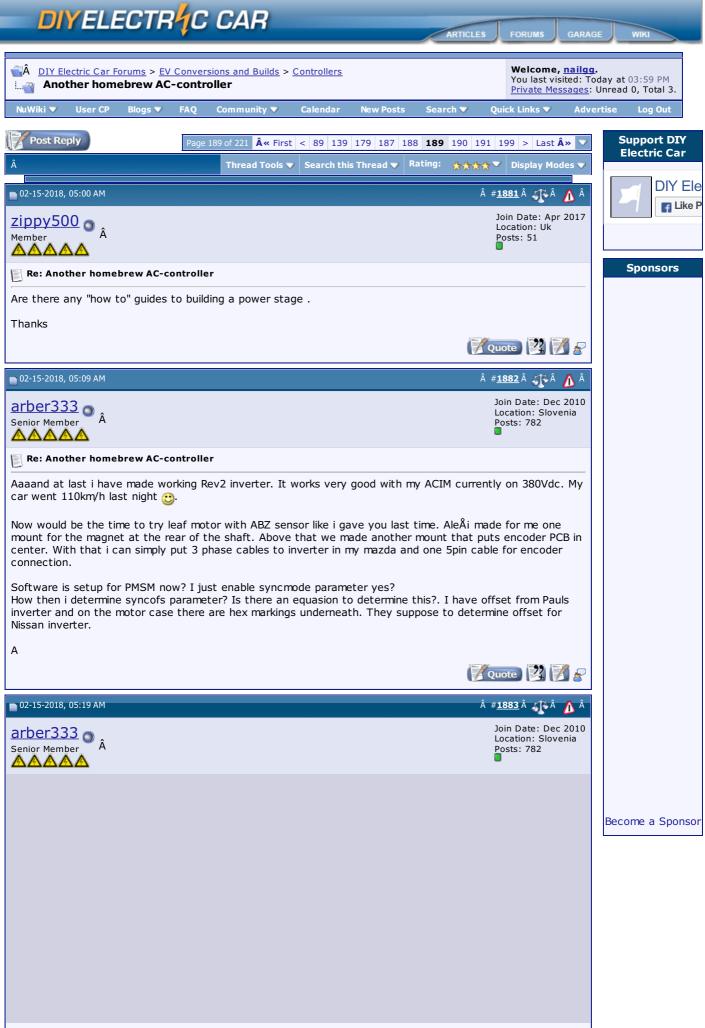






📔 Re: Another homeb	rew AC-controller			
Quote:				
Originally Posted Ok, video is up no				
	nverter teardown Jack Ba re isn't one, I'll make it 👸		s voltage, this is fault feedba	ack"
The Leaf inverter board should fit in	offers a lot of space for n. I don't think I'll make a	kidder, inspecting a BMS w control board retrofitting. custom logic board, mayb sync motor running reliably	even the 2-story through ho e a simple adapter board	ole
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options. Since my ampera inve 3V3 signal directly (in Connecting current se you could include one	erter driver board works w verted) adding pullup to s ensors to available slots.	rith 5V signal. I could just r 5V. The way i see this i cou I would have to use additic ors in your code. Interface	ainboard directly. Gives us gr nake an adapter board and su uld use V3 sensor board direc nal temperature sensor, but even has fault line, but i hav	upply tly. maybe
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Quote:

Originally Posted by $zippy500 \ge$ Are there any "how to" guides to building a power stage .

Thanks

Check this: http://www.instructables.com/id/200k...-Electric-Car/

this:

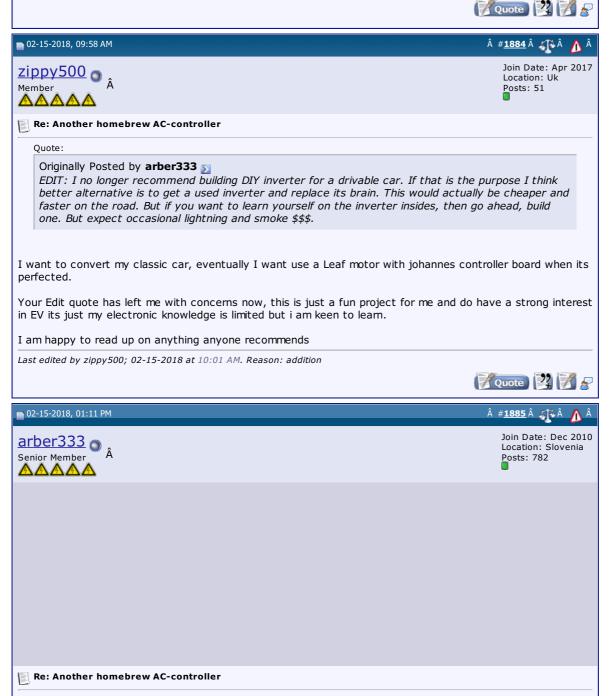
http://johanneshuebner.com/quickcms/...er-kit,10.html

or this: https://endless-sphere.com/forums/vi...p?f=30&t=57877

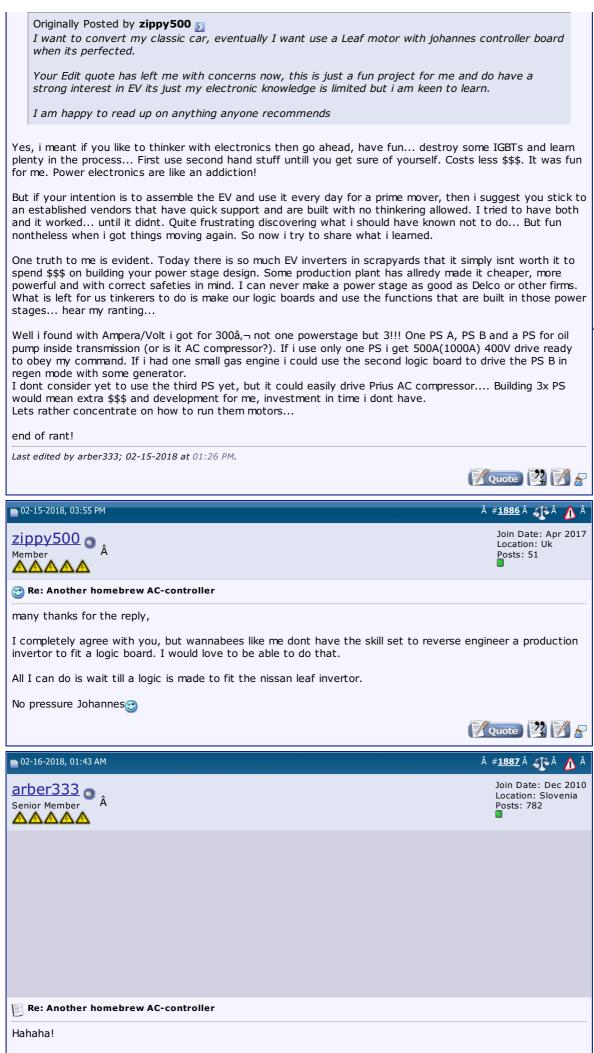
If you can read schematic, i suggest you buy one honda IMA inverter or Prius inverter dissassemble it and trace its functions. They are relatively cheap and can be controlled with different interfaces. You have idea what motor to run with it?

EDIT: I no longer recommend building DIY inverter for a drivable car. If that is the purpose I think better alternative is to get a used inverter and replace its brain. This would actually be cheaper and faster on the road. But if you want to learn yourself on the inverter insides, then go ahead, build one. But expect occasional lightning and smoke \$\$\$.

Last edited by arber333; 02-15-2018 at 07:44 AM.



Quote:



I just saw Daul Holmes made dual logic hoard for Amnera/Volt inverter! Creat minds do think alike. I may try

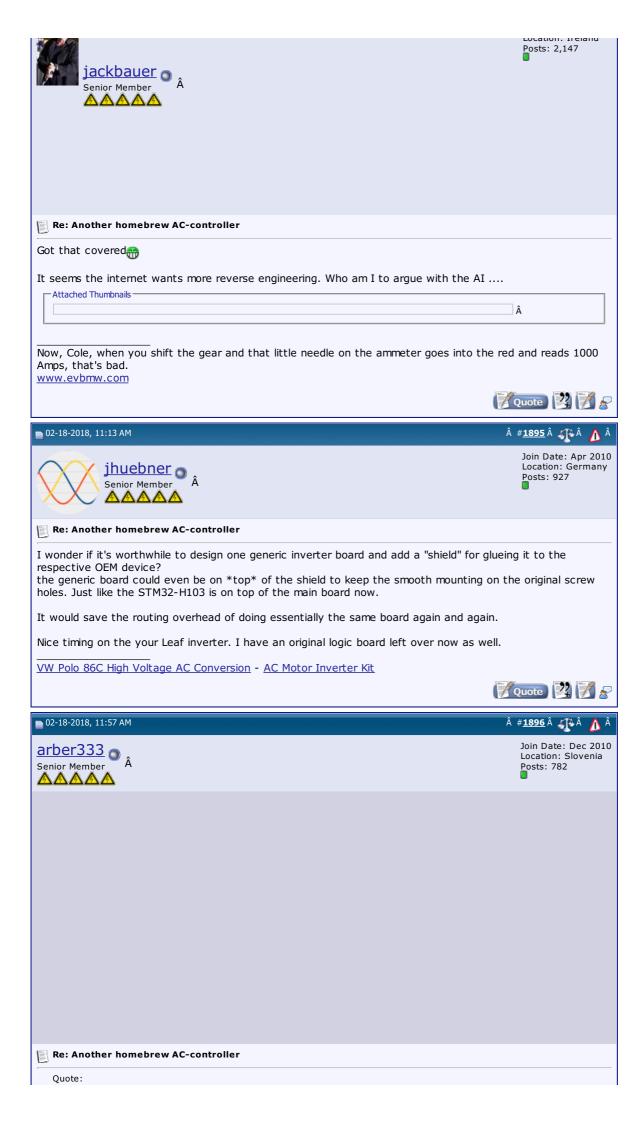


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Originally Posted by jhuebner <i>I wonder if it's worthwhile to design one generic inverter board and</i> <i>the respective OEM device?</i>	add a "shield" for glueing it to
the generic board could even be on *top* of the shield to keep the screw holes. Just like the STM32-H103 is on top of the main board	
It would save the routing overhead of doing essentially the same b	oard again and again.
Nice timing on the your Leaf inverter. I have an original logic board	l left over now as well.
I tried to fit your main board to Ampera inverter. It has a nice alu shield holes for nylon studs. It should work with components as they are, thou interface for driver section to pullup signals to 5V. Now I just need some 40V of batteries to drive the power section.	
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02-18-2018, 01:19 PM	# <u>1897</u> 🕂 🔥 Â
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782
Re: Another homebrew AC-controller	
Boards setup, I will wire drivers and current sensors and i still have to n on 5V command. Currently mainboard outputs 3V3. I dont want to relea But height is a problem! PSU capacitor and both relays are quite high it would probably require an extention. Maybe 3D printed border from AB should keep moisture away. Or custom board would have to be made wi profile.	se smoke. above and lid cannot be closed. Hm 35 with 2x O-ring grooves. That
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D2-20-2018, 10:17 AM	â # <u>1898</u> â 🕂 â \Lambda â
	Join Date: Apr 2010 Location: Germany Posts: 927
Re: Another homebrew AC-controller	
First resolver experiments today. Got a resolver to digital Eval board fro	
Thist resolver experiments today. Got a resolver to digital Eval board no	m Damien - yay thanks!

Tried the SPI interface with my analog discovery and after figuring out the basics, that went well i.e. I gol nice and stable angular reading. I noticed the resolver measures 2 rotations on 1 real shaft rotation.	t a
Next I tried hooking up the inverter with ABZ. I do get a reading up to 5Hz which equals 2048*5=10kHz on the encoder input. Any faster than that and it cuts out because of the RC low pass. Will remove that for t	
next try. I also consider using the SPI bus instead, because ST surprisingly put the SPI pins on the same as the	
encoder input 😳 The encoder chip has 6 signals of which 2 can be constant and 2 are equivalent	
 CLK - clock SAMPLE - prepare data to be put on the bus 	
 CS (chip select) - can always be low RD - Put data on bus 	
 RDVEL (select angle or velocity) - can always be high SO - serial output 	
There's supposed to be a delay between SAMPLE and RD but it worked perfectly when they were pulled low together.	
So basically the A-channel is SPI data in (SO), the B-channel is SPI data out and the Z-channel can be us for the SAMPLE/RD signal. Only issue being, that I will have to emulate the clock with SPI data out and wil read every bit twice. So a bit pattern of 1 0 0 1 would turn into 11 00 00 11.	
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<u>VW Polo 86C High Voltage AC Conversion</u> - <u>AC Motor Inverter Kit</u>	
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n 02-20-2018, 10:45 AM Â # <u>1899</u> Â 🕂 Â	ΔÂ
Join Date: Jan 2 Location: Irelan Destru 2 147	
Senior Member Â A A A A A	
Re: Another homebrew AC-controller	
Wow thats quick work	
Now, Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 100 Amps, that's bad. www.evbmw.com	D
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■ 02-23-2018, 05:00 AM Â # <u>1900</u> Â 🐢 Â	♪ Â
arber333 Join Date: Dec 2 Senior Member Â A A A A Posts: 782	
I≂ Re: Another homebrew AC-controller	
Re: Another homebrew AC-controller	

unscrew the nut and measure it. Mine is M12. AleĂi and I have made this magnet holder so it can be setup in center and adjusted for height. Then you torque the small Allen bolt on the side, which locks the threads in place.								
		der PCB plate to keep it i everything fits. Can you t						
https://leafdriveblog.wo	ordpress.com/2016/11/1	6/encoder/						
should work ABZ, which		and make a fit for the e ould like to use. So my m						
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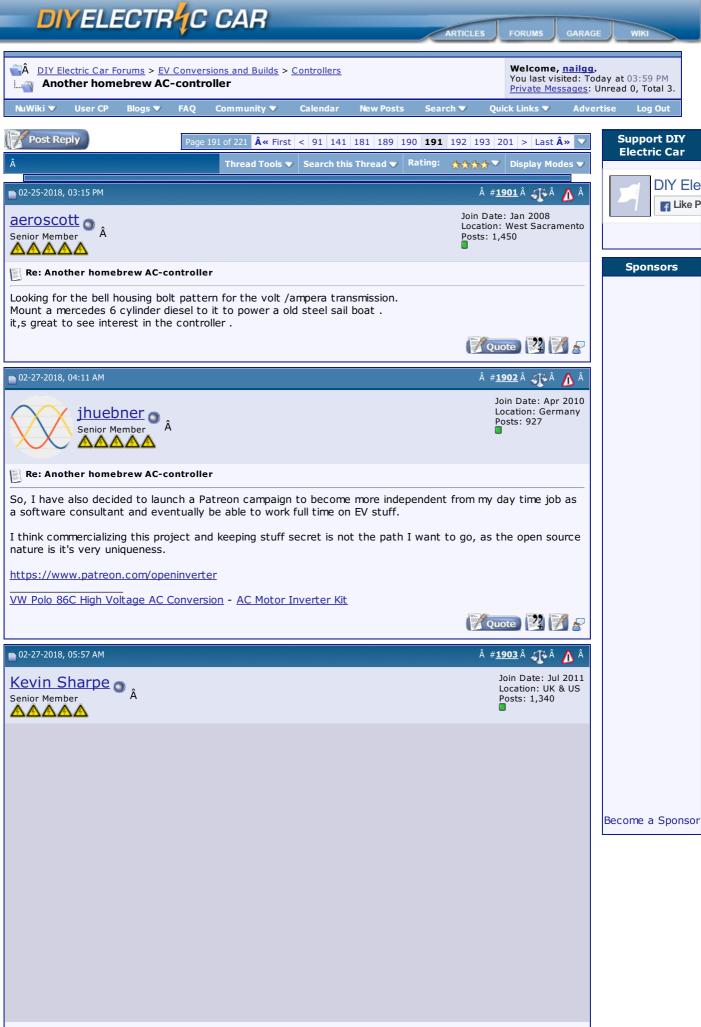
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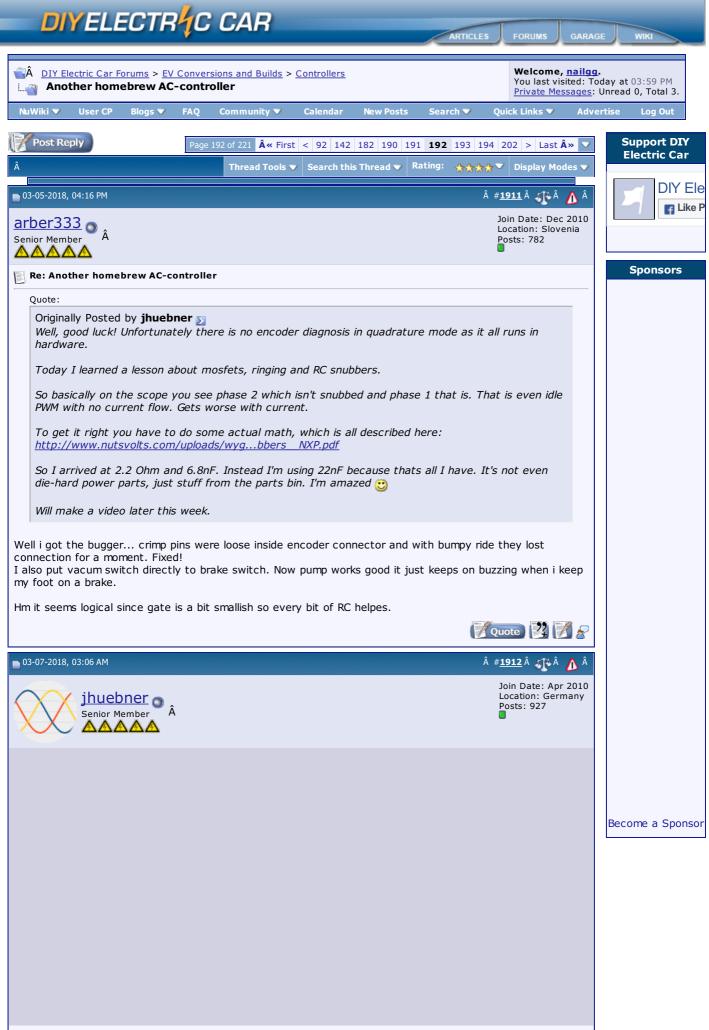


	Happened to me wi Re-aligned it and pr		isaligned. Like the IR bear	n barely shone through the hole.
Iw Ic Ne:	ill check sensor gap an also check if whe	though. It is said senso el is propperly fastened	ickup probe. So IR diode c r can read trough up to 2 by M6 bolts. It could slip ge. Like 12V instead of 5V	mm gap.
tn>	for ideas Johannes			
А				
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0	3-05-2018, 03:52 PM			â # <u>1910</u> â 🕂 â 🧥 â
5	jhuebno Senior Mem			Join Date: Apr 2010 Location: Germany Posts: 927
	Re: Another homebre	w AC-controller		
We	II, good luck! Unfortu	inately there is no enco	der diagnosis in quadratur	re mode as it all runs in hardware.
То	day I learned a lesso	n about mosfets, ringing	g and RC snubbers.	
		pe you see phase 2 whi ets worse with current.	ch isn't snubbed and phas	e 1 that is. That is even idle PWM
		e to do some actual mat om/uploads/wygbber	h, which is all described h <u>s_NXP.pdf</u>	nere:
		and 6.8nF. Instead I'm from the parts bin. I'm a		s all I have. It's not even die-hard
Wil	l make a video later	this week.		
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<u>V</u> W	Polo 86C High Volta	ge AC Conversion - AC	<u>Motor Inverter Kit</u>	
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As mentioned on the i3 thread I'm trying to interface resolvers directly. Some good resources have been posted there already.

So here is the plan

- 1. Generate a square wave at pwmfrq/2
- 2. Make a sine from it by 3-pole low-pass filtering
- 3. Amplify it with a cheap LM386 audio amp -> thats our excitation
- 4. On the rising edge of our self-generated square, start a timer (because of phase shift)
- 5. When timer times out, do the two injected conversion of sin and cos signal
- 6. use atan2(cos,sin) function to determine the angle

So I will use the existing encoder pins again, PD2 will generate the square, PA6 and 7 read the feedback. The signal conditioning will sit on a bread board but can be easily integrated onto the main board. Extra part cost is like 50 cents.

Attached Thumbnails Â VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit Quote 🕺 📝 🖉 #<u>1913</u>Â 🌆 Â 🗖 03-07-2018, 01:07 PM arber333 O Â Join Date: Dec 2010 Location: Slovenia Senior Member <u>P</u>osts: 782 AAAAA Re: Another homebrew AC-controller Quote: Originally Posted by jhuebner 5 As mentioned on the i3 thread I'm trying to interface resolvers directly. Some good resources have been posted there already. So here is the plan 1. Generate a square wave at pwmfrq/2 2. Make a sine from it by 3-pole low-pass filtering 3. Amplify it with a cheap LM386 audio amp -> thats our excitation 4. On the rising edge of our self-generated square, start a timer (because of phase shift) 5. When timer times out, do the two injected conversion of sin and cos signal 6. use atan2(cos,sin) function to determine the angle So I will use the existing encoder pins again, PD2 will generate the square, PA6 and 7 read the feedback. The signal conditioning will sit on a bread board but can be easily integrated onto the main board. Extra part cost is like 50 cents. Hm... i can see the appeal here. But how do you think you will connect the outputs? Dont forget sin/cos resolver has 6x wires. 2x excitation, 2x sin, 2x cos. Will you use diode bridge and rectify sin/cos return signal? Or do you wish to sense only sin and will just generate 90deg cos in the code? А Quote 🕺 📝 🔎 ■ 03-07-2018, 03:<u>03</u> PM #**1914** Â 🌆 Â ΛÂ Join Date: Apr 2010 jhuebner 💿 _Â Location: Germany Posts: 927 Senior Member Re: Another homebrew AC-controller 2x excitation goes to GND and amplifier output - capacitor takes care of removing the DC component 2x sin and 2x cos goes to 1.65V and ADC input (1.65 via resistor divider) both sin and cos are sensed and serve as input to atan2 function VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit 🛛 🛛 Quote 🕎 🏹 🔎 #**1915** Â 🎢 Â 🗖 03-08-2018, 05:03 PM Λ Join Date: Apr 2010

jhuebner Senior Member Â	Location: Germany Posts: 927
Re: Another homebrew AC-controller	
First cut done, software resolver works 🙂	
What you might be able to see in my creative chaos is the 3-pole low pass filt under my table (it goes to my Yamaha amplifier). Then you see the Nissan Lea Yamaha 8V peak-to-peak. This results in about 1V peak-to-peak using my too The neg outputs are pulled to about 1.4V using 2 series elcaps and the pos ou filtered and fed to the ADC.	f resolver being excited by the I socket 🤓
ADC timing is critical to get a good SNR. You want to hit the peak of your genuse of the ADCs dynamic range. So far the jitter is about +/-0.5Å $^{\rm o}$.	erated sine wave to make good
Therefor the resolver routine starts out with an offset calibration while excitat output pin high and starts the timer. The timer then triggers the ADC after sor next cycle the pin is pulled low, values are read and the angle calculated.	
Currently doing this at 5kHz resulting in 2.5kHz excitation. It will probably go w on.	with thw PWM frequency later
Attached Thumbnails	Â
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VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
	Quote 😰 🎽 🔗
■ 03-09-2018, 02:07 PM	â # <u>1916</u> â 🐠 â <u>۸</u> â
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782
Re: Another homebrew AC-controller	
You ve done it again! 💮	
I see that in newer leaf motor resolver is much different than in mine. Should be I am ashamed i didnt get far with my Leaf motor since i need my car a lot late motor and connect Leaf motor to my car tomorrow in the evening.	
Untill tomorrow evening then	
A	
	Quote 🕎 💋 🔗
■ 03-09-2018, 02:11 PM	â # <u>1917</u> â 🐠 â <u>۸</u> â
jackbauer Senior Member Â	Join Date: Jan 2008 Location: Ireland Posts: 2,147
Re: Another homebrew AC-controller	
Just be aware the resolver will act as an alternator when its running and the a increase with RPM.	mplitude of the Sin and Cos will
Now, Cole, when you shift the gear and that little needle on the ammeter goes Amps, that's bad. www.evbmw.com	s into the red and reads 1000
	📝 Quote 🕎 📝 🎤
■ 03-14-2018, 10:13 PM	# <u>1918</u> ∰ Â
Onegreenev Senior Member	Join Date: May 2012 Location: Marysville, CA Posts: 3,796

E Re: Another homebrew AC-controller	
Revision 3 Current Sensor Board. Does anyone have an image of the main board that one that is? I want to see how best to connect up the thermal sensor on this board. finally done. I will be looking into the newest current sensor boards but for now I nee connected up. Its been busy at work studying for my CT National Certification Test April. Once done I can once again get involved with my project using the inverter.	Looks like I got the rest ed to get this one
Question, one of the resistors had the coating chip a bit and left a bare metal spot. thing to coat it with that will be durable. I don't want to leave it exposed. The light top.	
Thanks for everyones help.	
Pete 🙂	
Attached Thumbnails	
	Â Â Â Â
Change comes, one conversion at a time. <u>http://onegreenev.blogspot.com/</u>	
https://www.youtube.com/user/onegreenev/videos	
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■ 03-15-2018, 01:54 AM	â # <u>1919</u> â 🐢â <u> </u> Â
	Join Date: Apr 2010
	Location: Germany Posts: 927
Re: Another homebrew AC-controller	
This is the best I could find, it's now buried in the car. Two of your resistors will look different as the are 82k instead of 100k for bigger curr	rent range.
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VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
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■ 03-15-2018, 08:58 AM	# <u>1920</u> ∡∰ <u>∧</u> Â
, ihushnar	Join Date: Apr 2010
jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
jhuebner Senior Member Â	Location: Germany
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	Location: Germany
Re: Another homebrew AC-controller	Location: Germany
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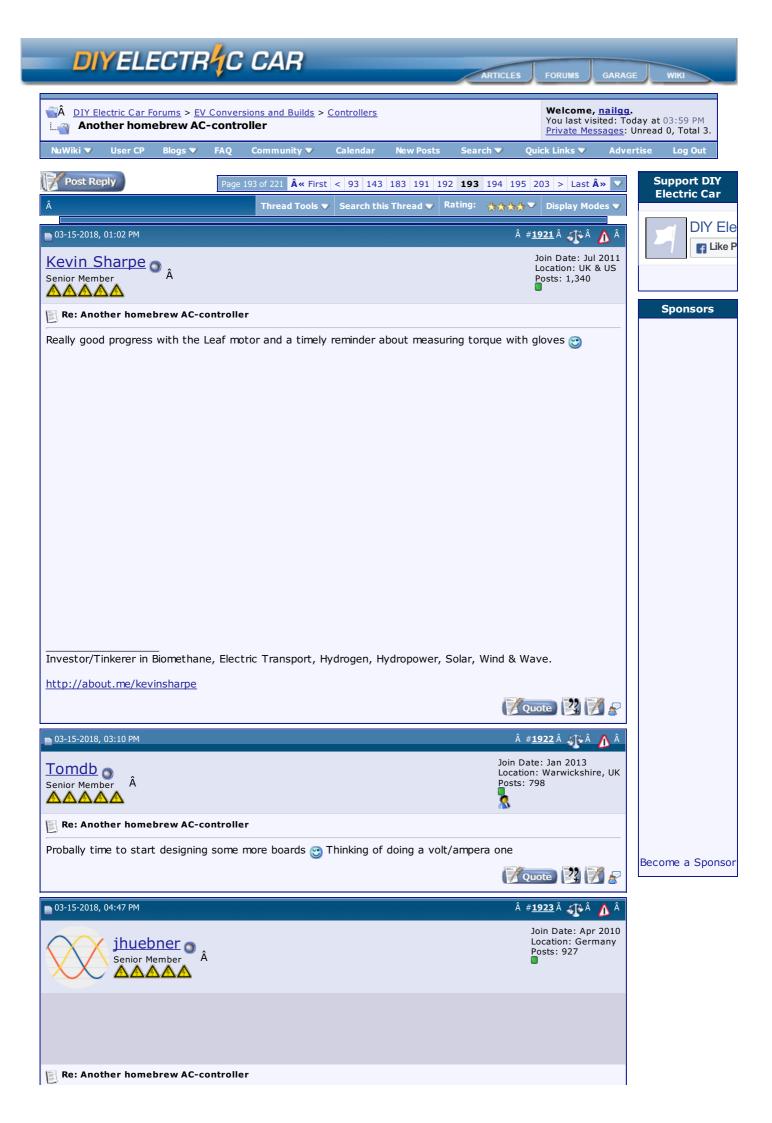
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Post Reply	Page 192 of 221	« First <	92 142	182 190) 191	192	193	194 20)2 >	Last Â>	
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That was amazing J! Even more the theory of voltage control.



		' I will see which motor I t. Unfortunately the HEF		e to couple to. I might use a	
Mayt Hm If sha groov Then any i missa	be clutch disk coupler? can you measure and aft is splined like with m ve. That will give me en we can make a direct	l draw a sketch of a Lea ny motor i need to know nough data to check amo coupler for the ACIM mo	f motor input shaft? I the diameter, numbe ongst used car clutch tor. That way we wo	o slack in control loop that w Do you have a vernier caliper? r of splines and depth of splin disks. uld have partly flexible coupli : DIY setup will allways have	e ng so
A				Quote	2
P	Post Reply	Page 193 of 221 « Fir	rst < 93 143 183 191	192 193 194 195 203 > La	ist » 🔽
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	Message: <u>A</u> <u>B</u> <u>U</u> <u>A</u> <u></u> Please click one of th Options Quote message in re	e Quick Reply icons in th	ne posts above to ac	tivate Quick Reply.]
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Re: Another homebrew AC-controller

Ok will check dimensions tomorrow.

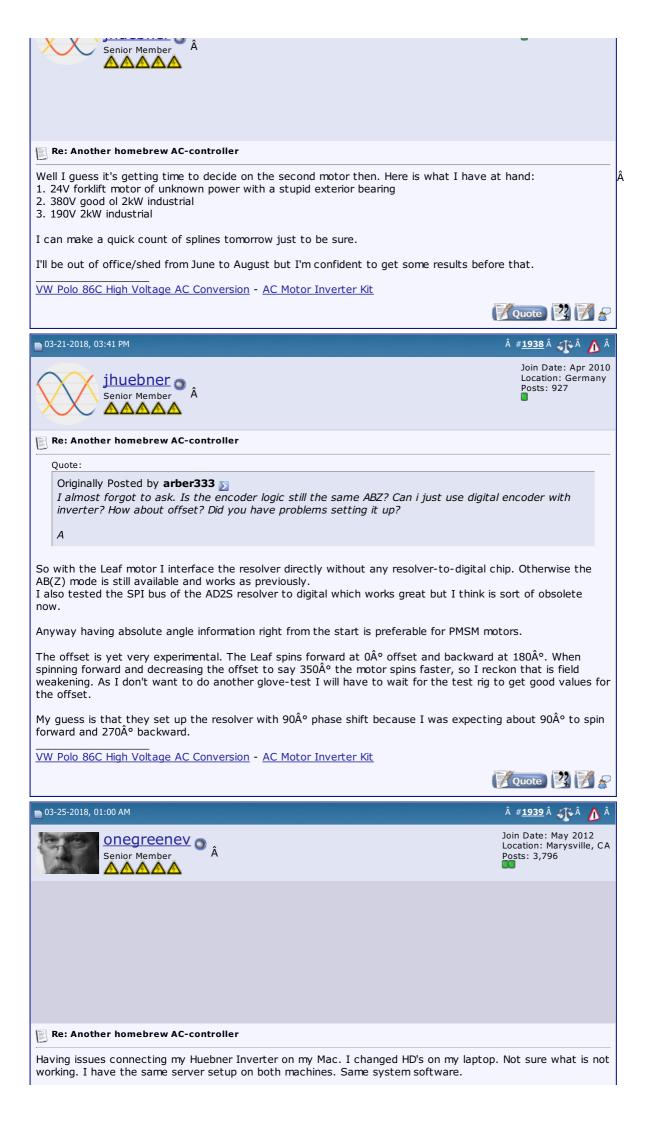
Today I tried regen using my Makita and 17mm tool socket 😳 It seems my voltage theory holds true. Also spinning backwards and forward is really easy, just shift the field by 180Ű. So, 4-quadrant control in place No video yet, but if weather permits I'll make one tomorrow.

VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit



🗖 03-21-2018, 03:18 PM #<u>1935</u>Â 🌆 Â arber333 O Â Join Date: Dec 2010 Location: Slovenia Senior Member Posts: 782 Re: Another homebrew AC-controller Quote: Originally Posted by jhuebner 5 Ok will check dimensions tomorrow. Today I tried regen using my Makita and 17mm tool socket 😁 It seems my voltage theory holds true. Also spinning backwards and forward is really easy, just shift the field by 180°. So, 4quadrant control in place 💮 No video yet, but if weather permits I'll make one tomorrow. Neat idea using power tool, though you can only rev so much. By hand human can hold/clench cca 100W worth. 200W if they would use their legs... Ales said he can make the coupler, I can provide the spline part of the clutch. We can trust Paul judjment or you can tell me: 1. How much splines on Leaf motor 2. What is the diameter of Leaf motor shaft across the splines Next dimensions of ACIM motor 3. What is the diameter of ACIM motor shaft? 4. Length of ACIM shaft protruding from motor 5. Dimension of ACIM shaft key ("nutkeil" in german) Measurement should be accurate to 0.1mm! Caliper is a must!!!! Your job after would be to effectively setup two motors one against the other in center with enough precision. Probably you could effectively use wooden construction with some shims. А 📝 Quote 🕎 📝 💂 #**1936** Â 🎢 Â 🗖 03-21-2018, 03:23 PM ΔÂ arber333 O Â Join Date: Dec 2010 Location: Slovenia Senior Member Posts: 782 AAAAARe: Another homebrew AC-controller I almost forgot to ask. Is the encoder logic still the same ABZ? Can i just use digital encoder with inverter? How about offset? Did you have problems setting it up? А Quote 🕎 🏹 🔎 #<u>1937</u>Â 🎢 Â 🗥 Â 🗖 03-21-2018, 03:34 PM





Been awhile since I hav	ve fired up this little thin	g. Cleaned up the wiring	so it is nice and clean.	
	d I even checked to see	-	er quick bump. No continuc bing out when I it did bump	
I'll keep pecking away	but may need some assis	stance getting around th	is Web interface.	
	-	es, one conversion at a t negreenev.blogspot.com/		
	https://www.yout	tube.com/user/onegreene	<u>ev/videos</u>	
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■ 03-25-2018, 02:10 AM			# 1940 .	🐠 🔥 Â
jackbauer Senior Member	Â		Locati	Date: Jan 2008 ion: Ireland : 2,147
Re: Another homebr	ew AC-controller			
Pete , setup a Raspber	ry Pi for the interface :]	https://github.com/damie	<u>enmaguire/Inverter-WiFi</u>	
Gets rid of a ton of hea	adaches. No more server	needed.		
Now, Cole, when you s Amps, that's bad. www.evbmw.com	hift the gear and that lit	tle needle on the ammet	er goes into the red and re	eads 1000
			Quote	2 🛛 🖉
Post Reply	Page 194 of 221	Â « First < 94 144 184 1	92 193 194 195 196 204	> Last » 🗸
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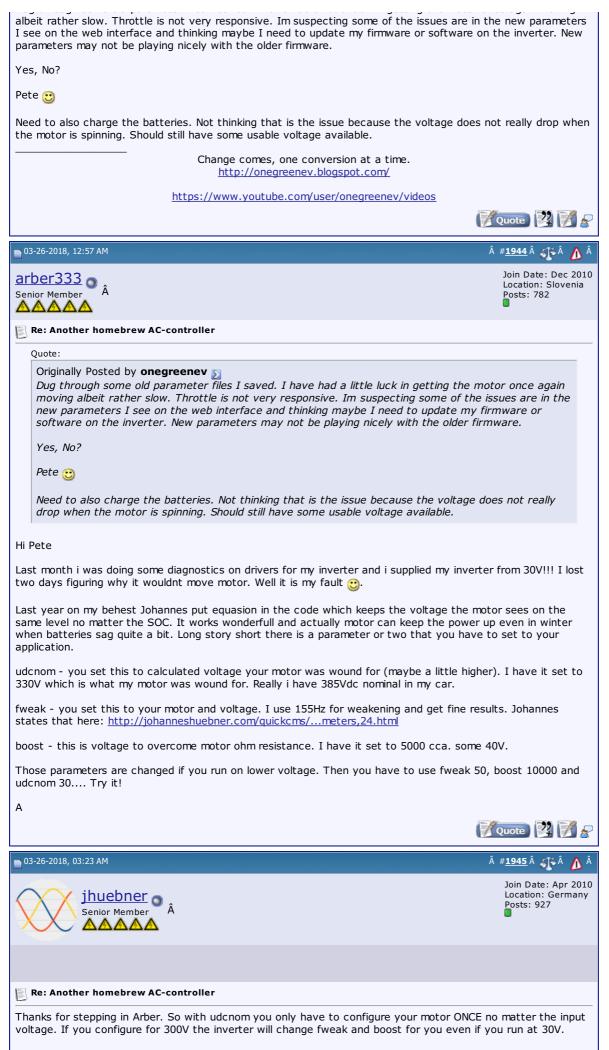
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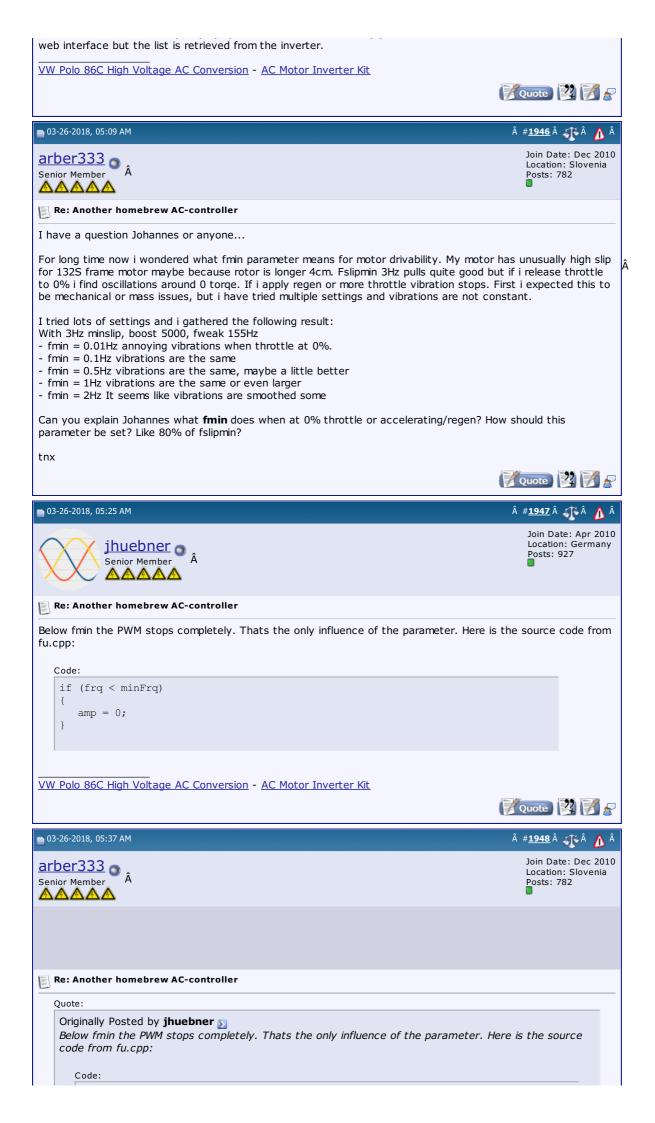
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BTW the web interface only displays parameters that are actually present in the firmware. There is no list in the

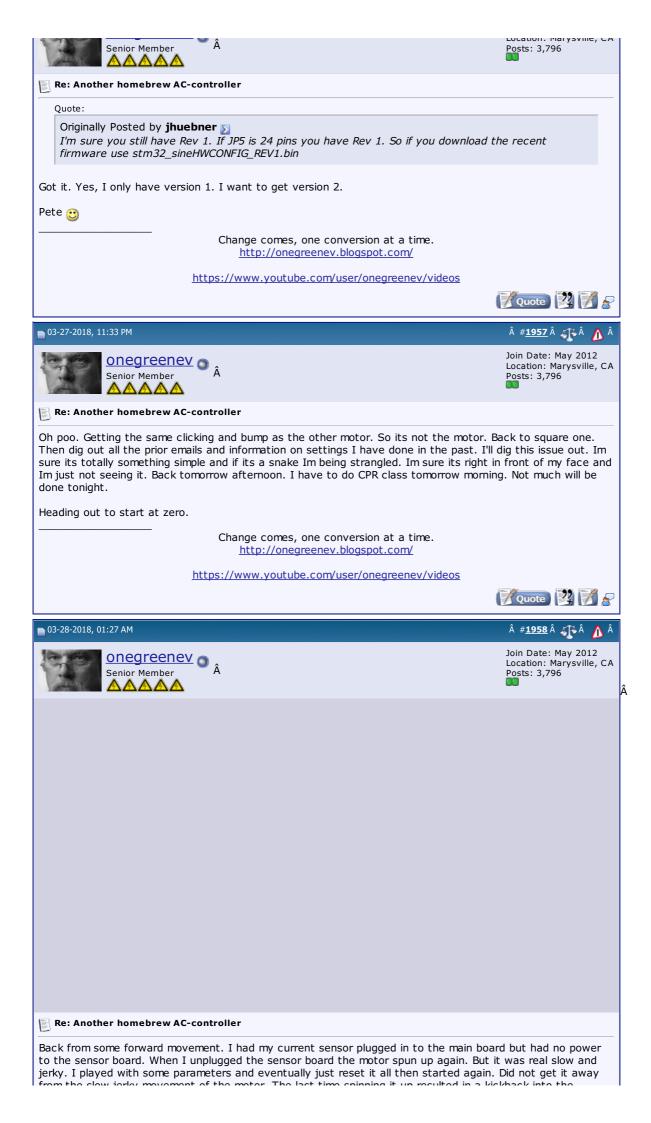


	<pre>if (frq < minFrq) { amp = 0; }</pre>	
How we fslipmi	y would there be higher vibrations with fmin = 0.01Hz than 2 ould you propose i set this? Like i use 2Hz or 2.5Hz or 2.8Hz i? What does the rest of the loop say? It is a PI loop so it s	? Does it matter how is it set within fmin <
A		Vuote 🕎 🎢 🔗
03-26-2	2018, 09:16 AM	# <u>1949</u> 🐠 🧄
\bigotimes	jhuebner Senior Member Â	Join Date: Apr 2010 Location: Germany Posts: 927
Re:	Another homebrew AC-controller	
	ny fmin < fslipmin is fine. is no PI loop anywhere in the main control so oscillation mus	t originate in some "parasitic" feedback loop
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arber	[333 🙈	Location: Slovenia
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Senior N Quot Quot Ori Yes The fee Hah it s zone. T If not i A	Another homebrew AC-controller te: iginally Posted by jhuebner es any fmin < fslipmin is fine. here is no PI loop anywhere in the main control so oscillation edback loop seems like i was my own damping. Now motor works smooth They are caused by either clutch disk or basket. Should hav i will have to spin motor with basket on and manually balanc	Posts: 782 must originate in some "parasitic" and only vibrations left are in the 3K RPM e this solved by changing clutch disk 180deg. e assembly.
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Senior N A Quot Ori Yes The fee Hah it s zone. T If not i A Share or Face	Another homebrew AC-controller te: iginally Posted by jhuebner seany fmin < fslipmin is fine. here is no PI loop anywhere in the main control so oscillation edback loop seems like i was my own damping. Now motor works smooth They are caused by either clutch disk or basket. Should hav i will have to spin motor with basket on and manually balanc st Reply Page 195 of 221 Â « First < 95 145 r Bookmark this	Posts: 782 must originate in some "parasitic" and only vibrations left are in the 3K RPM e this solved by changing clutch disk 180deg. e assembly. i 185 193 194 195 196 197 205 > Last » V
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Acaded Thurbuls A Boost for 36V should be higher. What is your motor would for? I recommend at least 10000. <th>ווטווו נוופ אטא זפוגא ווטעפוופווג טו נוופ ווטנטו. דוופ ומצג נווופ אטווווווון וג ען ונ</th> <th>פטונפט ווד מ אוכאטמכא ווונט נוופ</th>	ווטווו נוופ אטא זפוגא ווטעפוופווג טו נוופ ווטנטו. דוופ ומצג נווופ אטווווווון וג ען ונ	פטונפט ווד מ אוכאטמכא ווונט נוופ
holdid get the large motor running too as I want to use one of these inverters on the AC-50 that is going intro Nitro of beets. I don't want to use the Curtis controller as its limited in voltage. I want to run this at 156 volts minimum in the vehicle.	opposing direction and a smoked driver board. Smoked real good and one	of the other drivers got pretty hot. I
Richarded Thumbuak A A A A A A A Change comes, one conversion at a time. https://onegreeney.blogspol.com/ Into://onegreeney.blogspol.com/ Conversion at a time. http://onegreeney.blogspol.com/ Conversion at a time. Nuin Date: Dott Conversion at a time. http://www.youtube.com/user/onegreeney/videos Conversion at a time. Conversion at a time. Nuin Date: Dott Conversion at a time. Nuin Date: Dott Conversion at a time. Nuin Date: Dott Nuin Date: Do	should get the large motor running too as I want to use one of these inve	erters on the AC-50 that is going into
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A Decision Memory A Re: Another homebrew AC-controller Well you can certainly run your motor with higher voltage. You can run it at 200V if you like. You just have to be to parameters so inverter can adapt. f you posted your parameters there are some errors there 1. boost for 36V should be ligher. What is your motor wound for? I recommend at least 10000. 2. Frin parameter should be less than slipmin parameter. Lets set it to 0.8 3. what are the pole pairs? 4. Opcome is 500 fthen 3. Other are 100V 3. UDCrim = 100V 4. 1926 A C A 1 1 2 0 A 1 1 2 0 A 1 1 1 2 0 1 1 1 1 1 1 1 1 1 1	■ 03-28-2018, 03:45 AM	# <u>1959</u> 🏰 🔥 Â
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OS-28-2018, 05:12 AM	7. UDCmin = 100V 8. UCDsw = 120V 9. UDCmax = 160V	
03-28-2018, 05:12 AM Â # 1960 Â C Â A Orber333 A Senior Member Â Â Posts: 782 Osts: 782 Posts: 782 Senior Member Â A # 1960 Â C Â A A # 1960 Â C Â A Benior Member Â A # 1960 Â C Â A Benior Member Â Benior Member Benior Member Council Member Benior Member Council Member Benior Member Council Member	A	
Join Date: Dec 201 Join Date: Dec 201 Location: Slovenia Posts: 782 Posts: 782 <td></td> <td>Quote 🕎 📝 S</td>		Quote 🕎 📝 S
Re: Another homebrew AC-controller You still use old driver boards. They like to go up in smoke. decided they are good to try and build the system, but really to drive the car on long term you need something better.	03-28-2018, 05:12 AM	â # <u>1960</u> â 🐠 â 🧥 â
You still use old driver boards. They like to go up in smoke. decided they are good to try and build the system, but really to drive the car on long term you need something better.	arber333 Senior Member Â	
You still use old driver boards. They like to go up in smoke. decided they are good to try and build the system, but really to drive the car on long term you need something better.		
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decided they are good to try and build the system, but really to drive the car on long term you need comething better.	Re: Another homebrew AC-controller	
t is why i built my own interface board and i am using Slower 22 drivers supplied from 151/24 resultion. I and	You still use old driver boards. They like to go up in smoke. I decided they are good to try and build the system, but really to drive th something better.	ne car on long term you need
I S WORLDWIN OW OWOLDDEDALE ODALD AND LADDEDD SVOGE STOROGE CONDUCTION ISU OF FORDISTAP LAND	It is why i huilt my own interface board and i am using Slovor 22 drivers of	supplied from 151/3A regulator. Last

	and Ethink it offers best of	live and protection for the	nev.						
I did have to set unu	sualy high dead time betw	een pulses on encoder. B	ut they also offer hardware						
protection from shoothrough. I will add here BOM and some instructions, not that there is anything different from Skyper manual.									
I will add here BOM a	nd some instructions, not	that there is anything diff	erent from Skyper manual.						
Well since i can drive	pretty good now i can sho	ow my product here.							
It is revision 1 and i f	ound some small errors on	it, but it does not impare	the basic function.						
The greatest error is that i assumed skyper use positive signal to drive fault output and now i cant signal main board to stop PWM. No matter since all boards are linked together and if one stops other are stopped also.									
Cas attachment us	ally it is a way file and as a	taina anykawa awal daning (
change it for upload.	ally it is a .rar file and con	tains gerbers and design i	file to make interface board. I ha	id to					
EDIT: I will start my	own github for projects like	e this							
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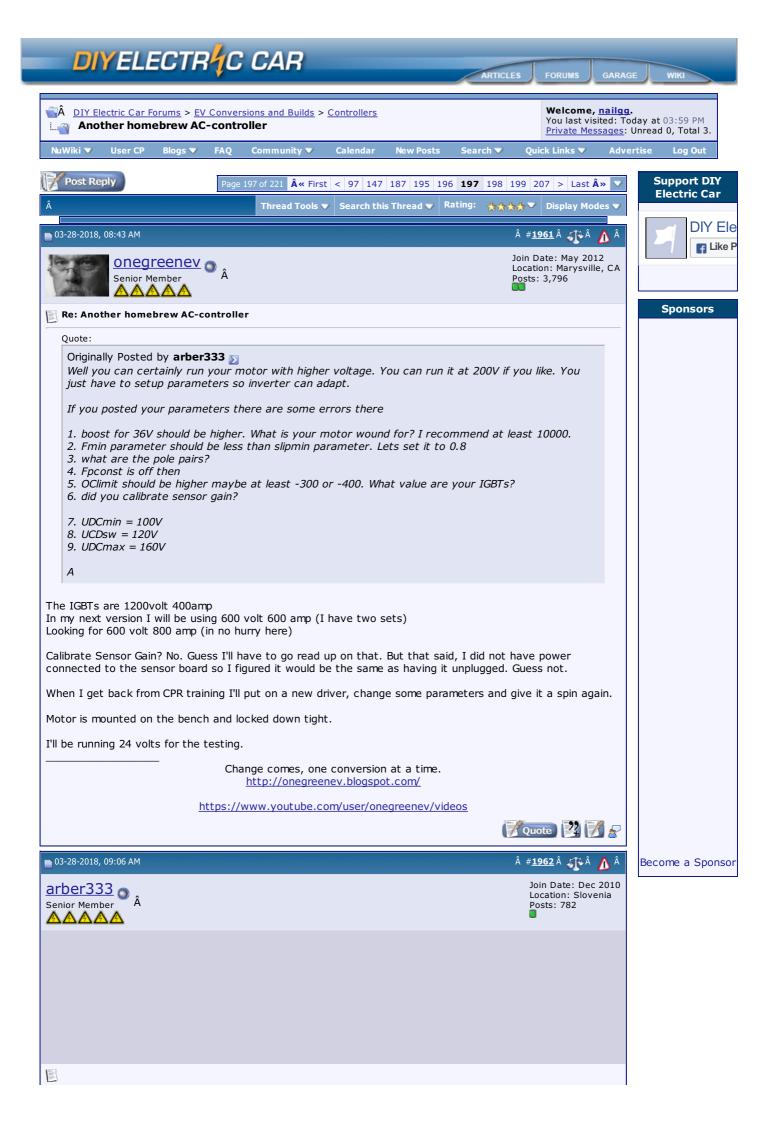
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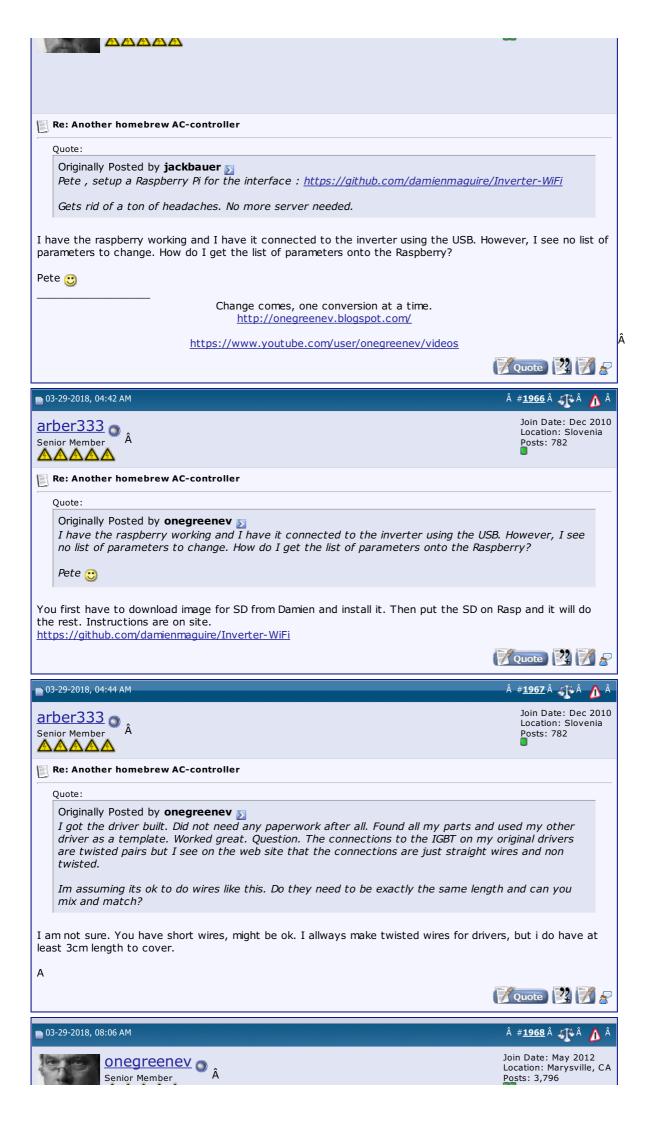
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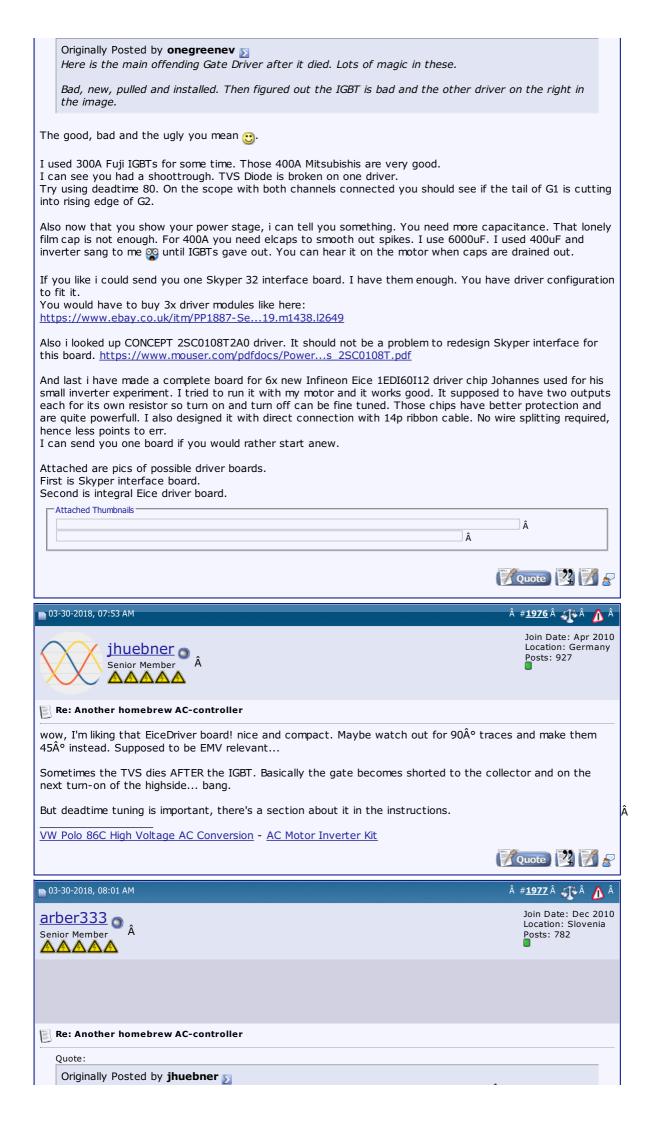
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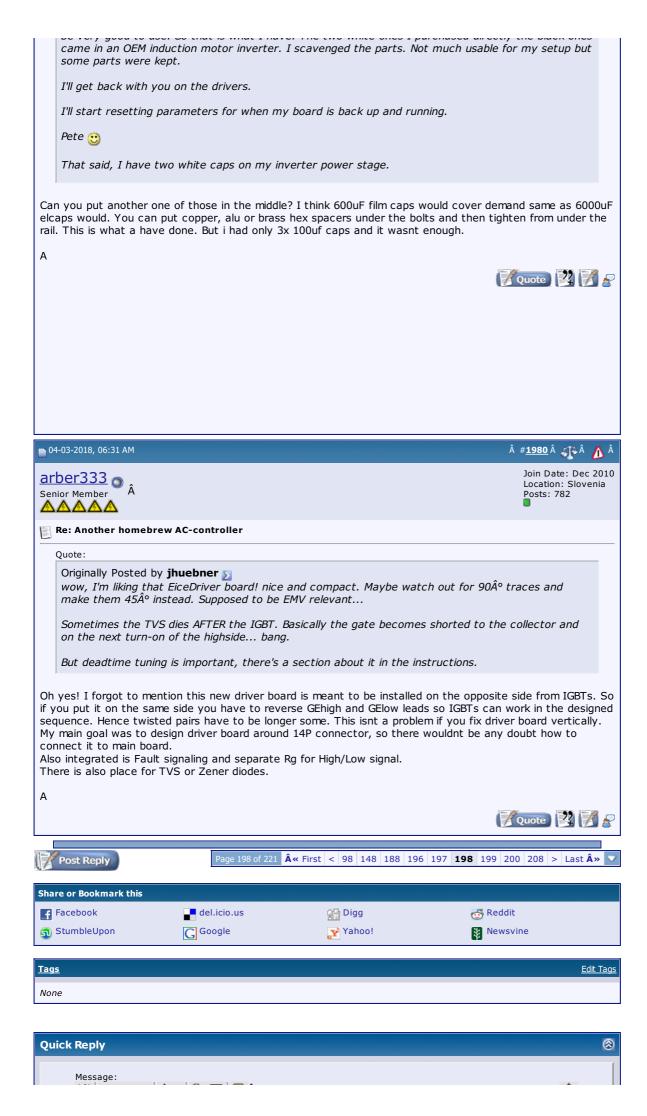
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Modules on the way. What other IGBT modules are a good choice for these inverters?				
Change comes, one conversion at a time. <u>http://onegreenev.blogspot.com/</u>				
https://www.youtube.com/user/onegreenev/videos				
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■ 03-29-2018, 09:09 PM	â # <u>1974</u> â 🐠 â 🧴			
A A A	Join Date: May 2012 Location: Marysville, CA Posts: 3,796			
Re: Another homebrew AC-controller				
Here is the main offending Gate Driver after it died. Lots of magic in these.				
Bad, new, pulled and installed. Then figured out the IGBT is bad and the other dr image.	iver on the right in the			
Attached Thumbnails	Â			
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Change comes, one conversion at a time. <u>http://onegreenev.blogspot.com/</u>				
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arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782			
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Re: Another homebrew AC-controller

Arrrrg, Bout ready to bail on this project. Put in three new IGBT modules, two new driver boards and pulled out the O-Scope. I have a singe probe so I can only test with a single instead of the dual channel like was stated in the instructions. No power to the IGBT modules and fired up the inverter. I tested all three drivers. The old driver had strange looking trace on the scope. The first of two drivers I just built had an odd trace and the last driver looked OK. I only say OK but you can help. I then pulled off the probe and probed one of the other drives so I could get a pic of that but when I connected my probe my good, or what I thought was a good board, smoked the DCDC on the driver. So yet another driver dead. Now I have no idea where to start in either fixing this or deciding to just build a whole new inverter and drivers. I have the parts to do that. If I go that route and it does not workout I'll bail out of the project. Just getting too frustrating. I'll give it a go but need help on where to start and how to proceed.

The short video is of the most recent driver board and also the driver board that cooked again.

The trace is off the ETOP. All the outputs looked like this on this board. The other boards did not. This board smoked before I could shoot a short video. It smoked just after finishing this short vid.

Not connected to the IGBT modules.



22 V ...

https://www.youtube.com/user/onegreenev/videos

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■ 04-06-2018, 12:12 AM	â # <u>1987</u> â 🐢 â <u> â</u> â	
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782	Â
Re: Another homebrew AC-controller		
Quote:		
Originally Posted by onegreenev <i>Arrrrg, Bout ready to bail on this project. Put in three new IGBT modules, two ne</i>	ew driver boards and	
pulled out the O-Scope. I have a singe probe so I can only test with a single inst channel like was stated in the instructions. No power to the IGBT modules and fi	ead of the dual	

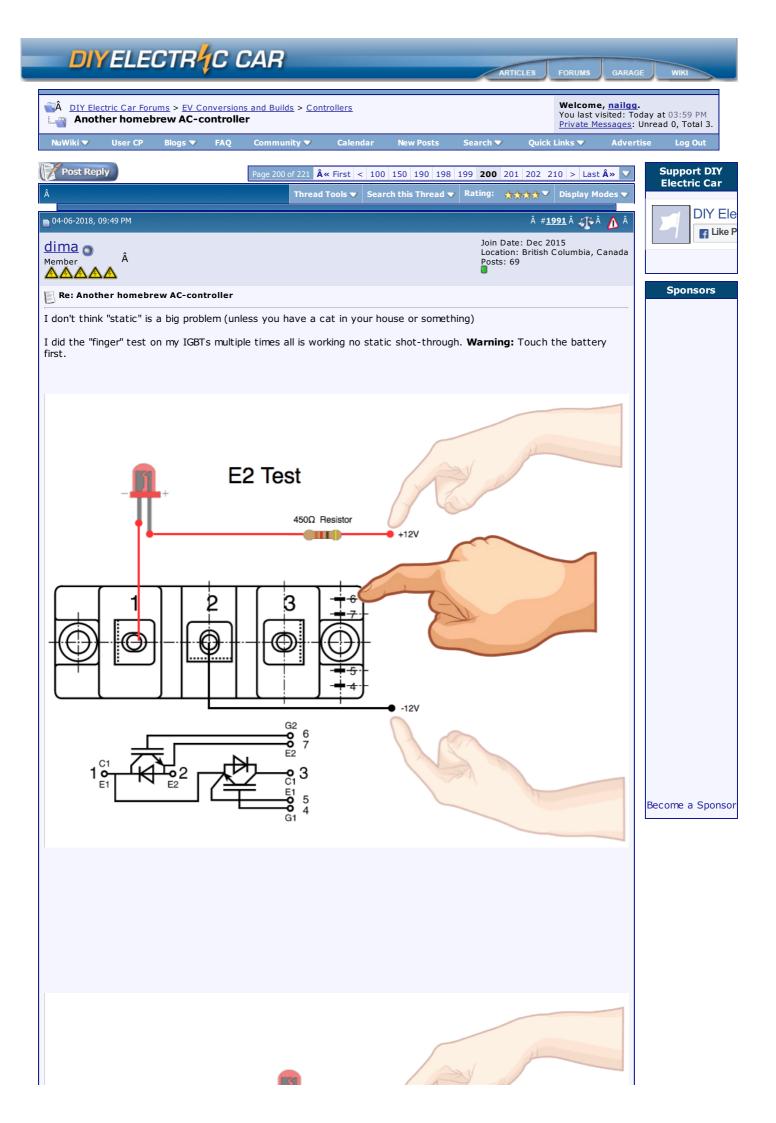
I tested all three drivers. The old driver had strange looking trace on the scope. The first of tw drivers I just built had an odd trace and the last driver looked OK. I only say OK but you can he then pulled off the probe and probed one of the other drives so I could get a pic of that but wi connected my probe my good, or what I thought was a good board, smoked the DCDC on the driver. So yet another driver dead. Now I have no idea where to start in either fixing this or de to just build a whole new inverter and drivers. I have the parts to do that. If I go that route a does not workout I'll bail out of the project. Just getting too frustrating. I'll give it a go but nee help on where to start and how to proceed.	elp. I hen I eciding nd it
The short video is of the most recent driver board and also the driver board that cooked again	1.
The trace is off the ETOP. All the outputs looked like this on this board. The other boards did not this board smoked before I could shoot a short video. It smoked just after finishing this short	
Not connected to the IGBT modules.	
I would say your driver chip was at end of its life. Probably this was caused by last event. Are your still good? They can get zapped by static only touching GE terminals with bare fingers. I wear grour bracelet when working with it. Faulty IGBT gate will almost allways take its driver chip with it. Can you verify by taking off rails and make a light bulb test? It is not conclusive though. Only desat will find partialy blown IGBT.	nded
Which DCDCs do you have? Are they SC proof? If you have DCDCs to spare i can send you a driver board to try. You would have to buy 6x Eice dri I think the single PCB would fit on your driver support perfectly. When you would receive PCB i can provide some instructions still.	ver chips.
Also i recommend you build at least one Damiens driver board with desat. I modified one of his PCBs diagnostic tool so i can connect one IGBT side and quickly identify if IGBT is good. LED shines if Fau active so i know something is wrong. This is always correct, while light bulb test is not always conc would recommend building something like this as a tool. I will check if i have any of Damiens boards for you.	ılt pin is
<u>A</u>	
Last edited by arber333; 04-06-2018 at 12:25 AM.	22 🏹 🔎
04-06-2018, 12:41 AM Â # 1988 Â	<u> </u>
Onegreenev Join Date: M Senior Member Â A A	arysville, CA
Re: Another homebrew AC-controller	
Well, the driver that cooked this time was a virgin driver. Never been hooked up. Can't imagine that expensive IGBT module can get ruined so easily. So I guess no safety features to prevent failure du static. Odd but ok. I would have expected the IGBT modules to be GOOD. I actually expect them to good but maybe not from what you say. If I can't get something going again with my new setup I'll	e to stray STILL be

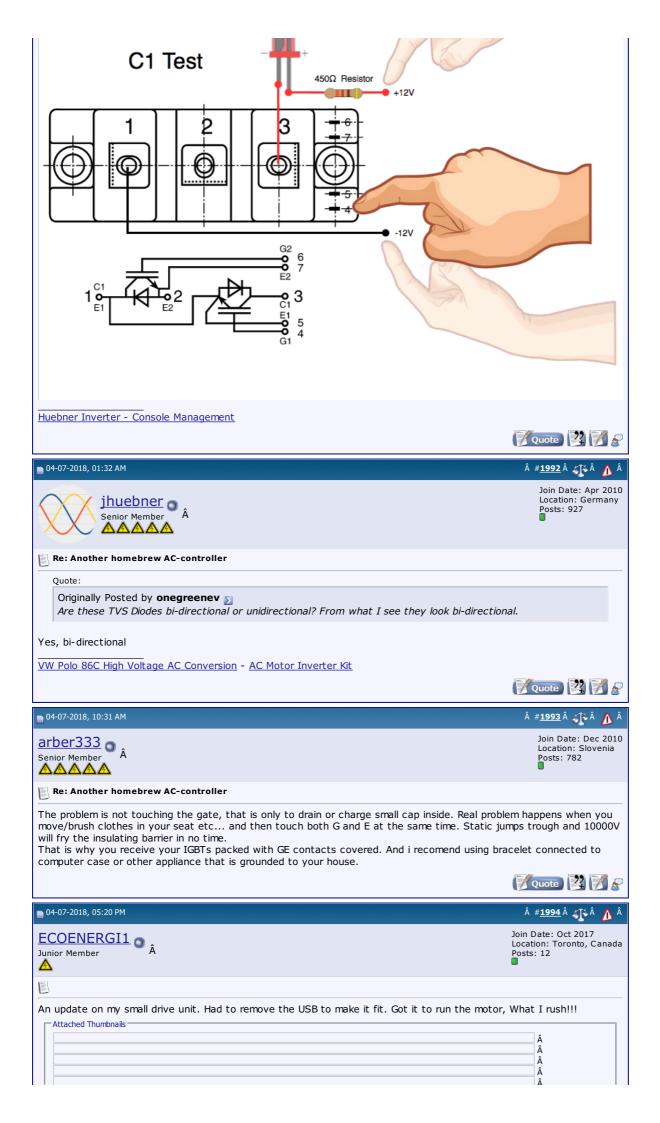
will work pretty much o		o have it done. Not as much fun b not really DIY then. But for non en	
	and the one driver that er and no IGBT connecti	smoked tonight was also a virgin. ions.	And only 12v to the
		es, one conversion at a time. negreenev.blogspot.com/	
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04-06-2018, 01:19 AM			â # <u>1989</u> â 😱 â 💧
jhuebn Senior Merr	Sec. 2		Join Date: Apr 2010 Location: Germany Posts: 927
📃 Re: Another homebr	ew AC-controller		
large IGBTs and 17.6k		ecially the old -15/+15 DC/DC conv though. Ringing don't look too goo see if its gone.	
VW Polo 86C High Volta	age AC Conversion - AC	<u>Motor Inverter Kit</u>	
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04-06-2018, 07:51 PM			# <u>1990</u> 🐢 <u>۸</u> Â
Onegre Senior Merr	eenev O Â		Join Date: May 2012 Location: Marysville, CA Posts: 3,796
🛐 Re: Another homebr	ew AC-controller		
Quote:			
overload with large	ncy are you running at? e IGBTs and 17.6kHz. 8.8	Especially the old -15/+15 DC/DC 8kHz should be ok though. Ringing diode once you're up again to see	don't look too good
Are these TVS Diodes	bi-directional or unidirec	tional? From what I see they look	bi-directional.
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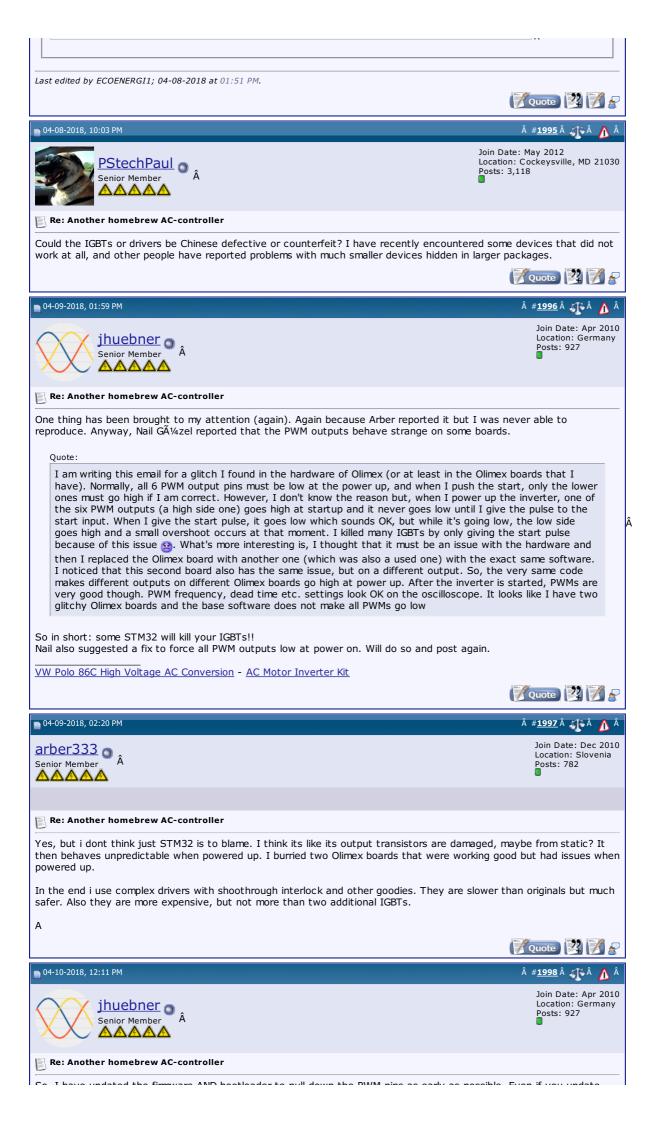
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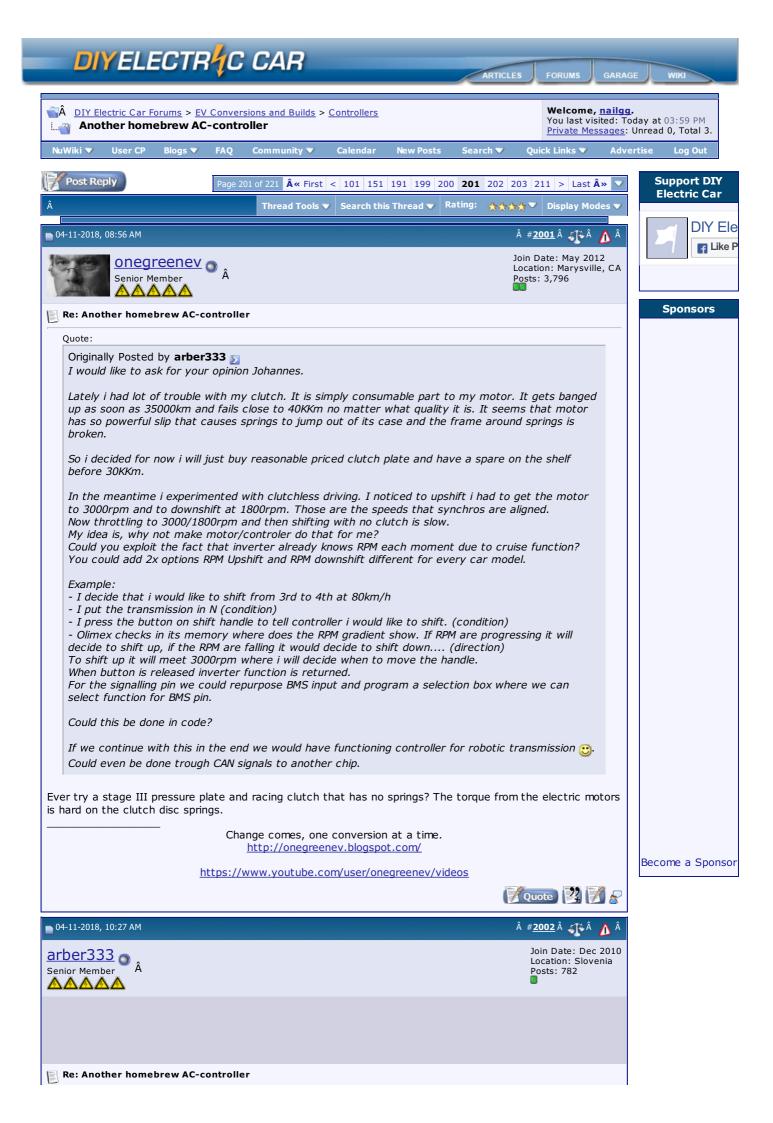
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📔 Re: Another homebrew	AC-controller		
Hi arber333			
I can ask what you set up a build vlog.	you have.What ca	r do you have. what electr	ic motor are you using. did you make
thanks			
			📝 Quote 🕎 🃝 🎤
04-14-2018, 03:08 PM			â # <u>2010</u> â 🐢 â 🍌 â
arber333 Senior Member Â			Join Date: Dec 2010 Location: Slovenia Posts: 782
🔋 Re: Another homebrew	AC-controller		
Quote:			
Originally Posted by zi <i>Hi arber333</i>	_		
you make a build vlog.		t car do you nave. what e	lectric motor are you using. did
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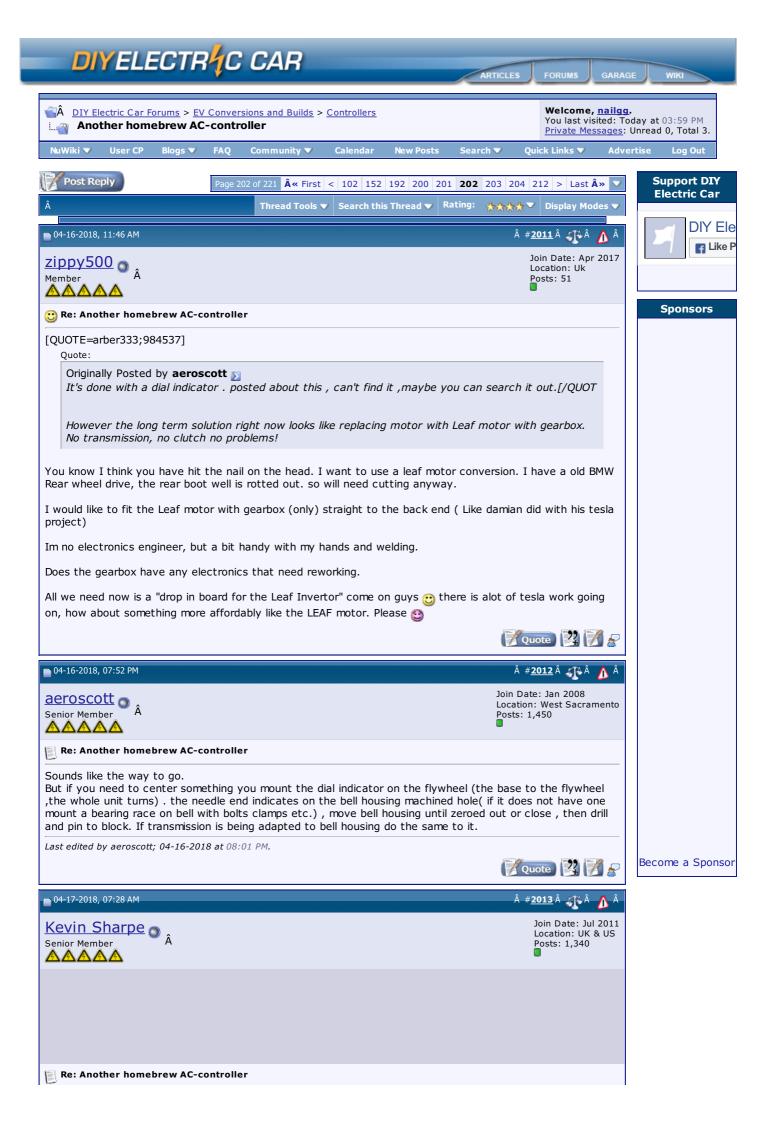
Â Controllers

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Oueto.	
Quote	
	-

Originally Posted by zippy500 🔊

All we need now is a "drop in board for the Leaf Invertor" come on guys 😁 there is alot of tesla work going on, how about something more affordably like the LEAF motor. Please 🙆

A number of forum members have donated BMW, Nissan, Tesla and other hardware to the open source projects. Indeed, without those donations we'd still be looking at \$\$\$\$\$ inverter solutions from commercial entities today 🔯

I agree that we need low cost solutions that end users can use in more affordable cars... indeed Damien's 1000 Euro conversion will be hard to beat \bigcirc However, if you want the joys of regeneration and the Leaf drivetrain, how about crowdfunding some funds to commission one of the developers to spend time making it a reality? Johannes has already shown the Leaf motor spinning with the open source inverter and I guess 5K would allow a developer to ignore the day job for a while 😁

Investor/Tinkerer in Biomethane, Electric Transport, Hydrogen, Hydropower, Solar, Wind & Wave.

🛛 🛛 Quote

http://about.me/kevinsharpe

04-17-2018, 11:<u>22 AM</u>

electro wr Senior Member

2 AM	â # <u>2014</u> â 🐠 â <u> </u> Â
ks o _Â	Join Date: Mar 2012 Posts: 534
L	

Re: Another homebrew AC-controller



Originally Posted by aeroscott 🔊

It's done with a dial indicator . posted about this , can't find it ,maybe you can search it out.[/QUOT

I put another normal clutch in and inspected the carnage up close.

I noticed small frewheeling bearing (inside clutch) looked weared a bit. So i went and measured the end of transmission shaft where it contacts this bearing. My hair stood up! Bearing inside diameter is 15mm, but shaft diameter is 14mm something. Clearly shaft is wearing down. Why probably some missalignment, but not too much. Since 110000Km and transmission bearing is still good.

I will check your posts for centering motor to transmission. However the long term solution right now looks like replacing motor with Leaf motor with gearbox. No transmission, no clutch no problems!



We are off topic, but here is your alignment problem, from your blog:

The transmission input shaft in your case is not supported well enough, by itself, to accurately align the adaptor plate. You may have noticed how loose it is. As aeroscott says, you will need to dial indicate the flywheel onto an accurately machined concentric surface on the bell housing or transmission.

One possibility is the sleeve the throwout(clutch release) bearing slides on. Unfortunately, there is no guarantee it is concentric enough with the centerline of the transmission to be useful. Also, it is not easy as you will have to read the dial indicator through the small openings in the bell housing.



We are off topic, but here is your alignment problem, from your blog:

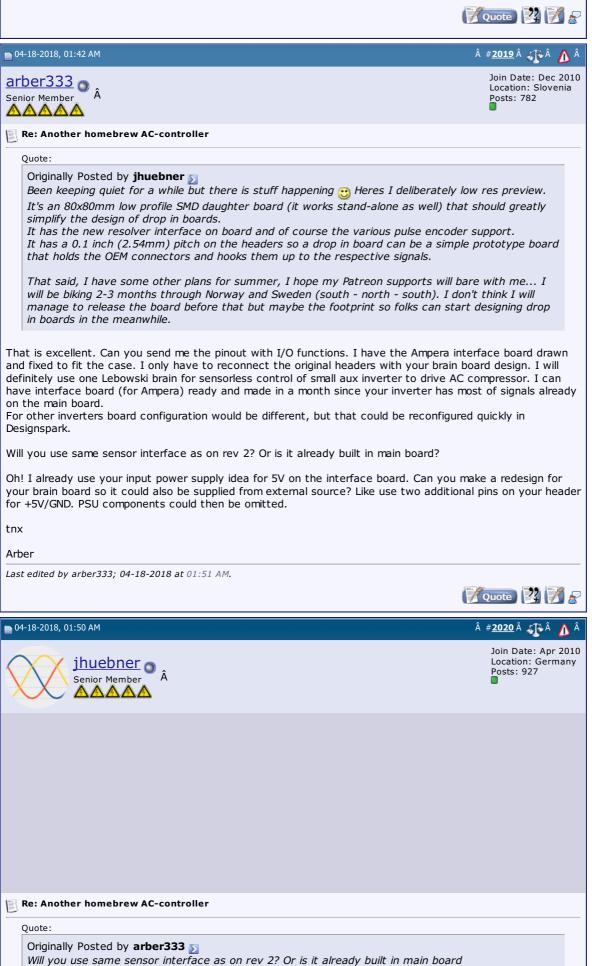


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One possibility is the sleeve the throwout(clutch release) bearing slides on. Unfortunately, there is no guarantee it is concentric enough with the centerline of the transmission to be useful. Also, it is not easy as you will have to read the dial indicator through the small openings in the bell housing.

Yes, the moment i saw the wear on the bearing surface i remembered that. However at the time i thought i had it centered quite good, or so it seemed... Well it is good that main bearing held for 100000km \bigcirc . I would need the sleeve to fit the small flywheel bearing and run the end shaft while it freewheels when released. That i think is one point of minimal radial misalignment. Clutch flex is fixing that to a degree. I think for now i will keep changing the clutch. Later i think i will try to find one Leaf motor with its gearbox and put that in... If the chassis says good.

VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit



What sensor do you mean? Except for the resolver function the board is pretty much identical to rev2.

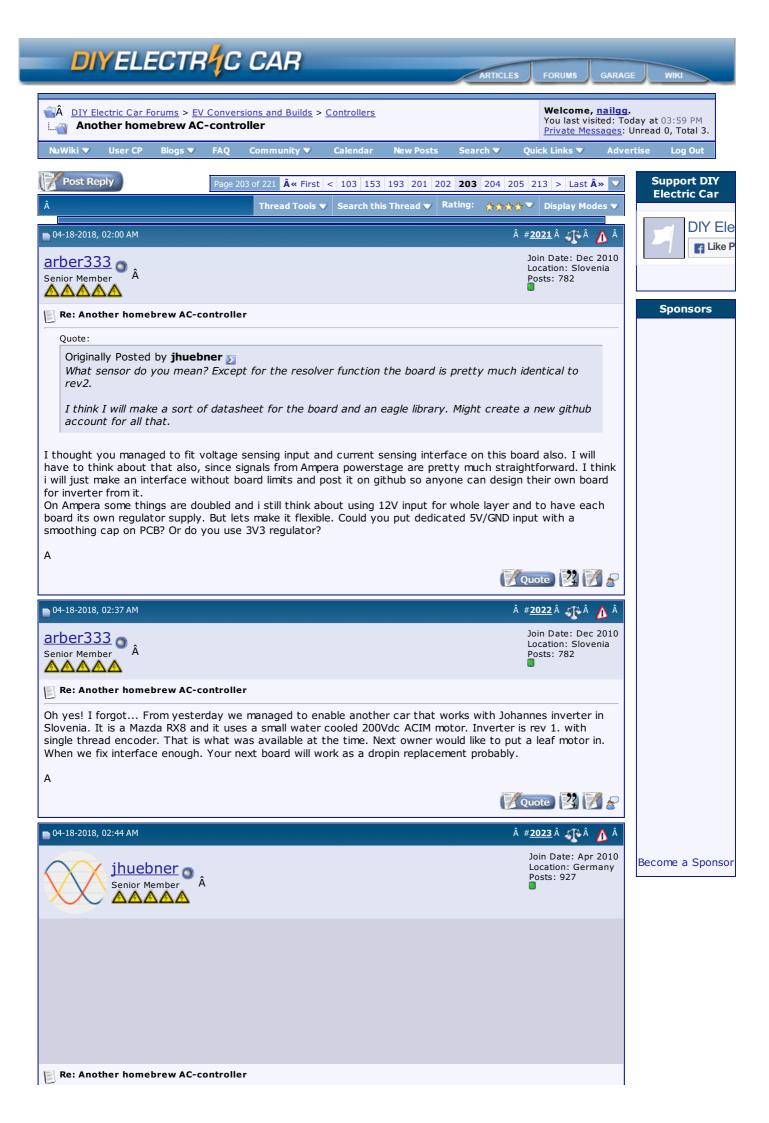
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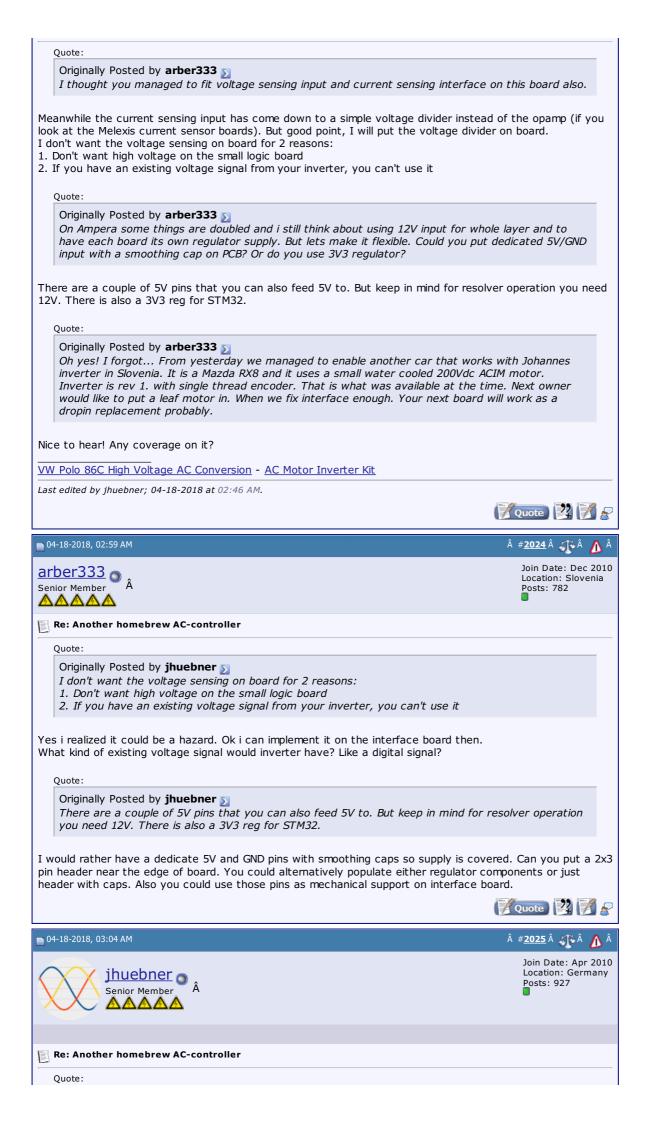
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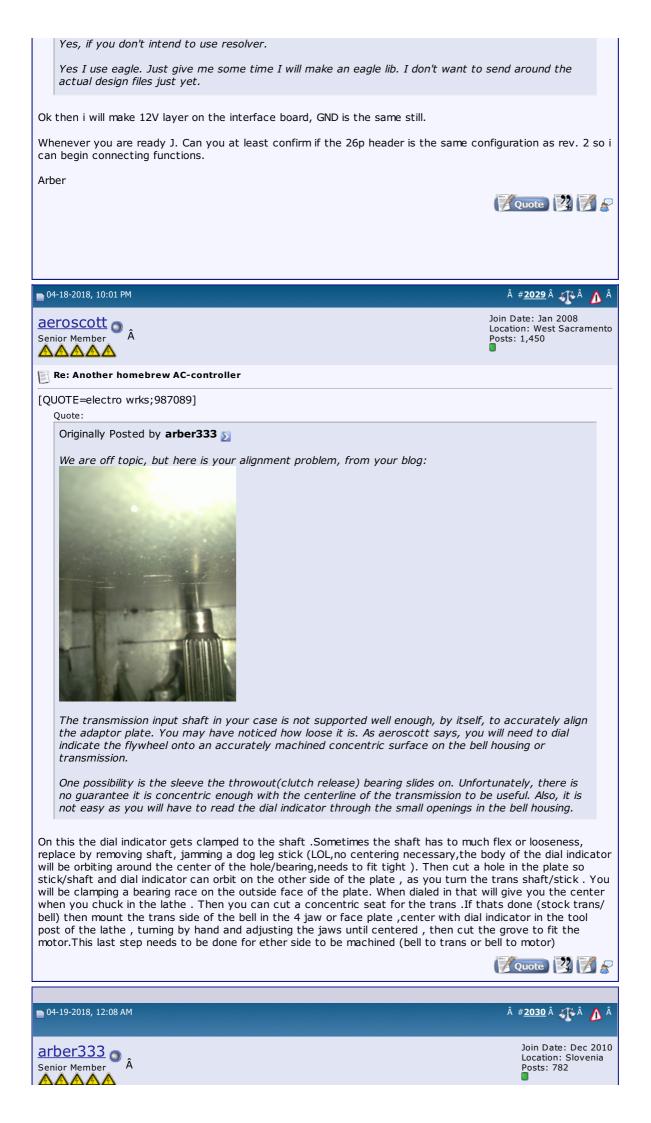
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Re: Another homeb	rew AC-controller		
[QUOTE=aeroscott;98	37561]		
Quote:			
On this the dial in looseness, replac body of the dial in Then cut a hole in , as you turn the plate. When diale concentric seat f in the 4 jaw or fa and adjusting the	e by removing shaft, jam ndicator will be orbiting ar n the plate so stick/shaft trans shaft/stick . You w d in that will give you the or the trans .If thats dom ce plate ,center with dial	ming a dog leg stick (LOL ound the center of the h and dial indicator can orl ill be clamping a bearing center when you chuck e (stock trans/ bell) then indicator in the tool post n cut the grove to fit the	e shaft has to much flex or ,no centering necessary,the ole/bearing,needs to fit tight). bit on the other side of the plate race on the outside face of the in the lathe . Then you can cut a o mount the trans side of the bell to of the lathe , turning by hand e motor.This last step needs to or)
fixed and probably ou		get center on the outer	plates without motor. inner plate is plate - motor flange so i can make t thought.
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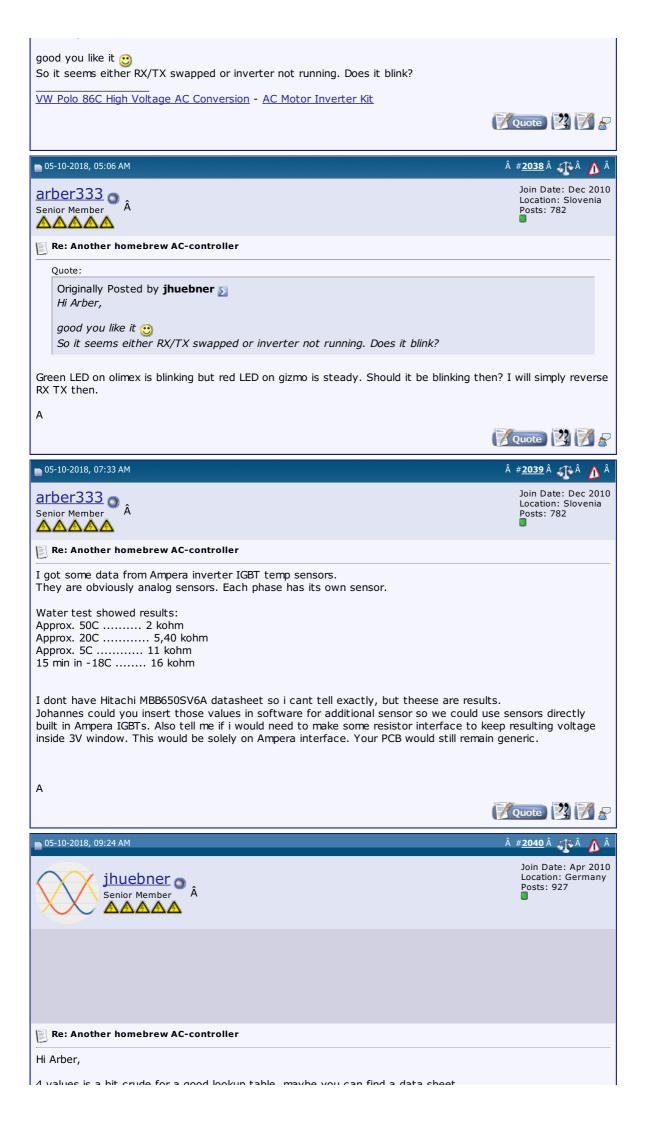
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1.875V	on the generic sensor bo	oard is 1k2. Would work	with the ampera sensor also,	50C ->
<u>VW Polo 86C High Volta</u>	<u>ge AC Conversion</u> - <u>AC r</u>	<u>iotor inverter kit</u>	Quote	2 📝 🖉
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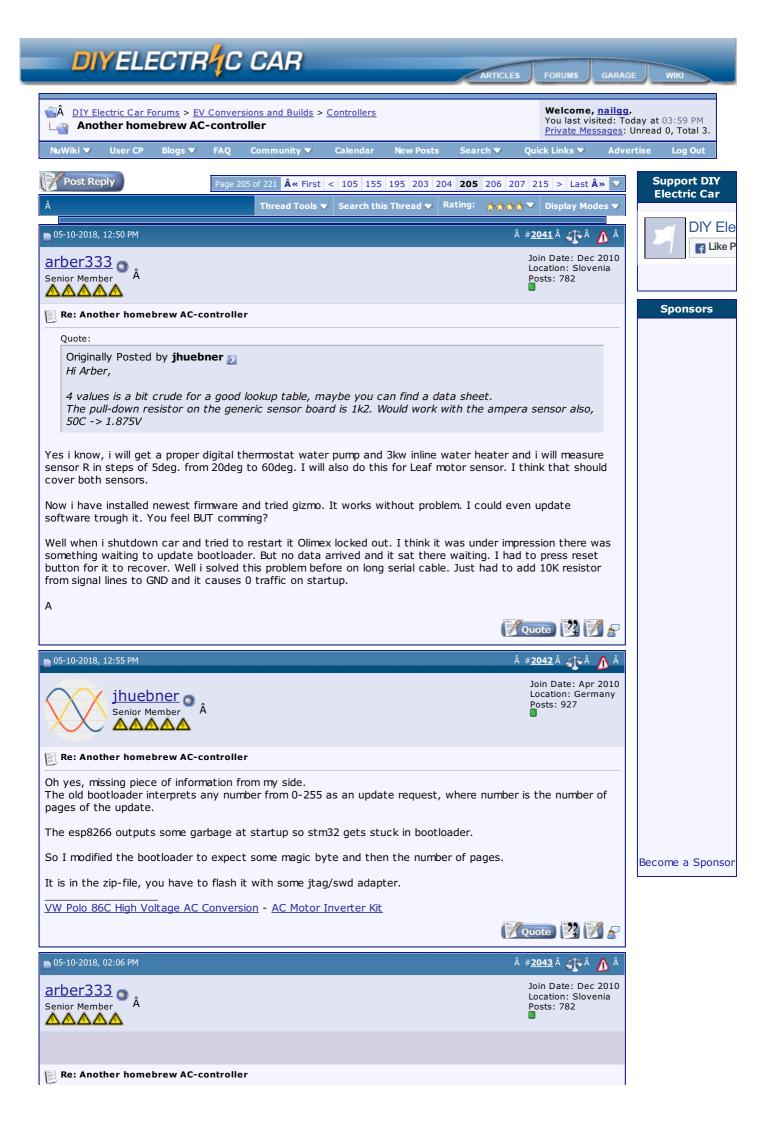


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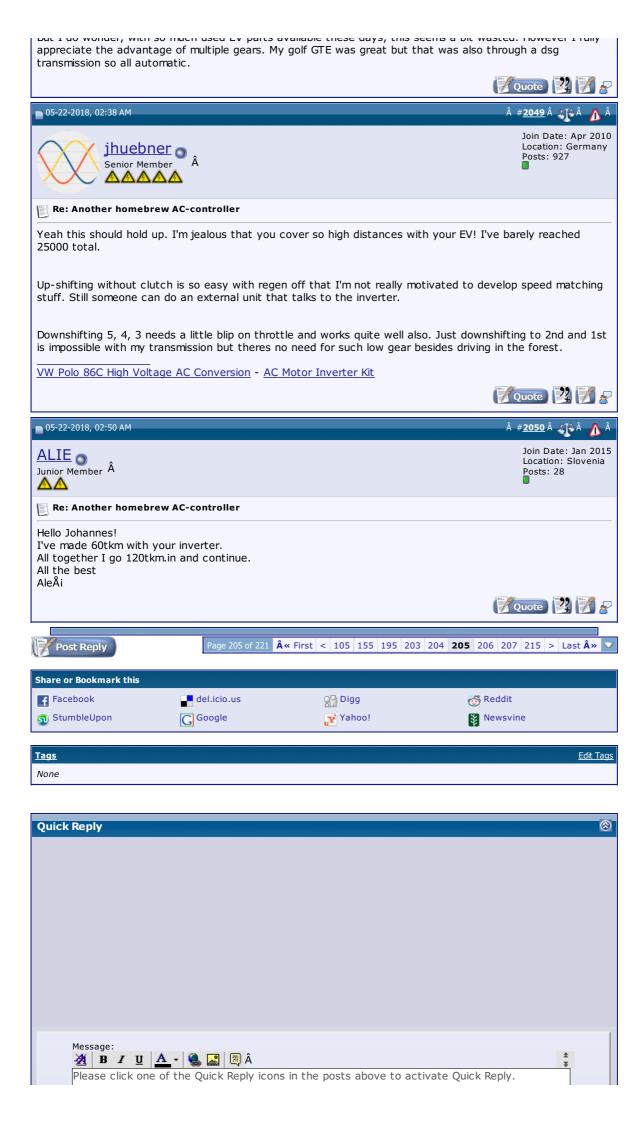
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Rut I do wonder with comuch used EV narts available these dave this ceams a hit wasted. However I fully



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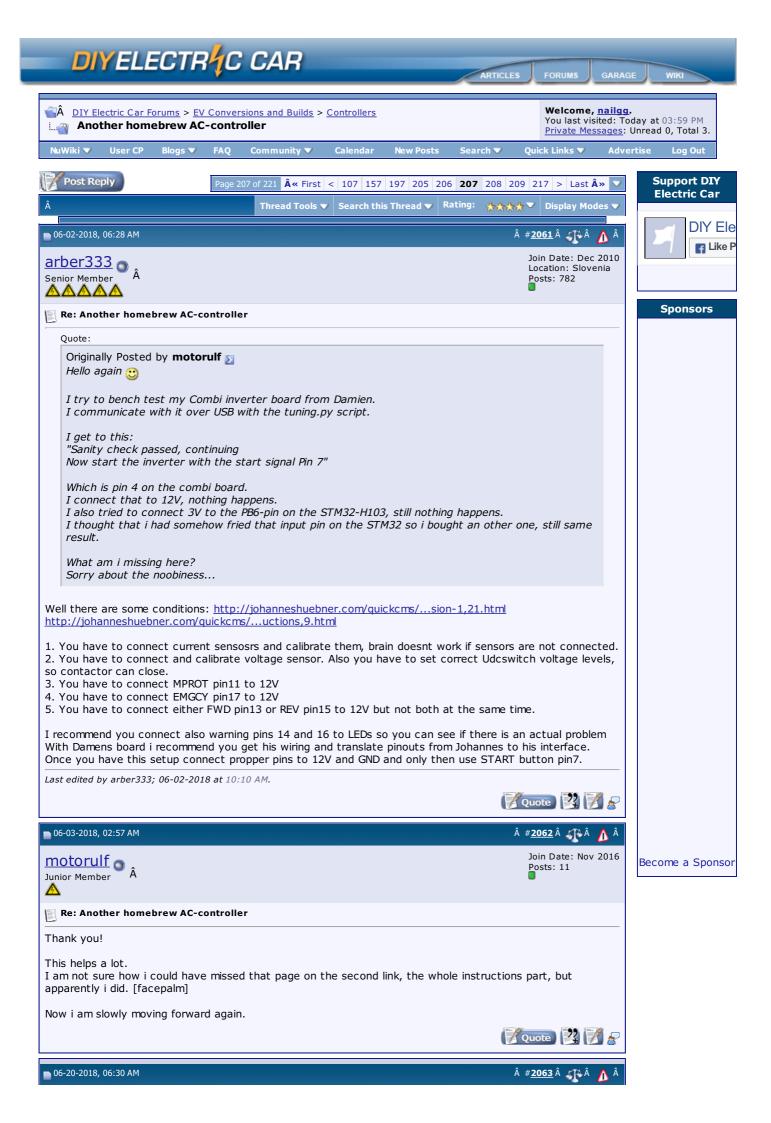
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05-23-2018, 07:18 AM	â # <u>2058</u> â 🐠 â 🧥
arber333 o	Join Date: Dec 2010 Location: Slovenia
Senior Member Â	Posts: 782
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by jhuebner You are using the correct one on the PWM connector. It has pullup to 5V to loaded with 1nF filtering cap	via 10k resistor and is
Also you can see from photo i use SN74L chip to invert signals. I connected or config, each signal its dedicated pullup resistor. However SN74L datasheet sho They recommend using 1k protection resistor and directly connecting +5V to t am not sure about this. Can you comment if i need to change my config or would it be ok?	ows a different configuration.
EDIT: It could also be used without SN74L chip. I could simply connect chip or and use existing pullups with inverted signals from olimex chip.	utput pads to correct inputs
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ast edited by arber333; 05-23-2018 at 07:36 AM.	
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05-26-2018, 05:30 AM	â # <u>2059</u> â 🐠 â 🧥
jhuebner 💿	Join Date: Apr 2010 Location: Germany
Senior Member Â	Posts: 927
Re: Another homebrew AC-controller	
Had to cancel the MOSFET project. So that gives me some more time for the r	new main board.

			12R) and that gave me a reall output 1W while the SOIC vers	
	at distorted and the SNR		peak-peak to 5V peak-peak. T plitude of 1.3 peak-peak on th	
amplifier to get the go run another redesign.	od SNR I had before. Un		th rather upgrade the excitation pin compatible parts so I will h XbUQnGBM=	
So, that was one step	back, but getting there			
				Â
VW Polo 86C High Volt	age AC Conversion - AC	<u>Motor Inverter Kit</u>		
Last edited by jhuebner; C	5-27-2018 at 04:03 AM.			
			Quote	4 🗹 🎸
06-01-2018, 04:04 PM			# <u>2060</u> 🍒	🏹 Â 🧥 Â
<u>motorulf</u> Junior Member ▲ Â			Join Date: Posts: 11	Nov 2016
Re: Another homebr	ew AC-controller			
Hello again 🙂				
	Combi inverter board fro over USB with the tuning			
I get to this: "Sanity check passed, Now start the inverter	continuing with the start signal Pin	ı 7 "		
Which is pin 4 on the o	combi board.			
	3V to the PB6-pin on th	ne STM32-H103, still noth pin on the STM32 so i bo	ing happens. ught an other one, still same r	result.
What am i missing here				
Sorry about the noobir	iess			
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Join Date: Jul 2016 Location: North East England Posts: 54

Re: Another homebrew AC-controller

I've got one of Damien's combi boards running an Enova inverter. I had it up and running from a 30V DC power supply a while back and everything worked great. I recently connected it all up again to try out my new throttle pot and get all the sensors working properly. I've had some issues which I'm hoping you guys can help with.

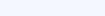
With the combi board powered up and 30V (limited to 20A) on the DC bus, every time I pressed the start button the power supply would hit the current limit as if there was a short. I double checked everything and retried a few times and eventually it turned on ok. It did drive the motor but there was a strange clicking noise coming from the inverter that I'd not heard before.

Yesterday, I tried again with a different power supply just to rule out the possibility of dodgy power supply. It did the same thing again but this time I couldn't get it to start at all even after multiple attempts. Every time I pressed the start button it just hit the current limit of the power supply. I had a read on here and noticed mention of the new firmware to make sure all the PWM pins are low. I have now flashed the new firmware and this has fixed it so that I can start the inverter up with no issues. However, it now hits the current limit of the power supply whenever I press forward or reverse (with the throttle pot at 0). This problem disappears if I unplug one of the IGBTs from the combi board. The other two appear to be fine.

It seems that I've been having the problem where the PWM pins are high on start up which has shorted one of the IGBTs. I'm guessing this may have now caused permanent damage to something. Any ideas what the most likely culprit is? Will it be the IGBT module itself? Is there any way I can test this?

Thanks,

Tom



💼 06-21-2018, 01:32 AM

arber333 O A

Senior Member



Join Date: Dec 2010 Location: Slovenia Posts: 782

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🛛 🛛 Quote 🕎 🏹 🔎

#<u>2064</u>Â 🌾 Â

Re: Another homebrew AC-controller

Quote:

Originally Posted by tom3141 🔊

I've got one of Damien's combi boards running an Enova inverter. I had it up and running from a 30V DC power supply a while back and everything worked great. I recently connected it all up again to try out my new throttle pot and get all the sensors working properly. I've had some issues which I'm hoping you guys can help with.

With the combi board powered up and 30V (limited to 20A) on the DC bus, every time I pressed the start button the power supply would hit the current limit as if there was a short. I double checked everything and retried a few times and eventually it turned on ok. It did drive the motor but there was a strange clicking noise coming from the inverter that I'd not heard before.

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Thanks,

Тот

Hm... different ways to skin a cat here.

Did you check Driver integrity? Maybe one of the drivers has a faulty solder? Also check DCDC power supplies. If you used Murata DCDCs they should be good, but you never know...

What is your 337 desat RC setting? Did you calculate it? Stock RC combination works up to some 100A. What is your deadtime setting in software? You may be getting a shootrough on one IGBT. I use quite large value, but for most cases 85 deadtime value should work. Check deadtime on scope WITH IGBTs connected and no power on DC link! both signals turn-on and turn-off curves should not overlap.

I had more or less the same problem with IGBTs a year ago.

This is why i selected <u>Skyper 32 pro</u> drivers to run my IGBTs. They are industrial quality and have all the protections built in. I just made an interface board that provides 15V power supply and separates driving circuits from sensors.

You can find it here, designed in DS:

https://github.com/arber333/Skyper-32-interface

Rev 2 board is in design, but Rev 1 works good in my car for more than a year now....

As for inspecting integrity of IGBTs i built one driver PCB that Damien constructed. It has ACPL 337 chip that can sense desat condition. I added one LED from Fault pin to 5V to signal if chip reports fault. Normaly i would connect it to suspect IGBT on G, E and C connector and provide 5V power. Then i would remove C line as a proof test if ACPL 337 works.

With this setup i got Fault reports on IGBTs that passed my light bulb test and i considered them good. That really opened my eyes.

Crude light bulb test of IGBT is here, but it doesnt always show degradation of gate substrat. http://inverterhome.blogspot.com/p/h...bt-module.html

Warning! Do not touch GE terminals with your fingers, you may cause static discharge that kills IGBTs. Always use ESD wristband with ground point when handling power electronics.

Last edited by arber333; 06-21-2018 at 01:43 AM.





	start button the power supply would hit the c	nited to 20A) on the DC bus, every time I pressed the urrent limit as if there was a short. I double checked ually it turned on ok. It did drive the motor but there inverter that I'd not heard before.
you' It al	ve only been using a lab power supply I don't	manently closed and the other switches "into" it. If suspect a broken IGBT (unless it was broken to start with). ignal integrity from mcu to gate driver. Check that all
VW	Polo 86C High Voltage AC Conversion - AC Mot	or Inverter Kit
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0 6-	22-2018, 02:10 PM	# <u>2066</u> ∡ ∏ ∛ _∧ Â
i i i e i i i	n3141 o Â	Join Date: Jul 2016 Location: North East England Posts: 54
F P	e: Another homebrew AC-controller	
Tha	nks for the help guys.	
I'm ;	away for a couple of weeks from tomorrow but	will do the tests you suggest when I get back.
Tom		,
		📝 Quote 🕎 📝 🎤
07-	21-2018, 02:42 PM	# <u>2067</u> ⋦ [% <mark>⋀</mark> Â
tor	n3141 o Â	Join Date: Jul 2016 Location: North East England
	ber Â	Posts: 54
R	e: Another homebrew AC-controller	
I ca	n't believe an entire year's worth of this thread	d has gone missing!
	may remember that I had an issue with Damie Is seems to be shorting when I turn it on (pow	n's combi board running my Enova inverter. One of the rered with a 30V PSU).
		n ago could remind me of the tests that you suggested I im to have gone missing when I returned from holiday!
		📝 Quote 🕎 🌠 🎤
07-	24-2018, 01:19 PM	# <u>2068</u> 💦 \Lambda Â
	oer333 or Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782
R. R	e: Another homebrew AC-controller	

Yesterday i had a new development. I had made new small interface boards that 1 main boards. They include signal inverting and current sensor connectors. But the size of the	
output. It is compact and suits well to single inverter use. However i still got OC limit error on trying to connect with inverter. When trying cable and OClimit stopped. When i investigated i found out that pin i thought a automaticaly connected to GND. There is like 47R difference from Fault pin to s Fault pin.	s driver Fault pin is
Do you have an idea how to use your scheme with that signal connection? Prol Fault condition, but i am not sure how to test it. Do i just join two phases? Or	
	📝 Quote 📴 🌠 🔗
07-29-2018, 02:18 PM	# <u>2069</u> ∢ TA <mark>∕</mark> Â
tom3141 Member Â	Join Date: Jul 2016 Location: North East England Posts: 54
Re: Another homebrew AC-controller	
So, I've had another go testing the inverter. Yesterday, I hooked it back up to ok but would intermittently make the strange clicking noise. I figured out the net the PSU not the inverter. I think that the PSU is cutting in and out really quick the clicking noise. Then after a brief break for some food I came back to it and clicking at all.	oise is actually coming from ly (due to a short?) causing
I gave it another go today to see if it was fixed for good but sure enough it's n back to shorting as soon as I click forward or reverse (throttle at 0). Again if I so I suspect there is a problem with the control electronics for this IGBT.	
I'm mechanically biased so could do with some guidance on what exactly I shou checked for obvious things like dodgy connections and also tried increasing the set at 63). This made no difference. Ouote:	
It also sounds like an intermittent fault so check signal integrity from mcu t all drivers output -8V in stop mode.	o gate driver. Check that
Could you expand on the best way to do this? Which pin do I need to be check	
obvious but I'm a novice in this kind of thing and I'm wary of sticking a scope/v and causing more problems!	oltmeter in the wrong place
	oltmeter in the wrong place
and causing more problems!	📝 Quote 🕎 🌠 🔗
and causing more problems!	#2070 Join Date: Dec 2010 Location: Slovenia
and causing more problems!	#2070 Join Date: Dec 2010 Location: Slovenia
and causing more problems!	#2070 Join Date: Dec 2010 Location: Slovenia
and causing more problems!	Image: Stress of the stress

	the problem with inve	rter.			
	2 and rev 1 main boa also inverter temp ou However i still got OC driver cable and OClin pin is automaticaly co would like to use Faul Do you have an idea I	rds. They include sig tput. It is compact of limit error on trying nit stopped. When i innected to GND. Th t pin. how to use your scho	nal inverting and current s and suits well to single invo to connect with inverter. investigated i found out th ere is like 47R difference fi eme with that signal conne	e boards that can connect rev. Sensor connectors. But there is erter use. When trying to find error i pulled at pin i thought as driver Fault rom Fault pin to sensor GND. I ection? Probably this pin goes t join two phases? Or phase and	đ
kind It c - o - fl Sig the Nov	d. I guess it signals a c hanges state pen collector to GND in oating pin when signali nal always goes to floa problem was. v i dont think it will imp	hange of operation t normal operation ng something It when i start PWM bede my use of Volt i	o brain so in the beginning it was inverter, i just would like to	Fault pin, but a signal pin of some quite frustrating to figure out whe have a Fault signal to suppleme one knows what signal is for?	ere nt
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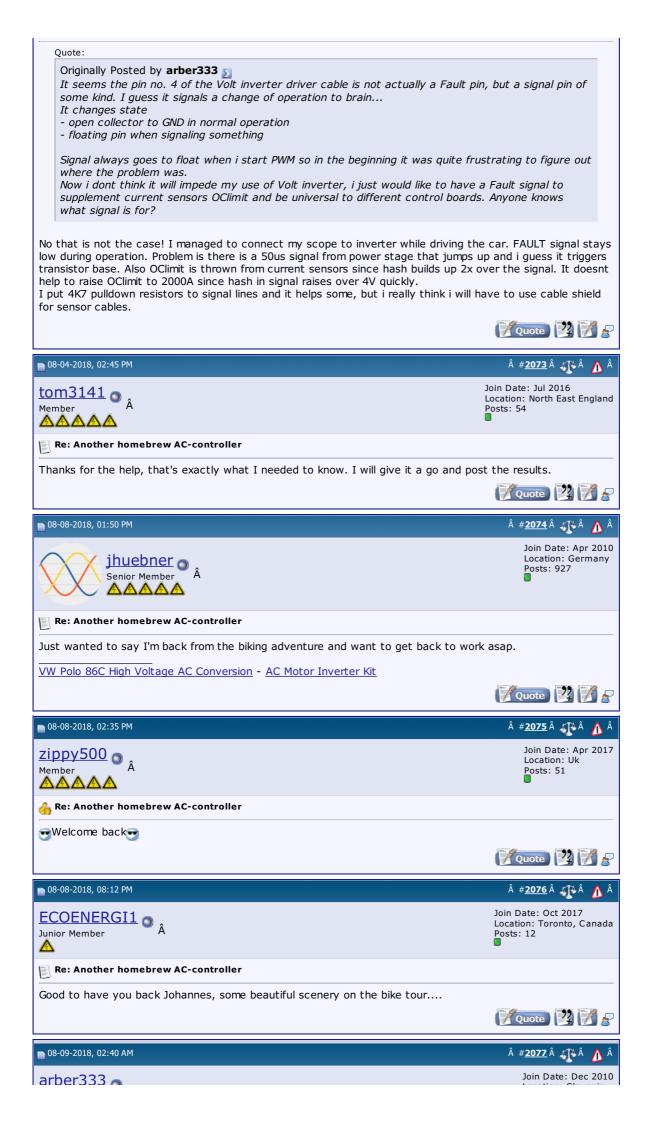
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🛐 Re: Another homeb	rew AC-controller			
Worked on CAN contro	ol this morning.			
This is the current sta	ate:			
 pot and pot2 mi Digital IO can be canio must be ni canio has a fixe It is ORed with Both pot and digital can be 	n must be explicitly set to ust be mapped to a CAN e mixed CAN and gpio napped to a CAN message d mapping: 1=Cruise, 2=S the gpio inputs, so e.g. c gio time out after 500ms ttle is set to 0 and ios to	message (web interface e Start, 4=Brake, 8=Fwd, 1 ruise_final = cruise_gpio	6=Rev, 32=Bms	
To be done:				
 Timeout means "no message has been seen on the CAN bus at all for 500ms". Of course thats misleading, we should only care about messages mapped to the inverter Therefor I need to set up the hardware filtering 				
Any other suggestions				
EDIT: haven't updated	d the official firmware yet	t as I want to do more te	esting prior to that	
			Â	
L				
VW Polo 86C High Volt	tage AC Conversion - AC	Motor Inverter Kit		
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	Originally Posted by arber333 <i>I have noticed you changed/added new parameters that show state in bottom section of interface</i> <i>site.</i>
	once. One is din_desat and one is din_ocur which was there before. However they now show state "1" and system works. It used to mean that state 1 tripped action. Can you explain change in polarity? Is the new SMD board able to run this? Can i update SMD board to rev. 3.75 over wifi?
sho	es I have unintentionally swapped polarity. Basically din_ocur and din_desat are now physical pins and I w their state. din_ocur is high when all is good, I know I used to invert this. The software will run on the D board.
C	Quote:
	Originally Posted by arber333 Johannes could you input Ampera thermistor data in your code? I believe i sent you datasheet for response graph.
	Also Leaf thermistor test results i posted here? I could better integrate everything that way.
I'm tabl	currently working on a more universal method using the <u>B-value</u> of NTC termistors instead of lookup es.
(Quote:
	Originally Posted by arber333 ∑ Hm could i run inverter in charger mode and vary amps using CAN commands? Also could i start/stop inverter/charger by CAN command?
	BMS using CAN is not that rare
arbi	, check docs linked above. You could either use SDO to change chargecur or map chargecur to some trary message and change it that way. With CAN mapped IO you can trigger BMS pin or forward/reverse
pair <u>htt</u> p	://johanneshuebner.com/quickcms/cation,31.html
VW	Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit
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	Join Date: Jan 2008 Join Date: Jan 2008 Location: Ireland Posts: 2,147
For Eno	Join Date: Jan 2008 Location: Ireland Posts: 2,147
For Enor http	Join Date: Jan 2008 Location: Ireland Posts: 2,147 Re: Another homebrew AC-controller centuries humanity has struggled with the age old question : Just how do I run one of these crappy va inverters? Behold yet another logic board!
For Enot http I ha BMV	Join Date: Jan 2008 Location: Ireland Posts: 2,147 te: Another homebrew AC-controller centuries humanity has struggled with the age old question : Just how do I run one of these crappy va inverters? Behold yet another logic board! is://github.com/damienmaguire/Enova-Inverter ve added Johannes's resolver interface to allow for PM motor experiments. Prototype will be tested in my
E For Eno http I has BMV	Join Date: Jan 2006 Location: Ireland Posts: 2,147 A te: Another homebrew AC-controller centuries humanity has struggled with the age old question : Just how do I run one of these crappy va inverters? Behold yet another logic board! vs://github.com/damienmaguire/Enova-Inverter ve added Johannes's resolver interface to allow for PM motor experiments. Prototype will be tested in my v E65 build. Enjoy: ttached Thumbnais A , Cole, when you shift the gear and that little needle on the ammeter goes into the red and reads 1000 rs, that's bad.
E For Eno http I has BMV	Join Date: Jan 2006 Senior Member Â Re: Another homebrew AC-controller centuries humanity has struggled with the age old question : Just how do I run one of these crappy va inverters? Behold yet another logic board! vs://github.com/damienmaguire/Enova-Inverter ve added Johannes's resolver interface to allow for PM motor experiments. Prototype will be tested in my V E65 build. Enjoy : ttached Thumbnails a
E For Eno http I has BMV	Join Date: Jan 2006 Location: Ireland Posts: 2,147 te: Another homebrew AC-controller centuries humanity has struggled with the age old question : Just how do I run one of these crappy va inverters? Behold yet another logic board! va inverters? Behold yet another logic board! vs://github.com/damienmaguire/Enova-Inverter ve added Johannes's resolver interface to allow for PM motor experiments. Prototype will be tested in my v E65 build. Enjoy :: ttached Thumbnais ttached Thu
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an option besides gen But hey i see it also h	eral NTC thermistor. as a typical koefficient of	f 0.61 %/K from 60°C u	es. It would be best to leave it in as p to 130°C. That should cover our ature i am getting anxious to stop and
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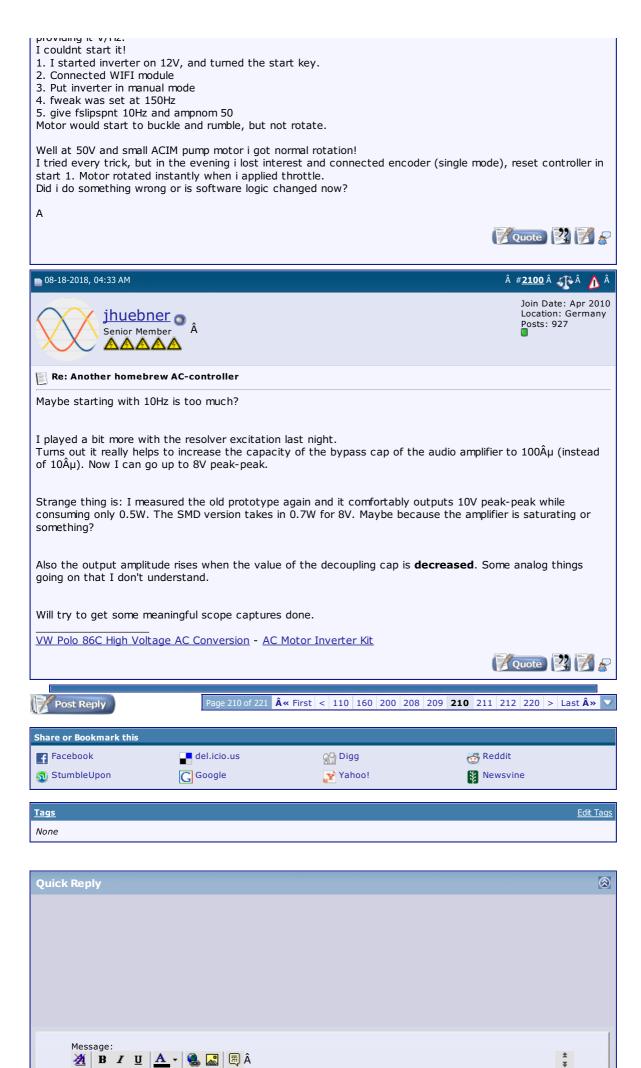
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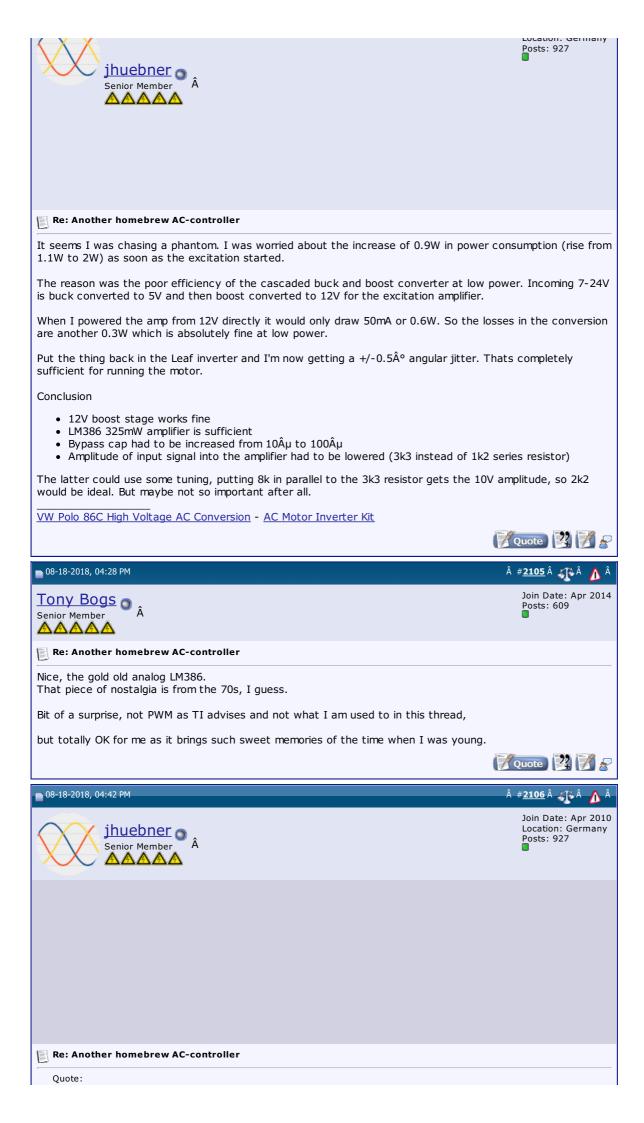
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Usually minimal analog here	e, maybe that's what	causing it.		
			o 70 degree C operating temp. ty sure TI has added a LM286	
	is great for a headph	one amplifier (section audi	o, radio and TV of the databoo	ok).
Last edited by Tony Bogs; 08-1	9-2018 at 03:31 AM. Rea	ason: P.S.		
			Quote	<u> 8</u>
■ 08-20-2018, 03:19 PM			# <u>2110</u> Æ Â	Â
Senior Member	Â		Join Date: Ap Location: Ger Posts: 927	
Re: Another homebrew A	AC-controller			
Good point, overlooked it a So the <u>NJM386</u> has extend		to -40°C and up to 85°	с	
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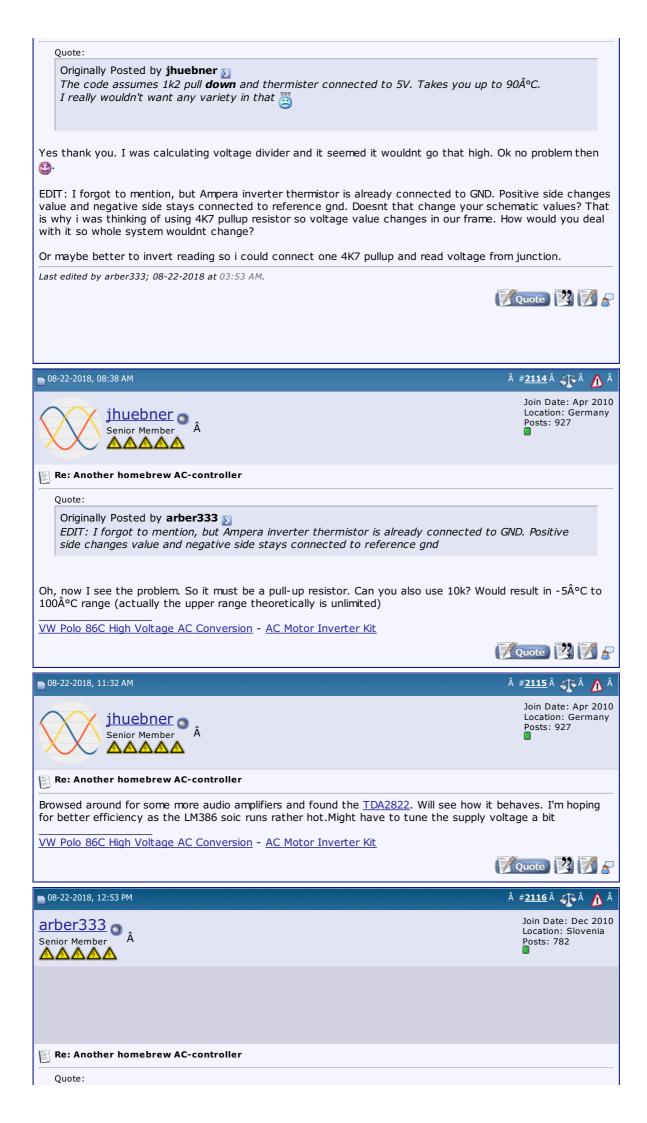
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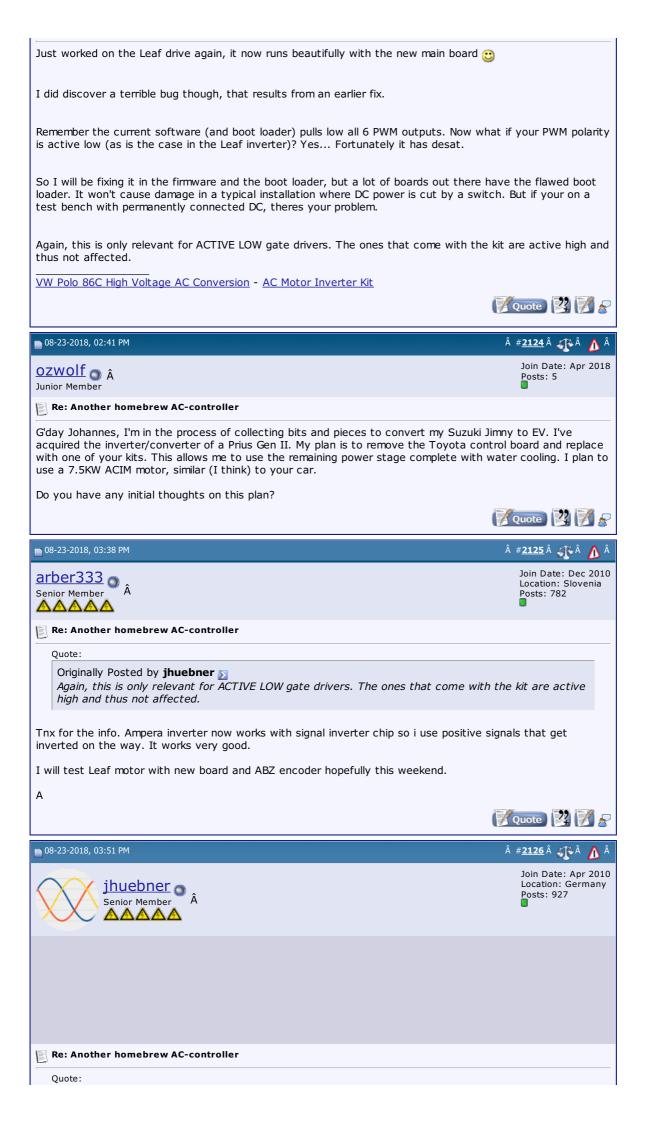


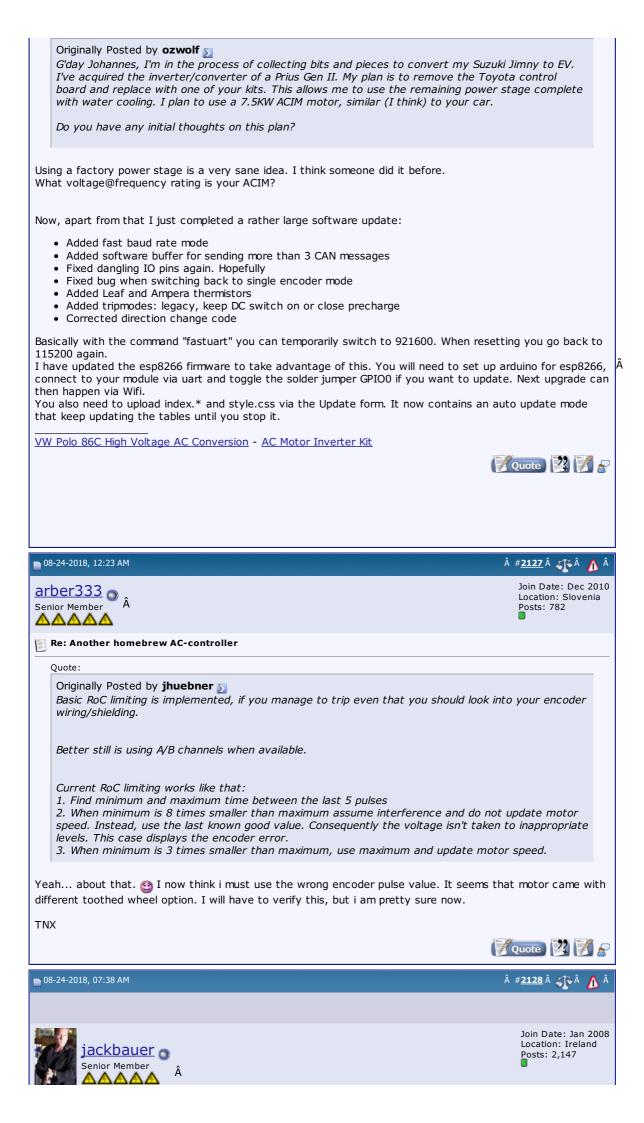
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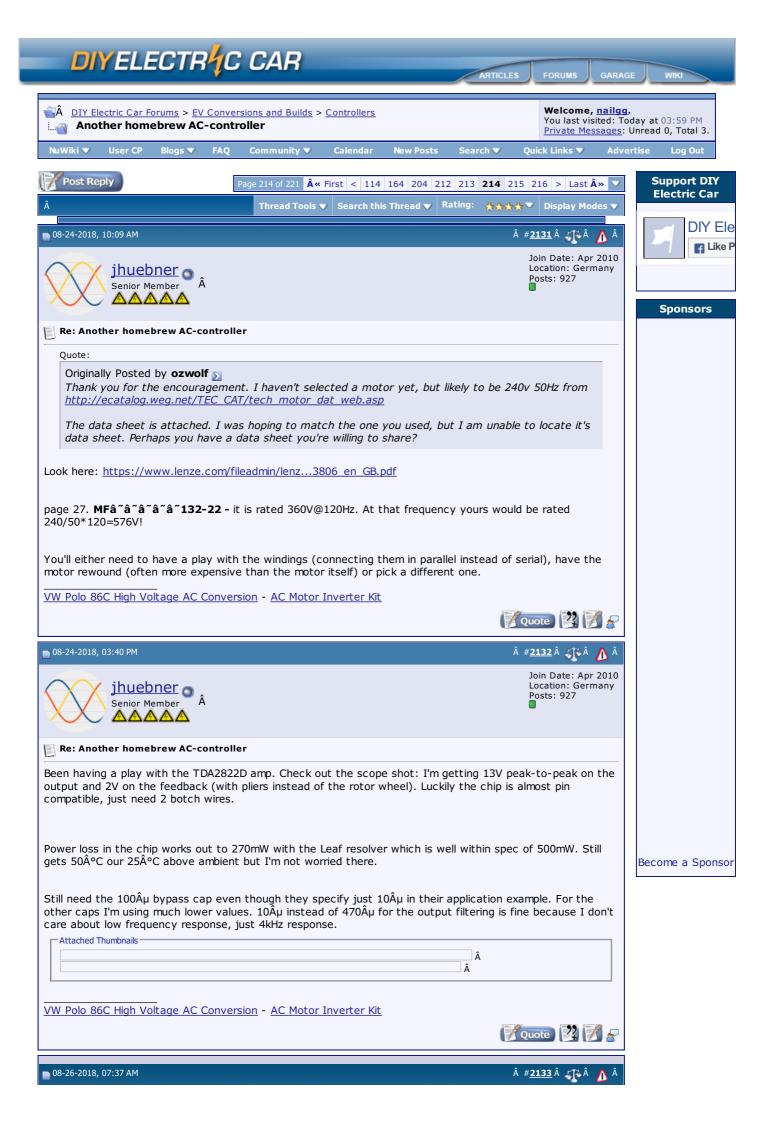
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■ 08-24-2018, 07:45 AM			# <u>2129</u> ∢ ∯ ∧ Â
			Join Date: Apr 2018
<u>ozwolf</u> A			Posts: 5
Junior Member			•
Re: Another homebrew	AC-controller		
Quote:			
Originally Posted by j			
Using a factory powe What voltage@freque		e idea. I think someone dia TM2	d it before.
What Voltage@heque	ancy rating is your Ac	1171:	
Thank you for the encour	agement. I haven't se	elected a motor yet, but lil	kely to be 240v 50Hz from
http://ecatalog.weg.net/			.,
The data sheet is attache	ed. I was hoping to m	atch the one vou used, bu	ut I am unable to locate it's data
sheet. Perhaps you have			
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<u>ozwolf</u> () Â			Join Date: Apr 2018 Posts: 5
Junior Member			•
Re: Another homebrew	AC-controller		
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cooling, IGBTs all came in	a ready made packa	ge.	
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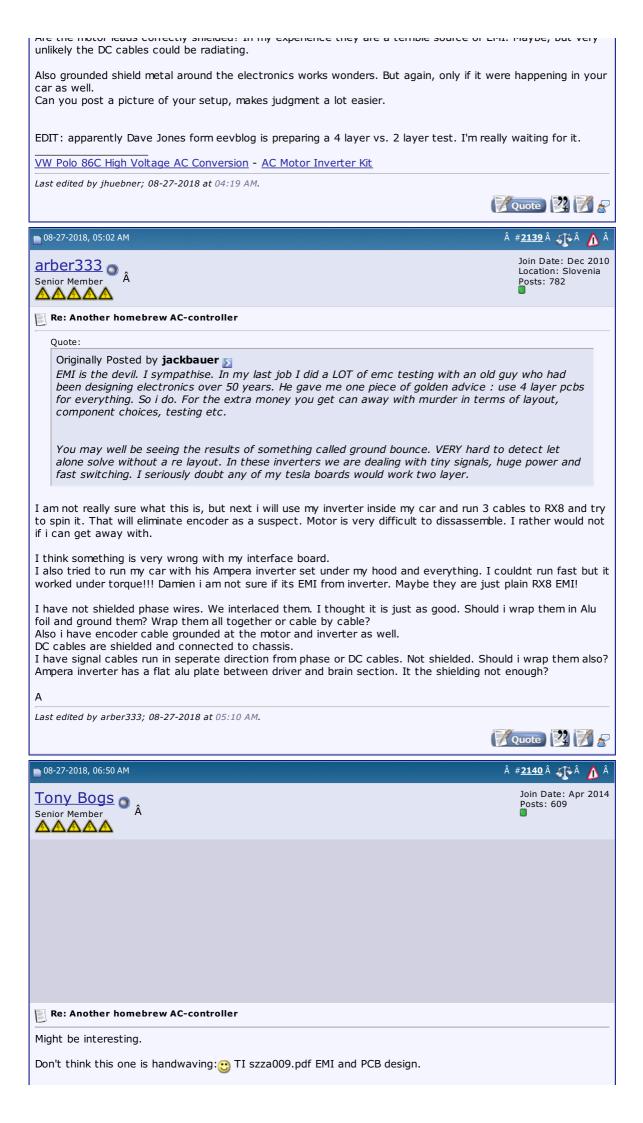
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Ampera inverter works with Rev. 2 mainboard and my car. I tried to run it up and down the driveway and it went good. While i try this on my friends car with similar ACIM motor inverter with 200Vdc it just trips OClimit error. Sometimes i get report "encoder error" also "throttle" and sometimes i just get "overcurrent". I replaced rev. 3 sensor board with my own interface board that grabs current sensor signals from phase C and B. I use a 3K3/10K divider to make 1.67V at OA. To detect DC voltage I use isolated opamp again the same as your circuit. Thinas i tried: 1. I added 4K7 pulldown resistors to hopefully reduce EMI in current signals same as factory board uses 2. I tried to run without encoder connected and still OClimit trips when i apply any current 3. I put his mainboard in my car and ran with it no problem single channel with my motor. I have ACIM with AB encoder and run at 380Vdc. 4. I tried to move the throttle limit up or down if there would be any difference.... 5. I connected scope to encoder signal and GND and turned the motor, signal is 5V square tooth with some switching hash 6. I disabled Fault pin reporting so i wouldnt have false reporting... 7. I tried different boost and deadtime settings in case that would cause some EMI. But oclimit trips regardless. Anyone has any suggestion what to try? I couldnt just put Damiens logic line RC filter in since it would mean major mainboard redesign, cutting thin traces etc... and obviously it ran good on my car with even higher voltage. Quote 🕺 📝 ج ■ 08-27-2018, 02:35 AM #**2137** Â 🌆 Â ΛÂ loin Date: lan 2008 jackbauer 👩 Location: Ireland Posts: 2,147 Senior Member AAAA Re: Another homebrew AC-controller





Ground issues (referencing Jackbauers remark about ground bounce):				
Even in 12V car systems engineers have to take several Volts of potential difference in the ground lines (body) into account.				
Source: Infineons "handbook" for automotive engineers (if I remember correctly, can't find the d*** pdf and the link).				
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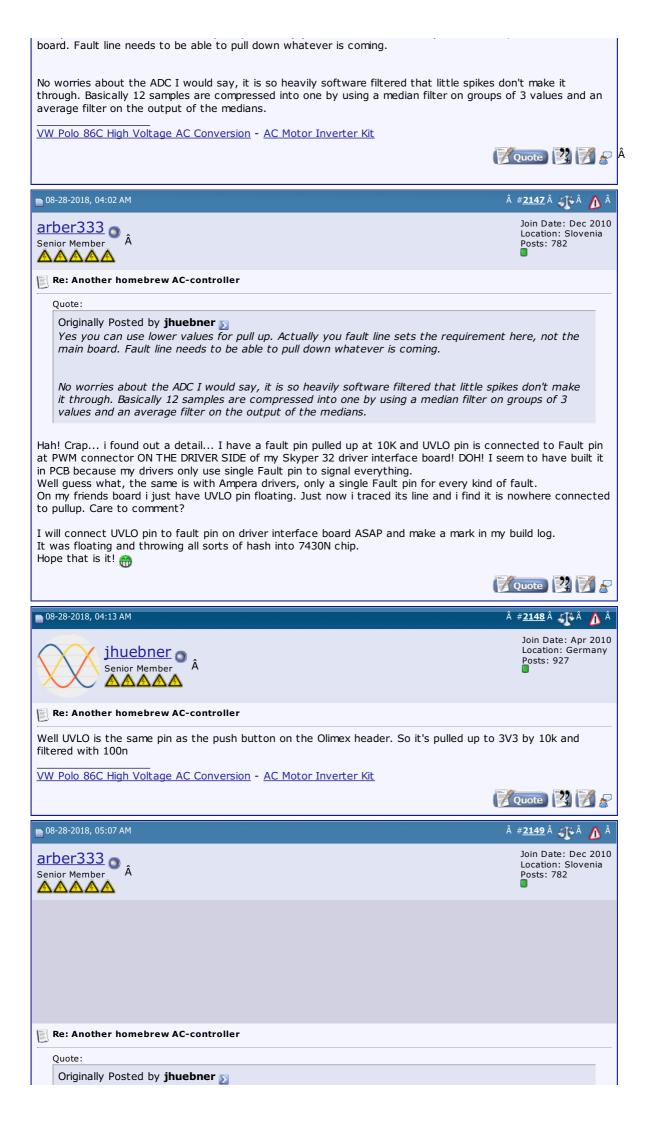
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stronger pullup.		uldnt i have 4K7 pullup to \ works good. Or so it seem	/cc then? That would be eve	'n
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gunnarhs Senior Member Â			Join Date: Apr 2012 Location: Iceland Posts: 292	
Re: Another homeb	rew AC-controller			
Quote:				
supply 125Vrms v	s relevant since with Joh	dc power. My motor is wo	lower effective voltage and t und 185Vrms and it works	thus
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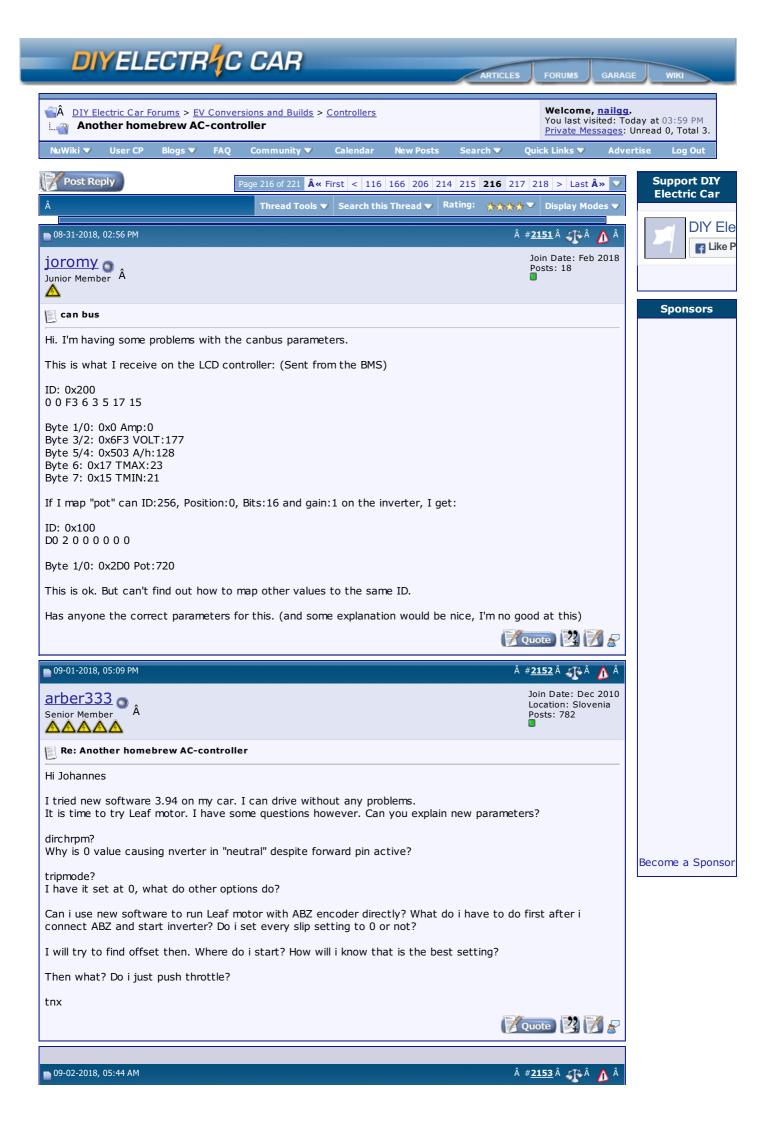
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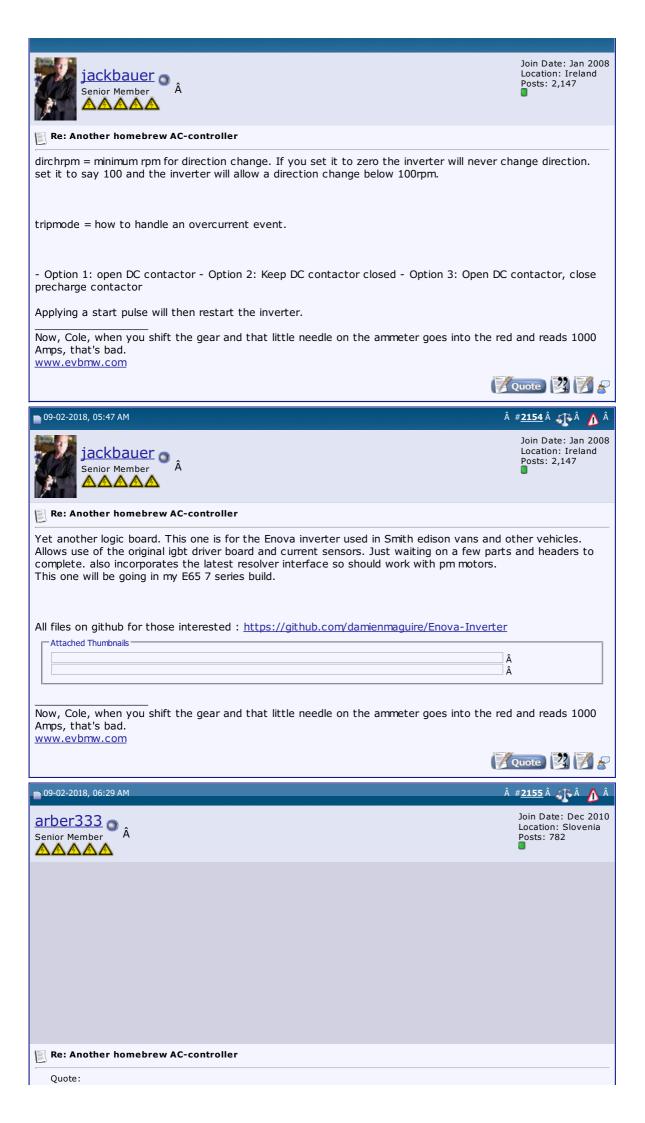
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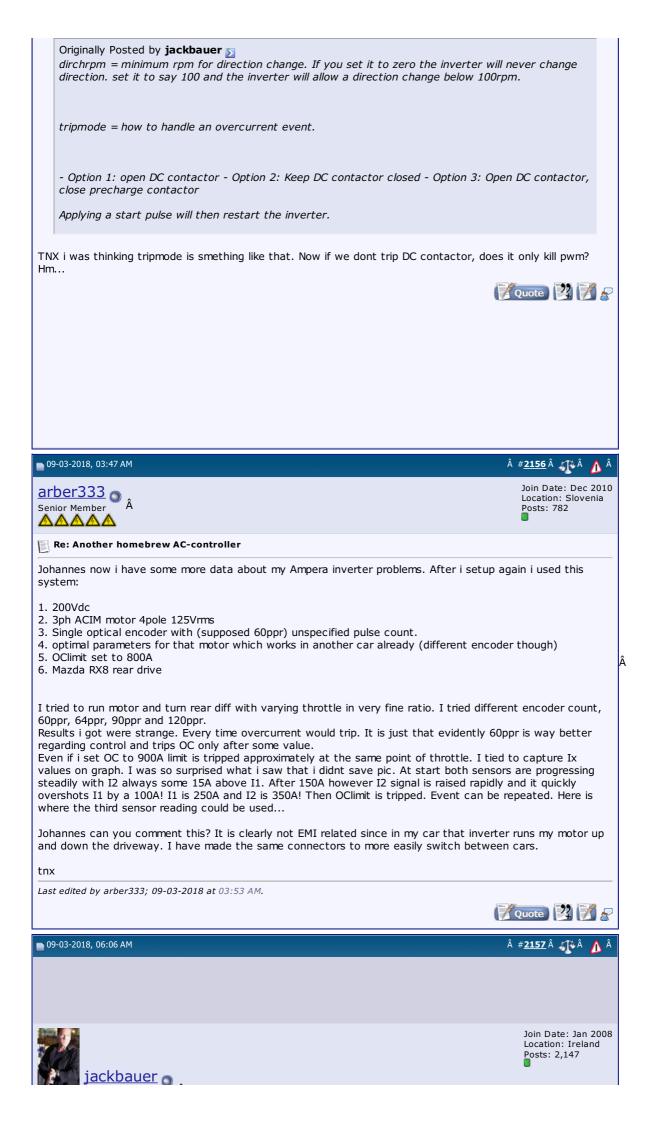
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■ 09-04-2018, 12:21 AM	# <u>2158</u> ∰ <mark>∆</mark> Â
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782
Re: Another homebrew AC-controller	
Well i went ahead and put Ampera inverter in my mazda with B channel of AB encoder only, but there were no limitations. Results were surprising. Using the same settings as my DIY more power from start. It was more direct. Response was in parameter for the thing to be more comfortable to drive. En no shielded cable. Granted it would benifit from shield a lot I used deadtime 116pt setting, 1,6us like TomDB suggested. motor was jittery and weak. I calibrated amp sensors gain to 3.0.	inverter Motor with Ampera inverter had noticably stantenous and rough. I had to lower ampmin coder was working no problems on just four wires,
Now the down side 1. I couldnt connect DC contactor directly to ULN chip. It k diode? Mabe EV200 economiser does not like ULN chip? I hav contactor and precharge.	
2. Whenever i touched throttle pedal many lights lit on my c for battery error was lit no matter what happened. I think U	
3. This is problematic! When i touched BMS button (as i 1050 and moved there about +/-30pt. That was just at move!!!! But i just pressed a totally unrelated button. I Regen pin is not connected and stays at 28pt. What input could cause this to throttle?	pove the 0% throttle so my car wanted to
I dont have anything like this happenning on my DIY inverte I did use the same wiring loom as in my car. I connect GND encoder. Anyone has similar event?	
Attached Thumbnails	
	Â
Last edited by arber333; 09-04-2018 at 02:27 AM. Reason: Photos	Quote 22
■ 09-04-2018, 12:00 PM	# <u>2159</u> ∰ <mark>∧</mark> Â
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782

🛃 Re: Another homeb	rew AC-controller			
Well saga continues with a twist. We took the motor down today and tested encoder. It works when turning shaft by hand Then we decided to dissassemble the motor core since we had it there. Lo and behold! Motor insides were toast! The smell was incredible and it was evident that one phase wire loom has melted on itself. We will now rewire motor and put two (!) KTY84 sensors on wires. Also we see that encoder sensor is a bit old and will replace it with AB magnetic sensor.				-
Inverter was working the shop for overhaul		e time. It was the motor	that was damaged. Now its going	to
To be continued				
			Quote 🕎	8
📄 09-06-2018, 03:00 AM			# <u>2160</u> ∢ ♪ ∕	۸ ۵
joromy Junior Member Â			Join Date: Feb 2 Posts: 18	2018
Re: Another homeb	rew AC-controller			
Does anybody have p	revious firmware, or link to	o d/l?		
I just u/l the newest (3.94 if I remember right) This does not work on my setup.				
Thanks			Quote 22	2
Post Reply	Page 216 of 2	21 Â « First < 116 166 20	06 214 215 216 217 218 > Last Â	» 🗸
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Originally Posted by MattsAwesomeStuff

I am looking at picking up a (free) AC induction motor from a forklift for use in an EV.

Arent we all?

Quote:

Originally Posted by MattsAwesomeStuff

The forklift controller is only a 48v, 700a controller, and, presumably isn't going to be very fast (designed for forklift speeds, not sure about gearing). So right now that's my biggest obstacle.

I have a Zapi 120V 800A inverter at home, that is 90kW approx. My Mazda with 28kW ACIM motor wound for 75Vrms went 180km/h max! It was no slouch either with 8s from 0 to 100km/h. You can get new for 2.5kâ, \neg . I can sell mine for 800â, \neg together with wiring loom.

Quote:

Originally Posted by **MattsAwesomeStuff** Without reading and trying to understand all 54 pages of this thread, can anyone tell me where this 8-year project is and whether it would be suitable?

We are moving at 130km/h every day from home to work and back. Hows that for DIY!

Quote:

Originally Posted by MattsAwesomeStuff 5

Depending on where this community goes and if we regain control of it, I would like to see a highlighted/curated project section to simplify adoption of these kinds of things. I think this is the 4th or 5th DIY controller thread on the forums, but, there's never any overview, summary, explanation, landing page, etc for any project. Which is normal for a discussion forum, it's a great place to discuss things, but it's a terrible place to use the knowledge.

You can start a thread and call it "redacted info of Johannes inverter".

Quote:

Originally Posted by MattsAwesomeStuff

Ideally, a novice could walk in, read up on what the project's goal is/was, what kinds of things it's suitable for, and documentation on how to build it.

You just walked in a store or what?

Quote:

Originally Posted by **MattsAwesomeStuff** *All of these threads are missing that kind of information and in my opinion it's among the most valuable parts of the website (just hidden away in 2200 posts to take this thread for example).*

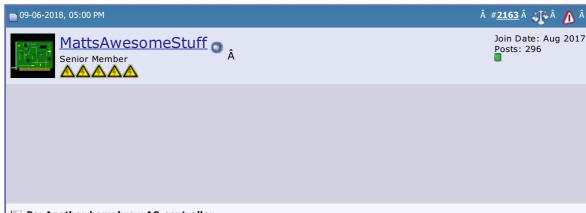
Its only missing because you didnt read it all. Its not about the end goal, its the journey man!

Quote:

Originally Posted by **MattsAwesomeStuff** \sum I'd like to be able to help document projects like this but I'd need help bridging the technical gap.

Quote 2

You are welcomed to give and you shall also recieve...



Quote:

Originally Posted by **arber333** *Arent we all*?

Let me rephrase.

I have been offered said motor and controller for free. As I finish up my motorbike conversion, I'd like to get started on a small car project for the winter.

Quote:

My Mazda with 28kW ACIM motor wound for 75Vrms went 180km/h max! It was no slouch either with 8s from 0 to 100km/h. You can get new for 2.5Kâ, \neg . I can sell mine for 800â, \neg together with wiring loom.

I'm confused. I'm not asking to purchase a motor. I'm asking if this controller project is suitable for EV use.

Quote:

You can start a thread and call it "redacted info of Johannes inverter". You just walked in a store or what? Its only missing because you didnt read it all. Its not about the end goal, its the journey man!

I'm not sure if this is you talking down to me or whatnot, seems like it. I'm not complaining, and I'm not saying I'm entitled to it. I'm saying, I've come across the thread, and I might like to use the knowledge here. But I can't tell what the project is and what it's suitable for, where the project is status-wise, what the latest revisions are, see how to build it, at what point the thread became tech support, what the most common questions are, etc... without reading 2200 posts of highly technical information spread over 8 years that is probably mostly obsolete but I don't know at which point.

My point is this...

If this was my project and my thread (it's not), I would get the most joy from it if the most number of people could benefit from it.

The best way to make that happen, is not "Go read a 2200-post 8-year conversation and figure it out for yourselves."

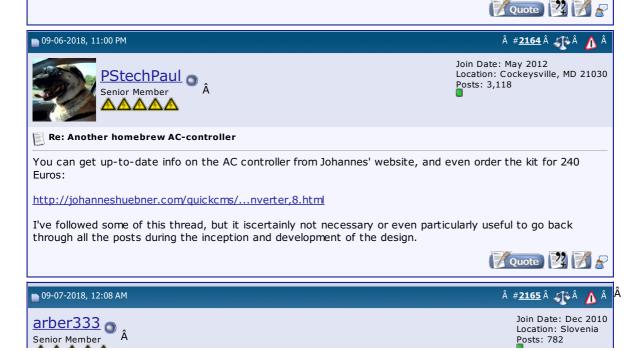
If 30 people have a meeting that goes on for days and days, until about 2200 comments have been said, is the best way to organize that information a gigantic 100 page rambling transcription of it? Or to have someone write out concise meeting minutes, summary, FAQ, etc?

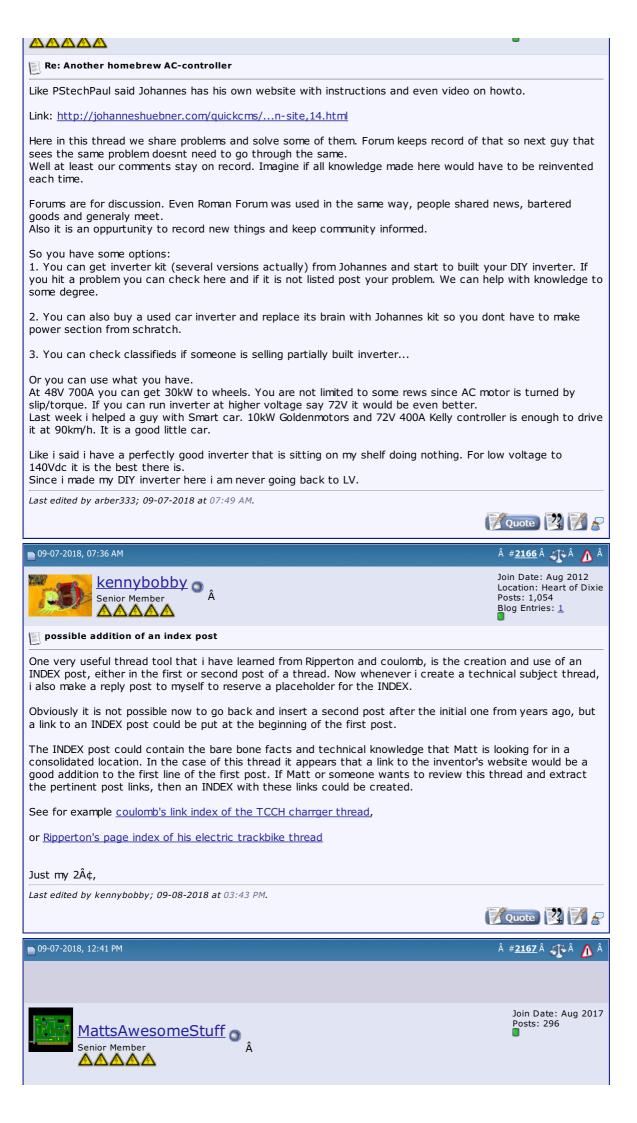
And then if someone asks those questions would you just snap at them and tell them to go read the whole conversation and figure it out themselves?

I think the community would really benefit if we could take some of these projects and create more central pages on them (I would like to see it organized and linked on the front page more like an article, not a forum thread). There's huge amounts of value in some of these projects, but they're poorly documented and the knowledge is poorly organized (by function of it being in a discussion thread, a place optimized to discuss, not host/document/teach).

And I'd offered to help with the documenting, though I'm not sure teaching me is the fastest road to getting there.

Just my two cents. Seems I've ruffled some feathers. Carry on.





Re: possible addition of an index post

Quote:

Originally Posted by **kennybobby** *the creation and use of an INDEX post*

Bingo.

For example, I had no idea Johannes had a website with this stuff on it. It's not linked on the first couple posts, I'm sure it's linked somewhere, probably many times in the following 2200 posts. It's one thing to go looking for something you know exists, but in this case you're looking for something that might not be there to be found, which is extra frustrating.

An index would be personally beneficial to me, but even as an observer, who is curious about these kinds of things, I've looked at some of these giant project threads before and, the lack context makes me tune out. Which is contrary to most people's goals I presume.

Better still, I think some projects like these should be featured prominently on the front page. For all the effort put into them, and the value they bring people, there should be some curated content.



Re: Another homebrev	v AC-controller			
In case anyone missed it https://www.youtube.co		unning on the dyno. Not ba WXLI	ad for open source 🙂	
Now, Cole, when you shi Amps, that's bad. www.evbmw.com	ft the gear and that I	ittle needle on the ammete	er goes into the red and reads 100	00
			Quote 🕎] 8
Post Reply	Page 217 of	221 Â « First < 117 167 20	07 215 216 217 218 219 > Last Â	.» 🗸
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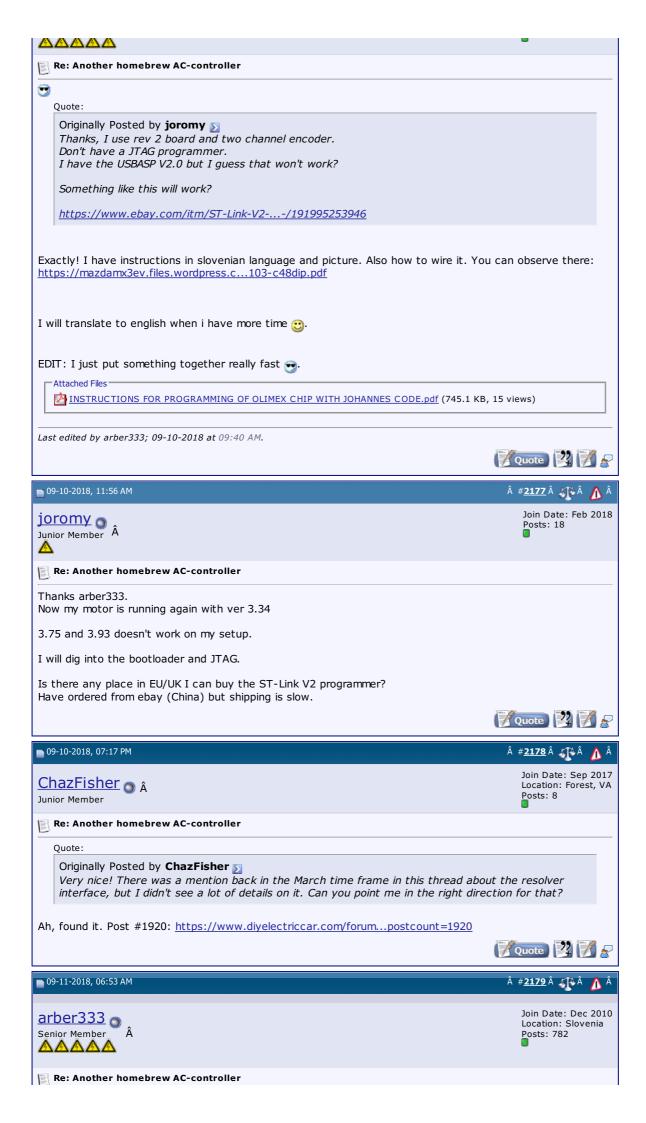
Ad M	anagement by <u>Re</u>	alyger
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Quote:	
Originally Posted by jackbauer BMW i3 traction motor running from the inverter using the LM3 seem to want to speed up beyond a few hundred rpm but that voltage (40v) that I was using. Also the exciter is only managin louder audio amp is needed	may be due to the low dc bus
Generates enough torque to bend a 10mm spanner from a deal engine with this thing	d stop. Next up : crank the rex
ery nice! There was a mention back in the March time frame in this didn't see a lot of details on it. Can you point me in the right direc	tion for that?
	VQuote 🕎 🎢
09-10-2018, 02:30 AM	# <u>2174</u> ≰ ≹ ∕
enior Member Â	Join Date: Dec 20 Location: Sloveni Posts: 782
Re: Another homebrew AC-controller	
UOTE=ECOENERGI1;1020193]	

Quote:	
Originally Posted by joromy Does anybody have previous firmware, or link to d/l?	
I just u/l the newest (3.94 if I remember right)	
This does not work on my setup.	
PM me for an older version	
I think you are using old bootloader. Johannes instructed me to first erase chip ar loader. That way new firmware works from the start. I think problem was with boo something. See some of firmware versions attached. Up to 2017 code was for rev. 1 board w 2018 i only found two versions one before safety correction and one after. From o master board.	otloader locking up or ith single channel only. For
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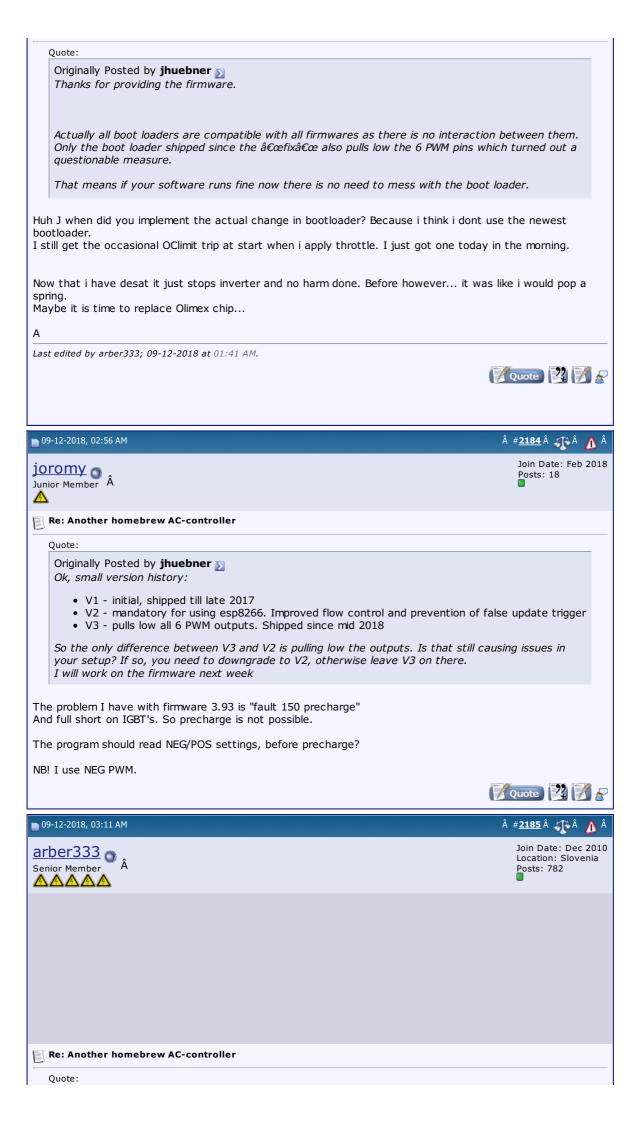


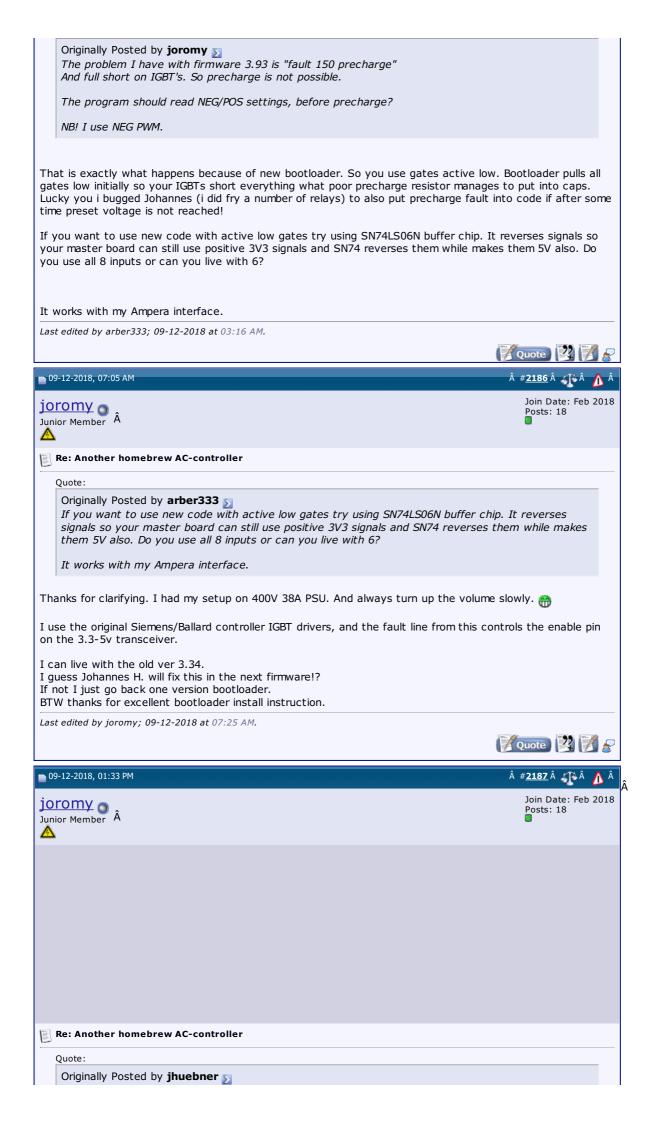
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Quote:			
Originally Posted b	v ioromv 🔊		
Thanks arber333.	_		
Now my motor is i	running again with ver 3	3.34	
3.75 and 3.93 doe	sn't work on my setup.		
I will dig into the b	pootloader and JTAG.		
	in EU/UK I can buy the n ebay (China) but shipp	ST-Link V2 programmer? bing is slow.	
Yes that is because yo	ou have to load new boo	otloader to use new code.	
Check here: https://www.mouser.c	:o.uk/ProductDeta0T2	LUQuW350%3d	
Should have it in stock			
Then make a harness t	to connect it to JTAG all	lways the same way.	
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Thanks for providing th	ne firmware.		
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Actually all boot loader	rs are compatible with a	ll firmwares as there is no in	nteraction between them. Only the
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	Ok, small version history:	
	 V1 - initial, shipped till late 2017 V2 - mandatory for using esp8266. Improved flow control and prevention of fa V3 - pulls low all 6 PWM outputs. Shipped since mid 2018 	alse update trigger
	So the only difference between V3 and V2 is pulling low the outputs. Is that still ca your setup? If so, you need to downgrade to V2, otherwise leave V3 on there. I will work on the firmware next week	using issues in
	t the jtag programmer. Tested to erased the chip, u/l bootloader V3 and firmware V3 ogrammer works.	.93. So the
But	- t where can I find bootloader ver2?	
		Vouote 22 7 🗩
09	9-12-2018, 01:54 PM	# <u>2188</u> ∕∏≷ ∧ Â
	ber333 nior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 782
	Re: Another homebrew AC-controller	
<u> </u>	Quote:	
	Originally Posted by joromy Got the jtag programmer. Tested to erased the chip, u/l bootloader V3 and firmwa programmer works.	are V3.93. So the
	But where can I find bootloader ver2?	
Che	eck my earlier post. There should be code dated 20.12.2016.	
This	is is V2 as you describe it but only for rev. 1 board. Bootloader is the same for both I	nowever.
A		
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jor	9-12-2018, 05:22 PM <u>romy</u> ior Member Â	
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📃 Re: Another home	brew AC-controller			
Quote:				
		h the low cost resolver int	erface 🙂	
Nice work, very smoo	oth. Did you have to setu	o a lot of parameters to ge	et I3 to start smooth?	
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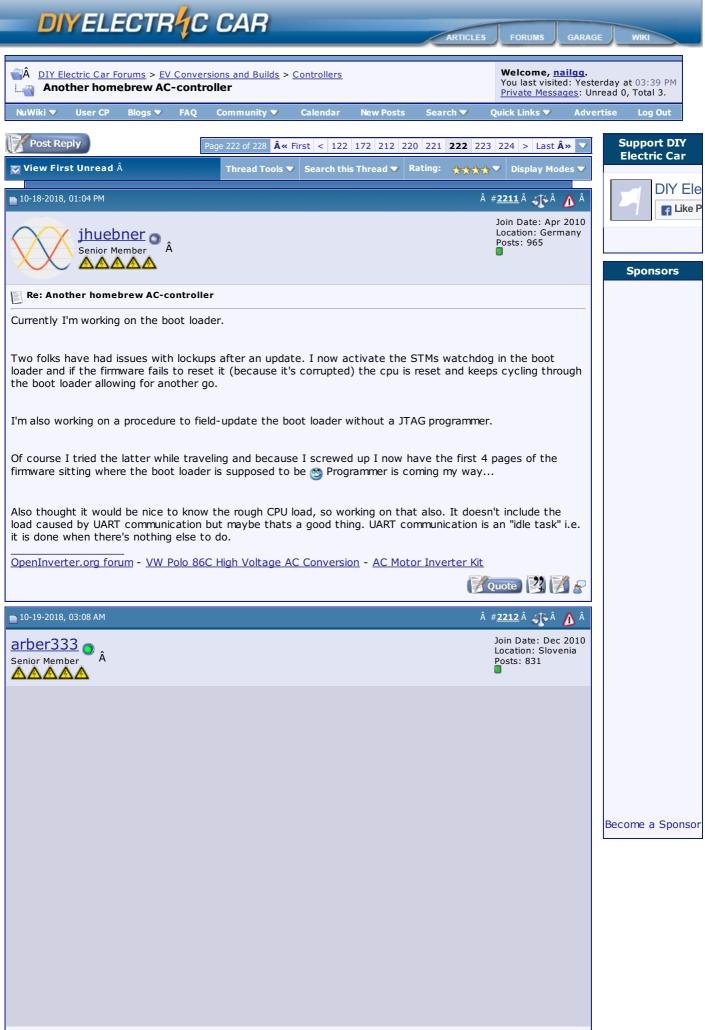
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09-19-2018, 03:42 AM				í	À # <u>2201</u> Â 🀠	À <u>/</u> Â	DIY Ele
jackbauer Senior Member Â					Join Date: Ja Location: Ire Posts: 2,147	land	Sponsors
📃 Re: Another homebrew AC-controller							
Very simple. Resolver position sensor, 3	pole pairs,sync	offset 11	000.				
Now, Cole, when you shift the gear and Amps, that's bad. www.evbmw.com	that little need	dle on the	ammeter goe	es into the re	d and reads 1	000	
				Z	Quote 💦	2	
09-19-2018, 08:13 PM				Í	À # <u>2202</u> Â ()	À 🛆 Â	
ChazFisher () Â Junior Member					Join Date: Se Location: For Posts: 8		
📃 Re: Another homebrew AC-controller							
Quote: Originally Posted by jhuebner Quote: Originally Posted by ChazFishe Do you have control of the DC of That might be a low-risk way to initial startup. Yes they actually default to off in re- is not sitting on a bench permanent	Link contactor o make sure th eset state. Of (e state of course tha	the PWM pin	s doesn't ma	tter on	21-	
Thanks. You're quite right, of course. I everything, it's up to me to make sure it		n I'm worki	ng with a be		at doesn't us Quote		
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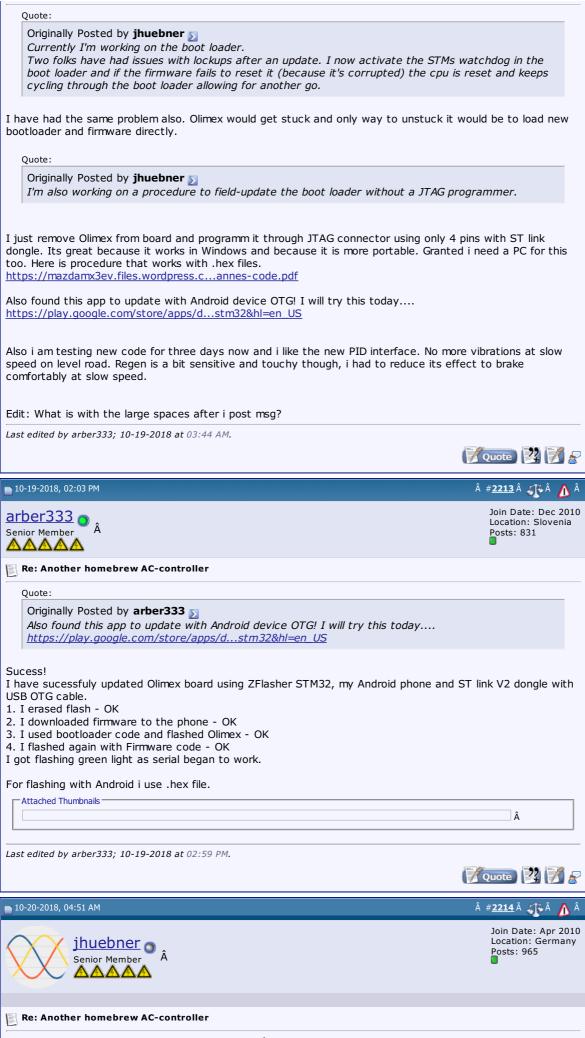
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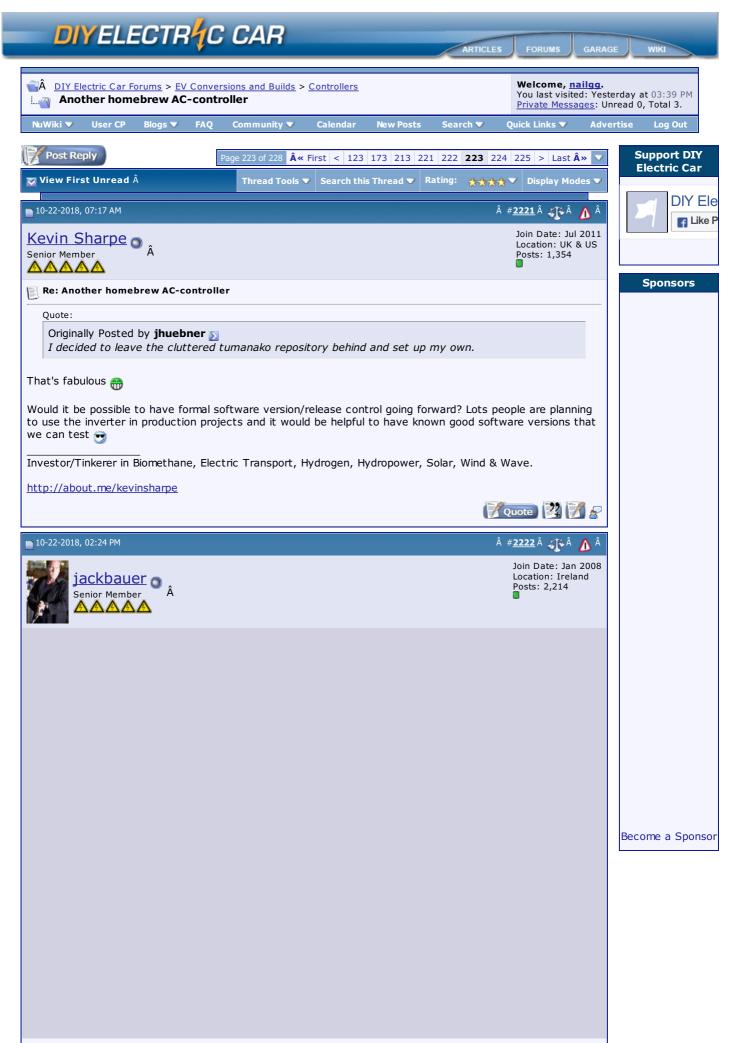
Sweet, over are the times when you needed 300â,¬ worth of equipment for this 😁

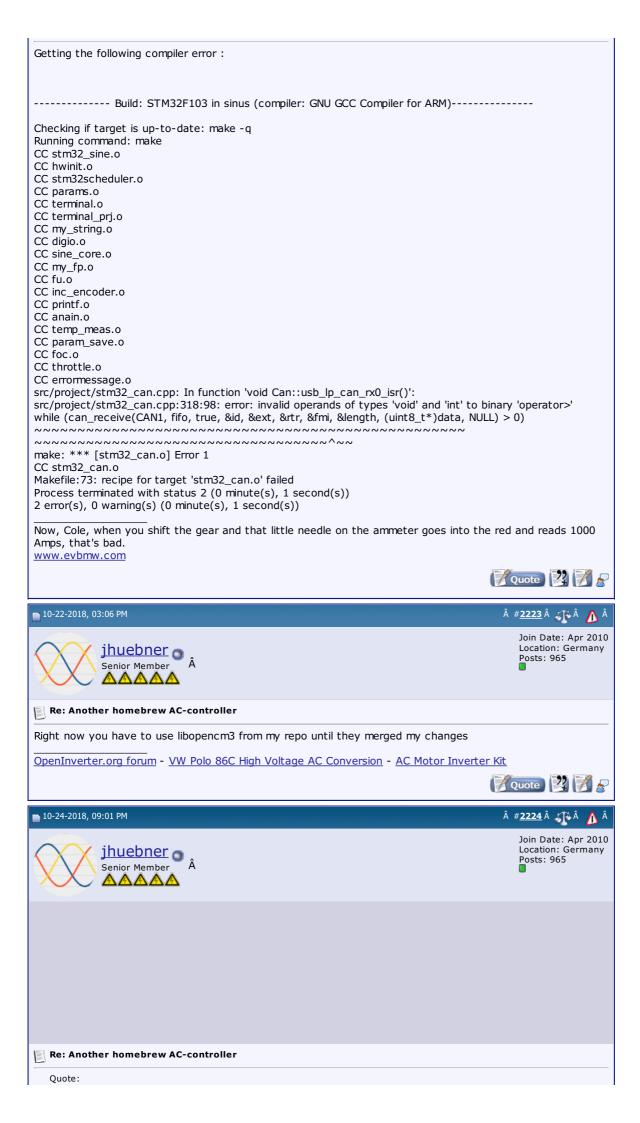




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Re: Another homebre	w AC-controller			
Can I ask is the B.O.M f	or the Leaf bare PCB	adapter Board ?		
Ask the question and loo	ok a fool for 5 minutes	5		
Don't ask the question a	and look a fool forever	. 😔		
			Quote	1
Post Reply	Page 225 o	f 228 Â « First < 125 175 21	5 223 224 225 226 227 > Last	» 🔽
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i don't know because it's not the same shematics.	
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■ 12-03-2018, 10:33 AM	â # <u>2255</u> â 🐠 â <u> â</u> â
ibuebper -	Join Date: Apr 2010 Location: Germany
jhuebner Senior Member Â	Posts: 965
Re: Another homebrew AC-controller	
Yes, 10 Ohm is correct	
OpenInverter.org forum - VW Polo 86C High Voltage AC Conversion - AC Motor Invert	ter Kit
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■ 12-03-2018, 10:43 AM	# <u>2256</u> 🐠 🔥 Â
d@f	Join Date: Jul 2018 Posts: 25
Junior Member Â	
A Re: Another homebrew AC-controller	
ok thanks ! i will try with it 😋	
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■ 12-04-2018, 04:32 AM	# <u>2257</u> ∡ T À ŠÂ
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 831
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by jhuebner Yes, 10 Ohm is correct	
Can you comment on connecting R2 to GND? This means Cruise mode is disabled no?	Is there a reason why?
I havent been paying attention much to resolver mode since i use ABZ encoder for L	
tnx	
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12-04-2018, 05:35 AM	# <u>2258</u> 🕵 🛕 Â
d@f Junior Member Â	Join Date: Jul 2018 Posts: 25
	Â
🛐 Re: Another homebrew AC-controller	

resolver.				
But i have a question on a another power stage with the motor is a leroy some	n a current feed back	?	we could use it to drive with	ו pwm
	nave an asservisseme	ver stage for the rotor, but nt on rotor power by accel	when the car will be on the and rpm.	road, i
			Quote	1 📝 🖉
■ 12-05-2018, 09:59 AM			# <u>2259</u> Â	🏹 Â 🚺 Â
<u>damian.lo</u> ◎ Â ^{Junior Member}			Join Date: Posts: 6	Apr 2018
Re: Another homebrew	AC-controller			
Quote:				
Originally Posted by a Can you comment or reason why?		ND? This means Cruise mod	e is disabled no? Is there a	
	attention much to re	esolver mode since i use AE	3Z encoder for Leaf motor	
tnx				
		done and I put also R6=10 to put encoder than make b	Ohms. Arber, why you put e board? 😋	ncoder
			Quote	1 📝 🖉
■ 12-05-2018, 03:11 PM			# <u>2260</u> Â	🏹 Â 🧥 Â
arber333 Senior Member Â			Join Date: Location: S Posts: 831	Slovenia
📃 Re: Another homebrew	AC-controller			
Pauls controller. It works becomes unbarable and n	nicely with ABZ enco	der up to some 100Vdc. Th	DC motor i was experimentin en chaos and mayhem EM en get ACIM motor work wit	I
at 300Vdc. In process of building ABZ again	' encoder adapter i d	amaged my resolver core. I	dont know if i could get it t	o work
			Quote	1 📝 🖉
Part Barly		age 226 of 228 Â « First < 126	176 216 224 225 226 227	228 > 🔽
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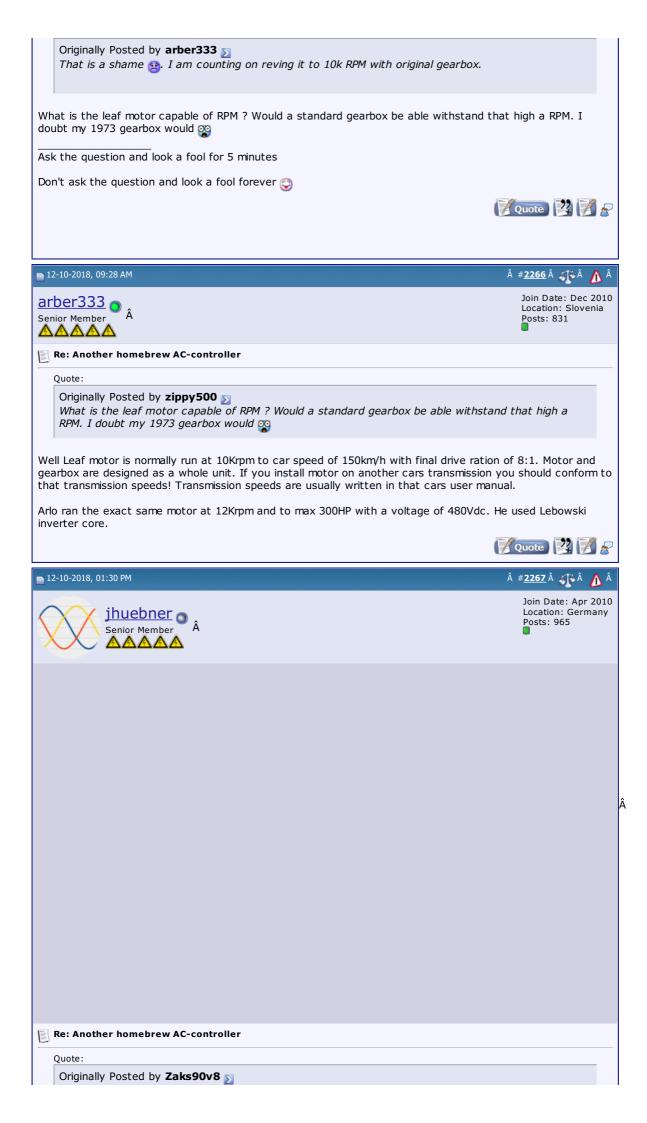
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Quote:	
Originally Posted by jhuebner <i>I lately added support for sin/cos encoders such as MLX90380. Works like your ABZ small magnet on the back of the axis.</i>	version with a
It can do all the high level functions. What it does not do right now is field weakening be able to exceed base speed (e.g. 3000rpm@360V for Leaf motor). But as soon as Touran conversion up and running I'll work on that.	
So the switch over is trouble?	
	Quote 😰 🏹 🎤
■ 12-10-2018, 03:39 AM	# <u>2264</u> 🐼 <u>Å</u> Â
arber333 Senior Member Â	Join Date: Dec 2010 Location: Slovenia Posts: 831
Re: Another homebrew AC-controller	
Quote:	
Originally Posted by jhuebner \sum <i>I lately added support for sin/cos encoders such as MLX90380. Works like your ABZ small magnet on the back of the axis.</i>	version with a
I still have to find the time to try the ABZ encoder with your rev. 3 brain. It will be interesting to try resolver core since for ABZ you have to determine the offset foffset required for resolver? At RLS they say it is essentially the same chip with different I/Os connected.	first. Is there an
Quote: It can do all the high level functions. What it does not do right now is field weakening be able to exceed base speed (e.g. 3000rpm@360V for Leaf motor). But as soon as I conversion up and running I'll work on that.	
That is a shame e. I am counting on reving it to 10k RPM with original gearbox. Do you t it enough field shift for the field to rotate that fast with just V/Hz control? Also dont forg becomes very different function when there is no slip there or can there be little slip hi the field back?	get the regen. It
EDIT: Well i have my Ampera pack just sitting in my workshop at 390Vdc and it volunteer inverter with your rev. 3 board and Leaf motor just lying about . I have one RPM count Want to give it a try at some long distance experimenting?	
A	
Attached Thumbnails	
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Last edited by arber333; 12-10-2018 at 03:46 AM.	
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■ 12-10-2018, 05:24 AM	# 2265 🏠 🧥 Â
zippy500 Member Â	Join Date: Apr 2017 Location: Uk Posts: 73
Re: Another homebrew AC-controller	
Quote:	



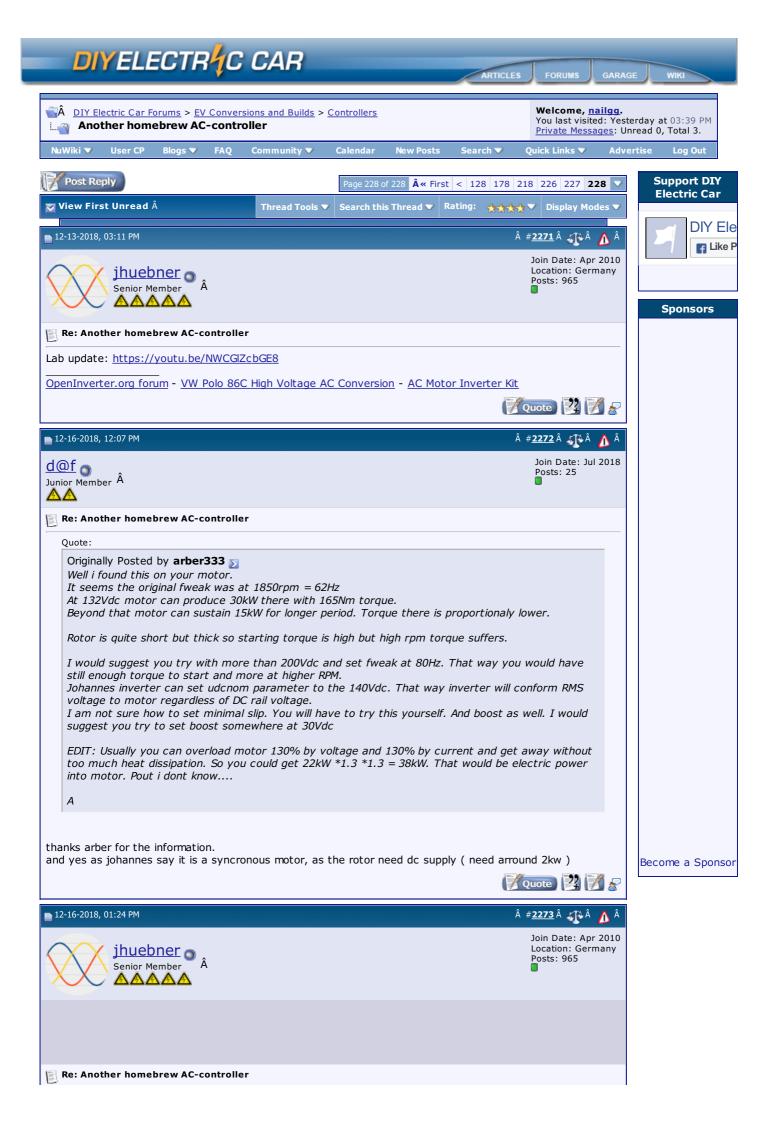
So the switch over is trouble?	
Well field weakening boils down to a different phase angle (syncofs). The higher the speed, the less the ango offset between rotor and stator, I believe. What I have to think through is the fault logic. Basically, if you rev the motor to 10krpm and then for some reason the inverter stalls, the motor will generate roughly 1kV of BEMF voltage as the field is no longer weakened. 1kV will destroy just about everything from IGBTs to caps or it will generate an enormous braking force if the current path to the battery is not interrupted. So it seems in field weakening mode I must never ever turn off the PWM. Any comments?	
Quote:	
Originally Posted by arber333 That is a shame a first a shame of the field shift for the field to rotate that fast with just V/Hz control? Also dont forget the regen. It becomes very different function when there is no slip there or can there be little slip hidden in V/Hz to shift the field back?	
EDIT: Well i have my Ampera pack just sitting in my workshop at 390Vdc and it volunteers to power Ampera inverter with your rev. 3 board and Leaf motor just lying about \bigcirc . I have one RPM counter and ABZ encoder. Want to give it a try at some long distance experimenting? A	
Regen seems pretty simple. Just set the AC output voltage below BEMF voltage. Fhanks for the offer, but I don't know which new info I could get from another idling motor right now. But naybe I can think of something tomorrow 🙂	
DpenInverter.org forum - VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit	
Quote 2	5
12-12-2018, 11:22 AM Â # 2268 Â 🕵 Â 🏠	Â
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J@f Join Date: Jul 20 Posts: 25	
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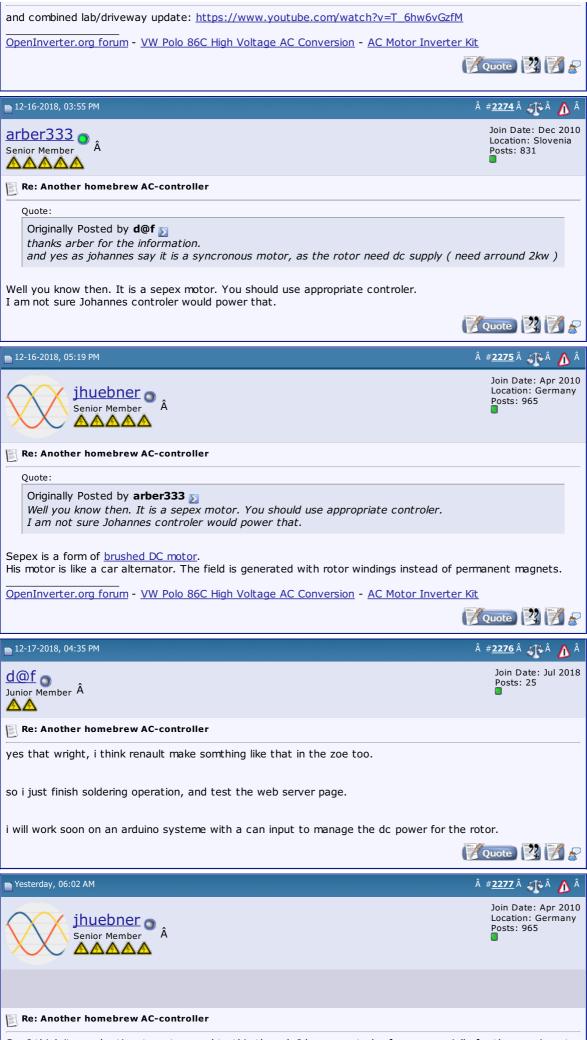
	anyone could help me to found the fweak ?
	it is a 4 poles motor but not conventionnal data on it, only rpm max and nominal voltage:
	ll i found this on your motor. eems the original fweak was at 1850rpm = 62Hz
At	132Vdc motor can produce 30kW there with 165Nm torque.
Bey	rond that motor can sustain 15kW for longer period. Torque there is proportionaly lower.
Rot	or is quite short but thick so starting torque is high but high rpm torque suffers.
Ιw	ould suggest you try with more than 200Vdc and set fweak at 80Hz. That way you would have still
	hugh torque to start and more at higher RPM.
	annes inverter can set udcnom parameter to the 140Vdc. That way inverter will conform <u>RMS Voltage</u> to corregardless of DC rail voltage.
Ιa	n not sure how to set minimal slip. You will have to try this yourself. And boost as well. I would suggest I try to set boost somewhere at 30Vdc
,	
hea	T: Usually you can overload motor 130% by voltage and 130% by current and get away without too much it dissipation. So you could get 22kW $*1.3 *1.3 = 38$ kW. That would be electric power into motor. Pout i it know
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It i Str 100 Op	Join Date: Apr 2010 Senior Member Â Re: Another homebrew AC-controller Is a synchronous motor, so no slip. ange torque curve. They say it runs at full torque till 1850rpm but the curve actually tapers off at 100rpm. cenInverter.org forum - VW Polo 86C High Voltage AC Conversion - AC Motor Inverter Kit Image 227 of 228 Â < First < 127
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So, I think it may be time to put an end to this thread. I have created a forum especially for the openinverter



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